libcpm

David Latham

September, 2025

Contents

1	Introduction		
	1.1	What Is libcpm ?	2
	1.2	Usage	2
2	Hea	aders	4
	2.1	C Runtime	4
	2.2	tms99xx	4
	2.3	stdlib	4
	2.4	stdio	4
	2.5	joystick	5
	2.6	$cp/m \ldots \ldots \ldots \ldots \ldots \ldots$	5
	2.7	ay-3-8910	5
3 Graphics Programming		6	
4	Exa	amples	6
\mathbf{A}_{1}	Appendices		
\mathbf{A}_{1}	Appendix A Build		
Appendix B. Skeleton Project			7

1 Introduction

This guide is intended provide some commentary that can be read along with the source code to showcase the various components of the library and how they can be used in your own applications.

You should read the comments in the header files. They are updated during development and will be the most accurate.

1.1 What Is libcpm?

libcpm is a C library that you can link to in your applications for use with the FUZIX-Compiler-Kit. The library is specifically targeted at the Z80-Retro! Single Board Computer by John Winans and the resident CP/M 2.2 operating sytem.

Some standard libraries are implemented where they can be easily backed by the CP/M 2.2 BDOS function calls. Additionally the library includes functions for working with the TMS9918 and Atari style joystick ports on the VDP daughter board designed for the Z80-Retro!.

For instructions on how to install the compiler and this library, see the ./BUILD.md documentation.

1.2 Usage

You can use the by including the headers you need, calling the functions in your code and finally compiling and linking. See: "Listing: 1.2 - Example Makefile" on page 3

The process is something like this:

- Compile fcc -O2 -mz80 -Iinclude -I /opt/fcc/lib/z80/include -c -o main.o main.c
- Link ldz80 -b C0x100 -o main.bin crt0.o main.o libcpm.a
- Truncate dd if=main.bin of=main.com skip=1 bs=256

The linker documentation is very minimal because it's a very minimal linker. The '-b' switch tells the linker to output a binary file without relocatable code. The -C0x100 tells the linker to begin the 'code' segment at 0x100 which is the beginning of the TPA for CP/M.

Because the linker always starts filling code from 0x0000 we need to remove the first 256 bytes using the 'dd' command.

 $^{^{1} \}rm https://codeberg.org/etchedpixels/fuzix-compiler-kit.git$

²https://github.com/z80-retro

Here is an example of one of the Makefiles in the examples directory.

```
TOP=..
  include ../Make.rules
  APPNAME = demo
  all: clean $(APPNAME).com
  $(APPNAME).bin: $(APPNAME).o
    $(LD) $(LDFLAGS) -o $0 $(CRT) $^ $(LIBS)
  $(APPNAME).com: $(APPNAME).bin
dd if=$^ of=$@ skip=1 bs=256
13
14
15
  clean:
    rm -fv $(APPNAME).bin $(APPNAME).com
16
    find . -name "*.o" -exec rm -fv {} \;
  copy: $(APPNAME).com
19
```

Listing 1: Example Makefile

This example does not show the actual FCC commands explicitly. Make is automating that step for us.

2 Headers

The headers are all located in the projects "include" directory. You just need to #include the ones you need and make sure to link to the libcpm.a library.

As the code is split out into multiple translation units, your resulting binary should include almost no wasted code.

2.1 C Runtime

There is a provided crt0.0 object file which should be included in the linking stage. The C runtime performs the following actions:

prep stack Preserve the CP/M stack pointer and set up a new stack pointer at the top of the TPA.

init_sys Calls the _init_sys routine to initialise the "sys_open_files" array.

execute Call the main() function

return Return to CP/M (restoring the CP/M stack and freeing the tms_buffer along the way)

2.2 tms99xx

See Graphics Programming on page 6 for details.

2.3 stdlib

There are two parts to the malloc / free implementation in this library. The first is the implementation of the "sbrk()" system call and the second is the malloc and free functions themselves.

The sbrk() function was copied and adapted from the HiTech C compiler project.

The malloc and free functions are transcribed directly from "The C Programming Language - Second Edition" By Biran W. Kernignhan and Dennis M. Ritchie.

There are is no defragmentation or garbage collection. Malloc doesn't usually make all that much sense in embedded environments.

- \bullet ABS
- EXIT
- FREE From The C Programming Language Book
- ITOA
- MALLOC From The C Programming Language Book
- PUTS Print a zero terminated string constant to the screen. No formatting.

2.4 stdio

- PRINTF Simple implimentation of printf with support for the %c, %s, %d and %x format specifiers only.
- SPRINTF Same as printf but copies formatted text into memory instead of stdout.

2.5 joystick

• JOY(UINT8_T IDX) read the joystick given by idx. 0 = J3, 1 = J4

Also provided in the joy.h header are the button and axis mappings. The bits are aligned with how they are laid out on the 2063 VDP PCB.

Listing 2: Joystick Button Mapping

2.6 cp/m

The CP/M header provides C wrappers for almost all the CP/M BDOS function calls.

For example, if you want to check for keyboard input without blocking, you can call the cpm_rawio() function which returns the ascii char or 0. Unlike cpm_conin(), this function does not emit the typed character to the terminal.

The standard argc, **argv approach for handling command line arguments is currently managed by a seprate function called cpm_parse_args(char **argv, uint8_t count) This will populate an array of pointers with pointers to space sperated tokens from the CPM commandline buffer (0x80). In fact the function makes a copy of this buffer first in case CPM needs it for something later on.

You can find an example of how to use the fileio functions in the "test" folder. The "fcntl.h" header file contains lots of additional information.

2.7 ay-3-8910

The library has some rudimentary support for the ay-3-8910 PSG as implimented on the Z80-Nouveau.

There is no easy way (at the moment) to compile this library for NABU support. A request has been made to the maintainer of FUZIX-Compiler-Kit to ask how to use the assembler in a more dynamic way.

3 Graphics Programming

Figure 1 shows the game loop state machine. The game state is initialised before entering the loop. The loop itself, consists of reading user input, updating the game state and frame-buffer, waiting for vsync, rendering the frame-buffer and looping back to user input.

The VSYNC signal from the VDP provides a stable 60 hertz timer which is used to normalize game speed on different CPU clock frequencies. The standard gameloop waits for the VSYNC signal before rendering to the display to leverage the fast write cycle times during the vertical blanking interval.

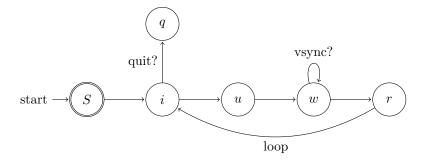


Figure 1: Game Loop

There are a range of TMS99xx functions in the libcpm to initialise the VDP in the various display modes and to manage the frame-buffer.

They can be grouped into the following categories:

- INITIALIZATION Init the VDP in a display mode, enable interrupts and sprite sizes
- LOADING DATA Load patterns, names and colors
- PLOTTING TO THE FRAME BUFFER Plot tiles or pixels in the XY coordinate space into the frame buffer memory.
- Sprites Update sprite attributes to move them around or hide them.
- Flushing the frame buffer to the video memory Stream the framebuffer into VDP memory and flush the sprites array into the Sprite Attribute Table in VDP memory.

Look at the examples/tms folder for an example of how the gameloop works.

4 Examples

There are a few examples in the Examples folder in the Git repository. Each one is designed to demonstrate specific features of this library.

Appendices

Appendix A Build

These are the instructions for getting setup with the compiler-kit so that you can build this library and use it in your code.

Appendix B Skeleton Project

Some text