

Saliency Map-aided Generative Adversarial Network for RAW to RGB Mapping

Yuzhi Zhao¹ Lai-Man Po¹ Tiantian Zhang¹ Zongbang Liao² Xiang Shi² et al.

¹City University of Hong Kong

²Huazhong University of Science and Technology



PROBLEM STATEMENT

Learn a **general mapping** from RAW file to RGB format.

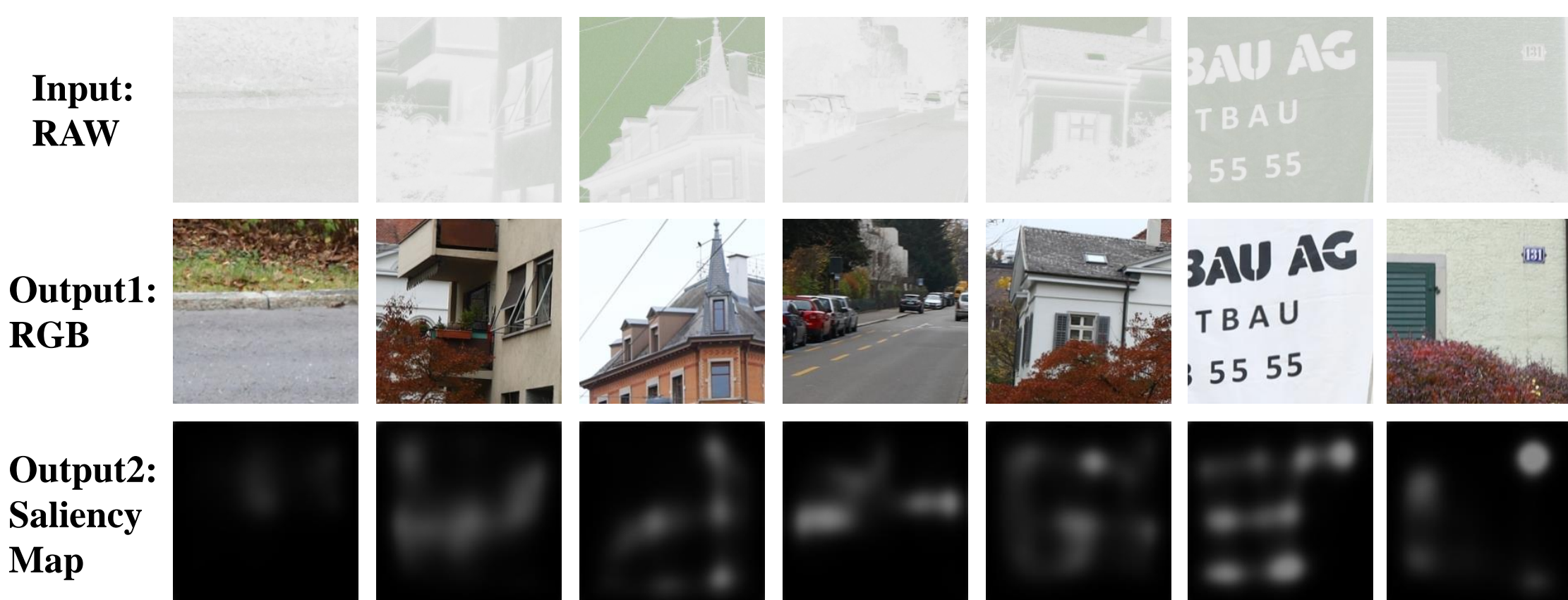
- 1) **Saliency map** implicit data augmentation
 - 2) **Fastest** network across all solutions that produces 28 images per second (224×224 resolution)
 - 3) Transform Huawei RAW file to Canon RGB quality
 - 4) Train a **RAW2RGB GAN** on your own dataset
- Try it: <https://github.com/zhaoyuzhi/RAW2RGB-GAN>

SALIENCY MAP DATA AUGMENTATION (SMDA)

Problem: Traditional data augmentation method (flipping, cropping, rotation) only perform physical transformation.

Goal: Add semantic information to system, which is significant for many domain transfer applications

Procedure: A pre-trained Sal-GAN is adopted to generate saliency maps automatically. Then, the generated saliency maps are utilized to scale pixel-level L1 loss as a proxy target.



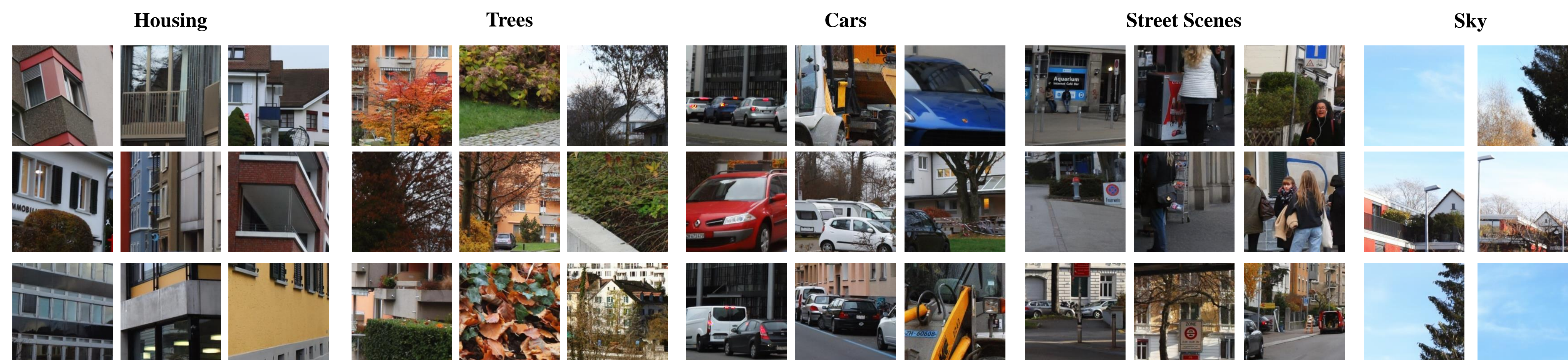
Analysis: RAW2RGB-GAN is a multi-task system. At backward propagation, the gradients from saliency map prediction branch revises mainstream.

Quantitative Result:

We have done an experiment on ImageNet training set on colorization task. SMDA obviously improve high-level representation. Please see more details through this link:

<https://github.com/zhaoyuzhi/Semantic-Colorization-GAN>

QUALITATIVE SAMPLES (224×224 PATCHES)



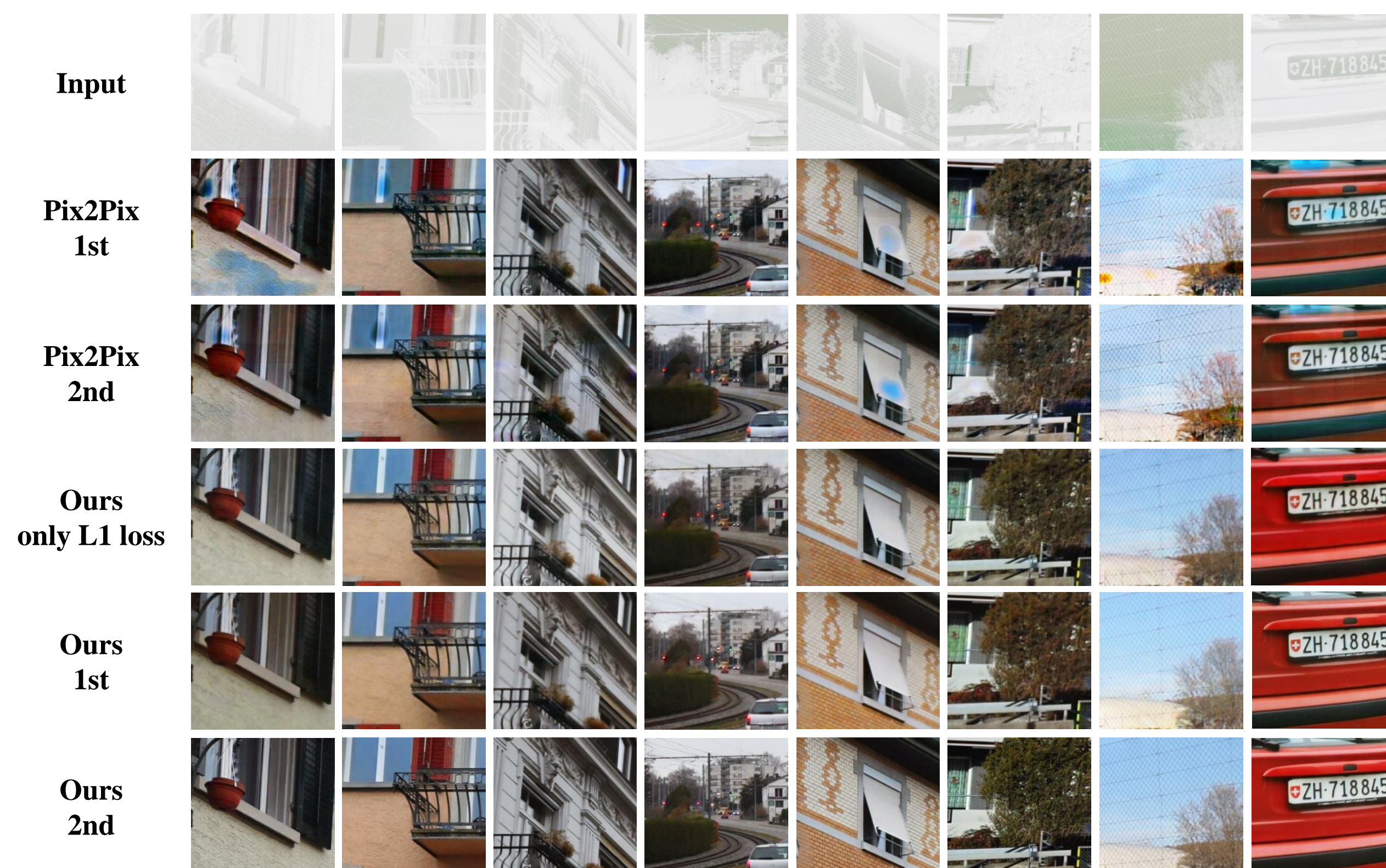
QANTITATIVE ANALYSIS

Baseline: Pix2Pix framework

Stage 1st: only L1 Loss, same epochs

Stage 2nd: L1 Loss, Perceptual Loss, GAN Loss, Attn Loss (Ours)

Method	PSNR	SSIM
Pix2Pix 1st	19.123838	0.712934
Pix2Pix 2nd	19.491088	0.727142
Ours L1	22.244904	0.798523
Ours 1st	22.067571	0.798382
Ours 2nd	22.455825	0.798674



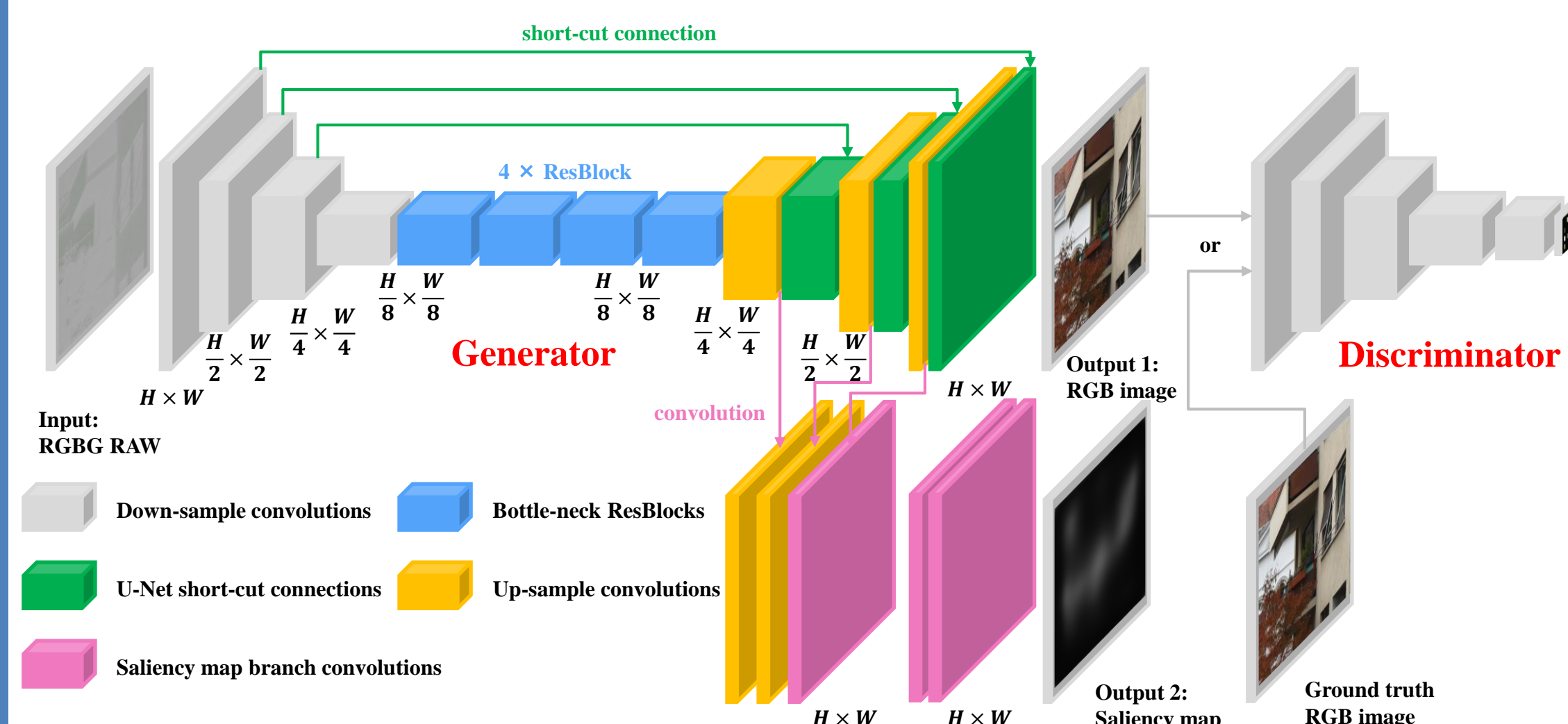
Test Time: For 224×224 patches, it takes 0.03571s (27.98 images / second) to transfer an image on single 1080 Ti.

Full Resolution Testing Result: It takes only 0.5 second for rendering approximately 2000×1500 image.



RAW2RGB-GAN ARCHITECTURE

There are three main parts: mainstream G_1 , saliency map prediction branch G_2 , and patch-based discriminator D .



How to scale L1 Loss using saliency map? (Element-wise)

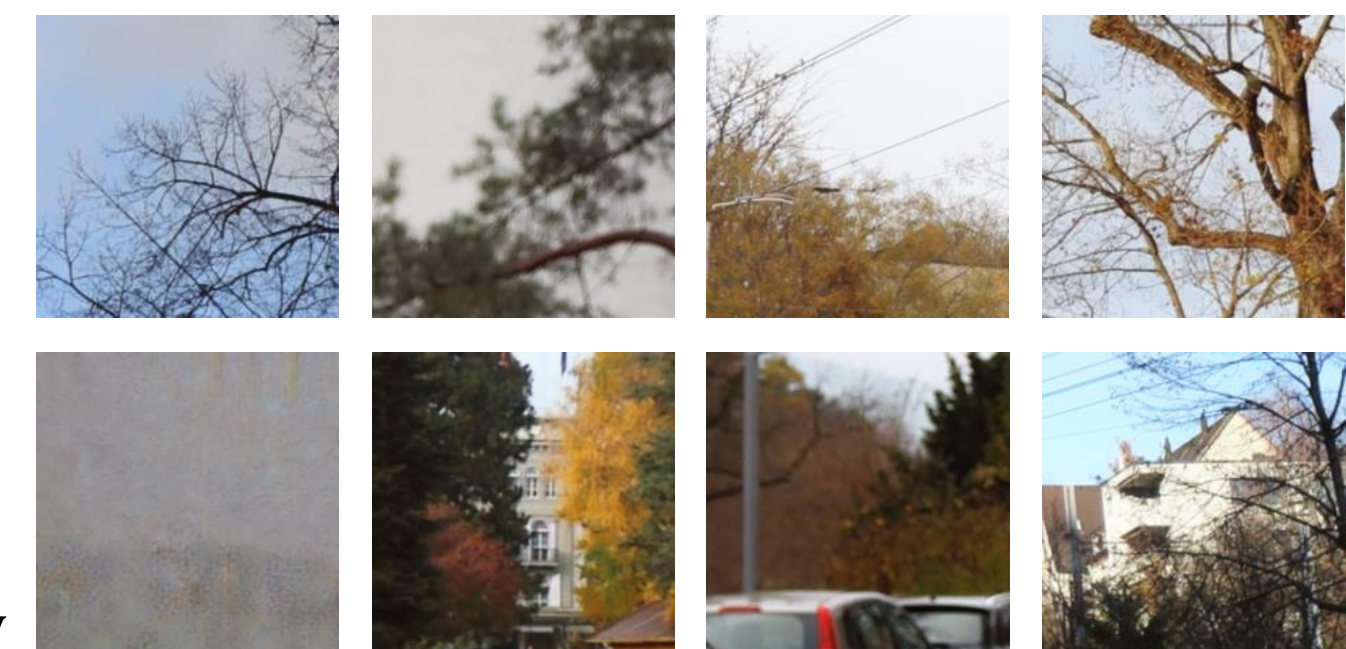
Pixel L1 Loss: $L_1 = \mathbb{E}[\|G_1(x) - y\|_1]$; Attn Loss: $L_A = \mathbb{E}[\|G_1(x) \odot G_2(x) - y \odot s\|_1]$.

How to train the GAN system? (LSGAN, TTUR)

G Loss: $L_G = \frac{1}{2} \mathbb{E}[(D(G_1(x)) - 1)^2]$; D Loss: $L_D = \frac{1}{2} \mathbb{E}[(D(G_1(x)) - 1)^2] - \mathbb{E}[(D(G_1(x)))^2]$.

FAILURE CASES

- 1) Unreasonable blurry
 - 2) Little color bleeding
- In the future, multiple dataset and advanced network architecture can enhance mapping quality



CONCLUSION

We achieve 21.91 PSNR on ZRR testing set, and there are main contributions of proposed RAW2RGB-GAN.

- 1) The saliency map data augmentation (SMDA) enhances the training of network and has been demonstrated in other image translation tasks like colorization.
- 2) A GAN-based solution to automatically transform RAW file of phone to Canon DSLR camera RGB quality.
- 3) The fastest framework that generates nearly 30FPS.