Tommaso Proietti, Ph.D.
Postdoctoral Research Fellow

👤 18/03/1988, Rome, Italy | 📍 150 Western Av., 02134 Boston, MA | 📱 (+1) 857-243-5510
✉ tproietti@g.harvard.edu | 💻 tommasoproietti-robotics.github.io

Education

Ph.D. in Robotics Engineering
Jan 2014 - Mar 2017

Université Pierre et Marie Curie
Paris, France

- Thesis: *Characterizing the reciprocal adaptation in physical Human-Robot Interaction to address the inter-joint coordination in neurorehabilitation*
- Supervisors: A. Roby-Brami, N. Jarrassé

MS in Control Engineering
Nov 2010 - Oct 2013

Sapienza University of Rome
Rome, Italy

- Final score: 110/110 magna cum laude
- Thesis: *Hybrid Dynamic Nonprehensile Manipulation: Application to a 3-DOF Robot*
- Supervisors: G. Oriolo (Sapienza University of Rome), K. Lynch (Northwestern University)

BS in Automated Systems Engineering
Sep 2007 - Oct 2010

Sapienza University of Rome
Rome, Italy

- Final score: 107/110
- Thesis: *Modeling and Controlling Composability Property in Embedded Systems by applying Hybrid Automata Theory*
- Supervisors: F. Delli Priscoli, A. Fiaschetti

Experience

Postdoctoral Research Fellow
Jun 2019 - present

Harvard University
Cambridge, MA, USA

📍 *Harvard John A. Paulson School of Engineering and Applied Science*

- Main research topic: development and evaluation of soft wearable robots for upper-limb assistance.
- Affiliated with the Wyss Institute for Biologically Inspired Engineering.
- PI: Prof. Conor J. Walsh - Lab: Harvard Biodesign Lab

Control System Engineer
Apr 2017 - Apr 2019

General Motors
Turin, Italy

📍 *GM Global Propulsion Systems*

- Control function development and algorithm design for GM diesel vehicles.
- Certification: GM Design For Six-Sigma - Green Belt

Ph.D. in Robotics Engineering
Jan 2014 - Mar 2017

Université Pierre et Marie Curie
Paris, France

📍 *ISIR - Institut des Systèm Intelligents et de Robotique*

- Main research topic: development and evaluation of control strategies for wearable robots to induce relearning of motor coordination after stroke.
- PI: Prof. Agnes Roby-Brami

Visiting Pre-Doctoral Fellow   **Oct 2012 - Oct 2013**

Northwestern University   *Evanston, IL, USA*

📍 *McCormick School of Engineering*

- ○ Main research topic: trajectory planning and control of a nonprehensile manipulator through hybrid dynamic modeling.
- ○ PI: Prof. Kevin M. Lynch - Lab: Neuroscience and Robotics Lab

Publications

▣ Google Scholar page   👤 Orcid: 0000-0002-8875-8646.

Journal Papers

6. Zhou Y.M., Hohimer C., **Proietti T.**, O'Neill C., Walsh C. (2021) Kinematics-based control of an inflatable soft wearable robot for assisting the shoulder of industrial workers, *IEEE Robotics and Automation Letters*, vol. 6:2, pp. 2155-2162.
5. **Proietti T.***, O'Neill C.*, Hohimer C., Nuckols K., Clarke M., Zhou Y.M., Lin D., Walsh C. (2021) Sensing and control of a multi-joint soft wearable robot for upper-limb assistance and rehabilitation, *IEEE Robotics and Automation Letters*, vol. 6:2, pp. 2381-2388. *Authors equal contribution.
4. O'Neill C.*, **Proietti T.***, Nuckols K., Clarke M., Hohimer C., Cloutier A., Lin D., Walsh C. (2020) Inflatable soft wearable robot for reducing therapist fatigue during upper extremity rehabilitation in severe stroke, *IEEE Robotics and Automation Letters*, vol. 5:3, pp. 3899 - 3906. *Authors equal contribution.
3. **Proietti T.**, Guigon E., Roby-Brami A., and Jarrassé N. (2017) Modifying upper-limb inter-joint coordination in healthy subjects by training with a robotic exoskeleton, *Journal of NeuroEngineering and Rehabilitation*, vol. 14. pp. 55.
2. **Proietti T.**, Crocher V., Roby-Brami A., and Jarrassé N. (2016) Upper-limb robotic exoskeletons for neurorehabilitation: a review on control strategies, *IEEE Reviews in Biomedical Engineering*, vol. 9, pp. 4-14.
1. Jarrassé N., **Proietti T.**, Crocher V., Robertson J., Sahbani A., Morel G. and Roby-Brami A. (2014) Robotic exoskeletons: a perspective for the rehabilitation of arm coordination in stroke patients, *Frontiers in Human Neuroscience*, vol. 8:947, pp. 1-10.

Conference Papers

4. **Proietti T.**, Parry R., Lejeune F., Roby-Brami A., and Jarrassé N. (2018) Adaptation of upper limb movement using exoskeleton-based training and transfer of cinematic patterns to unconstrained movement: A preliminary study, *Annals of Physical and Rehabilitation Medicine*, vol. 61, pp 488, 12th World Congress of the International Society of Physical and Rehabilitation Medicine (Paris, France).
3. **Proietti T.**, Roby-Brami A., and Jarrassé N. (2017) Comparison of different error signals driving the adaptation in assist-as-needed controllers for neurorehabilitation with an upper-limb robotic exoskeleton, *IEEE International Conference on Robotics and Automation* (ICRA17, Singapore), pp. 6645-6650.
2. **Proietti T.**, Roby-Brami A., Jarrassé N. (2016) Learning motor coordination under resistive viscous force fields at the joint level with an upper-limb robotic exoskeleton, *3rd International Conference on NeuroRehabilitation* (ICNR16, Segovia, Spain), in Converging Clinical and Engineering Research on Neurorehabilitation II, pp. 1175-1179, Springer International Publishing.
1. **Proietti T.**, Jarrassé N., Roby-Brami A., and Morel G. (2015) Adaptive control of a robotic exoskeleton for neurorehabilitation, *7th International IEEE/EMBS Conference on Neural Engineering* (NER15, Montpellier, France), pp. 803-806.

Teaching & Mentoring

Guest Lecturer *Harvard University*   **2020**

Course: Physiological Foundations for Bioengineering (BS in Biomedical Engineering)

Undergraduate Students Mentoring *Harvard University*   **2019 - 2020**

Course: Robotics Projects (BS in Mechanical Engineering)
Responsibilities: Helped in developing research projects, supervised and assisted graduate students during their summer/winter projects in the lab.
Number of mentored students: 3.

Teaching Assistant *Polytech Sorbonne*   **2015**

Course: Mobile Robotics (MS in Robotics Engineering)
Responsibilities: Prepared, supervised, and assisted 15-ish graduate students in weekly 6-hour lab course. Assistance to final project evaluation. The course was provided in French.

Grants & Prizes

Cullen Eduction and Research Fund (CERF) Medical Prize - Co-Writer   **2021**

Goal: to promote research into aspects of muscle atrophy and loss of functionality associated with motor neuron disease / amyotrophic lateral sclerosis (MND/ALS).
Value: EUR 1.000.000
Status: Finalist - Under Review

Honors & Awards

IEEE Engineering in Medicine and Biology Prize Paper Award - 3rd place with [J2] paper - USD 300.   **2019**

Personal Skills

⬤ Languages

 Italian: Mother Tongue | **English**: Fluent - C2 | **French**: Proficient - B2/C1

</> Computer skills

 Programming: Matlab/Simulink, C, C++, Python, Java, HTML, CSS, PHP, MySQL
 Software: Solidworks/Fusion360, Qt, Qualisys Track Manager, Visual3D, Unity3D, ROS, INCA, Git, LaTeX
 OSs: Linux, Windows

✹ Certifications

 2021 - Science Education Undergraduate Mentoring Workshop *from* Harvard University
 2019 - Green Belt of Design For Six-Sigma *from* General Motors
 2014 - "European Computational Motor Control" Summer School *from* Université de Montpellier 1