# Modeling of bending-torsion couplings in active-bending structures. Application to the design of elastic gridshell.



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### 1 Parabolic interpolation

#### 1.1 Introduction

In this appendix, we give the required formulas to conduct a parabolic interpolation of a scalar or vector-valued function over an interval.

We look for a polynomial interpolation of order 2 of a continuous scalar or vector-valued function  $\mathbf{V}: t \mapsto \mathbf{V}(t)$  over the interval  $[t_0, t_2]$ ; supposing that the value of the function is known for three distinct parameters  $t_0 < t_1 < t_2$ :

$$\boldsymbol{V}(t_0) = \boldsymbol{V}_0 \tag{1.1a}$$

$$\boldsymbol{V}(t_1) = \boldsymbol{V}_1 \tag{1.1b}$$

$$\mathbf{V}(t_2) = \mathbf{V}_2 \tag{1.1c}$$

This interpolation method is employed several times in this thesis, for instance to evaluate the position of a kinetic energy peak during the dynamic relaxation process. It is also employed for evaluating the bending moment and the curvature of a discrete rod at mid-edge, knowing its values at vertices.

Note that this interpolation method is valid if the basis in which V is decomposed does not depend on the parameter t. Otherwise, the classical transportation term should be considered  $(\omega \times V)$ .

#### 1.2 Lagrange interpolating polynomial

The Lagrange interpolation of order two is given by the following polynomial:

$$\mathbf{V}(t) = \mathbf{V}_0 \frac{(t-t_1)(t-t_2)}{(t_0-t_1)(t_0-t_2)} + \mathbf{V}_1 \frac{(t-t_0)(t-t_2)}{(t_1-t_0)(t_1-t_2)} + \mathbf{V}_2 \frac{(t-t_0)(t-t_1)}{(t_2-t_0)(t_2-t_1)}$$
(1.2)

#### 1.3 Reparametrization

Lets introduce the distances  $l_0$  and  $l_1$  in the parametric space :

$$l_0 = t_1 - t_0 \tag{1.3a}$$

$$l_1 = t_2 - t_1$$
 (1.3b)

Lets introduce the change of variable  $u = t - t_1$ . The polynomial in eq. (1.2) can be rewritten in the form:

$$\mathbf{V}(u) = \mathbf{V}_0 \frac{u(u - l_1)}{l_0(l_0 + l_1)} - \mathbf{V}_1 \frac{(u + l_0)(u - l_1)}{l_0 l_1} + \mathbf{V}_2 \frac{u(u + l_0)}{l_1(l_0 + l_1)}$$
(1.4)

where:

$$u_0 = -l_0 \tag{1.5a}$$

$$u_1 = 0 \tag{1.5b}$$

$$u_2 = l_1 \tag{1.5c}$$

The derivative of this polynomial is also required to determine the extremum value of V. Differentiating eq. (1.4) gives:

$$\mathbf{V}'(u) = \mathbf{V}_0 \frac{2u - l_1}{l_0(l_0 + l_1)} - \mathbf{V}_1 \frac{2u + (l_0 - l_1)}{l_0 l_1} + \mathbf{V}_2 \frac{2u + l_0}{l_1(l_0 + l_1)}$$
(1.6)

This expression can be factorized to give the more compact form:

$$\mathbf{V}'(u) = \left(\frac{\mathbf{V}_1 - \mathbf{V}_0}{l_0}\right) \frac{l_1 - 2u}{l_0 + l_1} + \left(\frac{\mathbf{V}_2 - \mathbf{V}_1}{l_1}\right) \frac{l_0 + 2u}{l_0 + l_1}$$
(1.7)

#### 1.4 Characteristic values

Using eq. (1.4) the interpolated values of V at mid distance between  $t_0$  and  $t_1$  ( $u = -l_0/2$ ), and at mid distance between  $t_1$  and  $t_2$  ( $u = +l_1/2$ ) are given by :

$$\mathbf{V}_{01} = \mathbf{V}_0 \frac{l_0 + 2l_1}{4(l_0 + l_1)} + \mathbf{V}_1 \frac{l_0 + 2l_1}{4l_1} - \mathbf{V}_2 \frac{{l_0}^2}{4l_1(l_0 + l_1)}$$
(1.8a)

$$\mathbf{V}_{12} = -\mathbf{V}_0 \frac{{l_1}^2}{4l_0(l_0 + l_1)} + \mathbf{V}_1 \frac{2l_0 + l_1}{4l_0} + \mathbf{V}_2 \frac{2l_0 + l_1}{4(l_0 + l_1)}$$
(1.8b)

Using eq. (1.7) the interpolated values of V' at mid distance between  $t_0$  and  $t_1$  ( $u = -l_0/2$ ), and at mid distance between  $t_1$  and  $t_2$  ( $u = +l_1/2$ ) are given by:

$$\mathbf{V}_{01}' = \frac{\mathbf{V}_1 - \mathbf{V}_0}{l_0} \tag{1.9a}$$

$$V_{12}' = \frac{V_2 - V_1}{l_1} \tag{1.9b}$$

Remark that this is an interesting result as at these parameters the evaluation of V' boils down to a finite difference scheme.

Using eq. (1.7) and introducing  $\alpha = \frac{l_0}{l_0 + l_1}$  the interpolated values of V' at  $t_0$ ,  $t_1$  and  $t_2$  are given by:

$$\mathbf{V}_0' = (1+\alpha)\mathbf{V}_{01}' - \alpha\mathbf{V}_{12}' \tag{1.10a}$$

$$V_1' = (1 - \alpha)V_{01}' + \alpha V_{12}' \tag{1.10b}$$

$$\mathbf{V}_2' = (\alpha - 1)\mathbf{V}_{01}' + (2 - \alpha)\mathbf{V}_{12}' \tag{1.10c}$$

Lets rewrite eq. (1.8a) and (1.8b) with the help of  $\alpha$ :

$$\mathbf{V}_{01} = \frac{1}{4} \left( (2 - \alpha) \mathbf{V}_0 + \frac{2 - \alpha}{1 - \alpha} \mathbf{V}_1 - \frac{\alpha^2}{1 - \alpha} \mathbf{V}_2 \right)$$

$$(1.11a)$$

$$\mathbf{V}_{01} = \frac{1}{4} \left( -\frac{(1-\alpha)^2}{\alpha} \mathbf{V}_0 + \frac{1+\alpha}{\alpha} \mathbf{V}_1 + (1+\alpha) \mathbf{V}_2 \right)$$

$$(1.11b)$$

#### 1.5 Extremum value

The extremum value of the parabola is obtained for  $V'(u^*)=0$ . It's a minimum if  $V'_{12}>V'_{01}$  and it's a maximum if  $V'_{12}>V'_{01}$ :

$$u^* = \frac{l_1 V_{01}' + l_0 V_{12}'}{2(V_{01}' - V_{12}')} \tag{1.12}$$

Remark that if  $V'_{12} = V'_{01}$  it does not make sens to compute  $u^*$  as in this case the parabola degenerates into a line. The value of the function at this parameter is given by:

$$\mathbf{V}(u^*) = \mathbf{V}_1 + \frac{(l_1 \mathbf{V}_{01}' + l_0 \mathbf{V}_{12}')^2}{4(l_0 + l_1)(\mathbf{V}_{01}' - \mathbf{V}_{12}')}$$
(1.13)

The parabola in eq. (1.4) now writes:

$$\mathbf{V}(u) = -\frac{\mathbf{V}_{01}' - \mathbf{V}_{12}'}{l_0 + l_1} (u - u^*)^2 + \mathbf{V}(u^*)$$
(1.14)

The extremum is located in  $[t_0, t_2]$  if the sign of V' changes on this interval. This condition is satisfied whenever  $V'_{01} \cdot V'_{12} < 0$ .

Finally, in the special case of a uniform discretization where  $l_0 = l_1 = l$ , eq. (1.12) and (1.13) become :

$$u^* = \frac{l}{2} \left( \frac{\mathbf{V}_0 - \mathbf{V}_2}{\mathbf{V}_0 - 2\mathbf{V}_1 + \mathbf{V}_2} \right)$$
 (1.15a)

$$\mathbf{V}(u^*) = \mathbf{V}_1 - \frac{u^*}{4l}(\mathbf{V}_2 - \mathbf{V}_0)$$
(1.15b)