

servo\_mix\_quadcopter  
\_diag\_conf\_t

+ motor\_front\_right  
+ motor\_front\_left  
+ motor\_rear\_right  
+ motor\_rear\_left  
+ motor\_front\_right\_dir  
+ motor\_front\_left\_dir  
+ motor\_rear\_right\_dir  
+ motor\_rear\_left\_dir  
+ min\_thrust  
+ max\_thrust