

ENGR 3421: Robotics I (CRN22663)

Fall, 2021

Instructor

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Class & Lab

Time: Tuesday & Thursday, 10:40 AM–1:30 PM

Classroom: Lewis Annex 105

All students are expected to comply with the University policy regarding face coverings. UCAs Coronavirus page for students can be found here: <https://uca.edu/coronavirus/students/>. Students having any symptom of COVID-19 should stay at home and report to your healthcare provider. Check CDC with the most updated information of COVID-19. <https://www.cdc.gov/coronavirus/2019-ncov>

Overview

Course Description

Robotics I is a course that introduces the basic scientific and engineering knowledge of robots. Students are expected to familiarize the knowledge by assembling and programming autonomous mobile robots with gradually increased complexity. The classes will mix lectures and labs to help students better understand robotics. Students will work independently to build their own robots, but communications and discussions with others is highly encouraged.

Prerequisites

No courses nor skills are required in advance. Though, taking **ENGR 3410: Microcontrollers** and/or experience of Python programming in Linux may boost the speed of learning.

Textbooks

No textbooks is required. The students are expected to read a lot of on-line documentations.

- <https://ubuntu.com/tutorials/command-line-for-beginners> is a useful tutorial to get start with Linux command line.
- <https://wiki.python.org/moin/BeginnersGuide/Programmers> has plenty of tutorials for students to choose and to learn how to program in Python.
- <http://wiki.ros.org/ROS/Tutorials> is a good source to learn Robot Operating System.

Supplies

This course will provide everything for free, including robot assembly parts, microcontrollers, computers, sensors, crafting tools, measuring tools, programming software etc.. Students are welcome to ask the instructor to purchase upgrading materials for their robots.

Students can take their own robots, computers and sensors back home to work, but tools, monitors, keyboards and mice have to be kept in the lab.

Classroom Policy

The instructor and the students are expected to appear in the classroom/lab in every class. If a student cannot show up on time, he/she needs to contact the instructor in advance. The instructor will notify the students with any change of a class in advance. No food nor drinks are allowed in the classroom/lab.

Grading

As are 90-100%, Bs are 80-89%, Cs are 65-79%, D's are 64-50%, F's are 0-49%. The final grade will be determined by following criteria.

Component	Percentage
Attendance	1%
Assignment	19%
Mid-term Project	49%
Final Project	49%
Total	100%

Other Policies

The policies and procedures detailed in the UCA 2020-21 Student handbook are also part of this syllabus. Please refer to the relevant policies as your guidance.

<https://uca.edu/student/files/2021/03/STUDENT-HANDBOOK-2020-21-2.pdf>

If a student discloses an act of sexual harassment, discrimination, assault, or other sexual misconduct to a faculty member (as it relates to student-on-student or employee-on-student), the faculty member cannot maintain complete confidentiality and is required to report the act and may be required to reveal the names of the parties involved. Any allegations made by a student may or may not trigger an investigation. Each situation differs and the obligation to conduct an investigation will depend on those specific set of circumstances. The determination to conduct an investigation will be made by the Title IX Coordinator. For further information, please visit: <https://uca.edu/titleix>. *Disclosure of sexual misconduct by a third party who is not a student and/or employee is also required if the misconduct occurs when the third party is a participant in a university-sponsored program, event, or activity

The University of Central Arkansas affirms its commitment to academic integrity and expects all members of the university community to accept shared responsibility for maintaining academic integrity. Students in this course are subject to the provisions of the university's Academic Integrity Policy, approved by the Board of Trustees as [Board Policy No. 709](#) on February 10, 2010, and published in the Student Handbook. Penalties for academic misconduct in this course may include a failing grade on an assignment, a failing grade in the course, or any other course-related sanction

the instructor determines to be appropriate. Continued enrollment in this course affirms a student's acceptance of this university policy.

In addition to UCAs Academic Integrity policy we will also be mindful and knowledgeable of the National Society of Professional Engineers Code of Ethics.

<https://www.nspe.org/resources/ethics/codeethics>

The University of Central Arkansas adheres to the requirements of the Americans with Disabilities Act. If you need an accommodation under this Act due to a disability, please contact the UCA Office of Disability Services, 501-450-3613.

Course Contents

Please refer to the following for a tentative course plan. The actual contents will be subject to changes due to the progress of the course.

Module 1 - Introduction to Robotics

- Introduction to the world of robotics, with demonstrations of different kinds of robots and applications.
- Assembling the mobile robots which will be the physical developing platforms for students' learning in the rest of the course.
- Getting start with Github Classroom for retrieving project files and getting feedback from the instructor.

Module 2 - Introduction to Raspberry Pi

- Introduced to the microcontroller, RaspberryPi.
- Learning basics of Linux operating system and command line.
- Getting start with programming in Python.

Module 3 - Introduction to Sensors and Actuators

- Interaction with simple RaspberryPi add-ons (e.g., LEDs, buzzers, distance sensors, etc..).
- Fundamental of DC motors and the usage of a motor driver.
- Fundamental of Light Detection and Ranging sensor and the usage of RPLidar-A1.
- (Optional) Introduction to RaspberryPi Cameras

Module 4 - Introduction to Robot Operating System (ROS)

- Getting started with ROS.
- Programming in ROS using Python.
- Configure the ROS Network and remote developing environment.

(Optional) Module 5 - Gazebo Simulation

- Introduction to Gazebo Simulation and setting up a simulation world.
- Building a robot model using URDF format.
- Attach sensors and actuators to the robot in Gazebo.

Module 6 - Autonomous Navigation

- Mapping.
- Localization.
- Planning.
- Control.

In the final module, students are expected to develop an autonomous navigation application for their robots. The robots are expected to autonomously maneuver to given locations in maps created by the robots. Students will learn how to set up and configure the navigation stack on their robots using ROS. Final demonstration will be given to the peers.