Liu Hong

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EDUCATION

University of Illinois at Urbana-Champaign

Doctor of Philosophy in Theoretical and Appl Mechanics; GPA: 3.63/4.0

Expected December 2021

Purdue University

Indiana, USA

Bachelor of Mechanical Engineering; GPA: 3.47/4.0

Aug 2012 - May 2016

Illinois, USA

TECHNICAL PROFICIENCIES

• Languages: C++, Python

• Software: MATLAB, Ansys, Openfoam, UE4, GitHub, Docker, Colab, Creo, COMSOL

• Libraries: OpenGL, CUDA, PyTorch, Scikit-Learn, OpenCV, ROS

EXPERIENCE

Research Assistant January 2017 - Present

University of Illinois at Urbana-Champaign

Champaign, IL

- o Particle Image Velocimetry (PIV): Accelerated seeded particle tracking based on high speed vision for fluid experiment
- Particle Tracking Velocimetry(PTV): Improved structure dynamics reconstruction with stereo view of camer
- o FSI: Experimented real time Fluid-Structure interaction motion tracking for artificial swimmers

Product Engineer Intern

July 2016 - December 2016

Vofon Turbo System

Ningbo, China

 Quality detection: Implemented computational fluid dynamic algorithm on turbocharger inner wall design to simulate the working performance

Research Assistant June 2015 - May 2016

Purdue University

West Lafayette, IN

- o Fluid simulation: Utilized SUNTANS to simulate flow behavior around continental shelf
- Micro-fluid motion: Created hydrophobic droplet generator to test the influence of surfactants to alga

PROJECTS

Civil Project - Bridge defects Search: A graphical based model for 2D image recognition and 3D relocation

January 2019 - April 2019

- Implemented SFM method to reconstruct drone photo series and generated dense cloud point with CMVS
- Adjusted VGGNet for ROI processing to improve efficiency of FLANN matching
- The project code can be accessed here: https://github.com/lipilian/3D reconstruction of bridge

Graphene detection: A machine learning based model for graphene production rate calculation

May 2018 - July 2018

- Implemented PCA feature selection and QDA classifier to process SEM images
- The project code can be accessed here: https://github.com/lipilian/Automatic-Identification-of-Graphene

OpenGL office design: Developed OpenGL Code to simulate the office room

March 2019 - present

- Utlized GLFW, shadder mapping to control the camera and lightsource
- · Applied projection matrix, view matri and model matrix to create object motion and perspective view
- The project code can be accessed here: https://github.com/lipilian/OPENGL PROJECT

Robots for stair Cleaning: Designed and assembled a robot with ultrasonic sensors for stair climbing and cleaning

May 2016

• Designed robot basic structure and behavior based on sounding terrain

Escape Game design: Utilized Unreal Engine 4 to design simple game

November 2018 - present

- Coded C++ file with blueprint to inherit the trigger volume class
- · Created real time physics simulator to simulate collision and gravity
- The project code can be accessed here: https://github.com/lipilian/Escape-Game-C-

PUBLICATIONS

- Jin, Y., Kim, J. T., **Hong, L.**, Chamorro, L. P. (2018). Flow-induced oscillations of low-aspect-ratio flexible plates with various tip geometries. Physics of Fluids, 30(9), 097102.
- Hong, L., Kim, J. T., Jin, Y., Chamorro, L. P. (2018). Dynamics of flexible plates and induced flow under Heaviside acceleration heaving. Bulletin of the American Physical Society, 63.