

An Overview of Nonvolatile Emerging Memories— Spintronics for Working Memories

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Abstract—This paper reviews emerging nonvolatile random access memories (RAM) in recent years. It first benchmarks ferroelectric RAM (FeRAM), phase change RAM (PCRAM), resistive RAM (ReRAM), and spin-torque-transfer magnetic RAM (STT-MRAM), discussing each RAM's features and its applications. Then current status of spintronics developments including not only STT-MRAM but also nonvolatile logic LSI is described, which are particularly suitable for working memory applications.

Index Terms—CMOS, ferroelectric RAM (FeRAM), memory, nonvolatile, phase change RAM (PCRAM), resistive RAM (ReRAM), spin-transfer-torque magnetic RAM (STT-MRAM).

I. INTRODUCTION

IN INFORMATION and communication technology (ICT) equipment indispensable for modern society, semiconductor memory large scale integrated circuits (LSIs) occupy a main position in areas of silicon storage, working memories, and logic blocks. Semiconductor memories in ICT equipment normally constitute a pyramid-like structure as shown in Fig. 1 [1]–[3]. It consists of, from top to bottom, a processing core, cache memory by static random access memory (SRAM), main memory by dynamic random access memory (DRAM), and storage memory by solid-state disk (SSD), or hard disk drive (HDD). Located closer to the processing core, the faster the operating speed is required, whereas more distant from the core, larger density is required. In the processing core, even higher speed is required but with smaller capacity like flip-flops or registers. In recent years, in a large number of equipment,

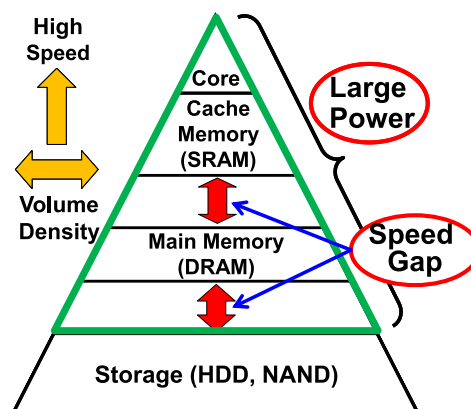


Fig. 1. Example of memory hierarchy in an ICT system. Speed gaps and large power are big issues for improving the system performance [1]–[3].

only semiconductor LSIs using NAND-flash storage instead of HDD are employed.

In the memory hierarchy in Fig. 1, cache memory and main memory are the working memories that are closer to the core. SRAM and DRAM have conventionally been adopted to the working memory. There are two key issues in such current semiconductor memory LSIs: 1) speed gap between different levels of the memory hierarchy and 2) rapid increase in the power consumption due to the increased density.

Issue 1 stems from the fact that DRAM is becoming a bottleneck of speed performance improvement. This is because DRAM must inevitably have several clocks of latency owing to its operating principle [4], [5], while the core processor and cache SRAM are able to operate with the frequency of 3 GHz or more, using the state-of-the-art process technology [6]–[9]. Also, there are essential speed gap between main memory and storage due again to the operating principle of NAND flash; it takes $\mu\text{s} \sim \text{ms}$ for write/erase [10], [11].

Regarding issue 2, the major factor is that the stand-by power to retain the information can no longer be ignored compared to the operating power to perform information processing, because of the characteristic of miniaturized transistors [12]. As for DRAM, in particular, the number of memory cells which must be refreshed simultaneously has reached the maximum limit from the viewpoint of the refresh current. This fact not only causes large power dissipation but has also become the obstruction of miniaturization.

In order for ICT technology to keep contributing to the world society under the situation, where the more energy-saving

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TABLE I
BENCHMARK OF EMERGING NONVOLATILE MEMORIES

Performance index	FeRAM	PCRAM	ReRAM	STT-MRAM	NAND flash	SRAM
Cell size (SLC*)	15 ~ 35F ²	4 ~ 19F ²	6 ~ 10F ²	6 ~ 14F ²	4F ²	160 ~ 280F ²
Operation voltage	~ 1.8 V	1.5 ~ 1.8 V	3.3 ~ 6.5 V	0.8 ~ 1.8 V	~ 20 V	0.6 ~ 1.1 V
Write current	~ 10 ⁻⁶ A**	~ 10 ⁻⁴ A	~ 10 ⁻⁴ A	~ 10 ⁻⁵ A	~ 10 ⁻⁷ A	~ 10 ⁻⁵ A
Write time	< 10 ns	~ 100 ns	~ 50 ns	< 10 ns	~ 1 ms	≤ 2 ns
Read time	< 5 ns	< 5 ns	< 5 ns	< 5 ns	~ 100 μs	≤ 2 ns
Retention	> 10 yrs	> 10 yrs	> 10 yrs	> 10 yrs	> 10 yrs	(volatile)
Endurance	10 ¹³	10 ⁹ ~ 10 ¹²	~ 10 ⁶	10 ¹⁵	~ 10 ⁵	10 ¹⁵

* SLC: Single-level cell. (In this table, only physical cell size is written. Multi-level cell and multi-layer cell is out of consideration.)

** Capacitive switching (no static current required).

is strongly required, it is essential to develop and commercialize LSIs which achieve both reduction of power dissipation and enhancement of speed performance. Currently many research institutions and manufacturers have actively been involved in research and development (R&D) for “emerging nonvolatile memory”. These R&D activities are based on the idea that emerging nonvolatile memory using new materials can be a promising candidate technology to break through the above speed gap and power consumption problems for conventional SRAM and DRAM. As examples of emerging nonvolatile memory, there are ferroelectric RAM (FeRAM), phase change RAM (PCRAM), resistive RAM (ReRAM), and spin-transfer-torque magnetic RAM (STT-MRAM).

In the following, we first benchmark emerging nonvolatile memories, and discuss what application would be most suitable for each type of emerging memory. Second, we particularly focus on STT-MRAM, which we consider the most optimal device for working memory in computer systems. Recent development results about STT-MRAM are summarized based on our recent effort in this direction.

II. BENCHMARK FOR EMERGING NONVOLATILE RAMS

Development of emerging nonvolatile memories with silicon CMOS technology started from early or mid 1980s. They use special materials having a bi-stable state in their electronic characteristics without power supply. The examples are FeRAMs [13]–[17], PCRAMs [18]–[23], ReRAMs [24]–[32], and STT-MRAMs [33]–[40]. The performance benchmark for each emerging memory is summarized in Table I. For reference purpose, NAND flash [76]–[79] and SRAM [80]–[83] are added to Table I. These will help us compare current status of each emerging memory and the existing working/storage memory.

Emerging nonvolatile memories generally have the structure like Fig. 2, in which the case of magnetic-tunnel-junction (MTJ)-based STT-MRAM is shown as an example. In Fig. 2, nonvolatile devices (MTJs) are fabricated directly on the CMOS circuit. Because of the close connection between the logic circuit and the memory compared to the conventional logic circuit with SRAM, the MTJ-based nonvolatile logic

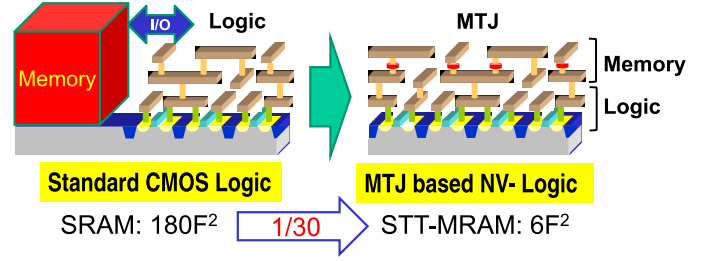


Fig. 2. Advantage of emerging nonvolatile memory, compared to a conventional standard CMOS logic with SRAM.

achieves not only drastic area and I/O power reduction but also improvement of data transfer speed.

The idea of FeRAM cell was first reported in 1987 [13], subsequently in the next year a 256-bit FeRAM was reported [14]. This early emerging nonvolatile memory used ferroelectric capacitors as a nonvolatile device combined with a CMOS circuit. However, FeRAM has a difficulty in scaling of its memory cell size: because it is not straightforward to process the ferroelectric materials, e.g., lead-zirconate-titanate (PZT), and the electrode materials, which are usually noble metals, e.g., platinum (Pt), iridium (Ir), without having reaction between the two. As a result of this, at the present moment, the most suitable applications for FeRAM are somewhat limited, to smart IC cards and small scale microcontrollers with a small storage capacity.

PCRAM is a nonvolatile memory using the chalcogenide material, which is widely used in storage media such as CD-ROM and DVD. The advantage of this device is its small storage element size. Due to this feature, PCRAM is suitable for the application area of program storage, where NOR flash memory has been traditionally used. And if further integration is achieved, storage class memory will also be covered as its application target. However, it has a significant difficulty in operation stability or reliability by temperature cross-talk between adjacent memory cells as the technology scales down, because it uses phase transition phenomenon by applying Joule heat as the non-volatile operation principle. If the endurance of 10¹⁵ order were achieved, it could replace DRAM. However, it remains to be seen how it overcomes the technology issue of chalcogenide material property.

ReRAM is relatively a new face among the emerging non-volatile memories. It was first reported around early 2000s. Since the recent researches have revealed that the redox reaction (oxidation-reduction reaction) of metals plays a major role in ReRAM, it is nowadays often referred to as the abbreviation of “Redox RAM”, instead of conventional “Resistive RAM”. There are several types of storage principle for ReRAM, which can be categorized into two types. One is conductive bridge RAM (CBRAM), and the other is oxide RAM (OxRAM). Both CBRAM and OxRAM use redox reaction in their operational principle [32], [75]. The principal advantage of the ReRAM is its simple device structure. In particular, if the device formation into the via hole and/or the multi-layer [29], [30] is achieved, it may be able to cover the storage application area where NAND flash currently occupies. It is also important to develop multi-level memory cell [28] utilizing the high on/off ratio of a redox material.

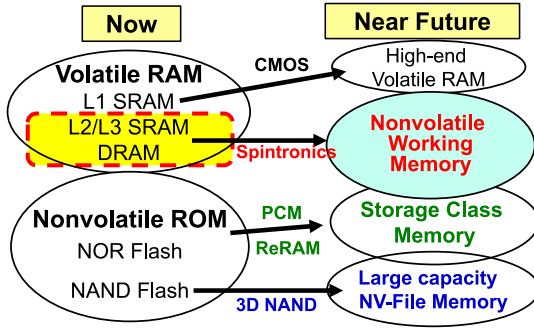


Fig. 3. Segmentation of each kind of emerging nonvolatile memories (conventional SRAM, Spintronics, PCRAM, ReRAM, and 3D NAND). Spintronics includes not only STT-MRAM but also nonvolatile logic using spintronics device.

MRAM initially adopted the data write scheme that used current-induced magnetic fields [67], [68]. However, the scheme had a serious problem in that write current increases inversely-proportional to the device feature size [40] and hence it has an early limit in scaling. By employing spin-transfer-torque operation principle [69], [70], which utilizes spin-torque transfer of spin-polarized current that induces magnetization switching, MRAM (STT-MRAM) overcame the scaling difficulty of the first generation MRAM. Remaining challenges to further scaling of STT-MRAM will be reducing switching current, stable data retention, obtaining low resistance and wider operational margin (increasing *MR ratio*). Since there are tradeoffs among these issues, clever arbitration will also be required. STT-MRAM will then become the most promising candidate of nonvolatile working memory owing to the MTJ's native virtues of low-voltage, high-speed, and practically infinite endurance.

Fig. 3 illustrates the segmentation of the above emerging nonvolatile memories for individual applications in the near future. Conventional SRAM may remain in the level-1 cache which is very close to MPU. STT-MRAM will be able to occupy the position of the level-2 cache and lower hierarchy level high-density working memory. In storage class memory, PCRAM and/or ReRAM, especially high-density memory with multi-layer or multi-level techniques is promising. For the application areas that require extremely large capacity, 3D-NAND will still be most appropriate.

III. SPINTRONICS: MATERIAL AND DEVICE TECHNOLOGY

This chapter through the next chapter reviews our recent development results for spintronics technology in detail. This chapter describes mainly material and device technology including the basics of MTJ device, and the next chapter concerns circuit and system technology.

A. Basics of MTJ Device

Fig. 4 illustrates schematic views of MTJ structure (a) and electronic characteristics (b) [41]. Here we take up perpendicular anisotropy MTJ (p-MTJ) as a typical example of MTJ devices. As shown in Fig. 4(a), MTJ has a structure with a thin

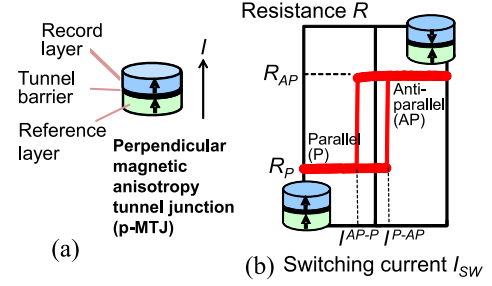


Fig. 4. Schematic views of MTJ device. (a) Structure of p-MTJ. (b) Resistance versus switching current characteristics.

tunnel barrier film composed of several atomic layers, sandwiched by two ferromagnetic layers. The upper ferromagnetic layer in Fig. 4(a) is the recording layer, in which the magnetization direction can be flipped upward or downward. On the other hand, the lower layer is the reference layer, in which the magnetization direction is fixed [upward in Fig. 4(a)]. The resistance across the MTJ device has a different value according to whether the magnetization direction for the recording layer is parallel to that for the reference layer or not. We define R_P as the resistance for the parallel (P) state, and R_{AP} for the anti-parallel (AP) state. R_{AP} is normally larger than R_P . This phenomenon is so-called tunnel-magneto-resistance (TMR) effect [42].

The MTJ resistance can be changed by flipping the magnetization direction of the recording layer. Spin-transfer-torque switching by spin-polarized current is usually chosen for the way to invert the magnetization direction. The spin-transfer-torque is a phenomenon that spin-torque, generated by exchanging the angular momentum between spin-polarized conduction electrons and the magnetization of the recording layer, makes the magnetization flipped. Using the spin-transfer-torque, the MTJ resistance state can be changed by applying the switching current (I_{SW}) to the MTJ, as shown in Fig. 4(b). There is the threshold current where the MTJ resistance is changed (shown as I^{AP-P} , I^{P-AP} in the figure).

The magnitude of the TMR effect can be usually measured by the *MR ratio*, which is defined as $(R_{AP} - R_P)/R_P$. The larger the *MR ratio* is, the larger the difference between R_P and R_{AP} . Hence for an MTJ with a large *MR ratio*, it is easy for the sensing circuit to distinguish which resistance state the MTJ is in. This is an advantage of the STT-MRAM operation. The *MR ratio* is often used as an index indicating the operational margin of STT-MRAM. In the past, typical *MR ratio* was less than several percent, but after the magnesium oxide (MgO)-CoFe(B) system was discovered, large *MR ratio* of more than 100% was able to be obtained [43]–[47].

There is another important index, thermal-stability factor Δ , which indicates the stability of data retention. Δ is defined as $E/k_B T$, where E is the energy barrier between P-state and AP-state, k_B is Boltzmann constant, and T is the junction temperature in Kelvin. The larger the Δ , the MTJ is more tolerant against the thermal disturbance, i.e., the MTJ's data retention is more stable. For example, reference [48] reported that the Δ of more than 67 was required for guaranteeing the nonvolatility of 32 Mbit STT-MRAM.

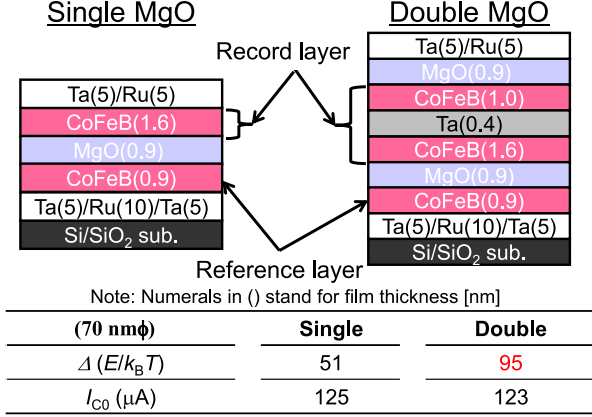


Fig. 5. Improvement of thermal stability factor Δ by applying double MgO structure. Δ was improved without increasing the switching current I_{C0} [51].

B. Recent Development of MTJ

After the first demonstration of the interfacial perpendicular anisotropy between the ferromagnetic electrodes (CoFeB) and the tunnel barrier (MgO) of MTJ [49], we have continued to pursue more miniaturization, higher performance, and higher reliability for p-MTJ.

Further improvement of thermal-stability factor Δ is strongly required for achieving Mbit class high density memory LSI. To tackle this issue, we focused on the fact that Δ is proportional to the thickness of the CoFeB recording layer [50]. Based on this fact, it was found that forming the double MgO structure, in which the CoFeB/Ta/CoFeB recording layer is sandwiched by two tunnel barrier MgO films, can increase the recording layer thickness by almost a factor of two [51]. The experimental result is summarized in Fig. 5, together with the result for the conventional single MgO structure as a reference. The MTJ size was 70 nm ϕ . As expected, Δ for the double MgO structure was 1.9 times larger than that for a single MgO. Moreover it was achieved without increasing the switching current I_{C0} .

The fringing magnetic field from the reference layer causes the asymmetry of Δ for P-state and AP-state, resulting in degradation of total thermal stability of MTJ. To solve this problem, we developed a synthetic ferrimagnetic (SyF) reference layer [52]–[54]. Fig. 6 summarizes the experimental result, together with the result of the reference sample. By applying an SyF structure to the Co/Pt multilayer based reference layer, the shift of the resistance-magnetic field curve was suppressed, thus the higher thermal stability of antiparallel magnetization configuration was obtained compared to that without a SyF structure. Moreover, the *MR ratio* of 120% at 8 $\Omega\mu\text{m}^2$ in the 10-nm-diameter p-MTJ with this stack structure using 300 mm Si wafer sputtering system showed almost no degradation after annealing at 400 °C [55], [56], indicating its high-temperature tolerance. The developed MTJ has a good affinity, with a capability to withstand the thermal budget of typical back-end-of-line (BEOL) process.

IV. SPINTRONICS: APPLICATION TO LSIs

In this chapter, recent development results of spintronics LSIs are reviewed. First we discuss STT-MRAM including the fast

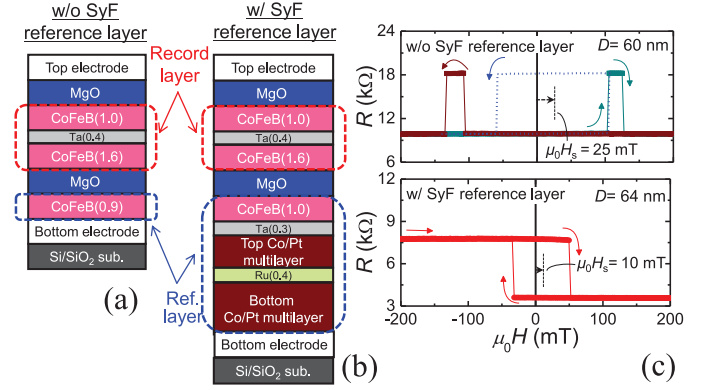


Fig. 6. Development of synthetic ferrimagnetic (SyF) reference structure which consists of a top [Co/Pt]/Ta/CoFeB multilayer and a bottom Co/Pt multilayer antiparallel-coupled by a Ru layer. The shift (H_s) of resistance versus magnetic field was reduced by applying SyF reference structure [52]–[54].

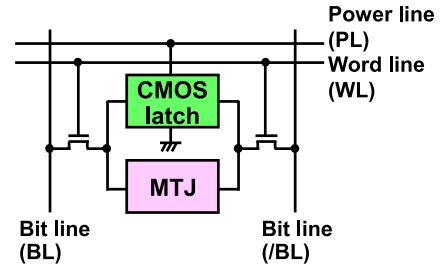


Fig. 7. Conceptual diagram of differential type STT-MRAM cell.

differential type and the high-density 1T1MTJ type, and then move on to spintronics logic LSIs.

A. High-Speed Differential Type STT-MRAM

In order to reduce the operating power of computer systems, it is effective to make working memory nonvolatile, and to cut off the power of memory area in stand-by. From the viewpoint of operation factors such as speed, write endurance, and low-voltage operability, STT-MRAM is at present the most probable candidate for nonvolatile working memory. By using a differential type memory cell, which combines a CMOS latch and MTJ devices as shown in Fig. 7, high-speed STT-MRAM comparable to SRAM was demonstrated [57].

However, the switching speed of MTJ is not fast enough to be applied to cache memory requiring several hundred MHz frequency or more. Since MTJ switching is related to write operation, write speed limits the STT-MRAM operation speed.

To solve this problem, a novel circuit technique, the background write scheme, has been developed [57]. This technique achieves high-speed write operation by “hiding” the MTJ switching time from the STT-MRAM operation. Fig. 8 shows the concept of this scheme and the diagram of 6 transistor(T)-2MTJ type STT-MRAM cell to realize this background write scheme. In this scheme, each STT-MRAM cell is configured with a normal 6T SRAM cell and a couple of MTJs. High speed write is carried out by the CMOS latch in the SRAM operation frequency, and nonvolatile write from the CMOS latch to the MTJ pair (called “backup to MTJ”) is subsequently performed apart from the SRAM frequency. For the backup to MTJ operation, 6T-2MTJ type STT-MRAM cell

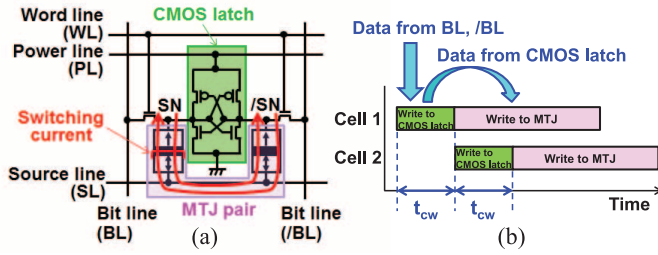


Fig. 8. 6T-2MTJ differential STT-MRAM with background write scheme [57].

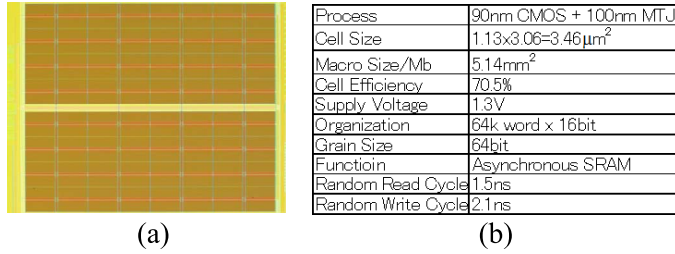


Fig. 9. 1 Mbit 6T-2MTJ STT-MRAM prototype with background write scheme. (a) Chip photo. (b) Chip features [57].

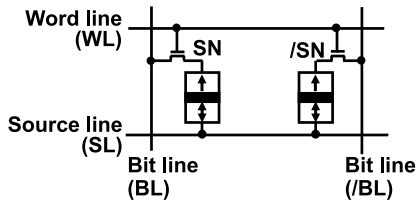


Fig. 10. 2T-2MTJ (Twin 1T-1MTJ) memory cell.

is the most suitable, because the write to MTJ can be done only by setting the source line (SL) to floating. The internal nodes of CMOS latch (SN, /SN) have a voltage difference. When the SL is set to floating, the voltage difference between SN and /SN makes current flow to the MTJ pair, by which the MTJ switching is automatically performed as shown in Fig. 8(a). This operation is apart from the CMOS latch operation, so it maintains the SRAM speed and also achieves nonvolatile write. 1 Mbit STT-MRAM prototype with this scheme was designed and fabricated using 90 nm standard CMOS and an additional 100 nm MTJ process technology. Fig. 9 summarizes the result. Read/write of 1.5 ns/2.1 ns has been realized, which is sufficient for cache memory application. Note that the write speed to MTJs are relaxed to the time sufficient to be switched (~ 7 ns [57]), by using the developed “background write scheme” previously explained in Fig. 8.

The smallest cell for the differential type STT-MRAM cell is 2T-2MTJ (or “twin 1T-1MTJ” in a sense of a combination of two 1T-1MTJ cells). The 2T-2MTJ cell is illustrated in Fig. 10 [58]. This cell has a simple structure, which consists of only selecting transistors and MTJs, removing a CMOS latch, compared to the fundamental differential type STT-MRAM cell in Fig. 7. This results in the minimum cell area among differential type memory cells. When this memory cell is applied to STT-MRAM, however, the degradation of operating speed may be concerned due to removing the CMOS latch, which provides high-speed operability equivalent to SRAM. According to an

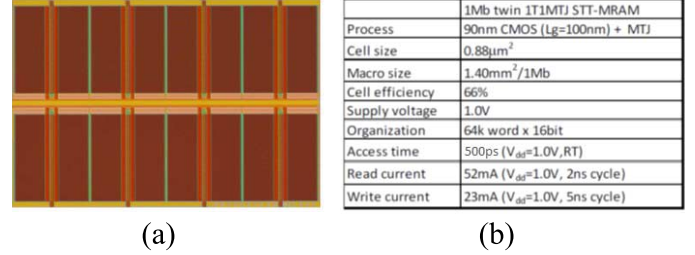


Fig. 11. 1 Mbit twin 1T-1MTJ STT-MRAM. (a) Chip photo. (b) Chip features [58].

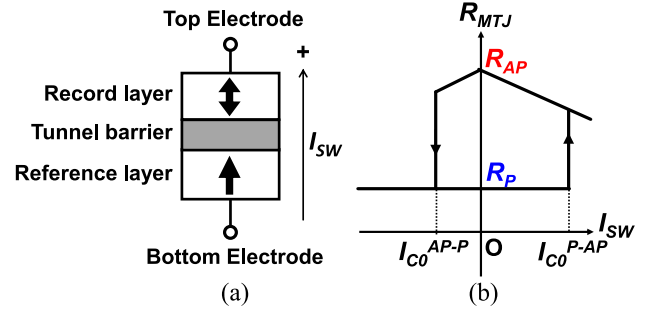


Fig. 12. Asymmetry of resistance-current characteristics of MTJ.

analysis using circuit simulation, a prospect for achieving the read latency of 500 ps by using a feedback type sense amplifier and optimizing the memory cell array configuration [58] has been shown. A fabrication result of 1 Mbit twin 1T-1MTJ STT-MRAM is shown in Fig. 11. The cell size for the twin 1T-1MTJ is $1/4$ ($0.88 \mu\text{m}^2$) compared to $3.46 \mu\text{m}^2$ of the 6T-2MTJ STT-MRAM in Fig. 10. The cell area efficiency is almost equal for both cells, thus the macro size per 1 Mbit is also $1/4$ (1.40 mm^2 for twin 1T-1MTJ, 5.14 mm^2 for 6T-2MTJ).

B. High-Density Single MTJ Type STT-MRAM

The 1T-1MTJ memory cell, which consists of 1-transistor and 1-MTJ, is the most suitable for main memory application due to its small cell size. There have been issues in circuit design and device/process technology, in order to take full advantage of the 1T-1MTJ memory cell.

Fig. 12 illustrates typical resistance—current (R-I) characteristics of an MTJ, together with a schematic MTJ structure for reference purpose. The switching current generally has an asymmetry that the value of the switching current is different depending on its switching direction [59], [60]. The forward current (I_{C0}^{P-AP}), which inverts the MTJ's magnetization direction from the R_P state to the R_{AP} state, is normally larger than the reverse current (I_{C0}^{AP-P}), which is opposite to the forward current. On the other hand, the memory cell transistor also has an asymmetry in the amount of cell current by its direction because of transistor's body effect, etc. Thus it is important to arbitrate between the two asymmetries so as to avoid causing a mismatch between the current required for MTJ switching and the current allowed to pass the memory cell. This is essential for enlarging the operational margin of scaled 1T-1MTJ memory [61].

Fig. 13 lists the possible combination of the MTJ structure and the cell transistor for a 1T-1MTJ memory cell. The structure of MTJ has two options depending on the longitudinal position

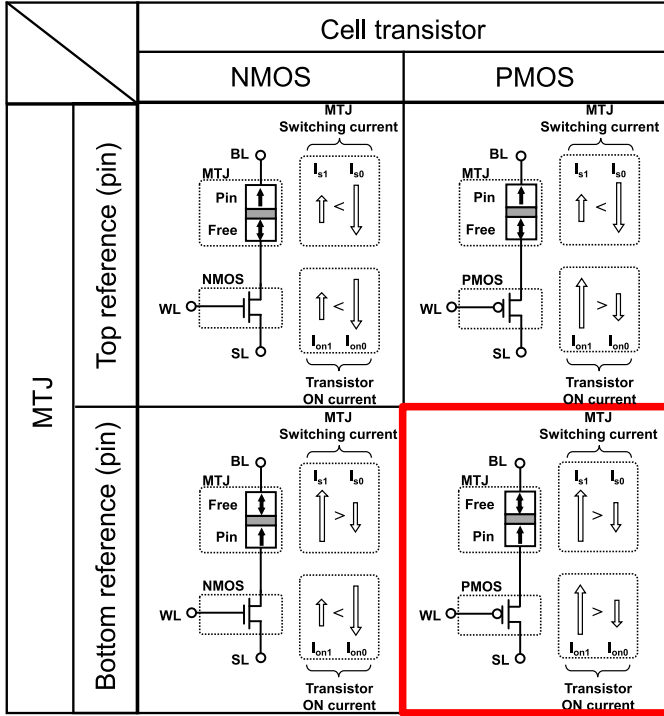


Fig. 13. Possible structure matrix for 1T-1MTJ memory cell. MTJ. The combination of a PMOS FET and a top-pin MTJ has been analyzed in [61].

of the reference layer, one is top reference layer and the other is bottom reference layer. The memory cell transistor can be an NMOS FET or a PMOS FET. In this figure, both directions for the current required from MTJ switching and for the current allowed to pass the cell transistor are respectively shown at the right side of each component. The length of each arrow represents their relative magnitudes.

From the viewpoint of current matching, it will be sufficient to consider only two cases, the NMOS – top reference and the PMOS—bottom reference. Several literatures have reported trials for top reference structure [71]–[73], but currently they still have some difficulties in attaining reliable MTJ characteristics.

We focused on PMOS—bottom reference structure. In order to evaluate the PMOS—bottom reference structure, a 1 kbit 1T-1MTJ STT-MRAM test chip was designed and fabricated using 90 nm standard CMOS and 100 nm MTJ process technology. Not only the PMOS cell but also the NMOS cell were prepared. The test chip microphotograph and experimental result are shown in Fig. 14 [61]. As shown in Fig. 14(b), the pass bit percentage for the PMOS cell exceeds that for the NMOS cell. This is because the NMOS cell cannot supply the current enough to switch from P-state to AP-state due to the current matching effect. Particularly, as shown in Fig. 13 (NMOS—bottom reference), the switching current passing through the memory cell is limited by the NMOS transistor for P to AP switching (I_{on1}), while the PMOS cell can provide sufficient switching current. Thus, it was demonstrated that the PMOS—bottom reference structure was effective.

Another issue for realizing high-density 1T-1MTJ STT-MRAM is to establish a process technology achieving a

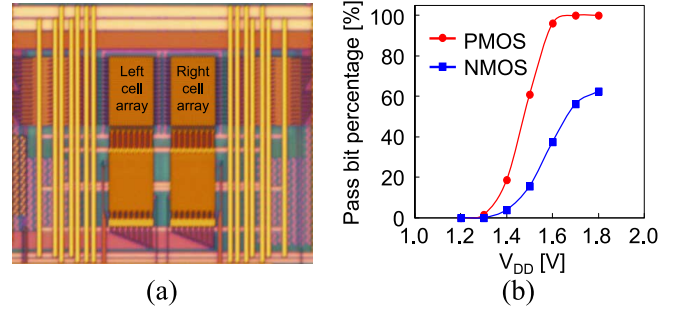


Fig. 14. 1 kbit 1T-1MTJ STT-MRAM test chip for evaluating PMOS—bottom reference structure. (a) Chip photo. (b) Experimental result [61].

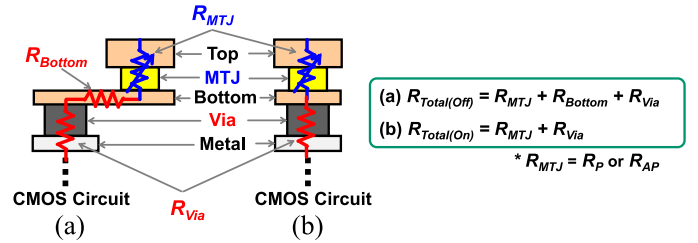


Fig. 15. MTJ film formation: (a) off via, (b) on via. Parasitic resistances and their impact to the MR ratio are described.

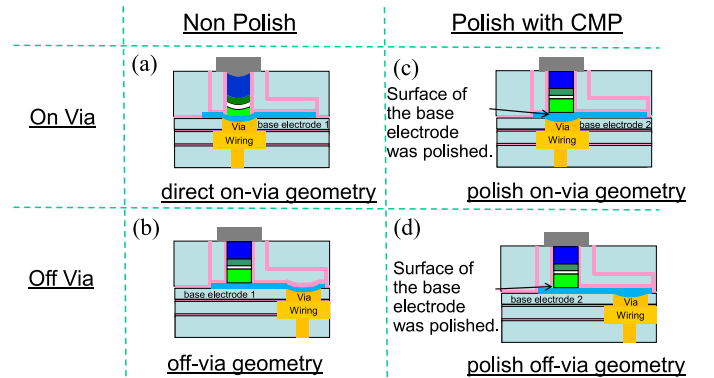


Fig. 16. Experimental conditions to establish MTJ formation process on a via hole [62].

small memory cell size. The formation of MTJ directly on the via hole is especially important because it can drastically shrink the memory cell size. In order to obtain satisfactory magnetic characteristics, roughness must be under a certain level before the deposition of MTJ films. Thus MTJs were formed not directly on the via hole (on-via), which connects the MTJ's electrode to the CMOS circuit, but on the position which is slightly apart from the via hole (off-via), as shown in Fig. 15. Obviously the on-via MTJ is preferable from the viewpoint of small cell area. But the on-via MTJ formation without characteristics degradation is usually difficult, because the surface of a via hole has a curved shape, so-called “dishing”.

To realize on-via MTJ formation with satisfactory characteristics, the chemical-mechanical polishing (CMP) technique specifically aiming at this film stack was developed [62]. Fig. 16 lists the experimental condition matrix to verify the effects of with/without CMP and on/off-via. The measured electrical characteristic (MR ratio) distributions are shown in Fig. 17. In the

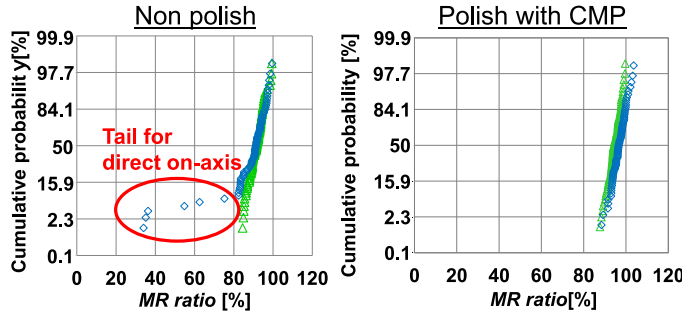


Fig. 17. Experimental result for on-via MTJ formation [62].

Low Power Tech.	Power State	VDD		Clock		MPU State	Cache	Idle Power	Entry/Exit Delay	Mode
		Core	Peri.	Core	Peri.					
N/A	C0	Full Supply	Full Supply	On	On	Keep	Full W/R	Large	No	Normal Operation
Clock Gating	C1	Full Supply	Full Supply	Off	On	Keep	Keep Data	Medium (But No Leak Reduction)	Negligibly Small	Halt
	C2	Full Supply	Full Supply	Off	Off	Keep	Keep Data	Medium (But No Leak Reduction)	Small	Clock Off
Power Gating	C3	Full Supply	Reduced	Off	Off	Lose	Flash Data	Small	Large	Sleep
	C4	Reduced	Reduced	Off	Off	Lose	Flash Data	Very Small	Very Large	Deep Sleep
	>C5	Further Reduced	Further Reduced	Off	Off	Lose	Flash Data	Negligible	Extremely Large	Deeper Sleep

Fig. 18. Example of an MPU's power state list.

case of on-via without CMP, many devices showed degraded *MR ratio*, enclosed by the red circle. On the other hand, with the developed CMP, no device revealed deteriorated *MR ratio*, even obtaining improved *MR ratio* because the parasitic resistance of the on-via with CMP was smaller than that of the off-via with CMP. This can be understood referring the difference of parasitic capacitance between off-via and on-via shown in Fig. 15. The total resistance of off-via device ($R_{Total(Off)}$) in Fig. 15) is larger by the parasitic resistance of thin-film bottom electrode (R_{Bottom}) than that of on-via device ($R_{Total(On)}$). R_{Bottom} is constant regardless of R_{MTJ} value, and it reduces the total *MR ratio* of the MTJ device. For example, if $R_P/R_{AP} = 3k/6k \Omega$ (intrinsic *MR ratio* = 100%) and $R_{Bottom} = 50 \Omega$, the total *MR ratio* = 98%, about 2% less than intrinsic one. (R_{Via} is neglected here for simplicity.)

Hence the developed CMP technique was effective for the miniaturization of 1T-1MTJ STT-MRAM cell.

C. Spintronics Circuit for Logic LSIs

For realizing low power logic LSIs for future applications, we are focusing on mainly two technologies, 1) power-gating, and 2) logic-in-memory (LiM).

In current logic LSIs, e.g., microprocessors (MPUs) or microcontrollers (MCUs), various power reduction technologies, such as reduced voltage operation, clock gating, and power gating, have been applied. Such logic LSI operation is categorized into some modes that are represented by parameters for several stages, called the processor power states, which are ranked according to their power consumption [74]. Fig. 18 is an example of an MPU's power state list [63]. In general, there exists a tradeoff between the power reduction and the operation performance. In Fig. 18, while the effect of the power reduction is enhanced further as the value of "n" (in Cn)

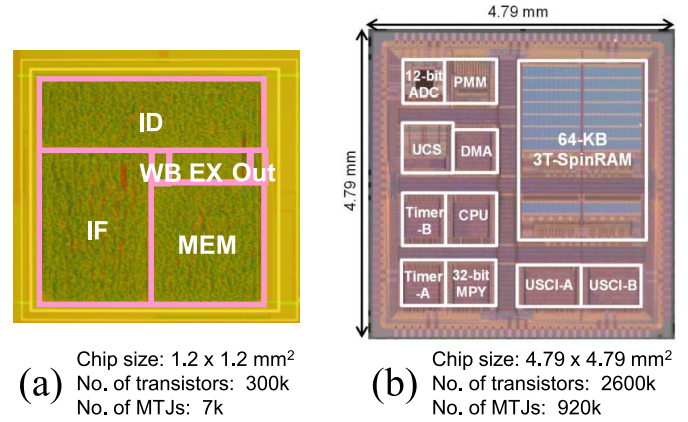


Fig. 19. Developed spintronic logic LSIs applying nonvolatile power-gating technology. (a) 32 bit MPU [63]. (b) 16 bit MCU [65].

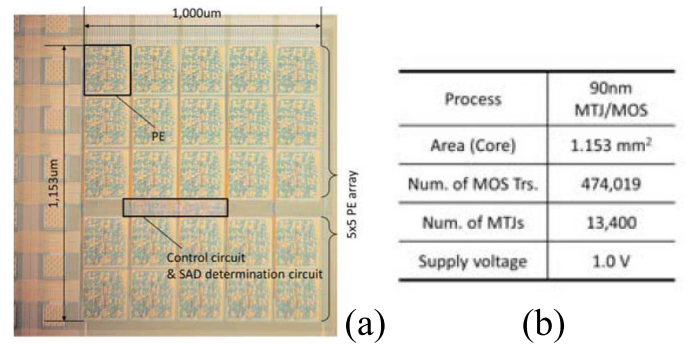


Fig. 20. Spintronic LiM chip [66]. (a) chip photo. (b) Chip features.

increases, the penalty for using the mode, i.e., the delay time to enter-into/exit-from the mode (entry/exit delay), increases.

The great advantage of using spintronic nonvolatile flip-flop (NV-FF) [64] or STT-MRAM is to reduce the entry/exit delay drastically, due to fast store/recall operation to/from nonvolatile memories by spintronics. This feature will enable more frequent entry of power-gating mode, resulting in the reduction of total system power.

Logic LSI prototypes based on the above idea have been reported [63], [65], and the chip microphotographs are shown in Fig. 19. Fig. 19(a) is a 32 bit prototype MPU, whose registers and memories are all replaced to NV-FF or STT-MRAM [63]. It achieves 3 μs entry/exit delay, which is one order of magnitude faster than the conventional volatile-memory based deep power down mode. Fig. 19(b) is a 16 bit prototype MCU, which employs a typical set of peripheral circuits, including several kinds of I/O, timers, an A/D converter, etc. [65]. Its entry delay is especially fast, 120 ns, because the MCU's circuit module divided into an optimal size can be controlled for individual power-gating. Moreover, by adding the "dirty bit" memories to nonvolatile registers, which indicates whether memory contents have been changed or not, the frequency of write operation to nonvolatile devices can be restricted to a minimum necessary. This leads to reduce write power to NV-FFs.

Logic-in-memory (LiM) is the computer architecture, which enables the amount of global data transmission to minimize by localizing the data transmission between the memory and the logical operating unit. In this architecture, energy dissipation in

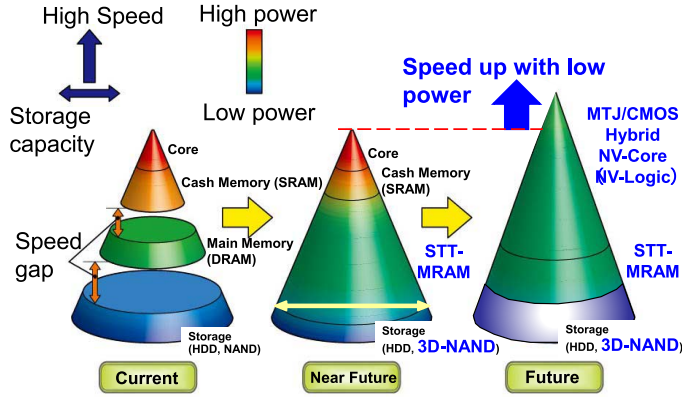


Fig. 21. Future vision of the memory hierarchy in computing system with spintronics technology.

data access can be minimized because the memory function and the logical operation function are compactly unified. This feature fits just to MTJ device, which has the excellent features such as low voltage operability (Table I), good endurance (Table I), and a CMOS compatible structure (Fig. 2) compared to the other kind of emerging memory devices. Also, since an MTJ functions as not only a memory device but also a variable resistor, it can be utilized for a part of logical operating unit by devising circuitry.

A LiM processor prototype based on the above idea is shown in Fig. 20 [66]. This processor is designed for image-processing like motion-vector prediction, realizing 75% leakage reduction compared to a conventional processor, by implementing the newly developed MTJ-based LiM circuit for logic components (full adder, etc.).

D. Future Vision of Spintronics Technology

Our vision for the memory hierarchy in computing system with spintronics technology is illustrated in Fig. 21. This illustration is drawn using a common pyramid manner like Fig. 1, and the additional color-coding which distinguishes the amount of each level's power dissipation.

Low power operation is being achieved in the near future by applying STT-MRAM to working memory. Subsequently further low power and high speed operation will be pursued by developing novel MTJ/CMOS hybrid nonvolatile core circuits.

V. CONCLUSION

Emerging memories, including Ferroelectric RAM, Phase change RAM, Resistive RAM, Spin-transfer-torque RAM, were reviewed and benchmarked, and their suitable applications were discussed. In particular, the recent developments for the application of spintronics technology to integrated circuits, which we currently focus on, were described in detail. Future energy-saving and high-performance electronics society will be opened by continuing integrating research and development for material/device through circuit/systems of emerging devices.

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