

BDC5101

Deterministic Operations Research Models

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Linear Programming and Its Applications

Prototype Example

- **Wyndor Glass Co.**
 - Produces windows and glass doors
 - Plant 1 makes aluminum frames and hardware
 - Plant 2 makes wood frames
 - Plant 3 produces glass and assembles products

Prototype Example

- Company introducing two new products
 - Product 1: 8 ft. glass door with aluminum frame
 - Product 2: 4 x 6 ft. double-hung, wood-framed window
- Problem: What mix of products would be most profitable?

Prototype Example

- **Data needed**
 - Number of hours of production time available per week in each plant for new products
 - Production time used in each plant for each batch of each new product
 - Profit per batch of each new product
 - Demand

Prototype Example

■ TABLE 3.1 Data for the Wyndor Glass Co. problem

Plant	Production Time per Batch, Hours		Production Time Available per Week, Hours
	1	2	
Product			
1	1	0	4
2	0	2	12
3	3	2	18
Profit per batch	\$3,000	\$5,000	

Demand: assume that all products produced can be sold.

Prototype Example

- **Formulating the model**

x_1 = number of batches of product 1 produced per week

x_2 = number of batches of product 2 produced per week

Z = total profit per week (thousands of dollars) from producing these two products

- **From bottom row of Table 3.1**

$$Z = 3x_1 + 5x_2$$

Prototype Example

- **Constraints (see Table 3.1)**

$$x_1 \leq 4$$

$$2x_2 \leq 12$$

$$3x_1 + 2x_2 \leq 18$$

$$x_1 \geq 0$$

$$x_2 \geq 0$$

- **Classic example of resource-allocation problem**
 - Most common type of linear programming problem

Prototype Example

- **Alternative formulation 1**

x_1 = number of batches of product 1 produced per week

s_1 = production time reserved at plant 1

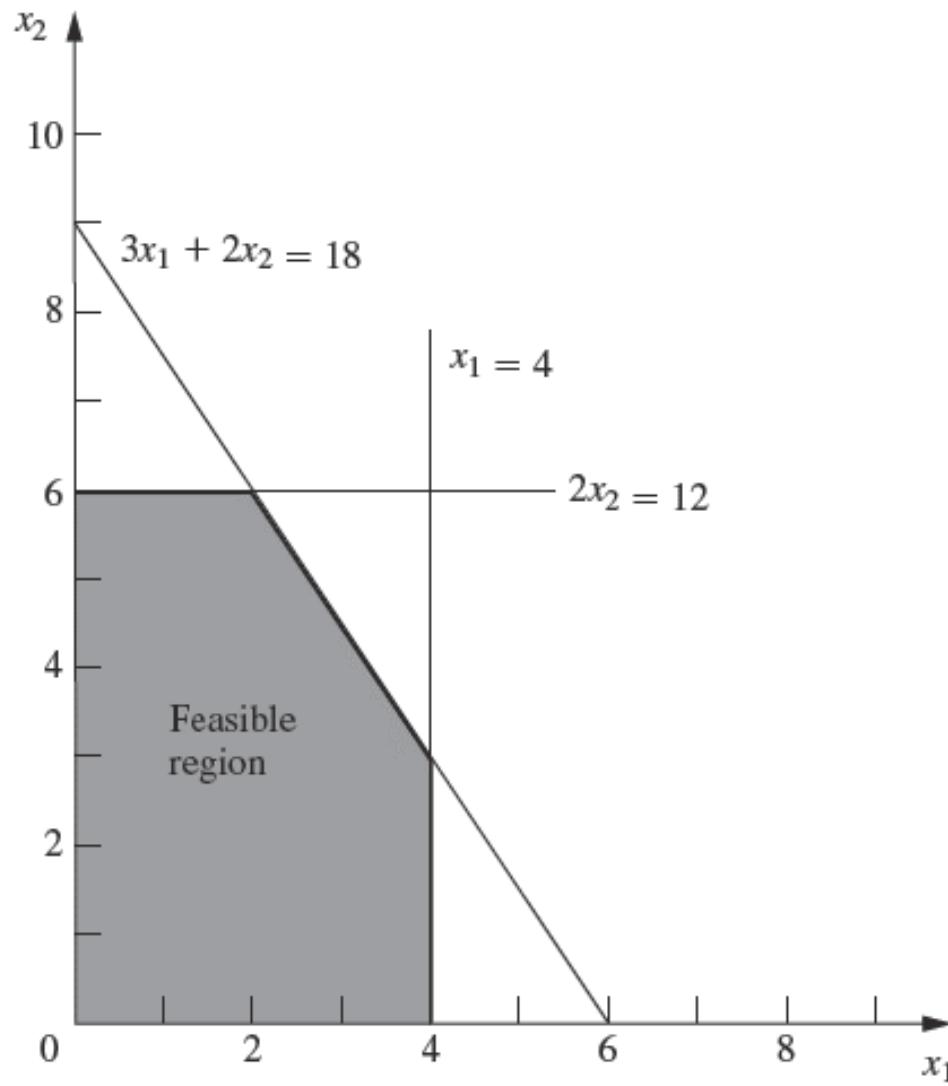
x_2 = number of batches of product 2 produced per week

- **Alternative formulation 2**

x_i = number of batches of product i produced per week, $i=1,2$

s_j = production time reserved at plant j , $j=1,2,3$

Graphical Approach/Contour Approach



■ **FIGURE 3.2**

Shaded area shows the set of permissible values of (x_1, x_2) , called the feasible region.

Graphical Approach/Contour Approach

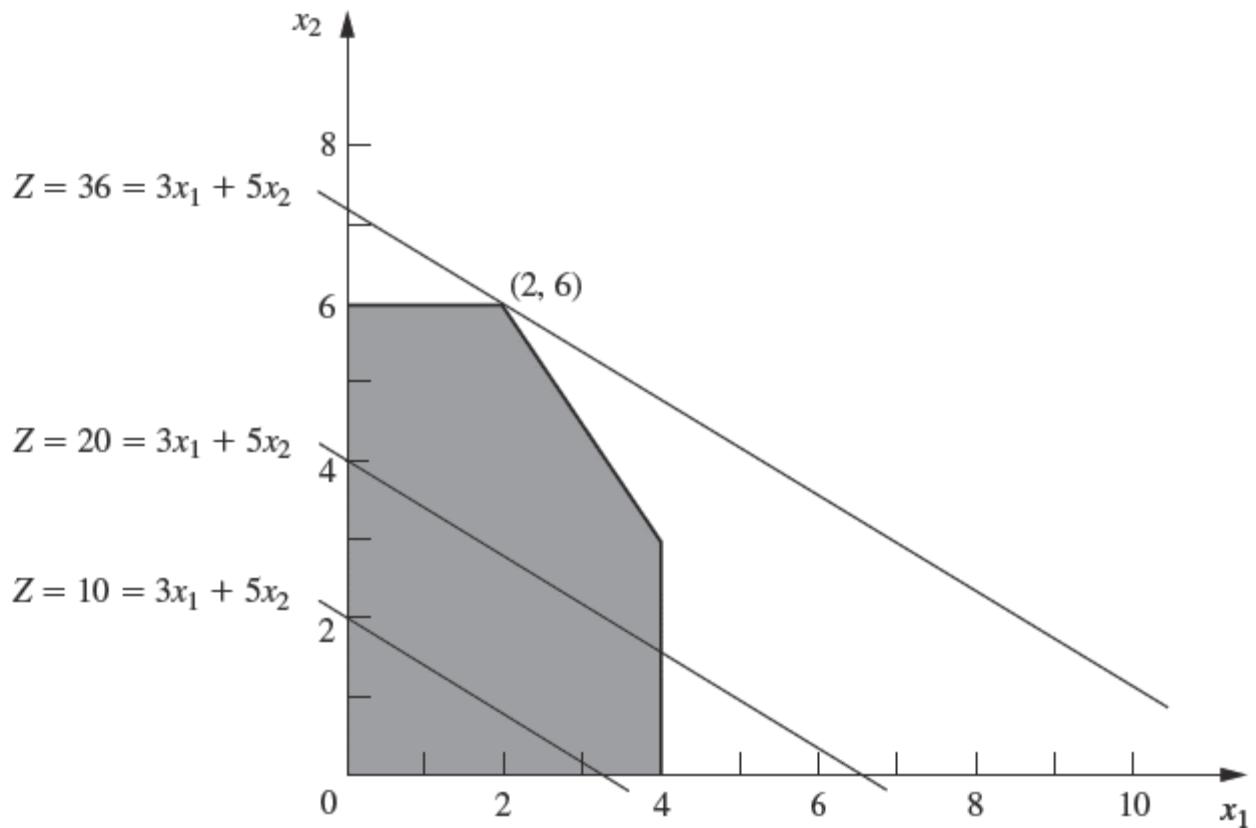


FIGURE 3.3

The value of (x_1, x_2) that maximizes $3x_1 + 5x_2$ is $(2, 6)$.

A General Linear Programming Problem

$$\begin{array}{ll} \min & c_1x_1 + \cdots + c_nx_n \\ \text{s.t.} & a_{i1}x_1 + \cdots + a_{in}x_n \geq b_i, i \in M_1 \\ & a_{j1}x_1 + \cdots + a_{jn}x_n \leq b_j, j \in M_2 \\ & a_{k1}x_1 + \cdots + a_{kn}x_n = b_k, k \in M_3 \\ & x_l \geq 0, l \in N_1 \\ & x_m \leq 0, m \in N_2 \end{array}$$

Linear functions

Standard Form

$$\begin{aligned} \min \quad & c_1x_1 + \cdots + c_nx_n \\ s.t. \quad & a_{i1}x_1 + \cdots + a_{in}x_n = b_i, i = 1, \dots, m \\ & x_1 \geq 0, \dots, x_n \geq 0 \end{aligned}$$

MATH 1001

- **Scalar**

- **Variable described by a single number**

$$x \in \mathbb{R} \quad x = 3$$

- **Vector**

- **Column of numbers**

$$x \in \mathbb{R}^n$$

$$x = \begin{pmatrix} 1 \\ 2 \\ 4 \\ 6 \\ 0 \end{pmatrix} \in \mathbb{R}^5$$

MATH 1001

- **Rectangular display of vectors in rows and columns**
 - Defined as rows x columns ($R \times C$)
- **Vector is just a $n \times 1$ matrix**

$$A \in \mathbb{R}^{m \times n} \quad A = \begin{pmatrix} 1 & 4 & 6 \\ 2 & 8 & 4 \\ 7 & 3 & 4 \\ 6 & 4 & 2 \end{pmatrix} \in \mathbb{R}^{4 \times 3}$$

Transposition

- Reflect over its main diagonal:
 - Write the rows of A as the columns of A'

$$A = \begin{pmatrix} 1 & 4 & 6 \\ 2 & 8 & 4 \\ 7 & 3 & 4 \\ 6 & 4 & 2 \end{pmatrix} \quad A' =$$

$$(A')' = A$$

Columns of Matrices

$$A = [A_1 A_2 \dots A_n] \in \mathbb{R}^{m \times n}$$

$$A_i \in \mathbb{R}^m, i = 1, \dots, n$$

ith column of matrix A

$$A = \begin{pmatrix} 1 & 4 & 6 \\ 2 & 8 & 4 \\ 7 & 3 & 4 \\ 6 & 4 & 2 \end{pmatrix} \quad A_2 =$$

Rows of Matrices

$$A = \begin{bmatrix} a'_1 \\ a'_2 \\ \vdots \\ a'_m \end{bmatrix} \in \mathbb{R}^{m \times n}$$

$a_i \in \mathbb{R}^n, i = 1, \dots, m$
ith row of matrix A

$$A = \begin{pmatrix} 1 & 4 & 6 \\ 2 & 8 & 4 \\ 7 & 3 & 4 \\ 6 & 4 & 2 \end{pmatrix} \quad a_2 =$$

Matrix Calculations

$$\begin{pmatrix} 1 & 4 \\ 2 & 8 \\ 7 & 3 \end{pmatrix} + \begin{pmatrix} 0 & 2 \\ -2 & 4 \\ 6 & 3 \end{pmatrix} =$$

$$\lambda \begin{pmatrix} 1 \\ 2 \end{pmatrix} + (1 - \lambda) \begin{pmatrix} 5 \\ 2 \end{pmatrix} =$$

Matrix Multiplication

- **Multiplication method:**

Sum over product of respective rows and columns

$$\begin{pmatrix} 1 & 0 \\ 2 & 3 \end{pmatrix} \times \begin{pmatrix} 2 & 1 \\ 3 & 1 \end{pmatrix} =$$

A **B**

Matrix Multiplication

$$\mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{pmatrix} \quad \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{pmatrix}$$

$$\mathbf{a}'\mathbf{x} =$$

Matrix Multiplication

$$A = \begin{bmatrix} a'_1 \\ a'_2 \\ \vdots \\ a'_m \end{bmatrix} \in \Re^{m \times n} \quad x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

$$Ax =$$

Matrix Multiplication

$$A = [A_1 A_2 \dots A_n] \in \mathbb{R}^{m \times n} \quad x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

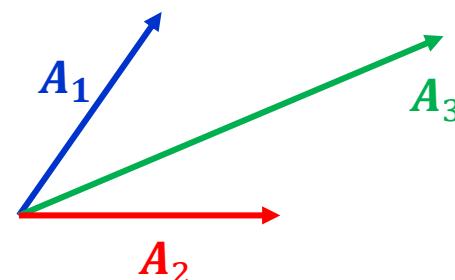
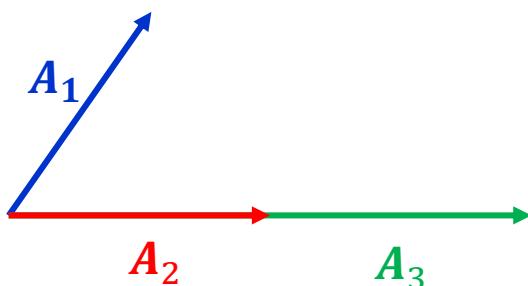
$$Ax =$$

Linear Independence

- We say y is a linear combination of A_1, \dots, A_n if for some scalars x_1, \dots, x_n

$$y = \sum_{i=1}^n x_i A_i$$

- A collection of m -dimensional vectors A_1, \dots, A_n is linearly independent if none of the vector is a linear combination of the rest of vectors.



Identity Matrix

- Is there a matrix which plays a similar role as the number 1 in number multiplication?
- Consider the $n \times n$ matrix:

$$I_n = \begin{pmatrix} 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \\ 0 & 0 & \dots & 0 & 1 \end{pmatrix}$$

For any $n \times n$ matrix A , we have $A I_n = I_n A = A$

Matrix inverse

- **Definition.** A matrix A is called **nonsingular** or **invertible** if there exists a matrix B such that:

$$AB = BA = I_n \quad \begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix} \times \begin{bmatrix} \frac{2}{3} & \frac{-1}{3} \\ \frac{1}{3} & \frac{1}{3} \end{bmatrix} = \begin{bmatrix} \frac{2+1}{3} & \frac{-1+1}{3} \\ \frac{-2+2}{3} & \frac{1+2}{3} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

- **Notation.** A common notation for the inverse of a matrix A is A^{-1} . So:

$$AA^{-1} = A^{-1}A = I_n$$

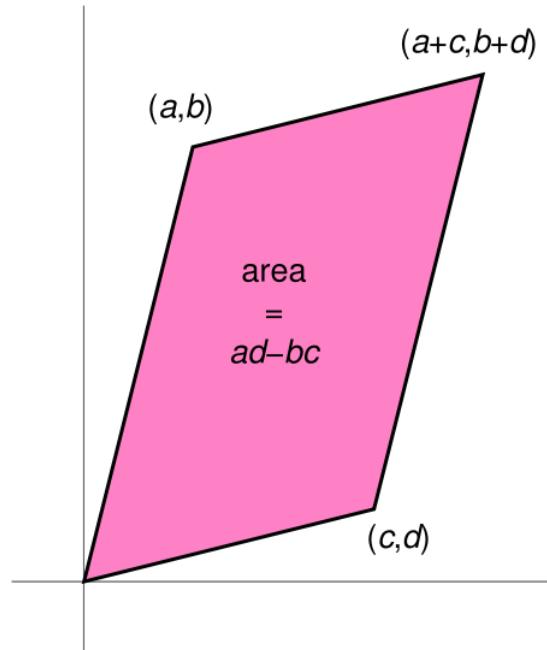
- The inverse matrix is unique when it exists.

Determinant

- The **determinant** is a function that associates a scalar $\det(A)$ to every square matrix A .
- Determinants can only be found for square matrices as it is related to the volume of a parallelepiped (think about diagonal matrix).

$$\det(A) = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$$

- What happens when (a, b) and (c, d) are linearly dependent?
- If elements in A are integers, is $\det(A)$ an integer?



Solving simultaneous equations

For one linear equation $ax=b$ where the unknown is x and b are constants, we have three possibilities:

- If $a \neq 0$ then $x = \frac{b}{a} \equiv a^{-1}b$ thus there is single solution
- If $a = 0, b = 0$ then the equation $ax = b$ becomes $0 = 0$ and any value of x will do
- If $a = 0, b \neq 0$ then $ax = b$ becomes $0 = b$ which is a contradiction

Solving simultaneous equations

- Eg. Two equations, two unknowns

$$2x_1 + 3x_2 = 5$$

$$x_1 + 2x_2 = 1$$

- In matrix form

$$\begin{pmatrix} 2 & 3 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 5 \\ 1 \end{pmatrix}$$

$$Ax = b$$

- What is x ?

Solving simultaneous equations

- If A is not invertible ...

$$\begin{pmatrix} 2 & 4 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 40 \\ 20 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 4 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 40 \\ 30 \end{pmatrix}$$

Summary

- If A is an $n \times n$ matrix, then the following are equivalent:
 - A is invertible
 - The simultaneous equations $Ax=b$ has a unique solution
 - a_1', \dots, a_n' are linearly independent
 - A_1, \dots, A_n are linearly independent
 - $\det(A) \neq 0$

Back to Standard Form

$$\begin{aligned} \min \quad & c_1x_1 + \cdots + c_nx_n \\ s.t. \quad & a_{i1}x_1 + \cdots + a_{in}x_n = b_i, i = 1, \dots, m \\ & x_1 \geq 0, \dots, x_n \geq 0 \end{aligned}$$

$$\begin{aligned} \min \quad & c'x \\ s.t. \quad & Ax = b \\ & x \geq 0 \end{aligned}$$

Reduction to Standard Form - Inequalities

$$\begin{aligned} \min \quad & x_1 + 2x_2 \\ \text{s. t.} \quad & x_1 + x_2 \leq 1, \\ & x_1 \geq 0, x_2 \geq 0 \end{aligned}$$

$$\begin{aligned} \min \quad & x_1 + 2x_2 + 0s_1 \\ \text{s. t.} \quad & x_1 + x_2 + s_1 = 1, \\ & x_1 \geq 0, x_2 \geq 0, s_1 \geq 0 \end{aligned}$$

Reduction to Standard Form - Inequalities

- $a_{i1}x_1 + \cdots + a_{in}x_n \geq b_i$
 $\Rightarrow a_{i1}x_1 + \cdots + a_{in}x_n - s_i = b_i, s_i \geq 0$

- $a_{j1}x_1 + \cdots + a_{jn}x_n \leq b_j$
 $\Rightarrow a_{j1}x_1 + \cdots + a_{jn}x_n + s_j = b_j, s_j \geq 0$

Reduction to Standard Form - Variables

$$\begin{aligned} \min \quad & x_1 + 2x_2 \\ \text{s.t.} \quad & x_2 \leq 1, \\ & x_2 \geq 0 \end{aligned}$$

$$\begin{aligned} \min \quad & x'_1 - x''_1 + 2x_2 + 0s_1 \\ \text{s.t.} \quad & x_2 + s_1 = 1, \\ & x'_1 \geq 0, x''_1 \geq 0, x_2 \geq 0, s_1 \geq 0 \end{aligned}$$

Reduction to Standard Form - Variables

- **Free variables:**

Replace x_j by $x'_j - x''_j$, and add constraints: $x'_j \geq 0, x''_j \geq 0$

- **Variable bounds:**

$$x_j \geq l_j \Rightarrow s_j = x_j - l_j, s_j \geq 0$$

$$x_j \leq u_j \Rightarrow s_j = u_j - x_j, s_j \geq 0$$

Reduction to Standard Form - Objective

- $\max c'x$
- $$\Rightarrow -\min -c'x$$

Wyndor Glass Co.

- **Original formulation**

$$\begin{aligned} \max \quad & 3x_1 + 5x_2 \\ \text{subject to } & x_1 \leq 4 \\ & 2x_2 \leq 12 \\ & 3x_1 + 2x_2 \leq 18 \\ & x_1 \geq 0, x_2 \geq 0 \end{aligned}$$

- **Matrix form**

- **Standard form**

Reduction to Standard Form

$$\max \quad c'x$$

$$s.t. \quad Ax \leq b$$

$$x \geq 0$$

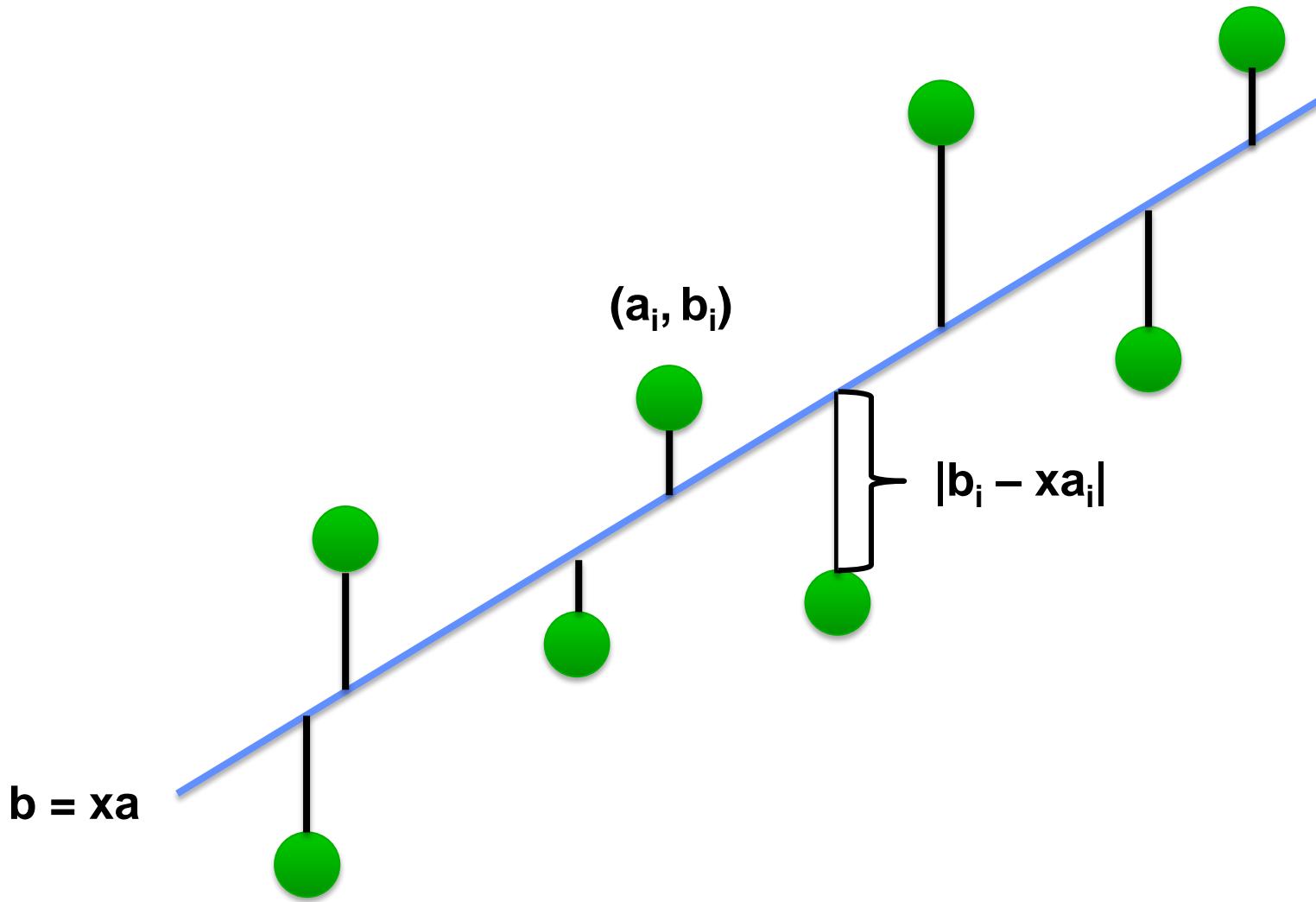
$$-\min \quad -c'x$$

$$s.t. \quad [A \quad I] \begin{bmatrix} x \\ s \end{bmatrix} = b$$

$$x, s \geq 0$$

More Applications

Simple Regression



Data Fitting Problem: L2 Criterion

- Minimize the sum of square of residual (least square):

$$\sum_{i=1}^m (b_i - a_i x)^2$$

- LP?

Data Fitting Problem: L1 Criterion

- Minimize the sum of residual (least absolute deviations):

$$\sum_{i=1}^m |b_i - a_i x|$$

- LP?

Data Fitting Problem: L1 Criterion

- Consider:

$$\min |x|$$

- LP formulation

Data Fitting Problem: L1 Criterion

- Least absolute deviations :

$$\min \sum_{i=1}^m |b_i - a_i x|$$

- LP formulation

$$\min_{z_i, x} \sum_{i=1}^m z_i$$

$$b_i - a_i x \leq z_i, \quad i = 1, \dots, m$$

$$-b_i + a_i x \leq z_i, \quad i = 1, \dots, m$$

L1 vs. L2

- **Difficulty**
- **Sensitivity to outliers**
- **Solution uniqueness**

Data Fitting Problem: Chebyshev Criterion

- Minimize the largest residual:

$$\max_i |b_i - a_i x|$$

- LP formulation

$$\min_{z,x} z$$

$$b_i - a_i x \leq z, \quad i = 1, \dots, m$$

$$-b_i + a_i x \leq z, \quad i = 1, \dots, m$$

Problems Involving Absolute Values

- Consider a problem:

$$\min_{x_i} \sum_{i=1}^n c_i |x_i|$$

$$Ax \geq b$$

- Cost coefficients c_i are assumed to be nonnegative
- LP formulation

$$\min_{z_i} \sum_{i=1}^n c_i z_i$$

$$Ax \geq b$$

$$x_i \leq z_i, \quad i = 1, \dots, n$$

$$-x_i \leq z_i, \quad i = 1, \dots, n$$

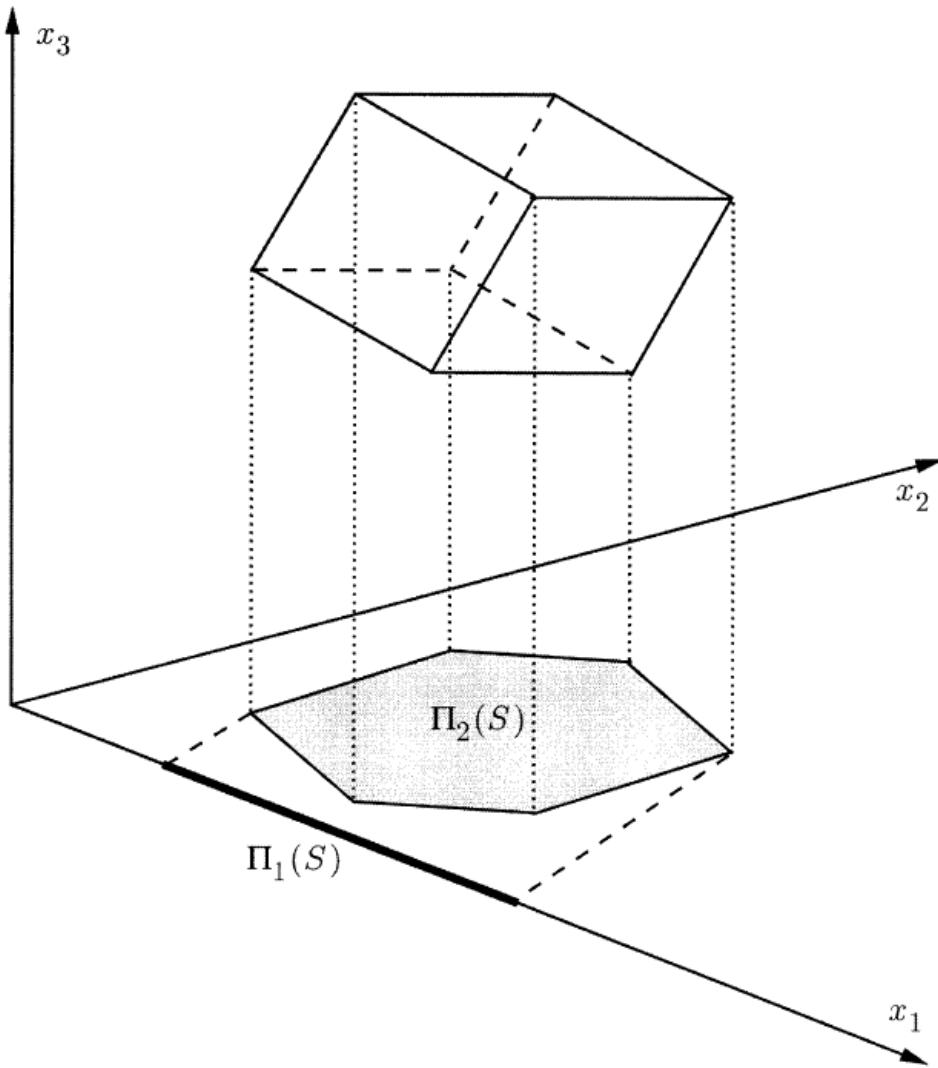
Problems Involving Absolute Values

- Consider a problem:

$$\begin{aligned} \min_{x_i} & \sum_{i=1}^n c_i x_i \\ & \sum_{i=1}^n |x_i| \leq b \end{aligned}$$

- LP formulation

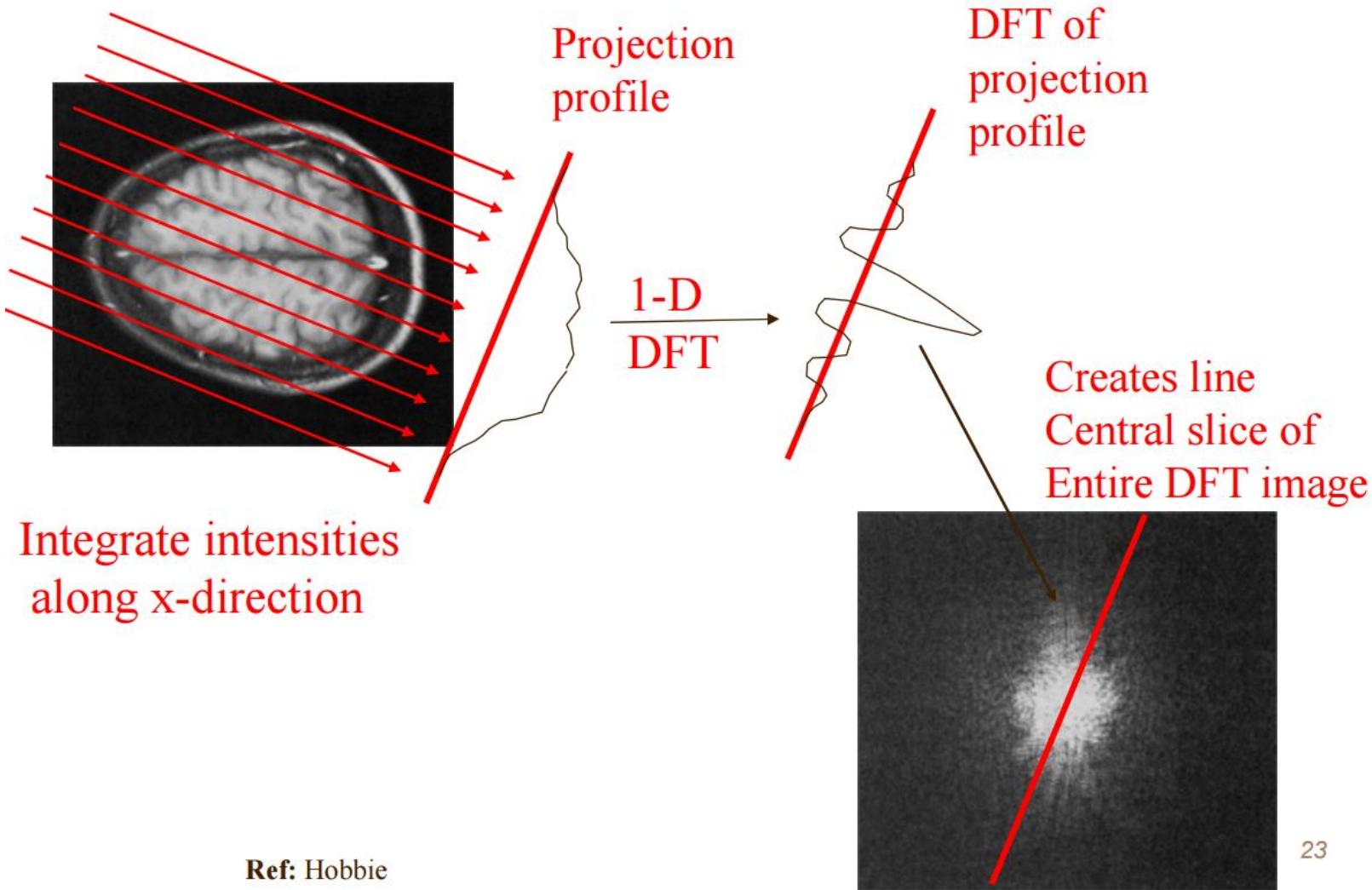
Projection Idea



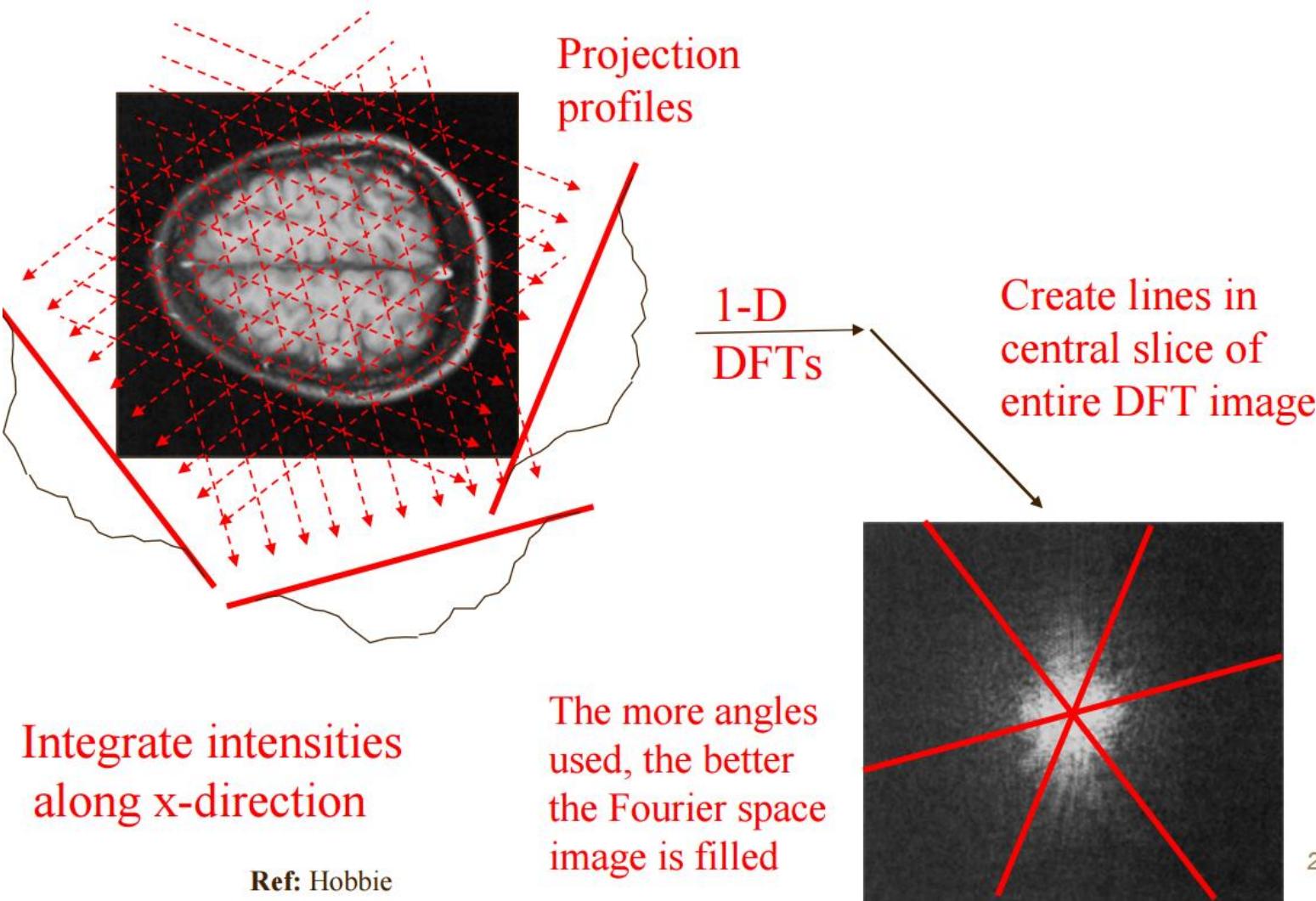
CT/MRI Scan



CT/MRI Scan



CT/MRI Scan



Compressed Sensing

- Consider a signal (e.g. sound, images):

$$x = (x_1, \dots, x_n)',$$

where n is very large (e.g. around 1,000,000).

- The signal is not directly observable. Instead, one observes a measurement

$$b = Ax \in R^m,$$

where m is small and A is an mxn matrix.

- The problem is then to find x given b .

Compressed Sensing: A Simple Example

- Consider an unknown signal:

$$x = (0, 1)'.$$

- The measurement matrix is:

$$A = [1 \ 2].$$

- The observable output is then

$$b = 2.$$

- If one solves the underdetermined system $b = Ax$, then any x satisfying the following is a solution

$$x_1 + 2x_2 = 2.$$

- What if we know the solution is sparse (most components are zero)?

Compressed Sensing

- Ideally, one want to solve

$$\min_x \#\{1 \leq i \leq n: x_i \neq 0\}$$
$$Ax = b$$

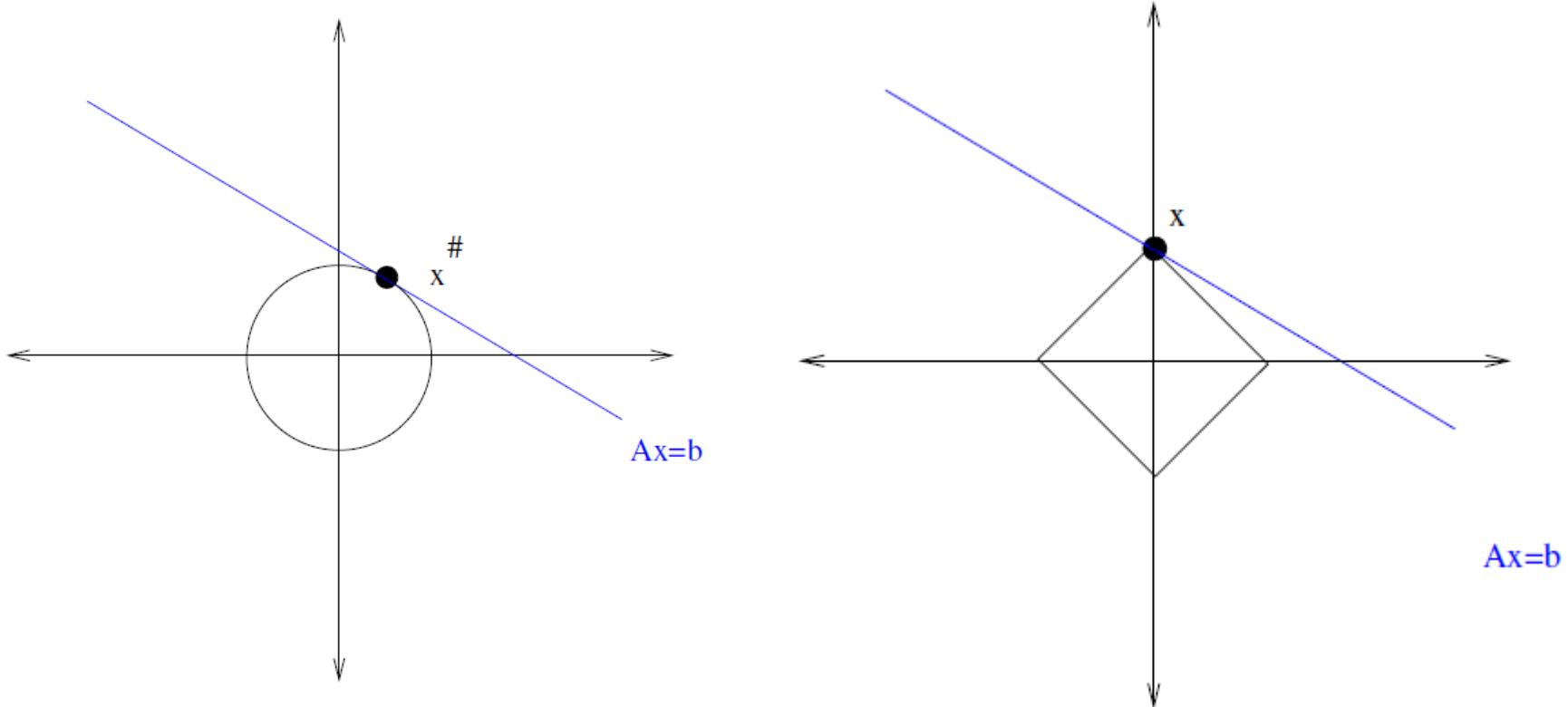
- The L1 Approach?

$$\min_x \sum_{i=1}^n |x_i|$$
$$Ax = b$$

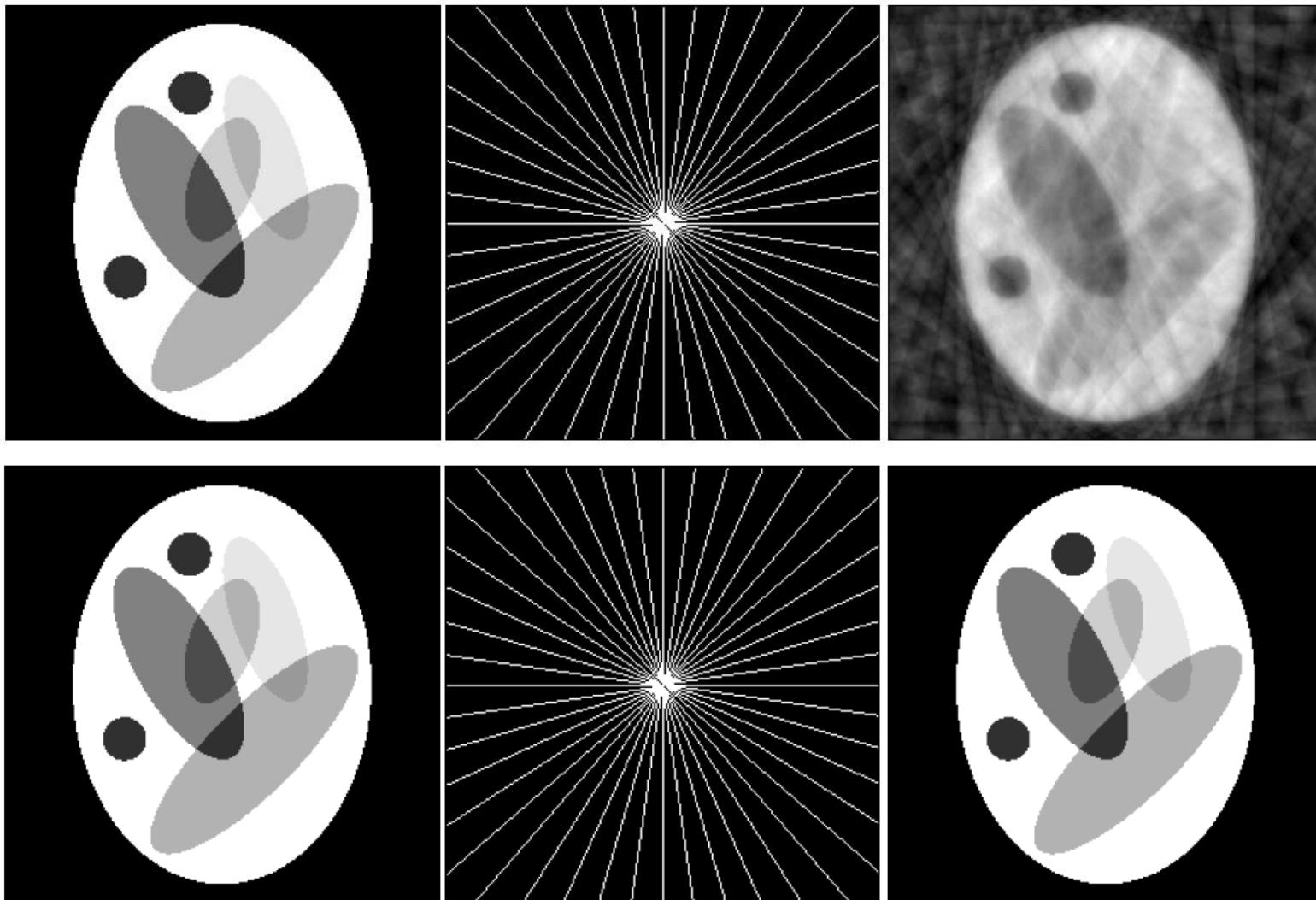
- The L2 Approach?

$$\min_x \sum_{i=1}^n x_i^2$$
$$Ax = b$$

Compressed Sensing



Compressed Sensing



Source: Terrence Tao, "Compressed sensing Or: the equation $Ax=b$, revisited", UCLA, Mahler Lecture Series