

# **ENGR 3321: Introduction to Deep Learning for Robotics**

**Convolutional Neural Network**

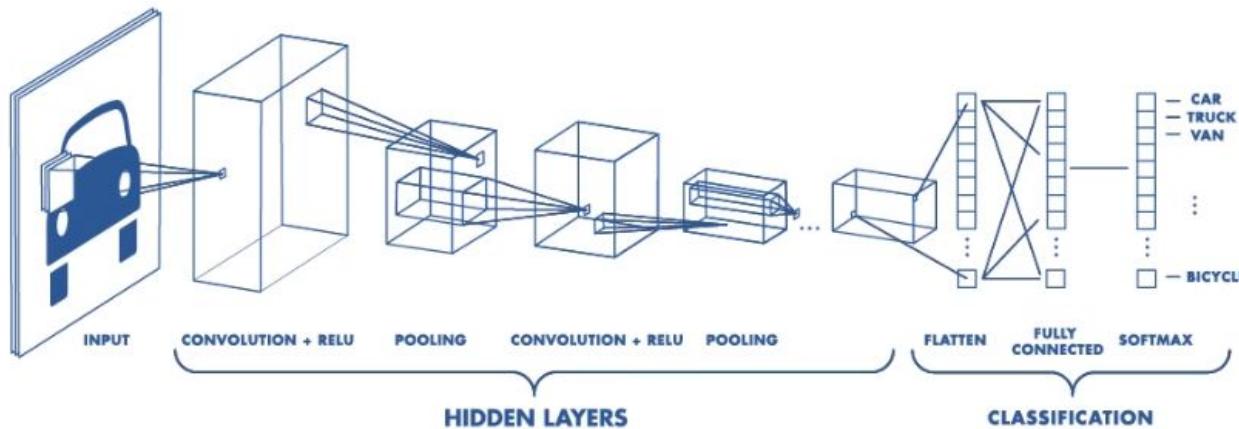
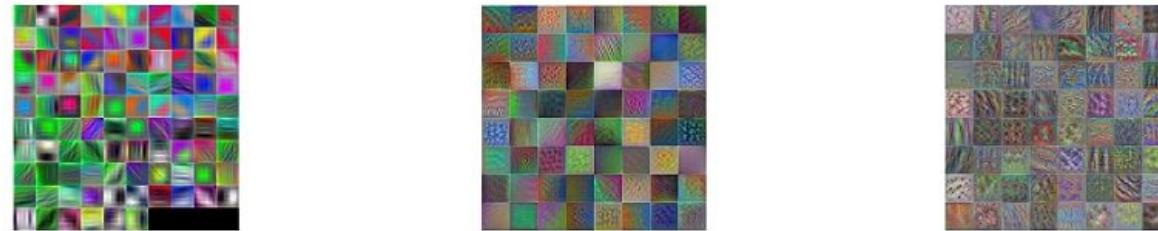
**11/10/2025**



# Outline

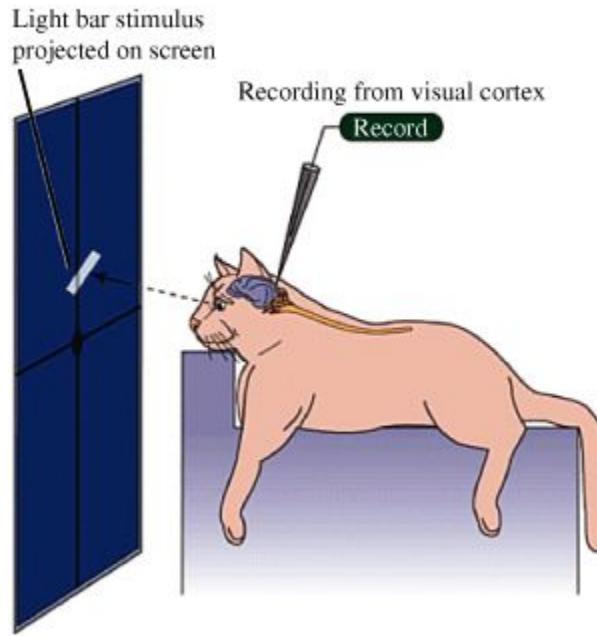
- Introduction
- Convolution Layer Principles
- Visualize Convolved Features
- Classical ConvNets

# Convolutional Neural Network

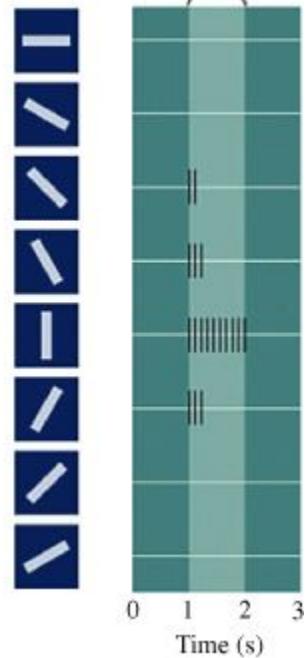


# Hubel & Wiesel's Cat Experiment

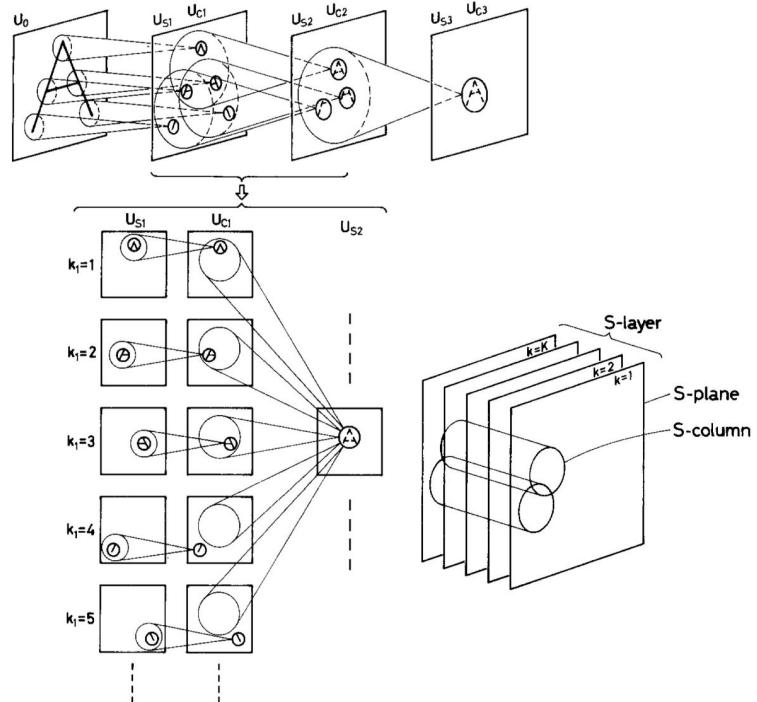
A Experimental setup



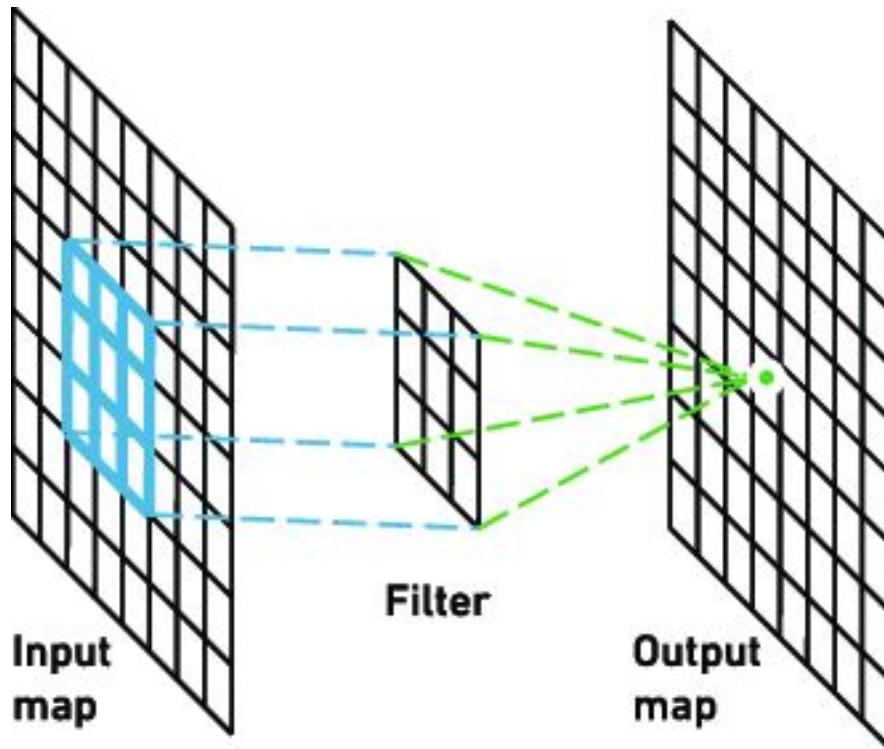
B Stimulus orientation      Stimulus presented



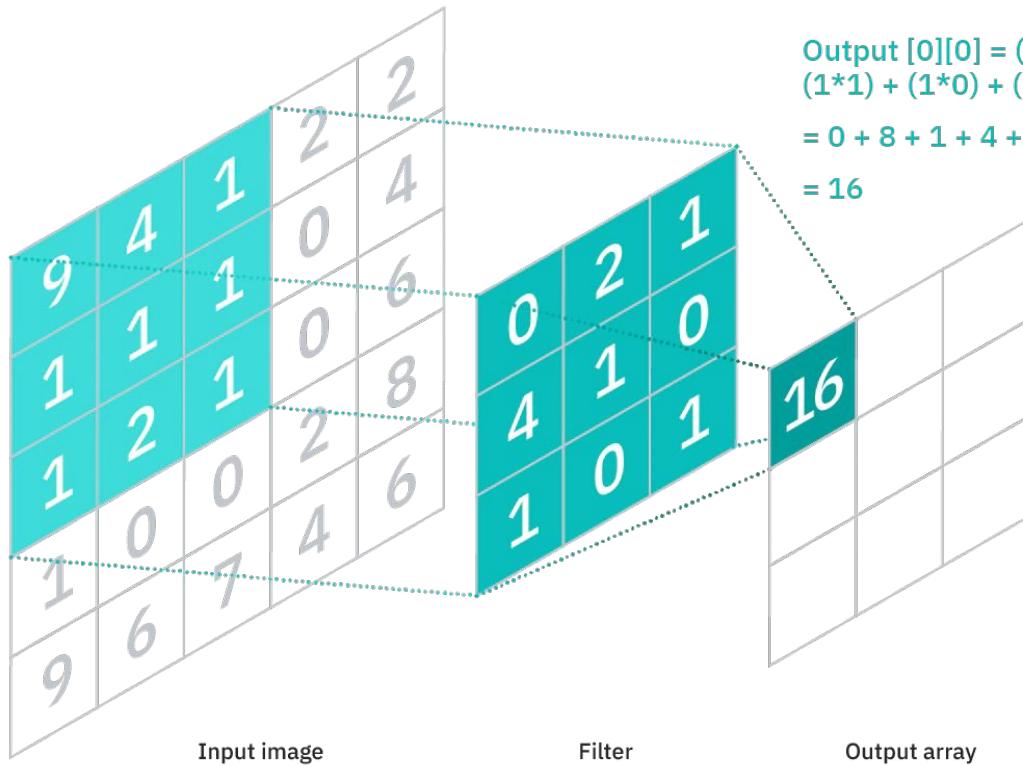
# Early ConvNet



# Convolution Layer



# Convolution Operation



$$W_{out} = \frac{W_{in} - K + 2P}{S} + 1$$

Kernel Size

Padding Size

S

Stride

# Pattern Detection

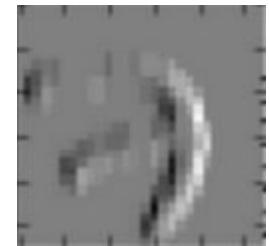
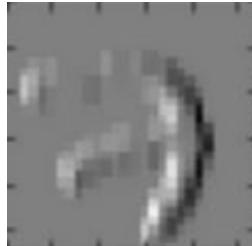


-1	-1	-1
1	1	1
0	0	0

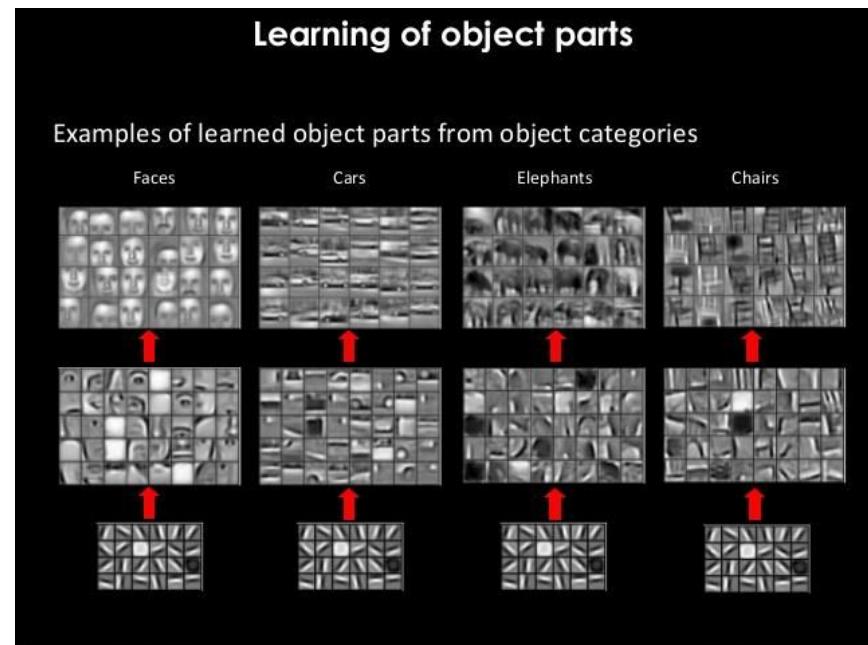
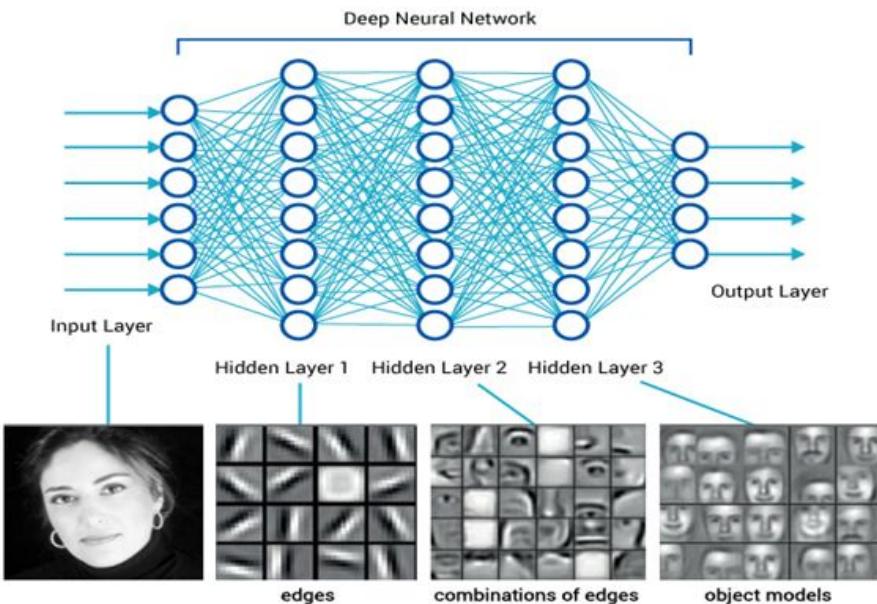
-1	1	0
-1	1	0
-1	1	0

0	0	0
1	1	1
-1	-1	-1

0	1	-1
0	1	-1
0	1	-1



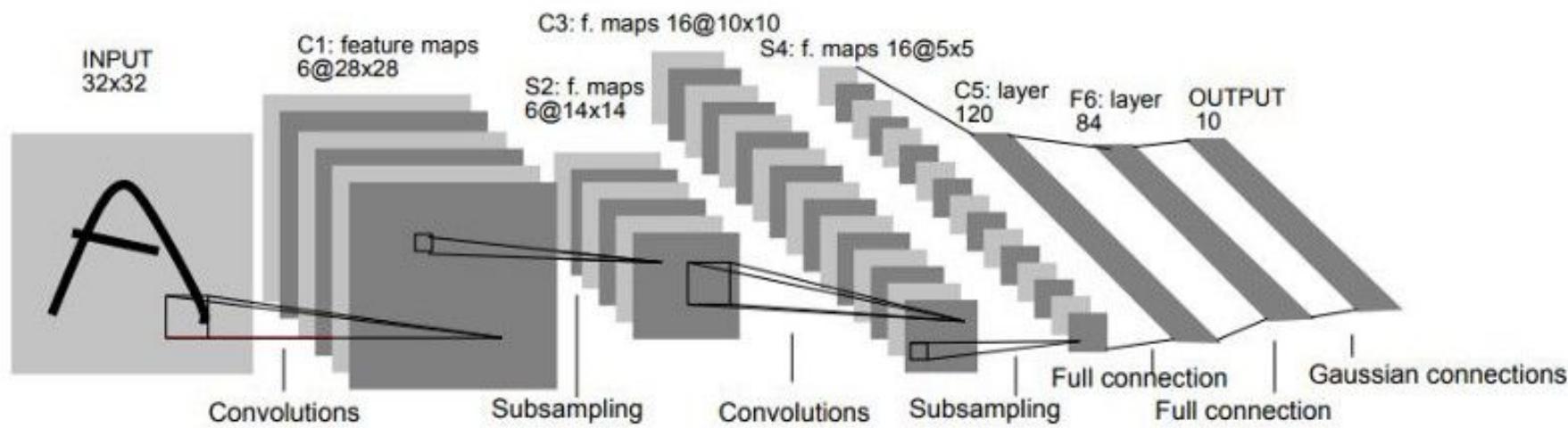
# Patterns in Conv Layers



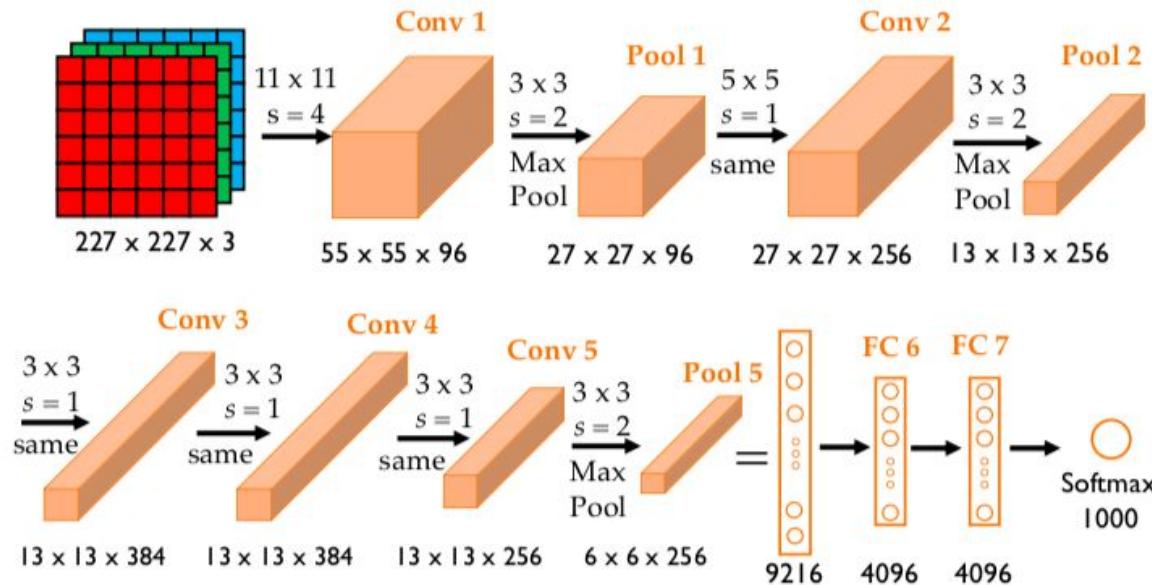
# **Advantages of ConvNets (vs. MLPs)**

- Parameter Efficiency
- Spatial Hierarchies and Feature Extraction
- Translation Invariance
- Improved Generalization with Limited Data
- Adaptability to Transfer Learning

# LeNet



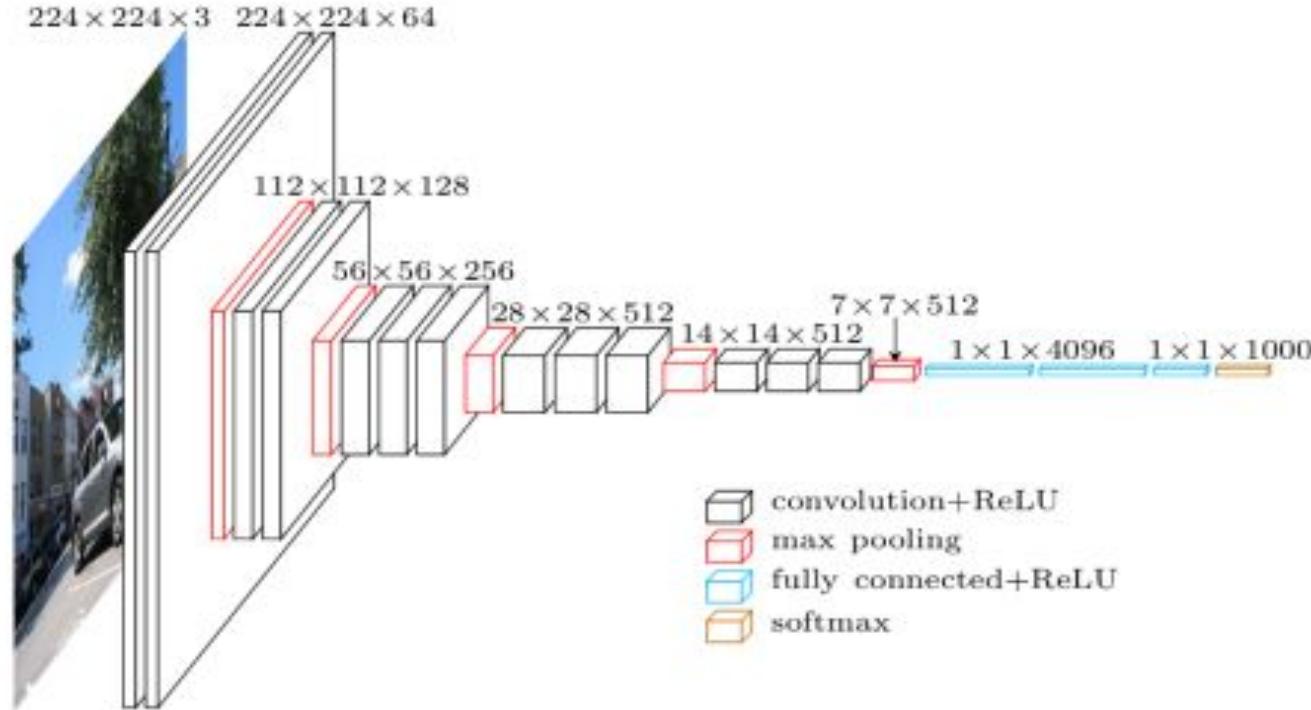
# AlexNet



# AlexNet

AlexNet Network - Structural Details													
Input		Output			Layer	Stride	Pad	Kernel size	in	out	# of Param		
227	227	3	55	55	96	conv1	4	0	11	11	3	96	34944
55	55	96	27	27	96	maxpool1	2	0	3	3	96	96	0
27	27	96	27	27	256	conv2	1	2	5	5	96	256	614656
27	27	256	13	13	256	maxpool2	2	0	3	3	256	256	0
13	13	256	13	13	384	conv3	1	1	3	3	256	384	885120
13	13	384	13	13	384	conv4	1	1	3	3	384	384	1327488
13	13	384	13	13	256	conv5	1	1	3	3	384	256	884992
13	13	256	6	6	256	maxpool5	2	0	3	3	256	256	0
					fc6			1	1	9216	4096	37752832	
					fc7			1	1	4096	4096	16781312	
					fc8			1	1	4096	1000	4097000	
Total											62,378,344		

# VGGNet

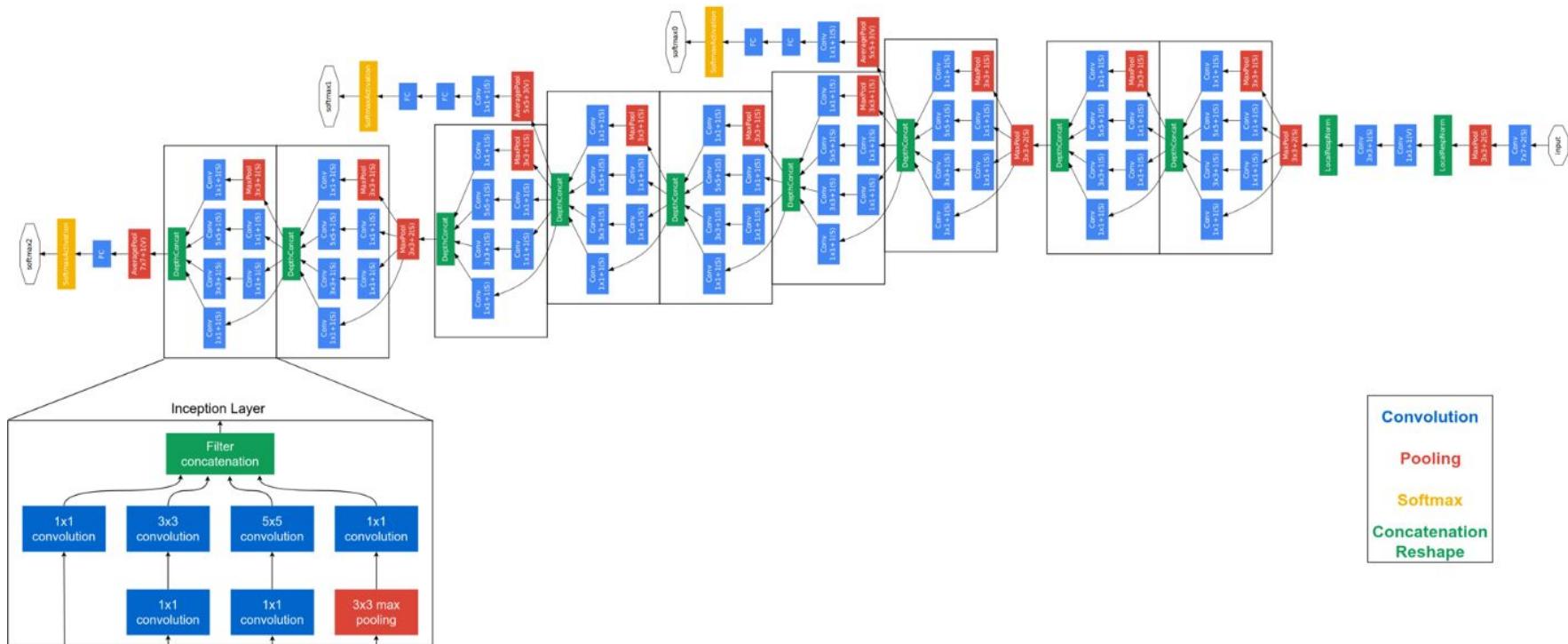


# VGGNet+

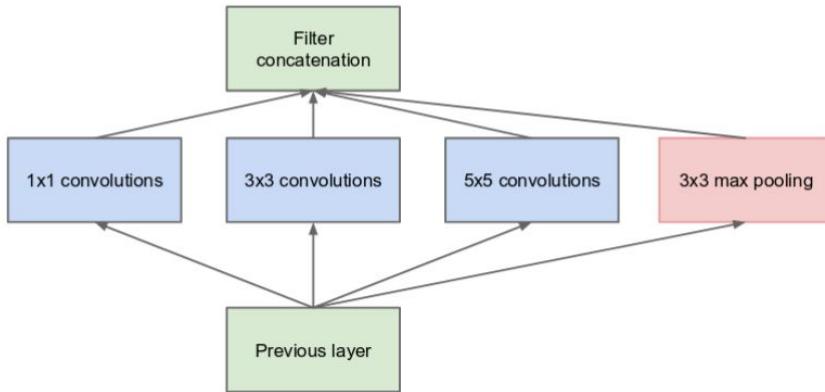
## VGG16 - Structural Details

VGG16 - Structural Details													
#	Input Image			output			Layer	Stride	Kernel		in	out	Param
1	224	224	3	224	224	64	conv3-64	1	3	3	3	64	1792
2	224	224	64	224	224	64	conv3064	1	3	3	64	64	36928
	224	224	64	112	112	64	maxpool	2	2	2	64	64	0
3	112	112	64	112	112	128	conv3-128	1	3	3	64	128	73856
4	112	112	128	112	112	128	conv3-128	1	3	3	128	128	147584
	112	112	128	56	56	128	maxpool	2	2	2	128	128	65664
5	56	56	128	56	56	256	conv3-256	1	3	3	128	256	295168
6	56	56	256	56	56	256	conv3-256	1	3	3	256	256	590080
7	56	56	256	56	56	256	conv3-256	1	3	3	256	256	590080
	56	56	256	28	28	256	maxpool	2	2	2	256	256	0
8	28	28	256	28	28	512	conv3-512	1	3	3	256	512	1180160
9	28	28	512	28	28	512	conv3-512	1	3	3	512	512	2359808
10	28	28	512	28	28	512	conv3-512	1	3	3	512	512	2359808
	28	28	512	14	14	512	maxpool	2	2	2	512	512	0
11	14	14	512	14	14	512	conv3-512	1	3	3	512	512	2359808
12	14	14	512	14	14	512	conv3-512	1	3	3	512	512	2359808
13	14	14	512	14	14	512	conv3-512	1	3	3	512	512	2359808
	14	14	512	7	7	512	maxpool	2	2	2	512	512	0
14	1	1	25088	1	1	4096	fc		1	1	25088	4096	102764544
15	1	1	4096	1	1	4096	fc		1	1	4096	4096	16781312
16	1	1	4096	1	1	1000	fc		1	1	4096	1000	4097000
	Total								138,423,208				

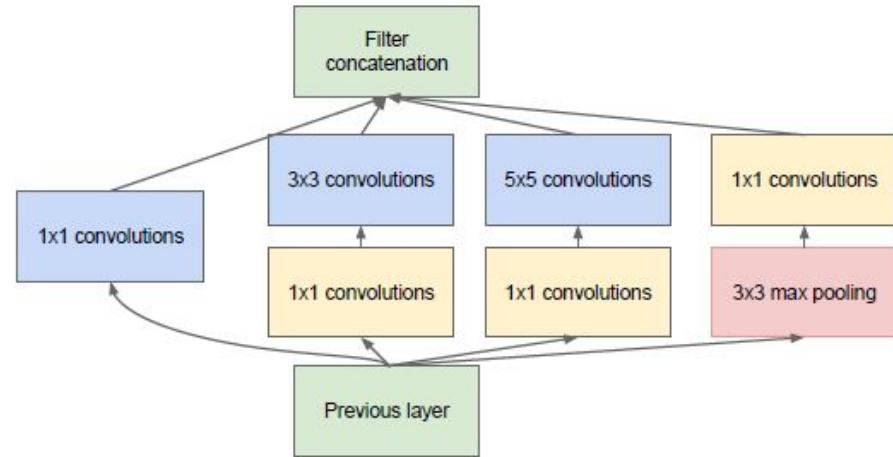
# GoogLeNet (Inception)



# GoogLeNet (Inception)



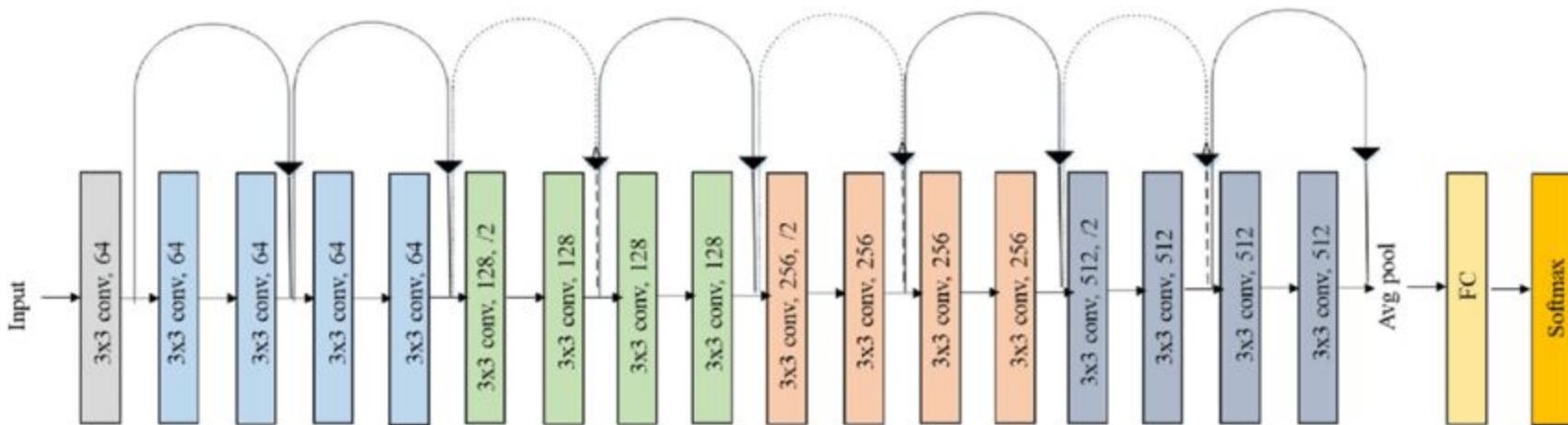
(a) Inception module, naïve version



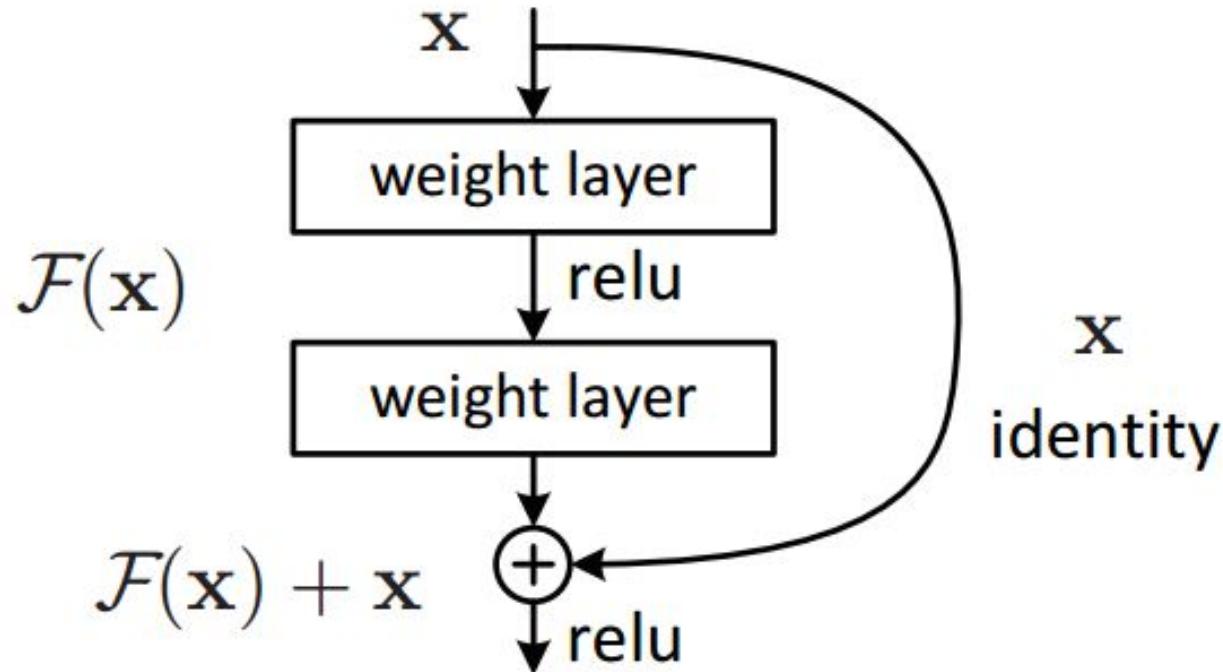
(b) Inception module with dimensionality reduction

# GoogLeNet (Inception)

# ResNet

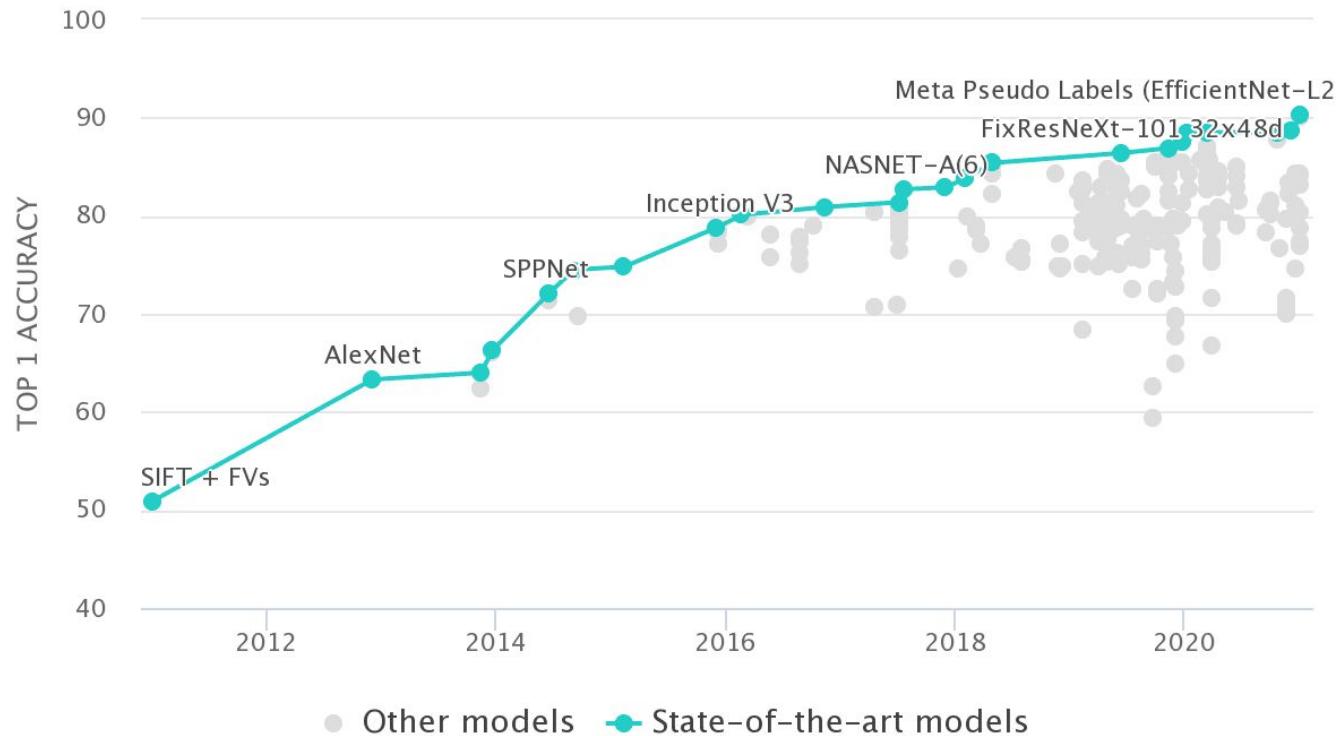


# ResNet

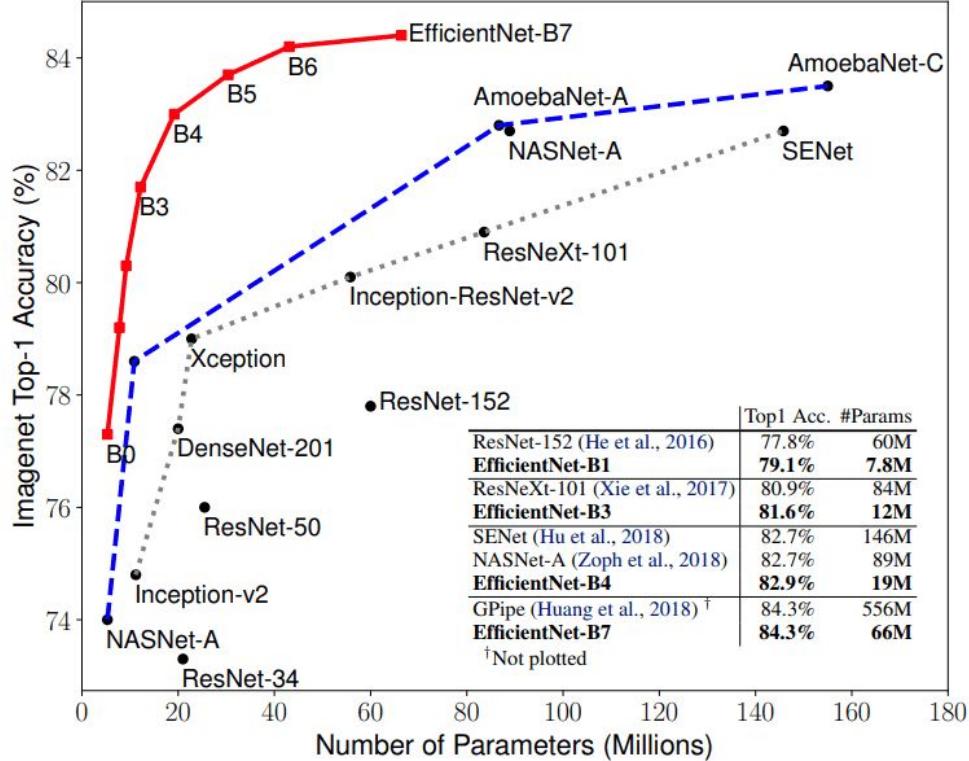
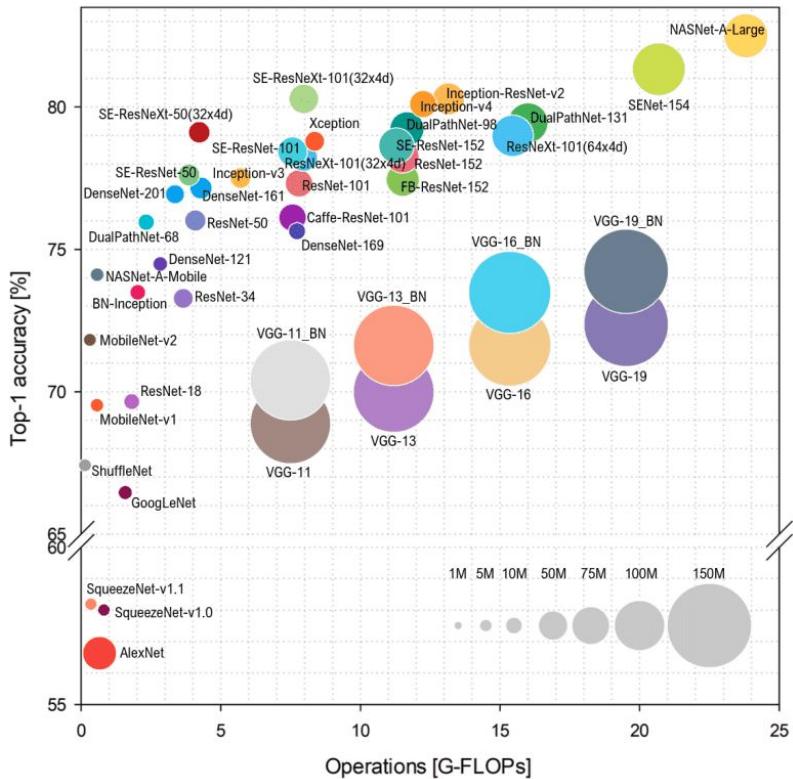


# ResNet

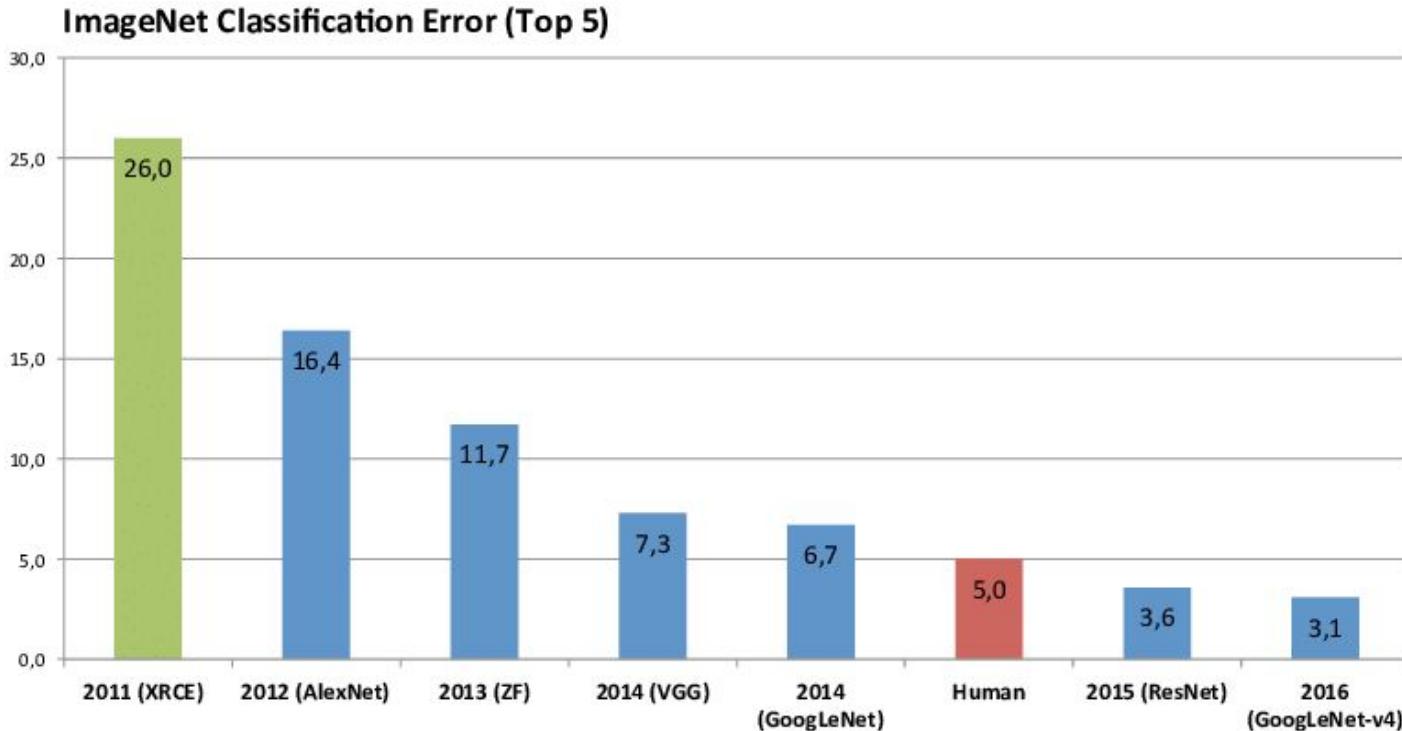
# ConvNets Benchmarks



# ConvNets Benchmarks



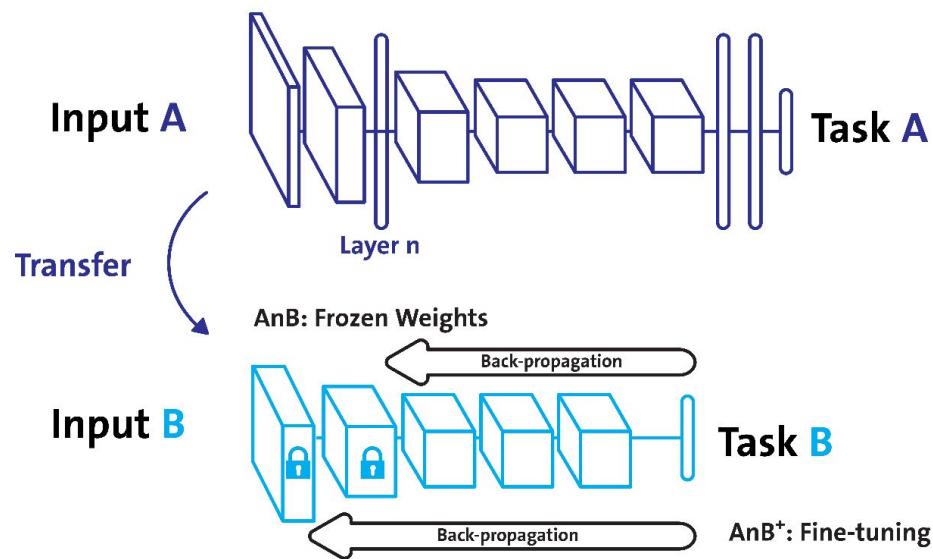
# ConvNets Benchmarks



Russakovsky O, Deng J, Su H, Krause J, Satheesh S, Ma S, Huang Z, Karpathy A, Khosla A, Bernstein M, Berg AC. Imagenet large scale visual recognition challenge. International journal of computer vision. 2015 Dec;115(3):211-52.

# Transfer Learning Guides

- [Models and pre-trained weights](#)
- [Transfer Learning Tutorial](#)



# **Online ConvNet Visualization**

<https://poloclub.github.io/cnn-explainer/>