# ENGR 3321: Introduction to Deep Learning for Robotics

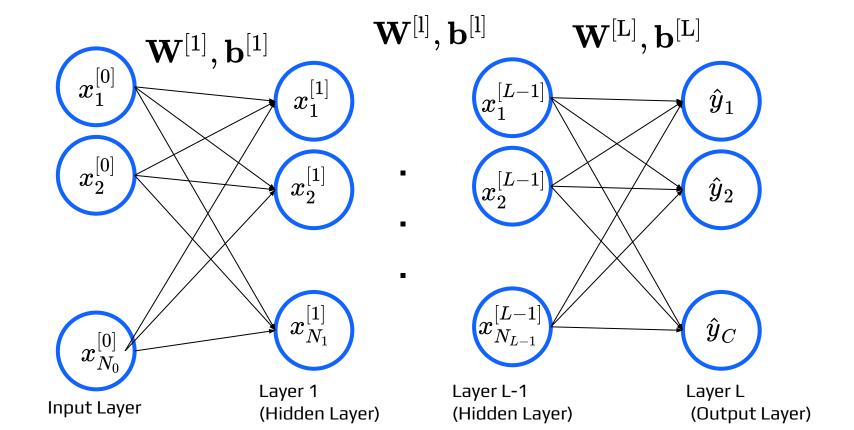
Neural Network NNN: Multi-Layer Perceptron Model



#### Outline

- Representations
- ReLU Activation
- One-Hot Encoding
- Softmax Activation
- Multi-Class Cross Entropy

## Multi-Layer Perceptron Model



## Individual Representation

$$x_n^{[l]} = \sigma \Big( w_{1n}^{[l]} x_1^{[l-1]} + w_{2n}^{[l]} x_2^{[l-1]} + \ldots + w_{N_{l-1}n}^{[l]} x_{N_{l-1}}^{[l-1]} + b_n^{[L]} \Big)$$

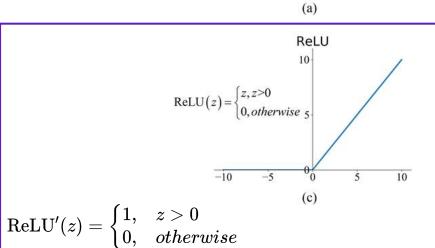
#### Matrix Form

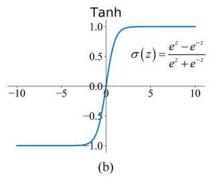
$$\mathbf{X}^{[l]} = a\Big(\mathbf{Z}^{[l]}\Big) = a\Big(\mathbf{X}^{[l-1]}\cdot\mathbf{W}^{[l]\mathrm{T}} + \mathbf{b}^{[l]}\Big)$$

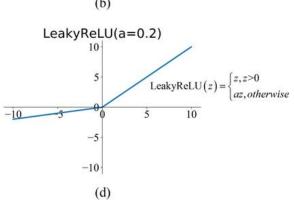
 $a(\cdot)$  activation function

#### Activation Functions

$$\sigma'(z)=\sigma(z)(1-\sigma(z))$$
 Sigmoid 
$$\sigma(z)=\frac{1}{1+e^{-z}}$$







 $ext{LeakyReLU}'(z) = egin{cases} 1, & z > 0 \ a, & otherwise \end{cases}$ 

 $\sigma'(z) = 1 - \sigma^2(z)$ 

## Feature (Input) Matrix

$$\mathbf{X}^{[0]} = egin{bmatrix} ^{(1)}x_1^{[0]} & ^{(1)}x_2^{[0]} & \dots & ^{(1)}x_{N_0}^{[0]} \ ^{(2)}x_1^{[0]} & ^{(2)}x_2^{[0]} & \dots & ^{(2)}x_{N_0}^{[0]} \ & & & \dots & & \ ^{(M)}x_1^{[0]} & ^{(1)}x_2^{[0]} & \dots & ^{(M)}x_{N_0}^{[0]} \end{bmatrix}_{(M,N_0)}$$

### Trainable Parameters

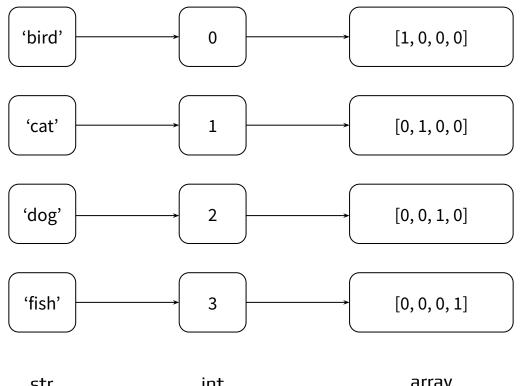
$$\mathbf{b}^{[l]} = egin{bmatrix} b_1^{[l]} & b_2^{[l]} & \dots & b_{N_l}^{[l]} \end{bmatrix}_{(1,N_l)}$$

## Target and Prediction

$$\mathbf{y} = \begin{bmatrix} egin{array}{c} (1) \mathbf{y} \\ (2) \mathbf{y} \\ \vdots \\ \vdots \\ (M) \mathbf{y} \end{bmatrix}_{(M,1)} \hat{\mathbf{y}} = \begin{bmatrix} egin{array}{c} (1) \hat{\mathbf{y}} \\ (2) \hat{\mathbf{y}} \\ \vdots \\ \vdots \\ (M) \hat{\mathbf{y}} \end{bmatrix}_{(M,1)}$$

**NOT RECOMMEND** 

## One-Hot Encoding on Targets



int str array

#### Softmax Activation on Predictions

$$\hat{y}_c = rac{e^{z_c^{[L]}}}{\sum_{c=1}^C e^{z_c^{[L]}}}, \, orall c = 1, \ldots, C$$

$$\sum igl[ {}^{(m)} \hat{y}_1 \quad {}^{(m)} \hat{y}_2 \quad \dots \quad {}^{(m)} \hat{y}_C igr] = 1$$
 Probability of the  $\emph{m}$ -th sample being

predicted as a member in class 1

#### Multi-Class Classification

$$\mathbf{Y} = \begin{bmatrix} {}^{(1)}y_1 & {}^{(1)}2 & \dots & {}^{(1)}y_C \\ {}^{(2)}y_1 & {}^{(2)}y_2 & \dots & {}^{(2)}y_C \\ & & & & & & \\ {}^{(M)}y_1 & {}^{(M)}y_2 & & {}^{(M)}y_C \end{bmatrix}_{(M,C)} \qquad \hat{\mathbf{Y}} = \begin{bmatrix} {}^{(1)}\hat{y}_1 & {}^{(1)}\hat{y}_2 & \dots & {}^{(1)}\hat{y}_C \\ {}^{(2)}\hat{y}_1 & {}^{(2)}\hat{y}_2 & \dots & {}^{(2)}\hat{y}_C \\ & & & & & \\ {}^{(M)}\hat{y}_1 & {}^{(M)}\hat{y}_2 & & {}^{(M)}\hat{y}_C \end{bmatrix}_{(M,C)}$$

# Forward Propagation

$$\mathbf{Z}^{[l]} = \mathbf{X}^{[l-1]} \cdot \mathbf{W}^{[l]\mathrm{T}} {+} \mathbf{b}^{[l]}$$

$$\mathbf{Z}^{[l]} = \begin{bmatrix} ^{(1)}x_1^{[l-1]} & ^{(1)}x_2^{[l-1]} & \dots & ^{(1)}x_{N_{l-1}}^{[l-1]} \\ ^{(2)}x_1^{[l-1]} & ^{(2)}x_2^{[l-1]} & \dots & ^{(2)}x_{N_{l-1}}^{[l-1]} \\ & & & & & & & \\ ^{(M)}x_1^{[l-1]} & ^{(M)}x_2^{[l-1]} & \dots & ^{(M)}x_{N_{l-1}}^{[l-1]} \end{bmatrix} \cdot \begin{bmatrix} w_{11}^{[l]} & w_{12}^{[l]} & \dots & w_{1N_l}^{[l]} \\ w_{21}^{[l]} & w_{22}^{[l]} & \dots & w_{2N_l}^{[l]} \\ & & & & & & \\ w_{N_{l-1}1}^{[l]} & w_{N_{l-1}2}^{[l]} & \dots & w_{N_{l-1}N_l}^{[l]} \end{bmatrix} + \begin{bmatrix} b_1^{[l]} & b_2^{[l]} & \dots & b_{N_l}^{[l]} \\ b_1^{[l]} & b_2^{[l]} & \dots & b_{N_l}^{[l]} \\ & & & & & \\ b_1^{[l]} & b_2^{[l]} & \dots & b_{N_l}^{[l]} \end{bmatrix}$$

$$\mathbf{X}^{[l]} = a\Big(\mathbf{Z}^{[l]}\Big)$$

Special Case:

$$\mathbf{\hat{Y}} = a\Big(\mathbf{X}^{[ ext{L}-1]}\mathbf{W}^{[ ext{L}] ext{T}} \!+\! \mathbf{b}^{[ ext{L}]}\Big) = a\Big(\mathbf{Z}^{[ ext{L}]}\Big) = \mathbf{X}^{[ ext{L}]}$$

#### Multi-Class Cross Entropy Loss

$$\mathcal{L}ig(\mathbf{\hat{Y},Y}ig) = rac{1}{M} \sum_{m=1}^{M} \left[ \sum_{c=1}^{C} \left( -^{(m)} y_c \ln^{(m)} \hat{y}_c 
ight) 
ight]$$

## Back-Propagation

$$abla \mathcal{L} = egin{bmatrix} \cdots & rac{\partial \mathcal{L}}{\partial w_{l-1,l}^{[l]}} & \cdots & rac{\partial \mathcal{L}}{\partial b_{l}^{[l]}} & \cdots \end{bmatrix}$$

$$d\mathbf{Z}^{[L]} = \frac{\partial \mathcal{L}}{\partial \mathbf{\hat{Y}}} \cdot \frac{\partial \mathbf{\hat{Y}}}{\partial \mathbf{Z}^{[L]}} = \mathbf{\hat{Y}} - \mathbf{Y}$$
NOTE: Only valid if
1. last layer is softmax activated;
2. Prediction is evaluated by cross entropy loss

For l from L to 1

$$egin{aligned} d\mathbf{W}^{[l]} &= d\mathbf{Z}^{[l]} \cdot rac{\partial \mathbf{Z}^{[l]}}{\partial \mathbf{W}^{[l]}} = d\mathbf{Z}^{[l]T} \cdot \mathbf{X}^{[l-1]} \ d\mathbf{b}^{[l]} &= d\mathbf{Z}^{[l]} \cdot rac{\partial \mathbf{Z}^{[l]}}{\partial \mathbf{b}^{[l]}} = mean\Big(d\mathbf{Z}^{[l]}, ext{ axis=0, keepdims=True}\Big) \ d\mathbf{X}^{[l-1]} &= d\mathbf{Z}^{[l]} \cdot rac{\partial \mathbf{Z}^{[l]}}{\partial \mathbf{X}^{[l-1]}} = d\mathbf{Z}^{[l]} \cdot \mathbf{W}^{[l]} \ d\mathbf{Z}^{[l-1]} &= d\mathbf{X}^{[l-1]} * a'\Big(\mathbf{X}^{[l-1]}\Big) \end{aligned}$$

## Gradient Descent Optimization

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Given dataset: \left\{ \begin{pmatrix} (^{1})\mathbf{x}, (^{1})\mathbf{y} \end{pmatrix}, \begin{pmatrix} (^{2})\mathbf{x}, (^{2})\mathbf{y} \end{pmatrix}, \dots, \begin{pmatrix} (^{M})\mathbf{x}, (^{M})\mathbf{y} \end{pmatrix} \right\}
Initialize \mathbf{W}^{[l]}, \mathbf{b}^{[l]}
Repeat until converge \left\{ \mathbf{W}^{[l]} := \mathbf{W}^{[l]} - \alpha \cdot d\mathbf{W}^{[l]} \right\}
\mathbf{b}^{[l]} := \mathbf{b}^{[l]} - \alpha \cdot d\mathbf{b}^{[l]}
\left\{ \mathbf{b}^{[l]} := \mathbf{b}^{[l]} - \alpha \cdot d\mathbf{b}^{[l]} \right\}
where \alpha is learning rate
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