

## GEOMETRY HOMEWORK 9

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December 1, 2011

**Problem 4** (Ex p.101 14). (*Gradient on Surfaces.*) The gradient of a differentiable function  $f : S \rightarrow \mathbb{R}$  is a differentiable map  $\text{grad } f : S \rightarrow \mathbb{R}^3$  which assigns to each point  $p \in S$  a vector  $\text{grad } f(p) \in T_p(S) \subset \mathbb{R}^3$  such that

$$\langle \text{grad } f(p), v \rangle_p = df_p(v) \quad \text{for all } v \in T_p(S)$$

Show that

- (a) If  $E, F, G$  are the coefficients of the first fundamental form in a parametrization  $\mathbf{X} : U \subset \mathbb{R}^2 \rightarrow S$ , then  $\text{grad } f$  on  $\mathbf{X}(U)$  is given by

$$\text{grad } f = \frac{f_u G - f_v F}{EG - F^2} \mathbf{X}_u + \frac{f_v E - f_u F}{EG - F^2} \mathbf{X}_v$$

In particular, if  $S = \mathbb{R}^2$  with coordinates  $x, y$ ,

$$\text{grad } f = f_x e_1 + f_y e_2$$

where  $\{e_1, e_2\}$  is the canonical basis of  $\mathbb{R}^2$  (thus, the definition agrees with the usual definition of gradient in the plane)

- (b) 為什麼不直接將  $\text{gradient } f$  定義成  $f_u \mathbf{X}_u + f_v \mathbf{X}_v$ ，這有什麼缺點 (例如座標變換)

*Proof.* (a) First,

$$\langle \text{grad } f(p), \mathbf{X}_u \rangle_p = df_p(\mathbf{X}_u) = f_u$$

$$\langle \text{grad } f(p), \mathbf{X}_v \rangle_p = df_p(\mathbf{X}_v) = f_v$$

Let  $\text{grad } f = q\mathbf{X}_u + r\mathbf{X}_v$ . Then

$$\langle \text{grad } f(p), \mathbf{X}_u \rangle = Eq + Fr = f_u$$

$$\langle \text{grad } f(p), \mathbf{X}_v \rangle = Fq + Gr = f_v$$

Therefore, solve the linear equations and get

$$q = \frac{f_u G - f_v F}{EG - F^2};$$

$$r = \frac{f_v E - f_u F}{EG - F^2}$$

Then the two results follow immediately.

- (b) If we define the gradient in that way, let  $S = \mathbb{R}^2$  be the surface and  $\mathbf{X}(u, v) = (u, v)$ ,  $\mathbf{Y}(s, t) = (s, s + t)$  be its two parametrizations. If  $f(u, v) = v$ , then  $f(s, t) = s + t$  and therefore  $\text{grad } f = \mathbf{X}_v = \mathbf{Y}_s + \mathbf{Y}_t$ . But clearly  $\mathbf{X}_v = (0, 1) \neq (1, 2) = \mathbf{Y}_s + \mathbf{Y}_t$ , which is a contradiction.

□

**Problem 7.** 計算下列 *surface* 的  $\Gamma_{ij}^k$  (共有六項)

(b)  $(x(t), y(t) \cos \theta, y(t) \sin \theta)$

(c)  $E = G = \lambda^2, F = 0$

*Proof.* (b) Let  $u = t, v = \theta$ .

$$\begin{aligned}\mathbb{X}_u &= (x_u, y_u \cos v, y_u \sin v) \\ \mathbb{X}_v &= (0, -y \sin v, y \cos v) \\ \rightarrow E &= x_u^2 + y_u^2 \\ F &= 0 \\ G &= y^2\end{aligned}$$

$$\begin{aligned}
[1, 1, 1] &= \frac{E_u}{2} \\
[1, 1, 2] &= -\frac{E_v}{2} \\
[1, 2, 1] &= \frac{E_v}{2} \\
[1, 2, 2] &= \frac{G_u}{2} \\
[2, 2, 1] &= -\frac{G_u}{2} \\
[2, 2, 2] &= \frac{G_v}{2} \\
\Gamma_{11}^1 &= \frac{E_u}{2E} \\
&= \frac{x_u x_{uu} + y_u y_{uu}}{x_u^2 + y_u^2} \\
\Gamma_{11}^2 &= -\frac{E_v}{2G} \\
&= 0 \\
\Gamma_{12}^1 &= \frac{E_v}{2E} \\
&= 0 \\
\Gamma_{12}^2 &= \frac{G_u}{2G} \\
&= \frac{y_u}{y} \\
\Gamma_{22}^1 &= -\frac{G_u}{2E} \\
&= \frac{yy_u}{x_u^2 + y_u^2} \\
\Gamma_{22}^2 &= \frac{G_v}{2G} \\
&= 0
\end{aligned}$$

(c)

$$\begin{aligned}
g^{11} &= \frac{1}{\lambda^2} \\
g^{22} &= \frac{1}{\lambda^2} \\
g^{12} &= g^{21} = 0
\end{aligned}$$

$$\begin{aligned}
[1, 1, 1] &= \frac{E_u}{2} \\
[1, 1, 2] &= -\frac{E_v}{2} \\
[1, 2, 1] &= \frac{E_v}{2} \\
[1, 2, 2] &= \frac{G_u}{2} \\
[2, 2, 1] &= -\frac{G_u}{2} \\
[2, 2, 2] &= \frac{G_v}{2} \\
\Gamma_{11}^1 &= \frac{E_u}{2E} \\
&= \frac{\lambda_u}{\lambda} \\
\Gamma_{11}^2 &= -\frac{E_v}{2G} \\
&= \frac{\lambda_v}{\lambda} \\
\Gamma_{12}^1 &= \frac{E_v}{2E} \\
&= \frac{\lambda_v}{\lambda} \\
\Gamma_{12}^2 &= \frac{G_u}{2G} \\
&= \frac{\lambda_u}{\lambda} \\
\Gamma_{22}^1 &= -\frac{G_u}{2E} \\
&= \frac{\lambda_u}{\lambda} \\
\Gamma_{22}^2 &= \frac{G_v}{2G} \\
&= \frac{\lambda_v}{\lambda}
\end{aligned}$$

□

**Problem 8** (Ex p.237 1, 2). (a) Show that if  $\mathbf{X}$  is an orthogonal parametrization, that is,  $F = 0$ , then

$$K = -\frac{1}{2\sqrt{EG}} \left\{ \left( \frac{E_v}{\sqrt{EG}} \right)_v + \left( \frac{G_u}{\sqrt{EG}} \right)_u \right\}$$

(b) Show that if  $\mathbf{X}$  is an isothermal parametrization, that is,  $E = G = \lambda(u, v)$  and  $F = 0$ , then

$$K = -\frac{1}{2\lambda} \Delta(\log \lambda)$$

where  $\Delta\phi$  denotes the Laplacian  $(\partial^2\phi/\partial u^2)+(\partial^2\phi/\partial v^2)$  of the function  $\phi$ . Conclude that when  $E = G = (u^2 + v^2 + c)^{-2}$  and  $F = 0$ , then  $K = \text{const.} = 4c$ .

*Proof.* (a)

$$\begin{aligned}g^{11} &= \frac{1}{E} \\g^{22} &= \frac{1}{G} \\g^{12} &= g^{21} = 0\end{aligned}$$

$$\begin{aligned}[1, 1, 1] &= \frac{E_u}{2} \\[1, 1, 2] &= -\frac{E_v}{2} \\[1, 2, 1] &= \frac{E_v}{2} \\[1, 2, 2] &= \frac{G_u}{2} \\[2, 2, 1] &= -\frac{G_u}{2} \\[2, 2, 2] &= \frac{G_v}{2} \\\Gamma_{11}^1 &= \frac{E_u}{2E} \\\Gamma_{11}^2 &= -\frac{E_v}{2G} \\\Gamma_{12}^1 &= \frac{E_v}{2E} \\\Gamma_{12}^2 &= \frac{G_u}{2G} \\\Gamma_{22}^1 &= -\frac{G_u}{2E} \\\Gamma_{22}^2 &= \frac{G_v}{2G}\end{aligned}$$

$$\begin{aligned}
R_{112}^2 &= \Gamma_{11,2}^2 - \Gamma_{12,1}^2 + \Gamma_{11}^1 \Gamma_{21}^2 + \Gamma_{11}^2 \Gamma_{22}^2 - \Gamma_{12}^1 \Gamma_{11}^2 - \Gamma_{12}^2 \Gamma_{12}^2 \\
&= -\left(\frac{E_v}{2G}\right)_v - \left(\frac{G_u}{2G}\right)_u + \frac{E_u}{2E} \frac{G_u}{2G} - \frac{E_v}{2G} \frac{G_v}{2G} + \frac{E_v}{2E} \frac{E_v}{2G} - \frac{G_u}{2G} \frac{G_u}{2G} \\
&= -\frac{GE_{vv} - G_v E_v}{2G^2} - \frac{GG_{uu} - G_u G_u}{2G^2} + \frac{E_u}{2E} \frac{G_u}{2G} - \frac{E_v}{2G} \frac{G_v}{2G} + \frac{E_v}{2E} \frac{E_v}{2G} - \frac{G_u}{2G} \frac{G_u}{2G} \\
&= \frac{1}{4G^2} \left( -2GE_{vv} + G_v E_v - 2GG_{uu} + G_u G_u + \frac{GE_u}{E} G_u + \frac{GE_v}{E} E_v \right) \\
K &= \frac{R_{1212}}{EG} \\
&= \frac{GR_{112}^2}{EG} \\
&= \frac{R_{112}^2}{E} \\
&= \frac{1}{4EG^2} \left( -2GE_{vv} + G_v E_v - 2GG_{uu} + G_u G_u + \frac{GE_u}{E} G_u + \frac{GE_v}{E} E_v \right) \\
&= \frac{1}{4} \left( -2\frac{E_{vv}}{EG} - 2\frac{G_{uu}}{EG} + \frac{E_v G_v}{EG^2} + \frac{E_u G_u}{E^2 G} + \frac{G_u G_u}{EG^2} + \frac{E_v E_v}{E^2 G} \right) \\
&\quad - \frac{1}{2\sqrt{EG}} \left\{ \left( \frac{E_v}{\sqrt{EG}} \right)_v + \left( \frac{G_u}{\sqrt{EG}} \right)_u \right\} \\
&= -\frac{1}{2\sqrt{EG}} \left\{ \frac{\sqrt{EG} E_{vv} - \frac{E_v G + EG_v}{2\sqrt{EG}} E_v}{EG} + \frac{\sqrt{EG} G_{uu} - \frac{E_u G + EG_u}{2\sqrt{EG}} G_u}{EG} \right\} \\
&= -\frac{1}{2} \left\{ \frac{E_{vv} - \frac{E_v G + EG_v}{2EG} E_v}{EG} + \frac{G_{uu} - \frac{E_u G + EG_u}{2EG} G_u}{EG} \right\} \\
&= \frac{1}{4} \left( -2\frac{E_{vv}}{EG} - 2\frac{G_{uu}}{EG} + \frac{E_v G_v}{EG^2} + \frac{E_u G_u}{E^2 G} + \frac{G_u G_u}{EG^2} + \frac{E_v E_v}{E^2 G} \right)
\end{aligned}$$

$$\text{So } K = -\frac{1}{2\sqrt{EG}} \left\{ \left( \frac{E_v}{\sqrt{EG}} \right)_v + \left( \frac{G_u}{\sqrt{EG}} \right)_u \right\}.$$

(b)

$$\begin{aligned}
K &= -\frac{1}{2\sqrt{EG}} \left\{ \left( \frac{E_v}{\sqrt{EG}} \right)_v + \left( \frac{G_u}{\sqrt{EG}} \right)_u \right\} \\
&= -\frac{1}{2\lambda} \left\{ \left( \frac{\lambda_v}{\lambda} \right)_v + \left( \frac{\lambda_u}{\lambda} \right)_u \right\} \\
\Delta(\log \lambda) &= (\log \lambda)_{uu} + (\log \lambda)_{vv} \\
&= \left( \frac{\lambda_u}{\lambda} \right)_u + \left( \frac{\lambda_v}{\lambda} \right)_v \\
&\rightarrow K = -\frac{1}{2\lambda} \Delta(\log \lambda)
\end{aligned}$$

□