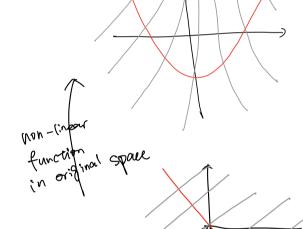


all point on this line have the same PCA coefficient

Non-linear

ut to project onto non-linear function



D: apply x transformation & Rernel trick

Isvear transform in high dim space

verrel PCA:

Data & MI, M)

Apply feat transform. $(x_1 - x_1) = X \rightarrow \mathbb{Q} = \mathbb{Q}(x_1) - \mathbb{Q}(x_1)$

- Assume X-formed data is centered . Ep(xi)=0
- conariance matrix in high-dim space

$$C = \frac{1}{N} \sum_{i=1}^{N} \phi(X_i) \phi(X_i)^{T} \quad (Note: Zen mean)$$

- Find
$$(x_i, v_j)$$
 eigen value / eigen vector

$$(v_j = \lambda_j v_j)$$

$$\frac{1}{N} \stackrel{\text{D}}{=} (x_m) \oint (x_m)^T v_j = \lambda_j v_j$$

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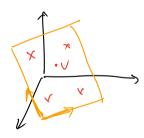
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$$\frac{1}{N} \stackrel{\text{D}}{=} (x_m) \oint (x_m) \oint$$

An equivalent set of equs is to project into x.x. the woodinates of Span of \$\bar{\pi}\$ and solve there.



eif k is not invertible the only difference is the eigenhectors of hi=0 sourt those ove not PC's because X=0 Solve 1 anyway

original eigen

$$KKaj = N\lambda_{1}Ka_{3}$$

$$N\lambda_{1}Kaj = N\lambda_{1}N\lambda_{1}a_{3}$$

$$N\lambda_{1}Kaj = N\lambda_{1}N\lambda_{1}a_{3}$$

$$N\lambda_{1}a_{3} = N^{2}\lambda_{1}^{2}a_{3}$$

$$N^{2}\lambda_{1}^{2}a_{3} = N^{2}\lambda_{1}^{2}a_{3}$$

PC should be normalized

$$\sqrt{j} V_j = 1 = \alpha_j^{\top} \vec{D}^{\top} \vec{D} \alpha_j = \alpha_j^{\top} k \alpha_j$$

$$= N \lambda_j \alpha_j^{\top} \alpha_j$$

$$\alpha_j \in \sqrt{N \lambda_j} \alpha_j$$

Kernel Centering

How to center the feature space?

centered feature

$$\widehat{\phi}(X_i) = \widehat{\phi}(X_i) - \frac{1}{N} \sum_{k=1}^{N} \widehat{\phi}(X_k)$$
we are in f.s
$$= \widehat{\phi}(X_i) - \frac{1}{N} \underbrace{p1}_{l} \underbrace{1 \text{ values}}_{l} [i]$$

Centered data

Centered Kernel

$$\widehat{K} = \widehat{\Phi}^{T} = (I - \overline{h}11^{T})^{T} \Phi^{T} \Phi (I - \overline{h}11^{T})$$

$$\widehat{K} = (I - \overline{h}11^{T}) K (I - \overline{h}11^{T})$$

test kernel:

nel:

$$\widetilde{K}(X_{k}, X_{j}) = K(X_{k}, X_{j}) - \overline{N}K_{k}^{T} [-\overline{N}K_{j}^{T}] + \overline{N}^{2}I^{T}K_{j}^{T}$$

Summary: KPCA

Dicalculate kernel matrix: K=[K(X:, X;)] =j

2) center the kernel, &=(I-\(\hat{11}\)\(\I-\(\hat{11}\)

3) Find the top D eigenhectors: Eag = 1500g, j=1....)

w) Scale age 方面; (Ngw新沙中所必里和上面或有不同,本情一样)

f) project data Xx: Zx, = Kx as

2*; = Z a; KCX*, (Xi)

Note: original problem needs d-dim eigenvector bernel problem needs M-dim eigenvector pick problem that is more efficient.

PS (0-15: Kernelized FLD-) Kernal discriminant analysis.

Dre-image Problem

Given PCA well ξ , we can reconstruct \hat{x} , e.g. denoisy x $\hat{x} = \frac{7}{5}v_1^2 + \frac{7}{5}v_2^2 + \frac{7}{5}v_1^2 + \frac{7}{5}v$

What about KPCA?

-Given Z. What is the high dimension feature?

 $\hat{\phi} = \sum_{j} V_{j} \geq_{j} = \sum_{j} \Phi \alpha_{j} \geq_{j} = \Phi \left(\sum_{j} \alpha_{j} \geq_{j} \right) \quad \hat{\phi} \in \operatorname{Span}(\overline{\Phi})$

But , not all points span (€) have a corresponding x!



Example: (et
$$\phi(x) = \begin{bmatrix} x^2 \\ x \end{bmatrix}$$
 $\begin{cases} x_1 = 1 \Rightarrow \phi(x_1) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{cases}$
 $\begin{cases} x_2 = 2 \Rightarrow \phi(x_1) = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \end{cases}$ what is \hat{x} set $\hat{\phi} = \phi(\hat{x})$?

There is no \hat{x} possible

Tokinste Pie. Image

Approximate Pre-Image general problem $\hat{\phi} = \bar{D} \propto = \bar{\Sigma} \Delta_z \Phi(x_z)$ Find $\hat{x} = \operatorname{argmin} \| \phi(x) - \hat{\phi} \|^2 \mathcal{L}$ find the x that gives the closest ϕ in the f.s. efective space) \(= argmn \(\(\times \(\times \) - 2\(\times \times \(\times \times \times \) + \(\times \tim = argmin K(x,x) - 2 [d: K(x,xi)

Solu 1: nearest neighbour select KEX (traing data)

Solu 2: solve optimization problem numerically up package

Soln 3: suppose KCX,X)=1, KCX2,X,) 20 (e.g. Gaussian)

$$\hat{X} = \operatorname{argmin} - \sum_{i} d_{i} \left(k(X_{i}, X_{i}) \right)$$

= argman [Schik (x. Vi) < \$\frac{1}{2} \times \t

assume homogenous beind, Kellk-Kill2)

iteractive algorithm $\hat{X} \leftarrow \frac{\sum_{i} d_{i} k' (||X_{i} - \hat{X}||^{2}) X_{i}}{\sum_{i} d_{i} k' (||X_{i} - \hat{X}||^{2})}$ Similiar to mean-shift on weights or on each point X2