

# DeepDream & Neural Style Transfer

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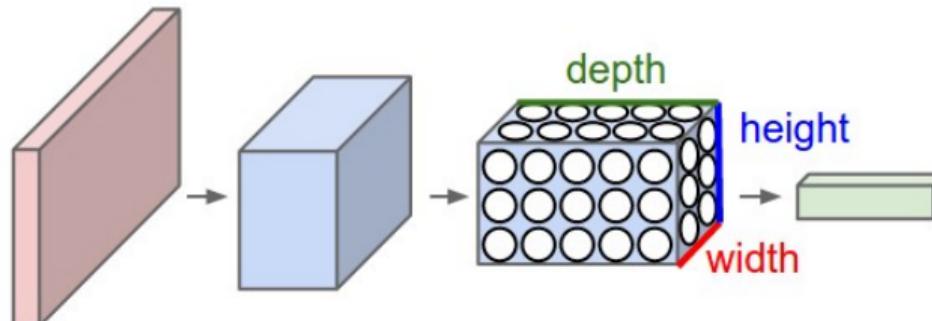
# Outline

- ▶ Revisit Convolutional Neural Networks
- ▶ DeepDream
- ▶ Neural Style Transfer

# Revisit Convolutional Neural Networks

A ConvNet is made up of Layers. Every Layer has a simple API: It transforms an input 3D volume to an output 3D volume with some differentiable function that may or may not have parameters

- Convolutional layer
- Pooling layer
- Fully connected layer



# VGG Network Recap

Published in the paper titled [Very Deep Convolutional Networks for Large-Scale Image Recognition](#)

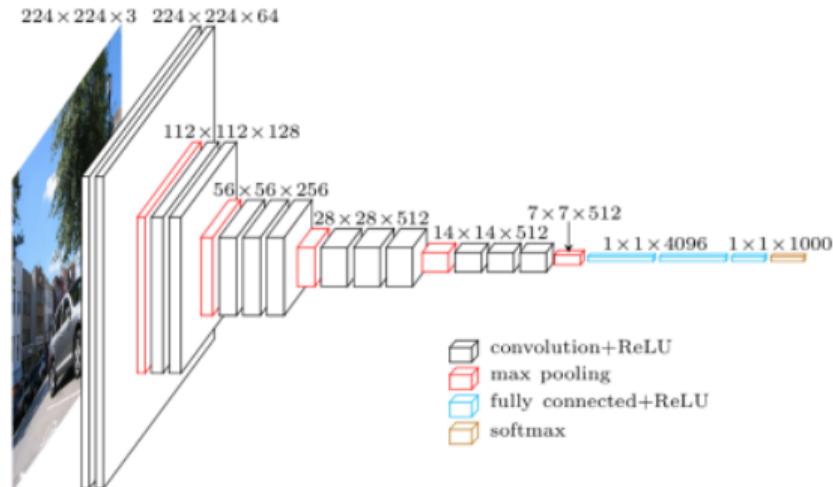


Figure: VGG16: a total of 16 weight layers.

# VGG Network Recap

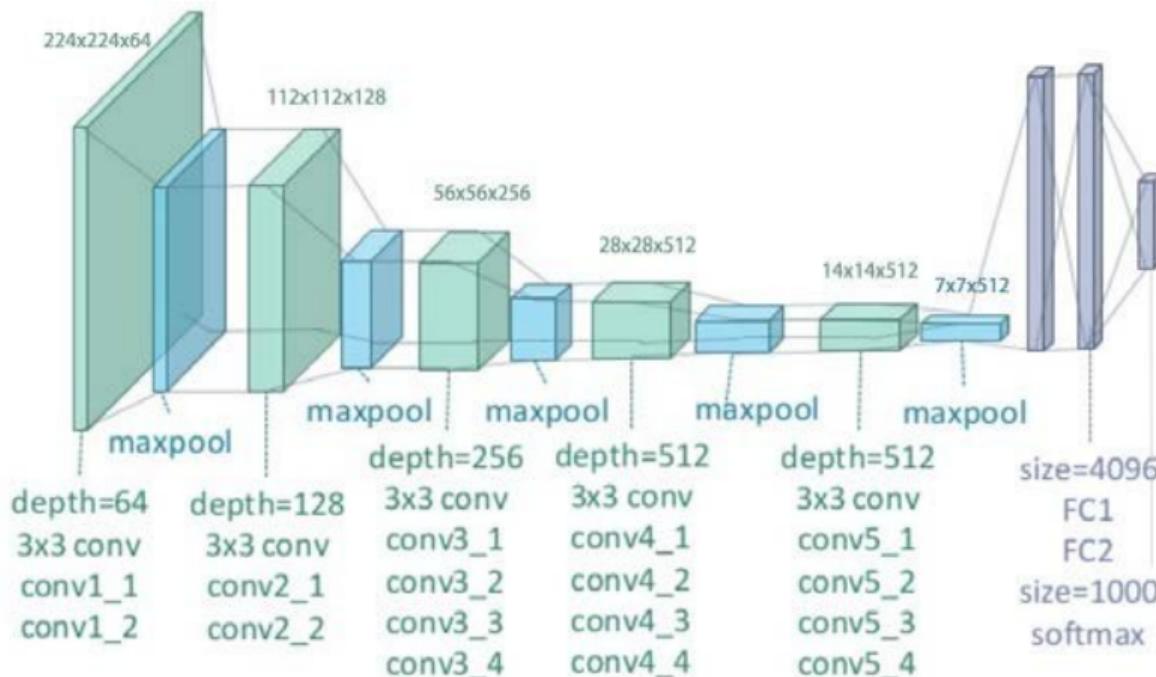


Figure: VGG19: A total of 19 weight layers.

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# DeepDream

- What is it? An algorithm that visualizes the patterns learned by a neural network
- Over-interprets and enhances the patterns it sees in an image

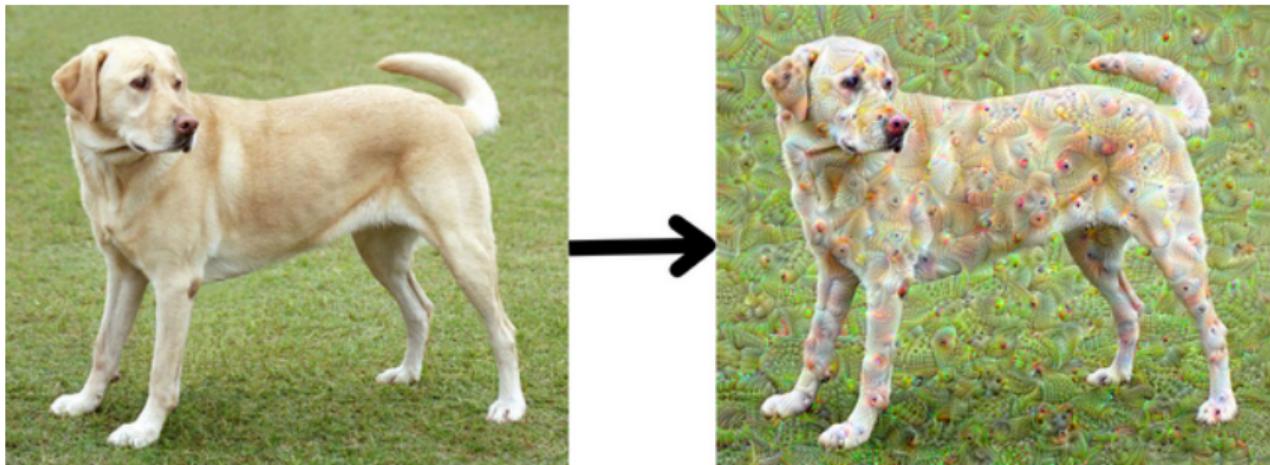


Figure: You can make a neural network “dream” and enhance the surreal patterns it sees in an image

# Intuition Behind: Going Deeper into Neural Networks

Whatever you see there, I want more of it!

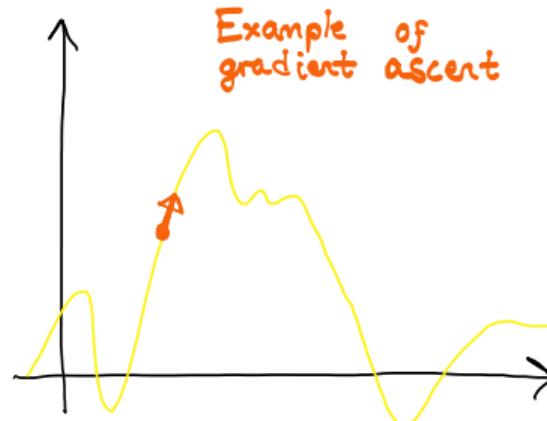
- Recall canonical ANN training procedures ([example](#))
- What exactly goes on at each layer?
- Amplify certain neuron's activation



**Figure:** Dream on Ameca at different steps: 100, 500, 1000, 2000

# How Does the DeepDream Algorithm Work

- Built upon a pre-trained convolutional neural network
- Select target layers and compute activations of the chosen layers
- Calculate the gradient of activations w.r.t the input image
- Update the image using **gradient ascent**



# DeepDream Implementation

- Prepare for the feature extraction

```
# Prepare the feature extraction model
base_model = tf.keras.applications.InceptionV3(include_top=False, weights='imagenet')
# maximize the activations of these layers
names = ('mixed3', 'mixed5')
layers = [base_model.get_layer(_layer_name).output for _layer_name in names]
# create the feature extraction model
dream_model = tf.keras.Model(inputs=base_model.inputs, outputs=layers)
```

- Calculate loss: sum of the normalized activations of chosen layers
- Calculate gradients of the loss w.r.t the image, and add them to the original image

## More Examples



**Figure:** The image on the top-left is the input image. Ask the GoogleNet to amplify the features recognized by the the inception\_5a/3x3 layer. Results after 10, 15, 20 iterations are demonstrated in the last 3 images.

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# Neural Style Transfer

- What is it?
- Separate and recombine **content** and **style** of natural images<sup>1</sup> (how?)

CONTENT IMAGE



STYLE IMAGE



GENERATED IMAGE



<sup>1</sup>Image Style Transfer Using Convolutional Neural Networks

# Content Representation

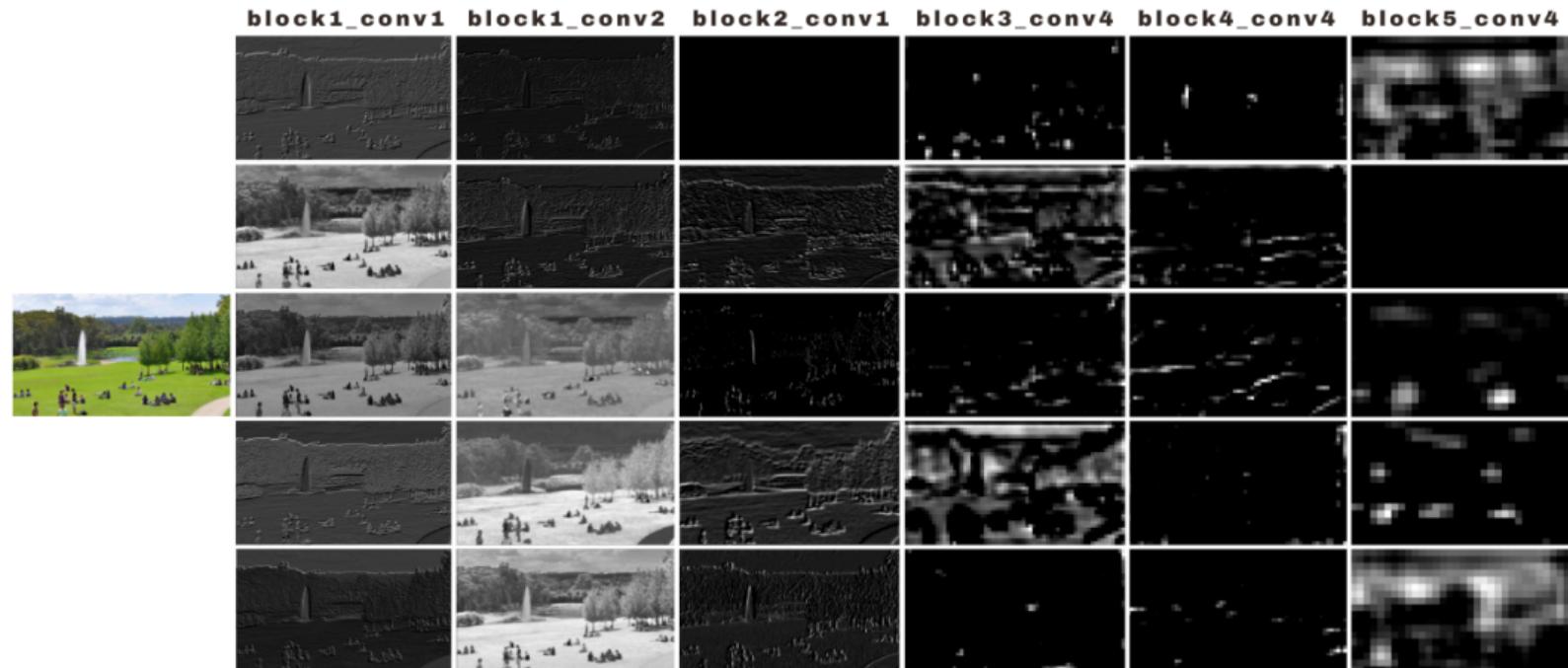


Figure: Visualization of feature maps at certain layers in VGG19.

# Content Representation

- Content representation: feature responses in higher layers of the network

$$F^l, P^l \in \mathcal{R}^{N_l \times M_l}$$

$$\vec{x}$$



$$\vec{p}$$



Figure: Left:  $\vec{x}$ , image to update. Right:  $\vec{p}$ , content image.

# Content Reconstruction

- Generate an image that minimizes the content loss

$$\mathcal{L}_{\text{content}}(\vec{p}, \vec{x}, l) = \frac{1}{2} \sum_{i,j} (F_{ij}^l - P_{ij}^l)^2 \quad (1)$$

- Compute derivative w.r.t. the activations in layer  $l$

$$\frac{\partial \mathcal{L}_{\text{content}}}{\partial F_{ij}^l} = \begin{cases} (F^l - P^l)_{ij} & F_{ij}^l > 0 \\ 0 & F_{ij}^l < 0 \end{cases} \quad (2)$$

# How to Optimize? Gradient Descent

- Gradient explanation:  $F^l$  is the feature representation at layer  $l$  with ReLU activation



$$\text{ReLU}(x) = \begin{cases} x & x > 0 \\ 0 & x \leq 0 \end{cases} = \max(0, x), \quad \text{ReLU}'(x) = \begin{cases} 1 & x > 0 \\ 0 & x \leq 0 \end{cases}$$

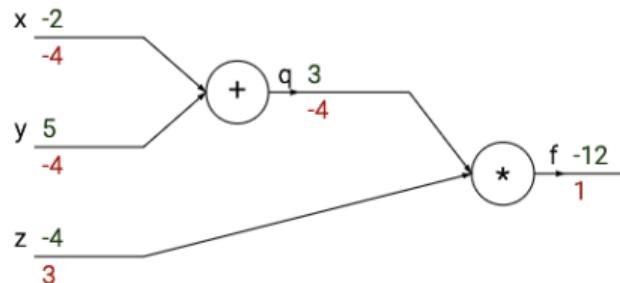
- Efficient gradient computation: [chain rule and backpropagation](#)

$$q = x + y, \quad f = q * z$$

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial x}$$

# Computational Graph

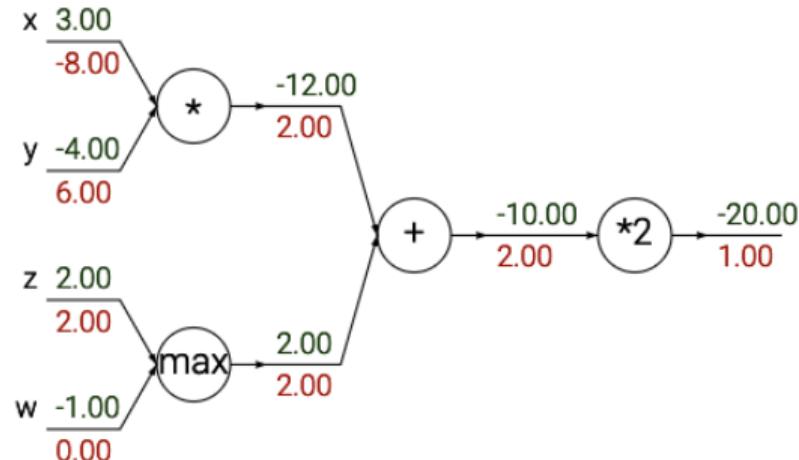
- Gates communicating to each other through gradient signal



```
# set some inputs
x, y, z = -2, 5, -4
# perform the forward pass
q = x + y # q becomes 3
f = q * z # f becomes -12
# perform the backward pass (backpropagation) in reverse order:
# first backprop through f = q * z
dfdz = q # df/dz = q, so gradient on z becomes 3
dfdq = z # df/dq = z, so gradient on q becomes -4
dqdx = 1.0
dqdy = 1.0
# now backprop through q = x + y
dfdx = dfdq * dqdx # The multiplication here is the chain rule!
dfdy = dfdq * dqdy
```

# Backpropagation: An Intuitive View

- Sum operation distributes gradients equally to all its inputs
- Max operation routes the gradient to the higher input
- Multiply gate takes the input activations, swaps them and multiplies by its gradients



# Content Reconstruction in Practice

- Define your `model`, loss function, select an optimizer and train
- Tensorflow will take care of the rest (no need to write the backprop on your own)

```
# optimizer
opt = tf.keras.optimizers.Adam(learning_rate=0.02, beta_1=0.99, epsilon=1e-1)
# loss function
def content_only_loss(outputs: dict, target_features: dict):
    return tf.add_n([tf.reduce_mean((outputs[name]-target_features[name])**2) for name in outputs.keys()])

@tf.function()
def train_step(model, image_to_gen, target_features, loss_func, optimizer):
    with tf.GradientTape() as tape:
        outputs = model(image_to_gen)
        loss = loss_func(outputs, target_features)
    grad = tape.gradient(loss, image_to_gen)
    optimizer.apply_gradients([(grad, image_to_gen)])
    image_to_gen.assign(clip_0_1(image_to_gen))
```

# Content Reconstructions



**Figure:** Reconstruct the content from different layers: conv1\_2, conv2\_2, conv3\_2, conv4\_2, conv5\_2.

# Style Representation

- Style representation: feature correlations between different filter responses

$$G^l, A^l \in \mathcal{R}^{N_l \times N_l}$$

$$G_{ij}^l = \sum_k F_{ik}^l F_{jk}^l \quad (3)$$

$\vec{x}$



$\vec{a}$



Figure: Left:  $\vec{x}$ , image to update. Right:  $\vec{a}$ , style image.

# Gram Matrix in Practice

- Hermitian matrix of inner products in an inner product space
- $G_{ij}^l$  is the inner product between the vectorised feature maps  $i$  and  $j$  in layer  $l$

$$G_{ij}^l = \sum_k F_{ik}^l F_{jk}^l$$

- Matrix formulation

$$F^l = \begin{pmatrix} F_{11}^l & \cdots & F_{1M_l}^l \\ \vdots & \ddots & \vdots \\ F_{N_l 1}^l & \cdots & F_{N_l M_l}^l \end{pmatrix}, \quad (F^l)^T = \begin{pmatrix} F_{11}^l & \cdots & F_{1N_l}^l \\ \vdots & \ddots & \vdots \\ F_{M_l 1}^l & \cdots & F_{M_l N_l}^l \end{pmatrix}$$

$$G^l = F^l (F^l)^T \in \mathcal{R}^{N_l \times N_l}$$

# Gram Matrix in Practice

Two implementations:

- version1: reshape and matmul

```
def gram_matrix_plain(input_tensor):  
    input_tensor = input_tensor[0] # (H, W, C) , C is the channel size or #filters  
    input_tensor = tf.transpose(input_tensor, perm: (2, 0, 1))  
    vectorized_fea = tf.reshape(input_tensor, shape: (tf.shape(input_tensor)[0], -1))  
    return tf.matmul(vectorized_fea, tf.transpose(vectorized_fea))
```

- version2: einsum

```
def gram_matrix(input_tensor):  
    result = tf.linalg.einsum( equation: 'bijc, bijd->bcd', *inputs: input_tensor, input_tensor)  
    input_shape = tf.shape(input_tensor)  
    num_locations = tf.cast(input_shape[1]*input_shape[2], tf.float32)  
    return result/num_locations
```

# Style Reconstruction

- Generate an image that minimizes the style loss

$$\mathcal{L}_{\text{style}}(\vec{a}, \vec{x}) = \sum_{l=0}^L w_l E_l \quad (4)$$

$$E_l = \frac{1}{4N_l^2 M_l^2} \sum_{ij} (G_{ij}^l - A_{ij}^l)^2 \quad (5)$$

- Compute derivative w.r.t. the activations in layer  $l$

$$\frac{\partial E_l}{\partial F_{ij}^l} = \begin{cases} \frac{1}{N_l^2 M_l^2} ((F^l)^T (G^l - A^l))_{ij} & F_{ij}^l > 0 \\ 0 & F_{ij}^l < 0 \end{cases} \quad (6)$$

# Style Reconstructions



**Figure:** Reconstruct the style from a style representation built on different subsets of CNN layers:  
{conv1\_1}, {conv1\_1, conv2\_1}, {conv1\_1, conv2\_1, conv3\_1}, {conv1\_1, conv2\_1, conv3\_1, conv4\_1},  
{conv1\_1, conv2\_1, conv3\_1, conv4\_1, conv5\_1}.

# Style Transfer

- Jointly minimize the distance of feature representations of a white noise image from
  - the content representation of the photograph in one layer and
  - the style representation of the painting defined on a number of layers

$$\mathcal{L}_{\text{total}}(\vec{p}, \vec{a}, \vec{x}) = \alpha \mathcal{L}_{\text{content}}(\vec{p}, \vec{x}) + \beta \mathcal{L}_{\text{style}}(\vec{a}, \vec{x}) \quad (7)$$



# Style Transfer

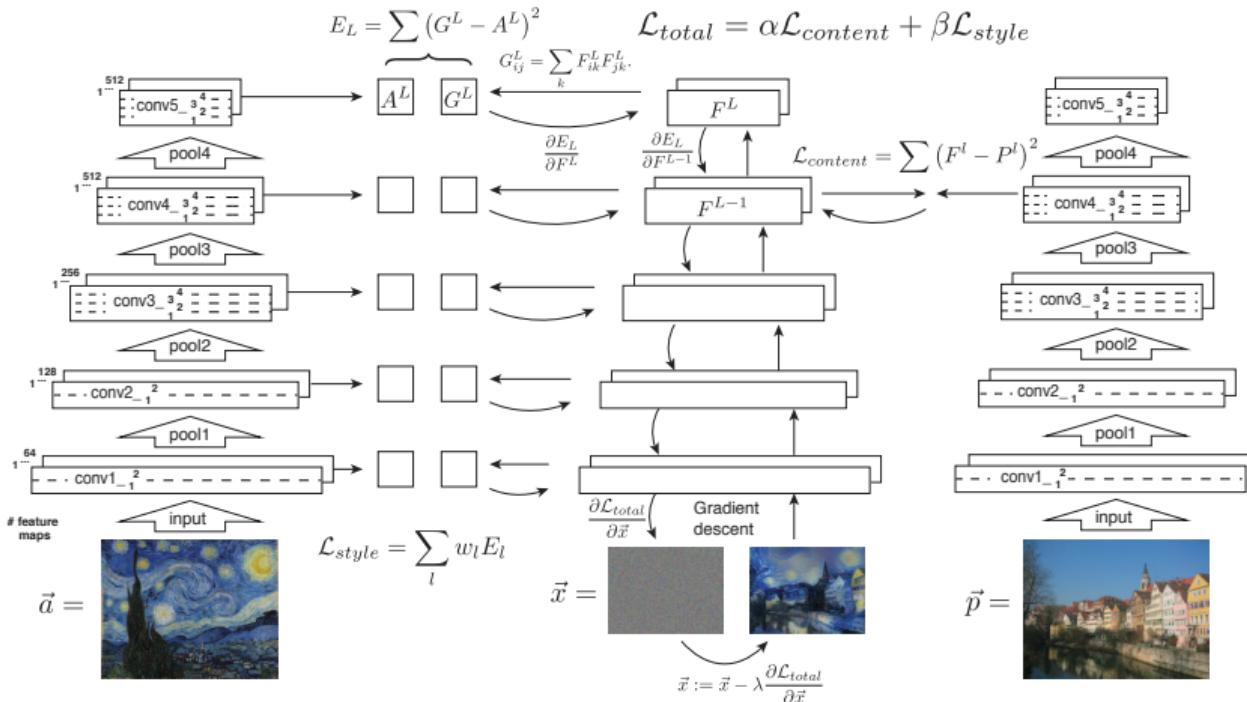
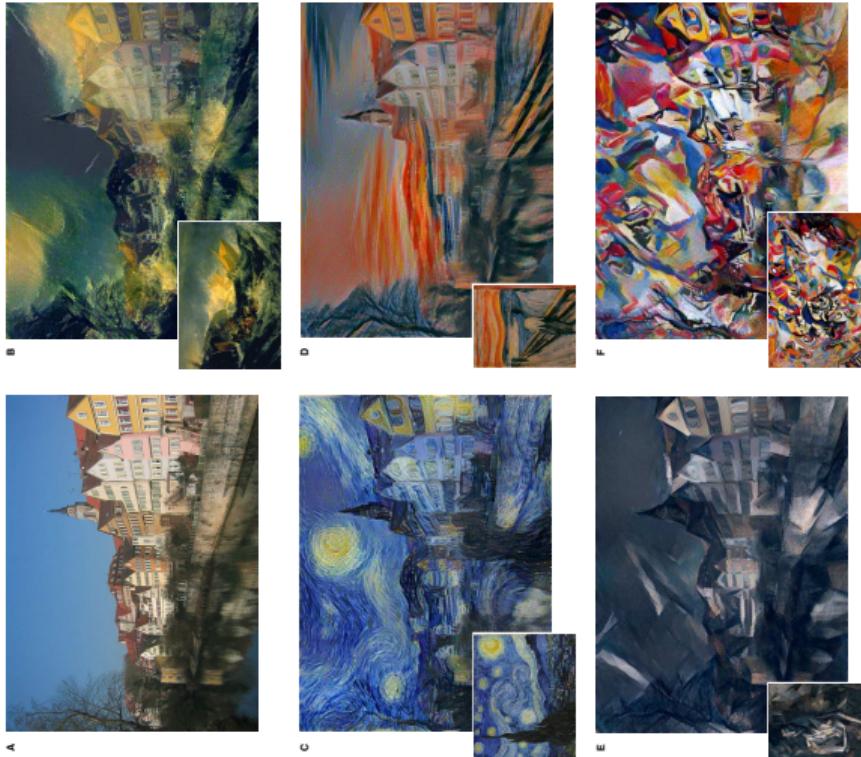


Figure: Overview of the style transfer algorithm.

## More Examples



**Figure:** **A** Neckarfront in Tübingen, Germany. **B** *The Shipwreck of the Minotaur*. **C** *The Starry Night*  
**D** *Der Schrei*. **E** *Femme nue assise*. **F** *Composition VII*.

# Trade-off Between Content and Style Matching

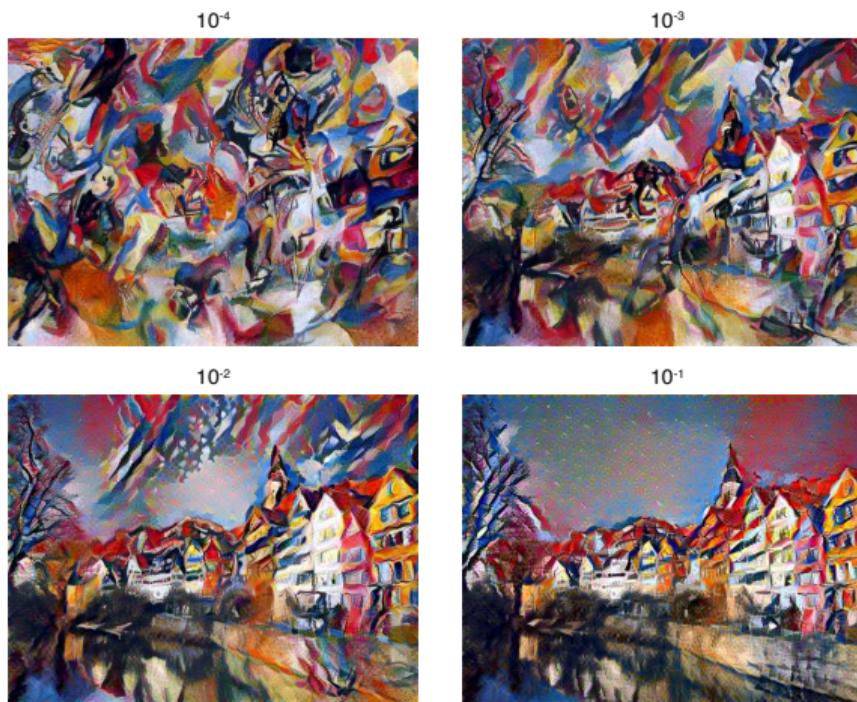


Figure: Relative weighting of matching content and style of the respective source images.

# Effect of Matching Different Layers in CNN



**Figure:** Matching the content representation on layer 'conv2\_2' preserves much of the fine structure of the original image. While the content is displayed in the style of the painting when matching the content representation on layer 'conv4\_2'.

# Initialisation of the Gradient Descent



**Figure:** **A** Initialisation from the content image. **B** Initialisation from the style image. **C** Four samples of images initialisation from different white noise images. ( $\alpha/\beta = 1 \times 10^{-3}$  for all images)

# Neural Style Transfer Implementation

- Define our `model` for both content and style feature extraction
- `Loss function` and `optimizer`
- Wrapping up

```
@tf.function()
def train_step(model, image_to_gen, loss_func, optimizer, **kwargs):
    with tf.GradientTape() as tape:
        outputs = model(image_to_gen)
        loss = loss_func(outputs, **kwargs)
        grad = tape.gradient(loss, image_to_gen)
        optimizer.apply_gradients([(grad, image_to_gen)])
        image_to_gen.assign(clip_0_1(image_to_gen))
```

# FYI

- DeepDream vs Neural Style Transfer
  - generative
  - feature map
  - gradient w.r.t the input image
  - ...
- References:
  - Convolutional Neural Networks for Visual Recognition
  - Inceptionism: Going Deeper Into Neural Networks
  - Image Style Transfer Using Convolutional Neural Networks
  - Very Deep Convolutional Networks for Large-Scale Image Recognition
- Code is available [here](#)

Thank you very much!  
Q&A

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