最近在看RCNN和微软的SPP-net,其中涉及到Non-Maximum Suppression,论文中没具体展开,我就研究下了代码,这里做一个简单的总结,听这个名字感觉是一个很高深的算法,其实很简单,就是把找出score比较region,其中需要考量不同region的一个重叠问题。

假设从一个图像中得到了2000region proposals,通过在RCNN和SPP-net之后我们会得到2000*4096的一个特征矩阵,然后通过N的SVM来判断每一个region属于N的类的scores。其中,SVM的权重矩阵大小为4096*N,最后得到2000*N的一个score矩阵(其中,N为类别的数量)。

Non-Maximum Suppression就是需要根据score矩阵和region的坐标信息,从中找到置信度比较高的bounding box。首先,NMS计算出每一个bounding box的面积,然后根据score进行排序,把score最大的bounding box作为队列中。接下来,计算其余bounding box与当前最大score与box的IoU,去除IoU大于设定的阈值的bounding box。然后重复上面的过程,直至候选bounding box为空。最终,检测了bounding box的过程中有两个阈值,一个就是IoU,另一个是在过程之后,从候选的bounding box中剔除score小于阈值的bounding box。需要注意的是:Non-Maximum Suppression一次处理一个类别,如果有N个类别,Non-Maximum Suppression就需要执行N次。

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源代码:
function pick = nms(boxes, overlap)
% top = nms(boxes, overlap)
% Non-maximum suppression. (FAST VERSION)
% Greedily select high-scoring detections and skip detections
% that are significantly covered by a previously selected
% detection.
% NOTE: This is adapted from Pedro Felzenszwalb's version (nms.m),
% but an inner loop has been eliminated to significantly speed it
% up in the case of a large number of boxes
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% All rights reserved.
%
% This file is part of the Exemplar-SVM library and is made
% available under the terms of the MIT license (see COPYING file).
% Project homepage: https://github.com/quantombone/exemplarsvm
if isempty(boxes)
  pick = [];
  return;
end
x1 = boxes(:,1);
y1 = boxes(:,2);
x2 = boxes(:,3);
y2 = boxes(:,4);
s = boxes(:,end);
area = (x2-x1+1) .* (y2-y1+1);
                                 %计算出每一个bounding box的面积
[vals, I] = sort(s);
                                   %根据score递增排序
pick = s*0;
counter = 1;
while ~isempty(I)
  last = length(I);
  i = I(last);
  pick(counter) = i;
                               %选择score最大bounding box加入到候选队列
  counter = counter + 1;
  xx1 = max(x1(i), x1(I(1:last-1)));
  yy1 = max(y1(i), y1(I(1:last-1)));
  xx2 = min(x2(i), x2(I(1:last-1)));
  yy2 = min(y2(i), y2(I(1:last-1)));
 w = max(0.0, xx2-xx1+1);
  h = max(0.0, yy2-yy1+1);
  inter = w.*h;
                      %计算出每一bounding box与当前score最大的box的交集面积
  o = inter ./ (area(i) + area(I(1:last-1)) - inter); %IoU (intersection-over-union)
  I = I(find(o<=overlap)); %找出IoU小于overlap阈值的index
end
pick = pick(1:(counter-1));
```