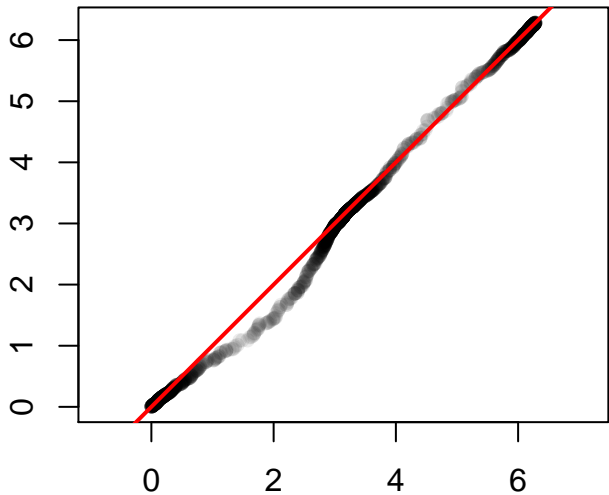


CDF of angles using hit-and-run



CDF of angles using rejection sampling