CIS3110 Lecture 8 - Summary Notes

Memory Management Techniques (Virtual Memory, 10.1-10.6)

Memory Allocation Strategies

- Best fit: Works well for data structures with regular-sized nodes (graphs, trees)
- First fit: More efficient for strings and variable-sized objects
- **Practical considerations**: The overhead of searching for optimal placement may exceed memory savings

Buddy System (Virtual Memory, 10.4)

- Binary search algorithm applied to memory management
- Divides memory holes in half recursively until reaching appropriate size
- Creates natural "buddies" for re-merging memory later
- Mathematically superior to other approaches but complex to implement
- Used extensively in Linux kernel

Memory Caching (Virtual Memory, 10.6)

- Cache: Temporary storage for frequently accessed data
- Purpose: Reduces access time by keeping copies closer to the CPU
- **RAM**: Functions as a cache for the paging disk
- Hardware implementation: Located between CPU registers and main memory

Cache Architecture

- Cache lines: Typically 128 bytes (smaller than page size)
- Tags: Memory address identifiers used for lookup
- Lookup method: Parallel hardware comparison (associative memory)
- Cache levels:
 - L1: Inside CPU, smallest, fastest, most expensive
 - L2: Larger, slower, cheaper than L1
 - Main memory: Much larger but significantly slower

Cache Operations

- Cache hit: Requested data found in cache
- Cache miss: Data not in cache; must fetch from slower memory
- During context switch: Caches must be cleared or tagged with process ID
- Cache coherence: Ensuring consistency between cache and memory

Hierarchical Page Tables (Virtual Memory, 10.5)

Problem Addressed

- Flat page tables for 64-bit address spaces would waste enormous amounts of memory
- Most entries would be empty (program only uses small portions of address space)

Implementation

- Two-level lookup:
 - 1. Page directory table: Uses most significant bits of virtual address
 - 2. Page table chunks: Located using page directory entry
- Benefits: Only allocates page table chunks that are actually used
- Addressing: Divides virtual address into:
 - Offset bits (same as traditional page tables)
 - Page directory bits (most significant)
 - Page table bits (middle portion)

Memory Efficiency

- Page table chunks typically page-sized
- Segmentation violations occur when accessing addresses not mapped to any page table chunk

Threads vs. Processes (Processes, 3.1, 3.4; Threads, 4.1-4.3)

Thread Advantages

- Resource efficiency: Share page tables, code, and data segments
- **Creation speed**: Much faster to create than processes
- Memory usage: Lower overhead, only need new stack

Thread Disadvantages

- Complexity: Requires critical section management
- Fragility: One thread crash affects entire process

• Coordination overhead: Requires semaphores, mutexes to prevent race conditions

Real-world Examples

- Microsoft web server: Thread-based (higher efficiency but less fault tolerance)
- Apache web server: Process-based (better isolation, recovery from individual failures)

I/O Systems (I/O Systems, 12.2-12.5)

Computer Architecture for I/O

- CPU-Memory: Connected via data bus
- CPU-Controllers: Connected via control bus
- DMA: Allows controllers direct access to memory

Data Transfer Methods

- **Serial mode**: One word at a time with CPU interrupts
- DMA mode: Bulk transfer directly to memory with single completion interrupt
- Usage patterns:
 - Block devices (disks): Use DMA for efficiency
 - Character devices (keyboards, mice): Use serial transfer

Mass Storage Structure (Mass-Storage Structure, 11.1-11.3)

Disk Drive Components

- Platters: Circular storage media with magnetic surfaces
- Read/write heads: Mounted on arms that move across platters
- Actuator: Moves heads to different positions

Disk Coordinates

- Cylinder: All tracks at same distance from center across all platters
- Head/Surface: Which platter surface
- **Sector**: Angular segment of a track

Disk Performance Factors

- Rotational latency: Time for disk to spin to correct position (3ms avg. at 10,000 RPM)
- Seek time: Time to move heads to correct cylinder (typically 5-10ms)

• Transfer rate: Determined by sector density and rotation speed

Modern Storage Technologies

- HDD: Traditional spinning disks, higher capacity, lower cost
- **SSD**: No moving parts, faster access, more expensive
- Interface compatibility: Both use cylinder/head/sector addressing for driver compatibility

Key Concepts

- 1. Memory management involves trade-offs between algorithmic complexity and actual efficiency gains.
- 2. Caching creates a hierarchy of storage with different speed/capacity/cost characteristics.
- 3. Hierarchical page tables solve the problem of storing page tables for massive address spaces.
- 4. Both threads and processes have specific advantages and disadvantages depending on application needs.
- 5. I/O systems use various strategies to optimize data transfer between peripheral devices and main memory.
- 6. Disk storage performance depends on both physical limitations and logical organization.