Plan de Thèse

I Elastic gridshell 6

1 A neat way to build free-form architecture 7

1.1 Building free-forms 7

1.1.1 Non-standard forms   7

1.1.2 Importance of free-forms in modern architecture   7

1.1.3 Canonical approaches to build free-forms   7

1.1.4 Main challenges   7

1.2 Gridshell structure : definition and classification 7

1.2.1 Historic overview   7

1.2.2 Rigid gridshell   7

1.2.3 Elastic gridshell 7

1.3 Elastic gridhshells : revisiting Mannheim 7

2 Experimenting elastic gridshells 8

2.1 Overall presentation 8

2.2 Tchebychev 8

2.3 Composite gridshells 8

2.4 Wooden gridshells 8

2.4.1 Double layer 8

2.4.2 Bracing 8

2.4.3 Wood testing 8

2.4.4 Mise en oeuvre 8

II Rich Kirchhoff beam model 9

3 Geometry of smooth and discret curves 10

3.1 Introduction 10

3.1.1 Goals and contributions 10

3.1.2 Related works 10

3.1.3 Overview 10

3.2 Paramectric Curves 10

3.2.1 Definition 10

3.2.2 Regularity 10

3.2.3 Reparametrization 10

3.2.4 Natural parametrization 10

3.2.5 Curve length 10

3.2.6 Arc-length parametrization 10

3.3 Frenet’s Trihedron 10

3.3.1 Tangent vector 10

3.3.2 Normal vector 10

3.3.3 Binormal vector 10

3.4 Curvature 10

3.4.1 Osculating circle 10

3.4.2 Curvature binormal vector 10

3.5 Torsion 10

3.6 Curve Framing 10

3.6.1 Moving frame 10

3.6.2 Adapted frame 10

3.6.3 Frenet frame 10

3.6.4 Bishop frame 10

3.6.5 Comparison between Frenet and Bishop frames 11

3.7 Discrete Curvature 11

3.7.1 Definitions 11

3.7.2 Variability of discrete curvature regarding α 11

3.7.3 Convergence benchmark κ1vs.κ2 11

4 kirchhoff rod: variational approach 12

4.1 Introduction 12

4.1.1 Goals and contributions 12

4.1.2 Related works 12

4.1.3 Overview 12

4.2 Elastic energy 12

4.3 Curve-angle representation 12

4.3.1 Zero-twistingframe 12

4.4 Strains 12

4.4.1 Axial strain 12

4.4.2 Bending strain 12

4.4.3 Torsional strain 12

4.5 Elastic energy 12

4.6 Quasistatic assumption 12

4.7 Energy gradient with respect to θ : moment of torsion 12

4.7.1 Derivative of material directors with respect to θ 12

4.7.2 Derivative of the material curvatures vector with respect to θ   12

4.7.3 Computation of the moment of torsion  12

4.8 Energy gradient with respect to x: internal forces 12

4.8.1 Derivative of material directors with respect to **x**   12

4.8.2 Derivative of the material curvatures vector with respect to **x** 12

4.8.3 Computation of the forces acting on the centerline 12

4.9 Conclusion 13

5 kirchhoff rod: equilibrium approach 14

5.1 Introduction 14

5.1.1 Goals and contributions 14

5.1.2 Related works 14

5.1.3 Overview 14

5.2 Dynamic Kirchhoff equations 14

5.2.1 Balance of the linear momentum 14

5.2.2 Balance of the angular momentum 14

4.3  Equations of motion 14

5.2.3 Constitutive equations 14

5.2.4 Internal forces and moments 14

5.2.5 Rod dynamic 14

5.3 Geometric interpretation 14

5.4 forces acting on the centerline 14

5.5 moment acting on the centerline 14

5.6 Conclusion 14

6 A rich discret Kirchhoff beam element 15

6.1 Introduction 15

6.1.1 Goals and contributions 15

6.1.2 Related works 15

6.1.3 Overview 15

6.2 Kinematic description 15

6.2.1 Centerline 15

6.2.2 Section 15

6.2.3 Hinged bi-arcs 15

6.3 Quasi-static actions on the centreline 15

6.3.1 Forces acting on the centerline (**x**) 15

6.3.2 Torsion acting on the sections (θ) 15

6.4 Boundary Conditions 15

6.5 Connexions : making grids 15

6.5.1 Infinitely stiff connexion 15

6.5.2 Spring connection 15

6.6 Integration with dynamic explicit solver 15

6.6.1 Fictious lumped mass 16

6.6.2 Double dynamic (x / θ) 16

III Application & Conclusion 17

IV Appendix 18

7 Calculus of variations 19

8 demo article audoly 20

1. Elastic gridshell

# A neat way to build free-form architecture

## Building free-forms

### Non-standard forms

### Importance of free-forms in modern architecture

### Canonical approaches to build free-forms

### Main challenges

## Gridshell structure : definition and classification

### Historic overview

### Rigid gridshell

### Elastic gridshell

## Elastic gridhshells : revisiting Mannheim

# Experimenting elastic gridshells

## Overall presentation

## Tchebychev nets

* Formfinding vs gridfinding
* Compass method
* Citer Yannick / Patch

## Composite gridshells

## Wooden gridshells

### Double layer

* Méthode de combinaison des contraintes
* Raideur de la poutrelle echelle
* Glissement du noeud

### Bracing

* Détail du pion
* Détail de l’écarteur
* Méthodologie de mise en place et phasage dans le projet

### Wood testing

* Small section
* Présence de defaults

### Mise en oeuvre

* Contrôle de forme
* Phasage : assemblage de la grille

1. Rich Kirchhoff beam model

# Geometry of smooth and discret curves

## Introduction

### Goals and contributions

### Related works

### Overview

## Paramectric Curves

### Definition

### Regularity

### Reparametrization

### Natural parametrization

### Curve length

### Arc-length parametrization

## Frenet’s Trihedron

### Tangent vector

### Normal vector

### Binormal vector

## Curvature

### Osculating circle

### Curvature binormal vector

## Torsion

## Curve Framing

### Moving frame

### Adapted frame

### Frenet frame

### Bishop frame

### Comparison between Frenet and Bishop frames

## Discrete Curvature

### Definitions

### Variability of discrete curvature regarding α

### Convergence benchmark κ1vs.κ2

# kirchhoff rod: variational approach

## Introduction

### Goals and contributions

### Related works

### Overview

## Elastic energy

## Curve-angle representation

### Zero-twistingframe

## Strains

### Axial strain

### Bending strain

### Torsional strain

## Elastic energy

## Quasistatic assumption

## Energy gradient with respect to θ : moment of torsion

### Derivative of material directors with respect to θ

### Derivative of the material curvatures vector with respect to θ

### Computation of the moment of torsion

## Energy gradient with respect to x: internal forces

### Derivative of material directors with respect to **x**

### Derivative of the material curvatures vector with respect to **x**

### Computation of the forces acting on the centerline

## Conclusion

# kirchhoff rod: equilibrium approach

## Introduction

### Goals and contributions

* This is a more straightforward way to achieved the same goal
* This way of doing things is more elegant, can be understand purely in terms of equilibrium, and is more conform to the approach of Days and Barnes
* We write the Kirchhoff dynamic equations for a slender beam (not common in the literature)

### Related works

### Overview

## Dynamic Kirchhoff equations

### Balance of the linear momentum

### Balance of the angular momentum

## 4.3  Equations of motion

### Constitutive equations

### Internal forces and moments

### Rod dynamic

## Geometric interpretation

## forces acting on the centerline

## moment acting on the centerline

## Conclusion

# A rich discret Kirchhoff beam element for numerical analysis

## Introduction

### Goals and contributions

* Bi-arc kinematic accounting for discontinuities (EI or Fext or Mext)
* Interpolation of internal forces and moments
* Time vs Space parallel transport of Bishop Frames
* Boundary conditions : forces vs speed way of dealing with it

### Related works

### Overview

## Kinematic description

### Centerline

### Section

### Hinged bi-arcs

## Quasi-static actions on the centreline

### Forces acting on the centerline (**x**)

### Torsion acting on the sections (θ)

## Boundary Conditions

* Soit géré en terme de vitesse soit en terme d’effort
* Calcul de la courbure aux extrémitées
* soit le repère est imposé et l’on cherche l’effort resultant (moment nule si rotule)
* soit l’effort en bout est connu (moment appliqué) et l’on cherche la courbure
* a chaque fois on part de la condition d’équilibre statique pour obtenir une info supplémentaire

## Connexions : making grids

### Infinitely stiff connexion

### Spring connection

## Integration with dynamic explicit solver

* Cas general vs dynamic relaxation

### Fictious lumped mass

Translational / Rotational

### Double dynamic (x / θ)

Quasistatic assumption

1. Application & Conclusion
2. Appendix

# Calculus of variations

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