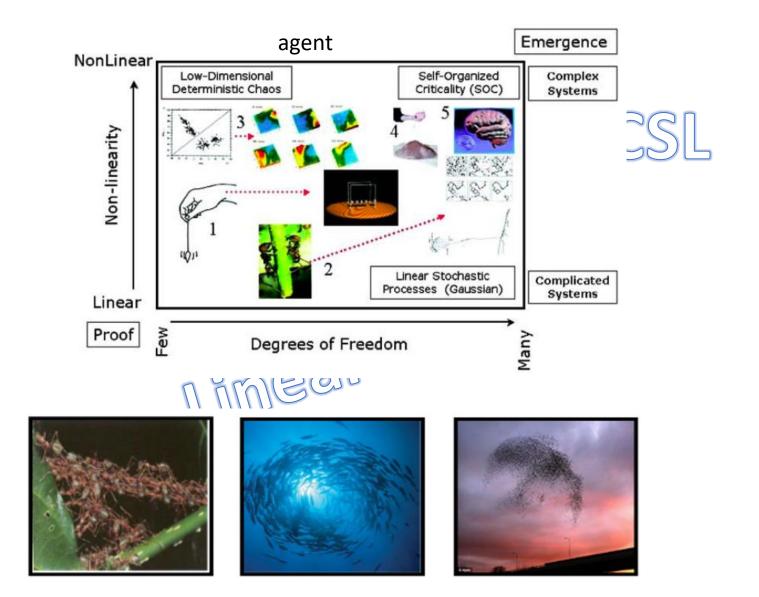
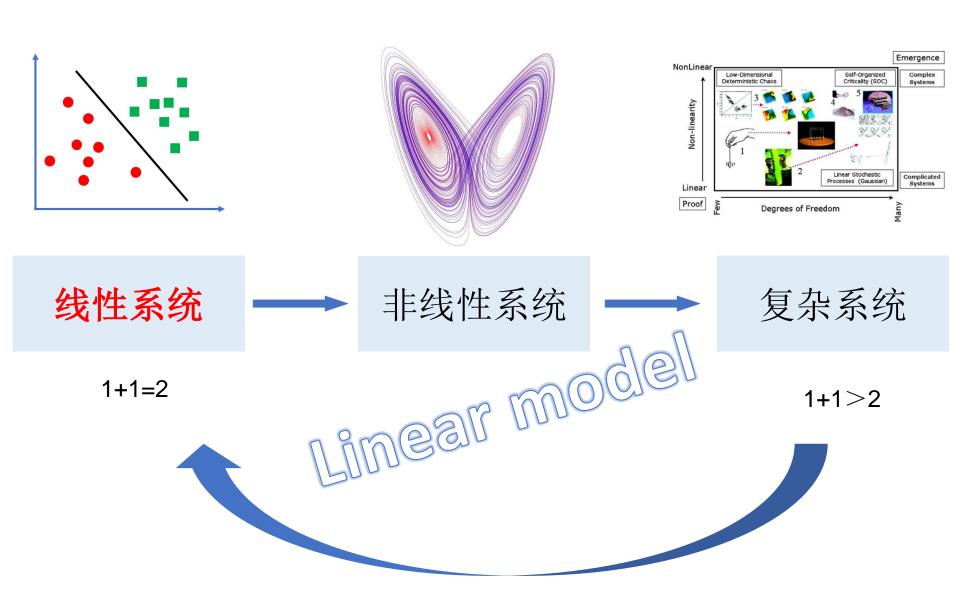
线性模型

CSL

复杂系统

I think the next century will be the century of complexity. — Stephen Hawking (2000)





机器学习:数据驱动的方法论 (工具)

程序员:能通过经验(数据)自动改进算法的计算机程序

应用数学: 逼近论, 函数拟合 (神经网络,...)

统计学: 不需要解释的简易统计学应用 (线性回归, ...)



数据挖掘:数据->信息->知识->智慧(目标)

经验主义:强调知识源于经验、强调归纳推理

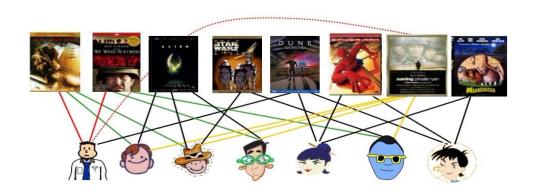
两类任务

・ 机器学习人的认知能力 (理性): speech, NLP, CV



CSL

・ 机器学习/理解人的行为 (有限理性、非理性)



LEARNING = REPRESENTATION + EVALUATION + OPTIMIZATION

机器学习 = 模型 + 评估 + 优化

| Representation | Evaluation | Optimization |
|---------------------------|-----------------------|----------------------------|
| Instances | Accuracy/Error rate | Combinatorial optimization |
| K-nearest neighbor | Precision and recall | Greedy search |
| Support vector machines | Squared error | Beam search |
| Hyperplanes | Likelihood | Branch-and-bound |
| Naive Bayes | Posterior probability | Continuous optimization |
| Logistic regression | Information gain | Unconstrained |
| Decision trees | K-L divergence | Gradient descent |
| Sets of rules | Cost/Utility | Conjugate gradient |
| Propositional rules | Margin | Quasi-Newton methods |
| Logic programs | | Constrained |
| Neural networks | | Linear programming |
| Graphical models | | Quadratic programming |
| Bayesian networks | | |
| Conditional random fields | | |

Domingos P M. A few useful things to know about machine learning[J]. Communications of The ACM, 2012, 55(10): 78-87.

假设空间

$$\mathcal{F} = \{ f \mid Y = f(X) \}$$

$$\mathcal{F} = \{P \mid P(Y \mid X)\}$$

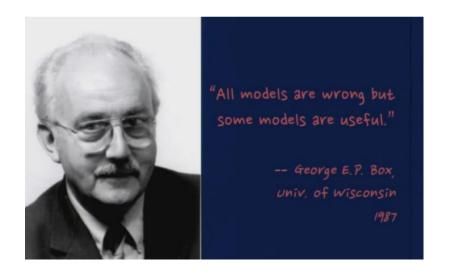
$$\mathcal{F} = \{ f \mid Y = f_{\theta}(X), \theta \in \mathbf{R}^n \}$$

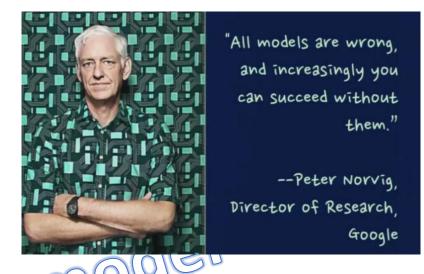
$$\mathcal{F} = \{ P \mid P_{\theta}(Y \mid X), \theta \in \mathbf{R}^n \}$$





All models are wrong?









度量模型与真实世界的相似性



度量模型与真实世界的相似性



 Y_i 损失函数 $L(y_i, f(x_i))$

经验风险(Empirical risk)(in-sample error)
$$R_{emp}(f) = 1/N \sum_{i=1}^{N} L(y_i, f(x_i))$$

泛化误差(General error) (out-of-sample error)

$$R_{gen}(f) = E_{p(x,y)}L(y_i, f(x_i))$$

度量模型与真实世界的相似性

$$Y_i \longrightarrow L(y_i, f(x_i)) \longleftarrow f(x_i)$$

0/1 损失:

$$L(Y, f(x)) = \begin{cases} 1, Y \neq f(X) \\ 0, Y = f(X) \end{cases}$$

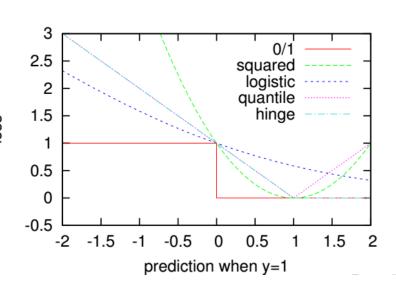
平方损失 (L2, MSE):

$$L(Y, f(x)) = (Y - f(X))^{2}$$

对数损失(交叉熵损失)

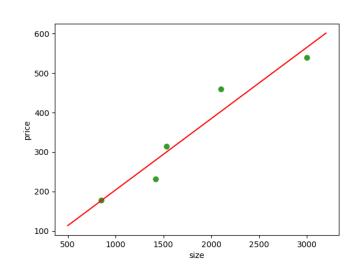
$$L(Y, f(x)) = -\log P(Y|X)$$





经验风险(Empirical risk) (in-sample error)

min
$$R_{emp}(f) = 1/N \sum_{i=1}^{N} L(y_i, f(x_i))$$



X = (2104, 1416, 1534, 852, 3000), Y = (460, 232, 315, 178, 540)

$$f(x) = ax + b$$

$$J(a,b) = \frac{1}{N} \sum_{i} (ax_i + b - y_i)^2$$

$$J(a,b) = \frac{1}{N} \sum_{i} (ax_{i} + b - y_{i})^{2}$$

$$X = \begin{pmatrix} 2104,1\\1416,1\\1534,1\\852,1\\3000,1 \end{pmatrix}, \quad w = \begin{pmatrix} a\\b \end{pmatrix}, \quad Y = \begin{pmatrix} 460\\232\\315\\178\\540 \end{pmatrix}$$

$$\widehat{w}_{oLS} = \begin{pmatrix} X^{T}_{1}\\X^{T}_{2}\\...\\X_{N} \end{pmatrix}$$

$$\widehat{w}_{oLS} = \begin{pmatrix} X^{T}_{1}X^{T}_{2}\\X^{T}_{2}\\...\\X_{N} \end{pmatrix}$$

$$\widehat{w}_{oLS} = \begin{pmatrix} X^{T}_{1}X^{T}_{2}\\X^{T}_{2}\\...\\X_{N} \end{pmatrix}$$

$$\widehat{w}_{oLS} = \begin{pmatrix} X^{T}_{1}X^{T}_{2}\\X^{T}_{2}\\...\\X_{N} \end{pmatrix}$$

$$\widehat{w}_{oLS} = \begin{pmatrix} X^{T}_{2}X^{T}_{2}\\X^{T}_{2}\\...\\X_{N} \end{pmatrix}$$

$$\widehat{w}_{oLS} = (X^{T}_{2}X^{T}_{2})^{-1}X^{T}_{2}Y$$

$$\widehat{array}([[\ 0.18078802], [22.98037744]])$$

normal equation

$$\min J(\mathbf{w}) = \frac{1}{2} \sum_{i} (\mathbf{Y}_{i} - \mathbf{w}^{T} \mathbf{X}_{i})^{2}$$

$$X = \begin{pmatrix} X_1^T \\ X_2^T \\ \dots \\ X_N \end{pmatrix} \quad J = \frac{1}{2} (Y - Xw)^T (Y - Xw)$$
$$X^T (Y - Xw) = 0$$
$$X^T Xw = X^T Y$$

$$\widehat{w}_{OLS} = (X^T X)^{-1} X^T Y$$
 array([[0.18078802], [22.98037744]])

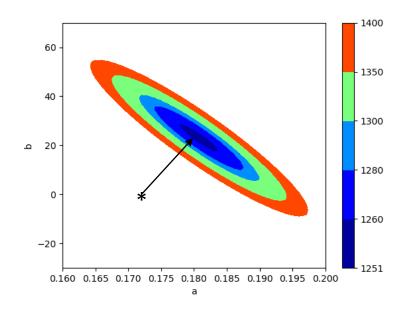
经验风险(Empirical risk) (in-sample error)

min
$$R_{emp}(f) = 1/N \sum_{i=1}^{N} L(y_i, f(x_i))$$
 f?

X = (2104, 1416, 1534, 852, 3000), Y = (460, 232, 315, 178, 540)

模型: f(x) = ax + b

评估: $J(a,b) = \frac{1}{N} \sum_{i} (ax_i + b - y_i)^2$ 优化: min J(a,b)



Taylor展开

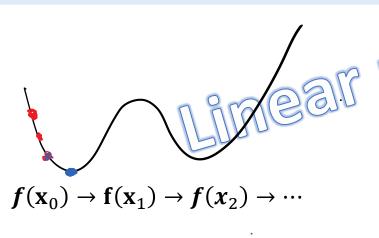
$$f(x + \Delta x) = f(x) + f'(x)\Delta x + 1/2f''(x)\Delta x^2 + o(\Delta x^2)$$

梯度下降法 (Gradient decent)

$$f(x + \Delta \mathbf{x}) = f(x) + \nabla f(x) \Delta x + \frac{1}{2\alpha} \Delta x^2 + o(\Delta x^2)$$

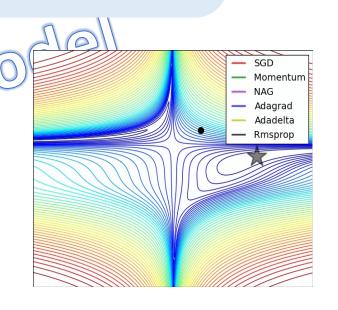
$$min f(x_0 + \Delta \mathbf{x}) = f(x_0) + \nabla f(x_0) \Delta x + \frac{1}{2\alpha} \Delta x^2 + o(\Delta x^2)$$

$$\Delta x = -\alpha \nabla f(x_0) \qquad x_{k+1} = x_k - \alpha \nabla f(x_k)$$



梯度下降法: 收敛率 $O(\frac{1}{K})$

近似 (已知->未知)



Taylor展开

$$f(x + \Delta x) = f(x) + f'(x)\Delta x + 1/2f''(x)\Delta x^2 + o(\Delta x^2)$$

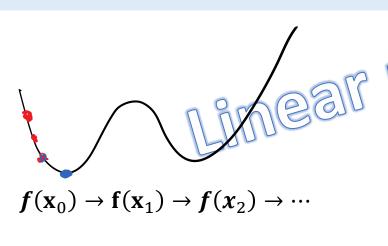
Newton法

$$f(x + \Delta \mathbf{x}) = f(x) + \nabla f(x) \Delta x + \frac{1}{2} \nabla^2 f(x) \Delta x^2 + o(\Delta x^2)$$

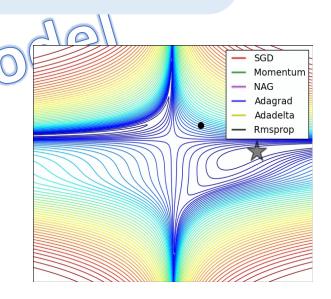
$$min f(x_0 + \Delta \mathbf{x}) = f(x_0) + \nabla f(x_0) \Delta x + \frac{1}{2} \nabla^2 f(x_0) \Delta x^2 + o(\Delta x^2)$$

$$\Delta x = -\nabla f(x_0) / \nabla^2 f(x_0)$$

$$x_{k+1} = x_k - \nabla f(x_0) / \nabla^2 f(x_0)$$



Newton法: 收敛率 $O(\frac{1}{K^2})$



$$\min J(\mathbf{w}) = \frac{1}{2N} \sum_{i} (\mathbf{Y}_{i} - \mathbf{w}^{T} \mathbf{X}_{i})^{2}$$

$$J(a,b) = \frac{1}{2N} \sum_{i} (ax_i + b - y_i)^2$$

while k > 最大步数 or $\nabla J(a_k, b_k) \approx 0$

$$a_{k+1} = a_k - \alpha \frac{\partial J(a_k, b_k)}{\partial a}$$

$$b_{k+1} = b_k - \alpha \frac{\partial J(a_k, b_k)}{\partial b_k}$$

$$J'(\mathbf{w}) = \frac{1}{N} \sum_{i} X_i^T (\mathbf{w}^T X_i - Y_i)$$

$$\frac{1}{N}\sum_{i}x_{i}(ax_{i}+b-y_{i})$$

$$\frac{1}{N}\sum_{i}1\left(ax_{i}+b-y_{i}\right)$$

批量梯度下降法 (Batch Gradient Descent)

Repeat {

$$w_{k+1} = w_k - \frac{1}{N} \sum X_i^T (\mathbf{w}^T X_i - Y)$$

随机梯度下降法

(Stochastic Gradient Descent)

- 1. Randomly shuffle dataset;
- 2. repeat{ for i=1, ..., N {

$$w_{k+1} = w_k - X_i^T (\mathbf{w}^T X_i - Y)$$

} .

Mini-batch Gradient Descent: batch size

批量梯度下降法 (Batch Gradient Descent)

Repeat {

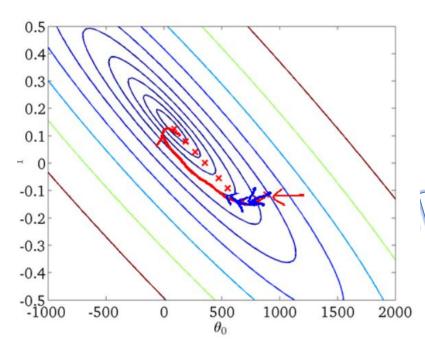
$$w_{k+1} = w_k - \frac{1}{N} \sum X_i^T (\mathbf{w}^T X_i - Y)$$

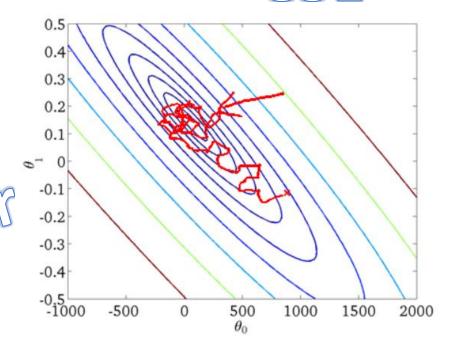
随机梯度下降法 (Stochastic Gradient Descent)

1. Randomly shuffle dataset;

2. repeat{
 for i=1, ..., N
 {

$$w_{k+1} = w_k - X_i^T (\mathbf{w}^T X_i - Y)$$
 }



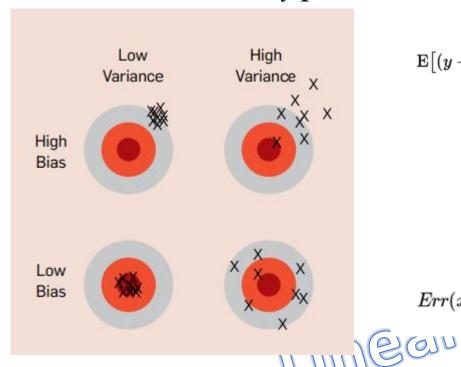


收敛率 $O(\frac{1}{K})$

收敛率 $O(\frac{1}{\sqrt{K}})$

偏差与方差

$$R_{emp}(f) = 1/N \sum_{i=1}^{N} L(y_i, f(x_i))$$
 $R_{gen}(f) = E_{p(x,y)} L(y_i, f(x_i))$



$$\begin{split} \mathbf{E} \big[(y - \hat{f})^2 \big] &= \mathbf{E} [y^2 + \hat{f}^2 - 2y \hat{f}] \\ &= \mathbf{E} [y^2] + \mathbf{E} [\hat{f}^2] - \mathbf{E} [2y \hat{f}] \\ &= \mathbf{Var} [y] + \mathbf{E} [y]^2 + \mathbf{Var} [\hat{f}] + \mathbf{E} [\hat{f}]^2 - 2f \mathbf{E} [\hat{f}] \\ &= \mathbf{Var} [y] + \mathbf{Var} [\hat{f}] + (f^2 - 2f \mathbf{E} [\hat{f}] + \mathbf{E} [\hat{f}]^2) \\ &= \mathbf{Var} [y] + \mathbf{Var} [\hat{f}] + (f - \mathbf{E} [\hat{f}])^2 \\ &= \mathbf{Var} [y] + \mathbf{Var} [\hat{f}] + \mathbf{E} [f - \hat{f}]^2 \\ &= \sigma^2 + \mathbf{Var} [\hat{f}] + \mathbf{Bias} [\hat{f}]^2 \end{split}$$

 $Err(x) = Bias^2 + Variance + Irreducible Error$

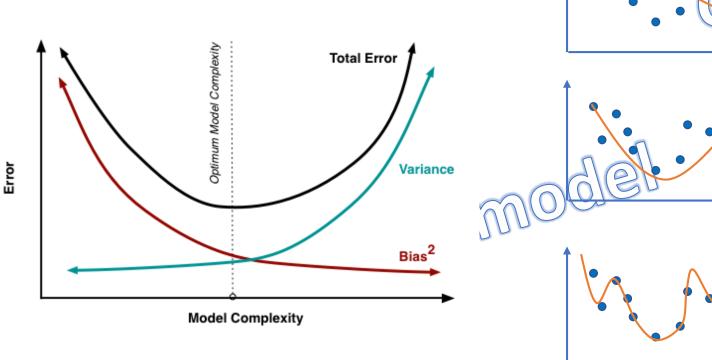
Bias: $(E[\hat{f}(x)] - f(x))^2$ 度量了学习算法的平均估计结果能逼近学习目标的程度。

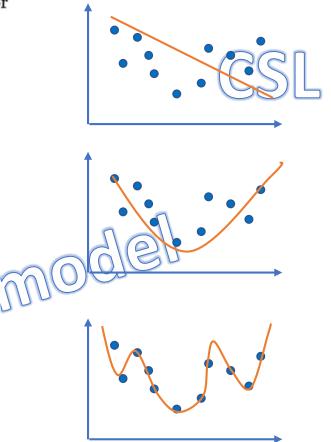
Variance: $E[(\hat{f}(x) - E[\hat{f}(x)])^2]$ 度量了面对不同训练集时,学习算法的估计结果发生变动的程度。

偏差与方差

$$R_{emp}(f) = 1/N \sum_{i=1}^{N} L(y_i, f(x_i))$$
 $R_{gen}(f) = E_{p(x,y)} L(y_i, f(x_i))$

 $Err(x) = Bias^2 + Variance + Irreducible Error$





交叉验证(cross validation)

全部数据

训练集

测试集

训练集

验证集

测试集

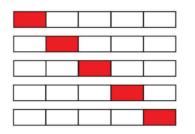
100let

训练集(training set): 用于训练模型

验证集 (validation set) 注 用于模型选择

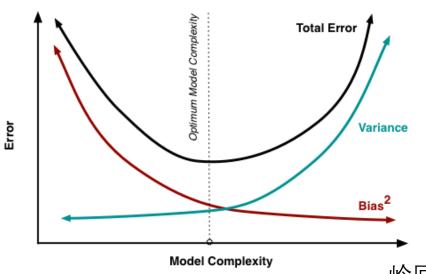
测试集(test set): 用于最终对学习方法的评估

训练集 | 训练集 | 训练集 | 验证集



正则化 (regularization)

偏差与方差 $Err(x) = Bias^2 + Variance + Irreducible Error$



L_p 正则化

 $\hat{w}^{L_p} = \arg\min_{w \in R^d} \sum_{i=1}^n (w^T X_i - Y_i)^2 \text{ subject to } \sum_{j=1}^d |w_j|^p \leq A.$

$$\hat{w}^{L_p} = \arg\min_{w \in R^d} \sum_{i=1}^n (w^T X_i - Y_i)^2 + \lambda \sum_{j=1}^d |w_j|^p$$

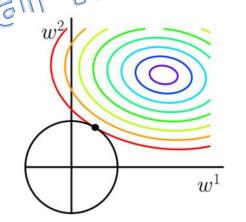
岭回归(Ridge Regression)

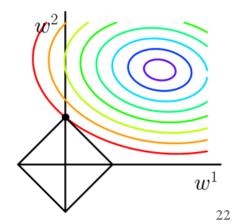
LASSO

 L_2 正则化: $\Omega(w) = \lambda ||w||_2^2 = \lambda \sum_{i=1}^d w_i^2$

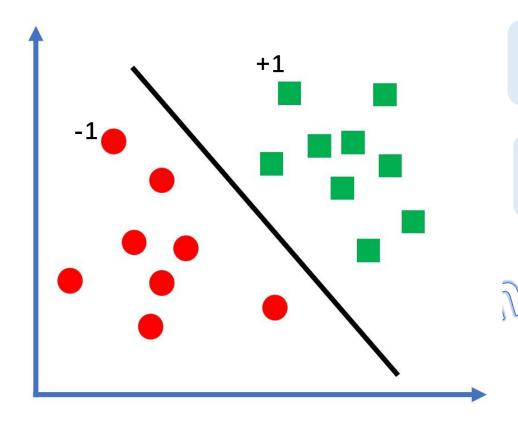
 L_1 正则化: $\Omega(w) = \lambda ||w||_1 = \lambda \sum_{i=1}^{d} |w_i|$

 L_0 正则化: $\Omega(w) = \lambda ||w||_0$





$$f(x_i) = h(w^T x_i + b)$$



感知机 (Perceptron)

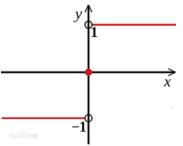
$$f(x_i) = sign(w^T x_i + b)$$

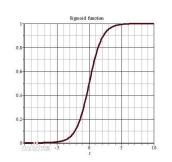
逻辑回归(Logistic regression)

$$f(x_i) = sigmoid(w^T x_i + b)$$

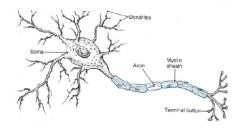
SVM (Support vector machine)

$$f(x_i) = sign(w^T x_i + b)$$



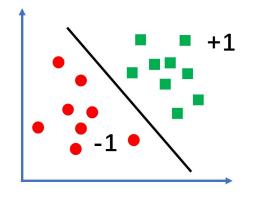


感知机



 w_n

1957年由Rosenblatt提出



McCulloch-Pitts模型

 $z = sign(w^T x_i)$ b

模型: $\hat{y} = w^T x_i + b$

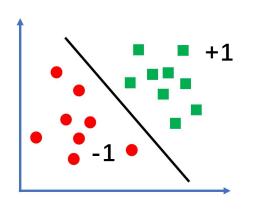
评估: $L(y_i, \widehat{y}_i) = -y_i(w^Tx_i + b)$

优化: $\min J(w) = \sum L(y_i, \widehat{y}_i) = -\sum_i y_i (w^T x_i + b)$

 x_2

 x_n

感知机



模型:
$$\hat{y} = w^T x_i + b$$

评估:
$$L(y, \hat{y}) = -y_i(w^Tx_i + b)$$

优化:
$$min J(w) = -\sum_{i} y_{i}(w^{T}x_{i} + b)$$

PLA (Perception Learning Algorithm)

- (1) 选取初值 w_0, b_0
- (2) 训练集中选取数据 (xi, yi)
- (3) if $y_i(w^Tx_i + b) \le 0$: $w = w + \alpha y_i x_i$ $b = b + \alpha y_i$
- (4) 转至(2), 直到训练集中没有误分类点

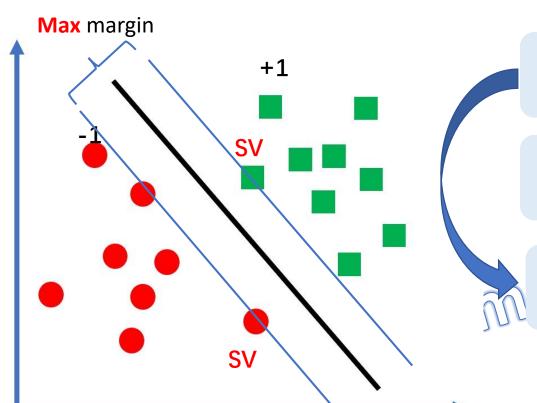


SGD

$$w_{k+1} = w_k - \alpha \frac{\partial J(w_k, b_k)}{\partial a}$$

$$b_{k+1} = b_k - \alpha \frac{\partial J(w_k, b_k)}{\partial b_k}$$

$$f(x_i) = h(w^T x_i + b)$$



感知机(Perceptron)

$$f(x_i) = sign(w^T x_i + b)$$

逻辑回归(Logistic regression)

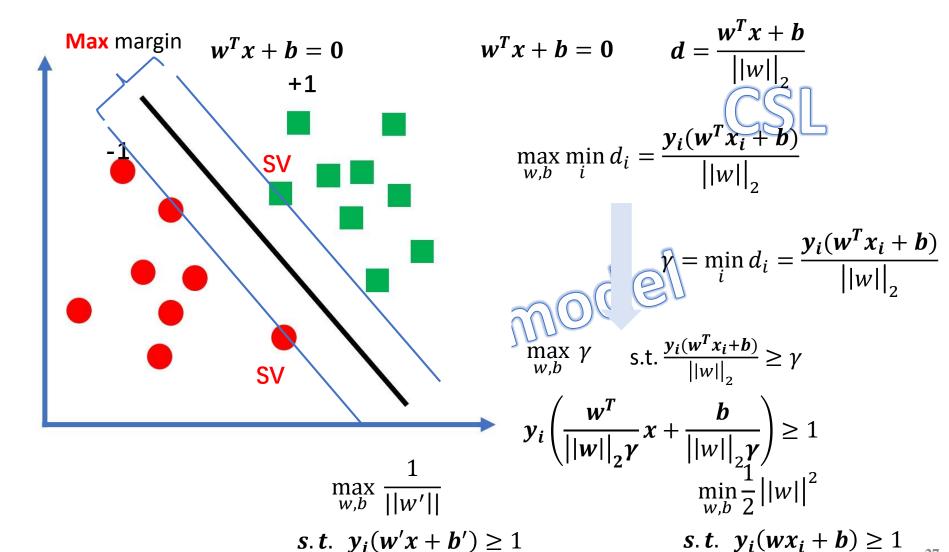
$$f(x_i) = sigmoid(w^T x_i + b)$$

SVM (Support vector machine)

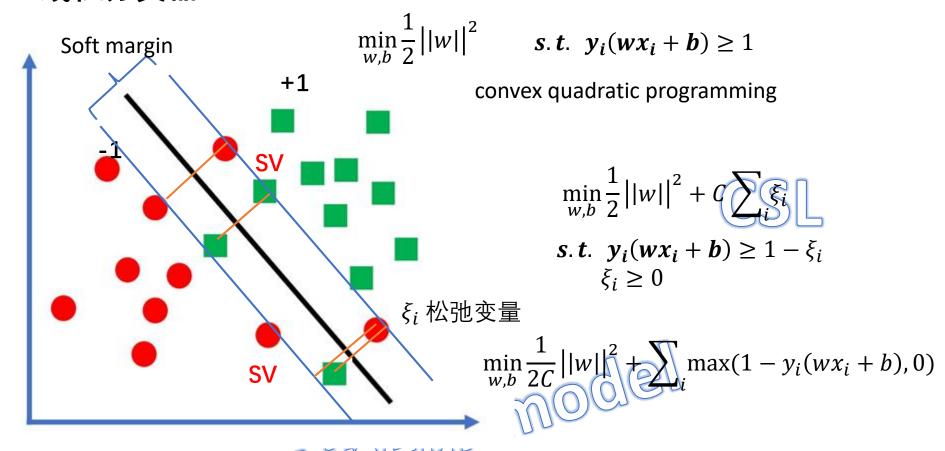
$$f(x_i) = sign(w^T x_i + b)$$

线性分类器 SVM

$$f(x_i) = h(w^T x_i + b)$$

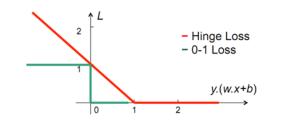


线性分类器 SVM



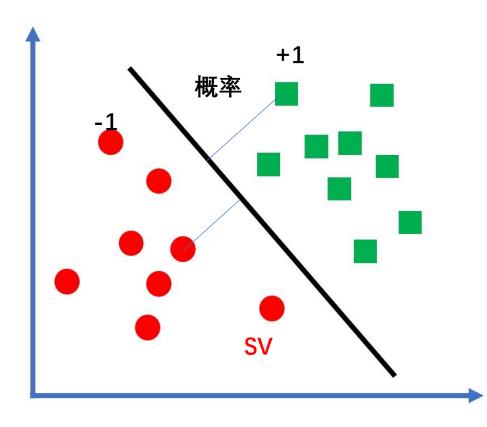
$$\min_{w,b} \sum_{i} \max(1 + y_i(wx_i + b), 0) + \lambda ||w||^2$$

Hinge Loss: $L(y_i, wx_i + b) = max(1 - y_i(wx_i + b), 0)$



2分类 -> 多分类 One-versus-all (one-versus-rest) One-versus-one

$$f(x_i) = h(w^T x_i + b)$$



感知机(Perceptron)

$$f(x_i) = sign(w^T x_i + b)$$

逻辑回归(Logistic regression)

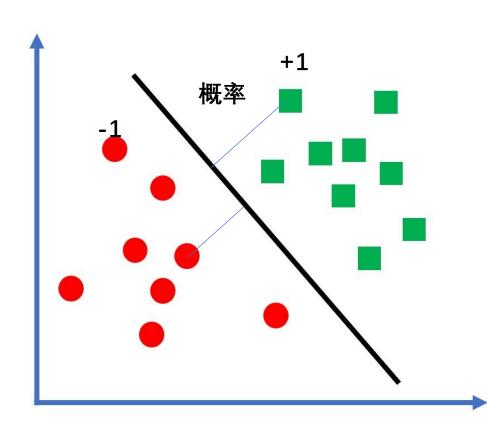
$$f(x_i) = sigmoid(w^T x_i + b)$$

SVM (Support vector machine)

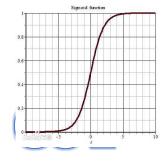
$$\int \int f(x_i) = sign(w^T x_i + b)$$

线性分类器 LR

$$f(x_i) = h(w^T x_i + b)$$



$$h(x) = \frac{1}{1 + e^{-x}}$$



- (1) 认知神经科学
- (2)物理学(Boltzmann分布)
- (3) 经济学(离散选择模型)

$$P(y_{i} = 1 | x_{i}) = \frac{1}{1 + e^{-(w^{T}x_{i} + b)}}$$

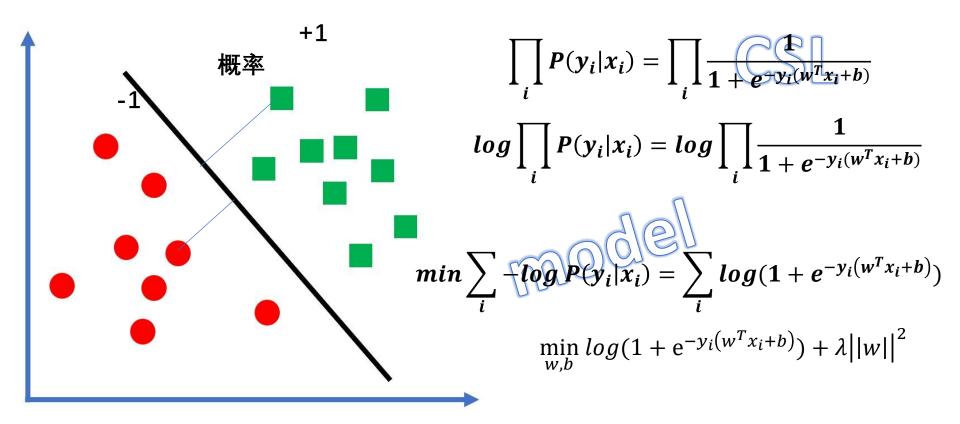
$$P(y_{i} = -1 | x_{i}) = \frac{1}{1 + e^{(w^{T}x_{i} + b)}}$$

$$\prod_{i} P(y_i|x_i) = \prod_{i} \frac{1}{1 + e^{-y_i(w^T x_i + b)}}$$

线性分类器 LR

$$P(y_i = 1|x_i) = \frac{1}{1 + e^{-(w^T x_i + b)}}$$

$$P(y_i = -1|x_i) = \frac{1}{1 + e^{(w^T x_i + b)}}$$



Logistic Loss: $L(y_i, wx_i + b) = log(1 + e^{-y_i(w^Tx_i + b)})$

线性分类器 LR

多项逻辑回归(multi-nominal logistic regression)

Softmax:
$$\sigma(\mathbf{z})_j = \frac{e^{z_j}}{\sum_{k=1}^K e^{z_k}}$$

$$P(y_i = 1 | x_i) = \frac{1}{1 + e^{-(w^T x_i + b)}}$$

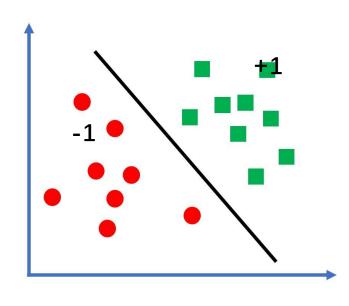
$$P(y_i = -1 | x_i) = \frac{e^{-(w^T x_i + b)}}{1 + e^{-(w^T x_i + b)}}$$

$$P(y_i = k | x_i) = \frac{e^{w_k^T x_i + b_k}}{\sum_k e^{w_k^T x_i + b_k}} \propto e^{w_k^T x_i + b_k}$$

$$log \prod_{i} \prod_{k} P(y_i = k | x_i)^{I(y_i = k)} = \sum_{i} \sum_{k} I(y_i = k) log \frac{e^{w_k^T x_i + b_k}}{\sum_{i} e^{w_k^T x_i + b_k}}$$

Cross entropy Loss:
$$L = \sum_{k} I(y_i = k) log \frac{e^{w_k^T x_i + b_k}}{\sum_{k} e^{w_k^T x_i + b_k}}$$

$$f(x_i) = h(w^T x_i + b)$$



感知机 (Perceptron)

$$f(x_i) = sign(w^T x_i + b)$$

逻辑回归(Logistic regression)

$$f(x_i) = sigmoid(w^T x_i + b)$$

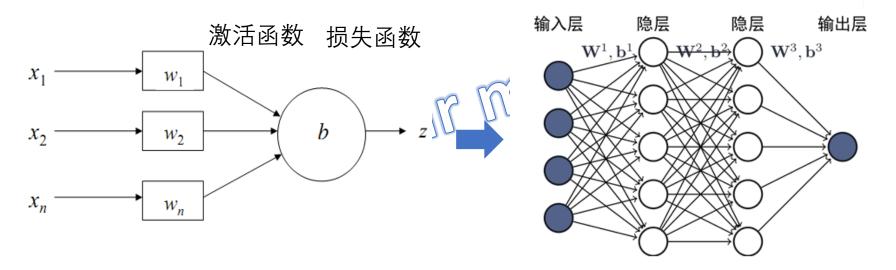
SVM (Support vector machine)

$$f(x_i) = sign(w^T x_i + b)$$

| | 模型 | 评价 | 优化 |
|------|---|---------------------------------------|-----|
| 感知机 | $\widehat{\boldsymbol{y}}_{i} = \boldsymbol{w}^{T} \boldsymbol{x}_{i} + \boldsymbol{b}$ | $L = -\widehat{y}_i y_i$ | SGD |
| 逻辑回归 | $\widehat{\boldsymbol{y}}_{i} = \boldsymbol{w}^{T} \boldsymbol{x}_{i} + \boldsymbol{b}$ | $L = log(1 + e^{-\widehat{y}_i y_i})$ | SGD |
| SVM | $\widehat{\boldsymbol{y}}_i = \boldsymbol{w}^T \boldsymbol{x}_i + \boldsymbol{b}$ | $L = max(1 - y_i \hat{y}_i, 0)$ | SGD |

线性分类器 = 浅层神经网络?

| | 模型 | 评价 | 优化 |
|------|---|---------------------------------------|-----|
| 感知机 | $\widehat{\mathbf{y}}_i = \mathbf{w}^T \mathbf{x}_i + \mathbf{b}$ | $L = -\widehat{y}_i y_i$ | SGD |
| 逻辑回归 | $\widehat{\boldsymbol{y}}_{i} = \boldsymbol{w}^{T} \boldsymbol{x}_{i} + \boldsymbol{b}$ | $L = log(1 + e^{-\widehat{y}_i y_i})$ | SGD |
| SVM | $\widehat{\boldsymbol{y}}_{i} = \boldsymbol{w}^{T} \boldsymbol{x}_{i} + \boldsymbol{b}$ | $L = max(1 - y_i \hat{y}_i, 0)$ | SGD |



由浅入深

总结

机器学习 = 模型 + 评估 + 优化

梯度下降法:

while True:

weights_grad = evaluate_gradient(loss_fun, data, weights)
weights += - step_size * weights_grad

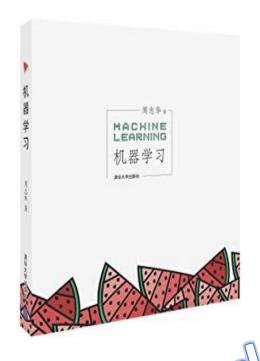


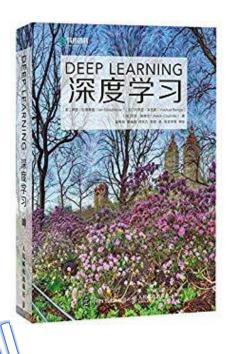
正则化:
$$\hat{w}^{L_p} = \arg\min_{w \in R^d} \sum_{i=1}^n (w^T X_i - Y_i)^2 + \lambda \sum_{j=1}^d |w_j|^p$$
 交叉验证

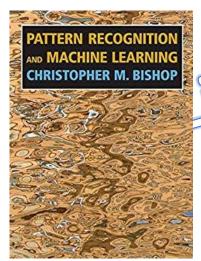
线性分类器:

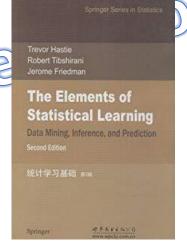
| | 模型 | 评价 | 优化 |
|------|---|---------------------------------------|-----|
| 感知机 | $\widehat{\boldsymbol{y}}_{\boldsymbol{i}} = \boldsymbol{w}^T \boldsymbol{x}_{\boldsymbol{i}} + \boldsymbol{b}$ | $L = -\widehat{y}_i y_i$ | SGD |
| 逻辑回归 | $\widehat{\boldsymbol{y}}_{\boldsymbol{i}} = \boldsymbol{w}^T \boldsymbol{x}_{\boldsymbol{i}} + \boldsymbol{b}$ | $L = log(1 + e^{-\widehat{y}_i y_i})$ | SGD |
| SVM | $\widehat{\boldsymbol{y}}_{\boldsymbol{i}} = \boldsymbol{w}^T \boldsymbol{x}_{\boldsymbol{i}} + \boldsymbol{b}$ | $L = max(1 - y_i \hat{y}_i, 0)$ | SGD |

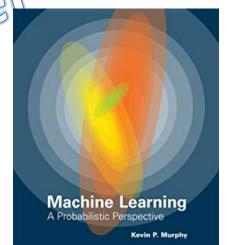








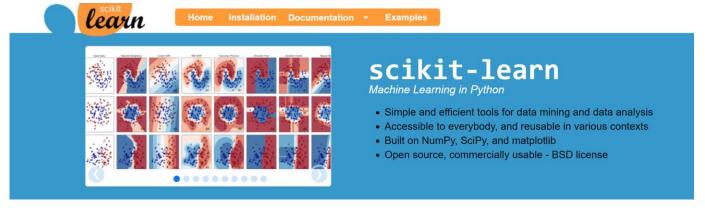


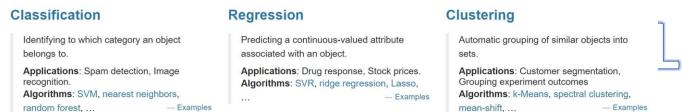


CSL

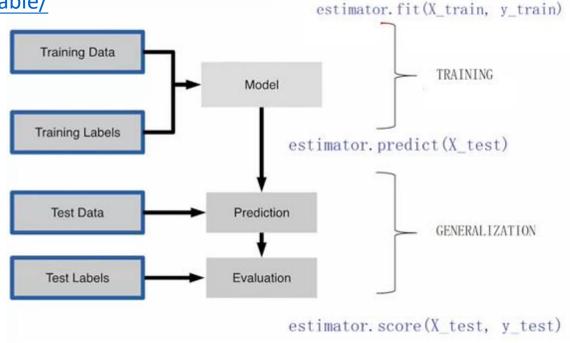
谢谢!

Linear model

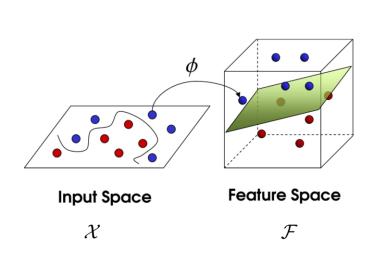




https://scikit-learn.org/stable/



核方法 (Kernel trick)



$$\min J(w) = 1/N \sum_{i=1}^{N} L(y_i, w^T \phi(x_i)) + \lambda ||w||^2$$

表示定理(Representer theory):

L(w)对于w是凸函数,则满足min I(w) 的 w可以表示为 $w = \sum \alpha_i \phi(x_i)$

核函数: $k(x_i, x_i) = \langle \phi(x_i), \phi(x_i) \rangle$

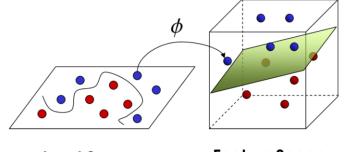
$$min_{\alpha}J(w) = 1/N\sum_{i=1}^{N}L(y_{i}, \sum \alpha_{j} < \phi(x_{i}), \phi(x_{i}) >) + \lambda < \sum \alpha_{i}\phi(x_{i}), \sum \alpha_{i}\phi(x_{i}) >$$

$$min_{\alpha}J(w) = 1/N\sum_{i=1}^{N}L(y_{i}, \sum \alpha_{j}k(x_{j}, x_{i})) + \lambda < \sum \alpha_{i}\phi(x_{i}), \sum \alpha_{i}\phi(x_{i}) >$$

$$\min_{\alpha} J(w) = 1/N \sum_{i=1}^{N} L(y_i, \sum \alpha_j k(x_j, x_i)) + \lambda < \sum \alpha_i \phi(x_i), \sum \alpha_i \phi(x_i) > 0$$

$$min_{\alpha}J(w) = 1/N\sum_{i=1}^{N}L\left(y_{i},\sum\alpha_{j}k(x_{j},x_{i})\right) + \lambda\alpha^{T}K\alpha$$

核方法 (Kernel trick)



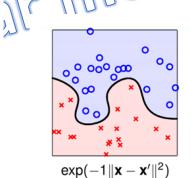
Input Space

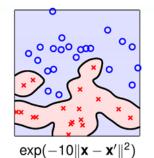
Feature Space

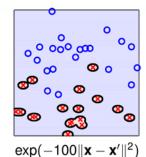
$$min_{\alpha} J(w) = 1/N \sum_{i=1}^{N} L\left(y_{i}, \sum \alpha_{j} k(x_{j}, x_{i})\right) + \lambda \alpha^{T} K \alpha^{T}$$

$$k(x_i, x_j) = \exp(-\gamma ||x_i - x_j||^2) = \exp(-\gamma (||x_i||^2 + ||x_j||^2 - 2x_i^T x_j))$$

| Kernel | Function |
|------------------|--|
| Linear | $k(x, x') = \langle x, x' \rangle$ |
| Hom. Polynomial | $k(x, x') = \langle x, x' \rangle k(x, x') = \langle x, x' \rangle^d$ |
| Inho. Polynomial | $k(x,x') = (\langle x,x'\rangle + c)^d$ |
| Gaussian RBF | $k(x, x') = \exp\left(-\frac{\ x - x'\ ^2}{2\sigma^2}\right)$ |
| Laplacian | $k(x, x') = \exp\left(-\frac{\ x - x'\ }{\sigma}\right)$ $k(x, x') = \tanh(\alpha \langle x, x' \rangle + c)$ |
| Sigmoid | $k(x, x') = \tanh(\alpha \langle x, x' \rangle + c)$ |







Lagrange对偶

$$\min_{w,b} \frac{1}{2} ||w||^2 \qquad s. t. \quad y_i(wx_i + b) \ge 1$$

$$L(w, b, \alpha) = \frac{1}{2} ||w||^2 + \alpha (1 - y_i(wx_i + b))$$

CSL

$$\min_{w,b} \max_{\alpha} L(w,b,\alpha) = \max_{\alpha} \min_{w,b} L(w,b,\alpha)$$

$$\nabla_{w}L(w,b,\alpha) = w - \sum_{i} \alpha_{i} y_{i} x_{i} = 0$$

$$\nabla_{b}L(w,b,\alpha) = \sum_{i} \alpha_{i} y_{i} + 0$$

$$\min_{w,b} L(w,b,\alpha) = -\frac{1}{2} \sum \alpha_i \alpha_j y_i y_j < x_i, x_j > + \sum \alpha_i$$

可解释性机器学习

Some models are easy to interpret

Linear/Logistic regression

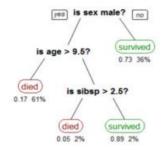
- Weight on each feature
- Know the exact contribution of each feature, negative or positive

$$Y = 3 * X1 - 2 * X2$$

Increasing X1 by 1 unit increases Y by 3 units

Single Decision Tree

 Easy to understand how a decision was made by reading from top to bottom

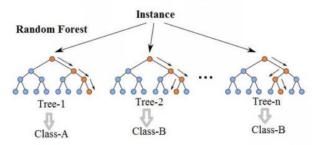


Some models are harder to interpret

Ensemble models (random forest, boosting, etc...)

- Hard to understand the role of each feature
- Usually comes with feature importance
- Doesn't tell us if feature affects decision positively or negatively

Random Forest Simplified



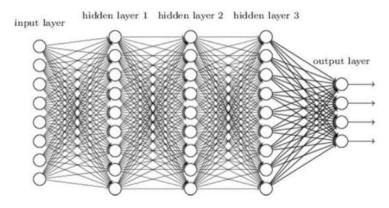
可解释性机器学习

Some are really hard to interpret

Deep Neural Networks

- No straightforward way to relate output to input layer
- "Black-box"

Deep neural network



个体的行为选择

- 决策者 (Decision Makers) ,即做出选择行为的主体。
- 备选方案(Alternatives), 通常会有多个方案供决策者选择
- 选择方案的属性 (Attributes of Alternatives)。每一种考虑因素
 称之为一个属性 (Attributes),以q_i表示
- 决策准则 (Decision Rules) Model (选择函数)

基本假设:人类行为是理性的 (偏好是完备的并具有传递习性)

Utility-based agent

• 定义(效用函数): p_i 是定义在特征向量空间上的线性 泛函 $v_{p_i} = p_i(q)$ 。由Riesz表示定理,偏好可以表示为 p_i , 则有 $v_{p_i}(q) = \langle p_i, q \rangle$.

• 定义(行为选择), R $A \to R$, 其中U 为个体i的效用 空间 $\pi(a|s) = P(A_t = a|S_t = s)$

离散选择模型



Daniel L. McFadden(2000诺奖)

$$u_{k,j} = v_{k,j} + \varepsilon_k = \langle p_k, q_j \rangle + \varepsilon_k$$

当 ε_i 满足Gumbel 分布(type I extreme value)时,

Utility Maximization

$$P_{ni} = \text{Prob}(V_{ni} + \varepsilon_{ni} > V_{nj} + \varepsilon_{nj} \ \forall j \neq i)$$

= \text{Prob}(\varepsilon_{nj} < \varepsilon_{ni} + V_{ni} - V_{nj} \ \forall j \neq i).

$$P_{ni} = \int \left(\prod_{j \neq i} e^{-e^{-(\varepsilon_{ni} + V_{ni} - V_{nj})}} \right) e^{-\varepsilon_{ni}} e^{-e^{-\varepsilon_{ni}}} d\varepsilon_{ni}. \qquad P_{ni} = \frac{e^{V_{ni}}}{\sum_{j} e^{V_{nj}}},$$

当只有2种行为时,上述模型退化为binary logit模型.

$$p(Y = 1|x) = \exp(f_w(x))/(1 + \exp(f_w(x)))$$

Logistic model

$$f_w(\mathbf{x}) = w_{k,0} + \sum_{i=1}^n w_{k,i} x_i = w_{k,0} + \langle p_{k'} q_j \rangle$$
Utility-based agent:
$$u_{k,j} = w_{k,0} + \langle p_{k'} q_j \rangle + \varepsilon_k$$

CSL

Factorization Machine model

$$f_w(\mathbf{x}) = w_{k,0} + \sum_{i=1}^n w_{k,i} x_i + \sum_{i=1}^n \sum_{j=i+1}^n \langle v_i, v_j \rangle x_i x_j$$
Utility-based agent:
$$u_{k,j} = w_{k,0} + \langle p_{k}, q_j \rangle + \sum_{i < j} \langle v_i, v_j \rangle x_i x_j + \varepsilon_k$$
• 一叔父化

Utility-based agent:
$$u_{k,j}(t) = w_{k,0}(t) + h(p_k(t), q_j(t)) + \varepsilon_k(t)$$

$$h\left(p_{k},q_{j}\right)=F_{GBDT}\left(p_{k},\ q_{j}\right)\qquad h\left(p_{k},q_{j}\right)=F_{DNN}\left(p_{k},\ q_{j}\right)$$

- 安装python (<u>Anaconda</u>)
 - 熟悉python的基本数据结构, tuple, list和dict.
 - 熟悉基本numpy操作
- 阅读sklearn中有关LR和SVM的文档,并尝试使用
- 找到非零x满足1.0+x==1.0?
- 尝试实现GD(SGD)求解LR
- 尝试实现算法求解LASSO的线性回归问题
- 比较GD和Newton法的收敛速度