

# Visión por Computador

## Repaso de álgebra

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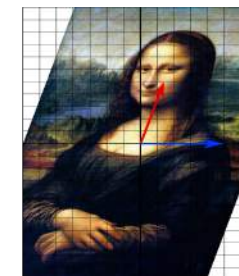
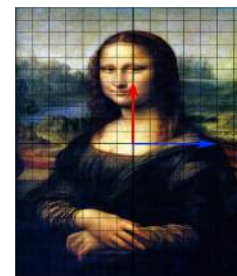
## Eigenvalues and eigenvectors



The **eigenvector**,  $v$ , of a square matrix,  $A$ , is a vector that does not change its direction under  $A$ ,

$$Av = v\lambda$$

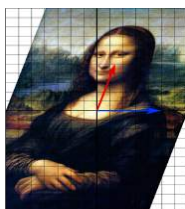
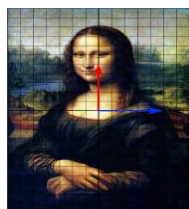
where  $\lambda \in \mathbb{R}$  is the **eigenvalue** associated to  $v$ .



## Eigenvalues and eigenvectors



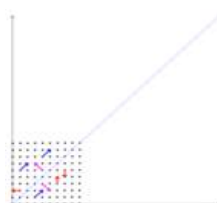
The **eigenvector**,  $v$ , points in a direction stretched by  $A$ , the eigenvalue,  $\lambda$ , is the factor by which it is stretched.



For matrix  $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$ ,

$v_1 = (1, 1)^T$ ;  $v_2 = (1, -1)^T$

$\lambda_1 = 3$ ;  $\lambda_2 = 1$



## Eigenvalues and eigenvectors



Let  $\lambda_1, \dots, \lambda_n$  and  $v_1, \dots, v_n$  be the eigenvalues and eigenvectors of  $A$ .

We can build matrices

$$Q = [v_1 | \dots | v_n] \quad \Lambda = \begin{bmatrix} \lambda_1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \lambda_n \end{bmatrix}$$

such that  $AQ = Q\Lambda$  hence,

$Q^{-1}AQ = \Lambda$ , so  $A$  is diagonalizable.

Also,  $A = Q\Lambda Q^{-1}$  is the **eigendecomposition** of  $A$ .

Let  $a$  and  $x$  be a vector of coefficients and variables respectively.

$$\frac{\partial(a^\top x)}{\partial x} = \frac{\partial(x^\top a)}{\partial x} = x$$

$$\frac{\partial(x^\top x)}{\partial x} = 2x$$

Let  $A$  be a symmetric coefficient matrix and  $x$  a vector of variables

$$\frac{\partial(x^\top Ax)}{\partial x} = 2Ax$$

Let  $A_{m \times n}$  and  $b_{m \times 1}$  be respectively a matrix and vector of coefficients and  $x_{n \times 1}$  a vector of variables, where  $m > n$ .

The least-squares solution to the system of equations

$$\begin{bmatrix} A \end{bmatrix} x = \begin{bmatrix} b \end{bmatrix}$$

is the minimum of  $J(x) = (Ax - b)^\top (Ax - b)$ , and

using the matrix derivation rules  $x = (A^\top A)^{-1} A^\top b$

## Least-squares solution of linear equation

Let  $A_{m \times n}$  and  $b_{m \times 1}$  be respectively a matrix and vector of coefficients and  $0_{n \times 1}$  a vector of zeros, where  $m > n$ .

The least-squares solution of the system of equations

$$\begin{bmatrix} A \end{bmatrix} x = \begin{bmatrix} 0 \end{bmatrix}$$

is the minimum of  $J(x) = \frac{x^\top (A^\top A)x}{x^\top x}$ , and using the matrix derivation rules:

The eigenvector associated with the smallest eigenvalue of  $A^\top A$

## Maximum likelihood estimation

Let  $\mathcal{D} = \{x_1, x_2, \dots, x_n\}$  be a set of i.i.d. samples, their **likelihood**

$$p(\mathcal{D}|\theta) = \prod_{k=1}^n p(x_i|\theta)$$

their *loglikelihood*

$$l(\theta) = \log p(\mathcal{D}|\theta) = \sum_{k=1}^n \log p(x_i|\theta)$$

so  $\hat{\theta} = \arg \max_{\theta} \{l(\theta)\}$

Hence, a set of equations to estimate  $\theta$  are

$$\nabla_{\theta} l(\theta) = 0$$

