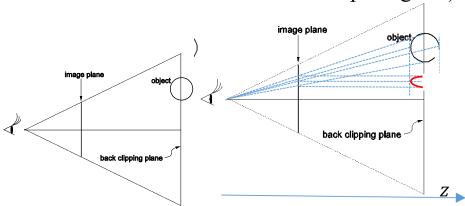
1. In the lecture, we have learned the line clipping algorithm, in which the clipping region is a rectangular in 2D space. Please show the **main** idea for extending this algorithm in 3D space, i.e., clipping a line against a 3D cubic. [15 points]

There are 6 borders (i.e., the 6 faces of the 3D cube), top, bottom, left, right, front, back, 27 sub-regions, and thus the **6-bit** code-words should be defined. Define the trivial accept and trivial reject criteria

2. Show the output of the following object after perspective **transformation** and clipping. (Indicate how you obtain the output figure.) [8 points]



Perspective transformation is computed as:

$$x' = d * x / z$$

$$y' = d * y / z$$

$$z' = z$$

The key point of this question is that the z dimension will retain after the perspective **transformation**, which is different from perspective **projection** 

3. A 3D object is rotated by 90 degrees about an axis passing from (1, 0, 1) to (1, 2, 1). It is then uniformly scaled 4 times relative to the origin. Write in their proper order the individual matrices composing this transformation. [12 points]

$$\begin{bmatrix} 4 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

4. Describe what transformation the matrix **M** performs when applied to 3D points. [10 points]

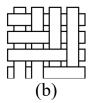
$$\mathbf{M} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

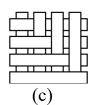
$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

First rotate 90 degree around the x-axis and then perform the non-uniform scaling around the x, y and z-axes with factors 1, 2, and 3, respectively.

5. Which of the following scenes in Figure 3 would cause problems for the painter's algorithm? Please justify your answer and suggest a method to







address the issue. (These drawing are in image space; each rectangle is a single primitive) [6 points]

- (b) there is cyclic overlapping. We can use z-buffering algorithm.
- 6. Do parallel lines remain parallel in the axonometric projection? Justify your answer. [6 points]

yes

axonometric projection is parallel projection.

7. Please explain the **main** differences between Gouraud shading and Phone shading and show their advantages and disadvantages. [12 points]

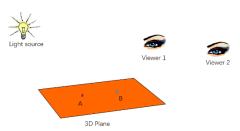
Gouraud shading: interpolate colors; difficult to handle specular reflection.

Phong shading: interpolate normal; render more realistic images but higher computational complexity

8. List all stages involved in the rendering pipeline.

[8 points]

- (1) world coordinate transformation
- (2) perspective transformation
- (3) back-face removal
- (4) clipping
- (5) rasterization
- (6) hidden surface removal
- (7) shading
- 9. As shown in the right figure,
- (a) Assume the 3D plane has the uniform diffuse reflection property. If the light source is a directional light source, what is relationship between the diffuse reflections at points A and B? Please justify your answer [4 points]



Let  $I_d^A$  and  $I_d^B$  be the diffuse reflections at points A and B, respectively. Let  $\theta_A$  and  $\theta_B$  are the incident angles of the light rays at points A and B, i.e., the angle between the light ray and the surface normal vector, respectively.

As it is a directional light source, the incoming light rays are parallel, i.e.,  $\theta_A = \theta_B$ . Based on the formula of computing diffusion reflection, we can know  $I_d^A = I_d^B$ 

(b) Assume the 3D plane has the uniform diffuse reflection property. If the light source is a point light source, what is relationship between the diffuse reflections at points A and B? Please justify your answer [4 points]

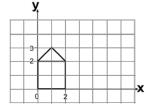
As it is a point light source, the incoming light rays are divergent, i.e., the incident angles of the light rays at points A and B are different. If your answer is  $I_d^A > I_d^B$ , your justification should be  $\theta_A < \theta_B$ ; if your answer is  $I_d^A < I_d^B$ , your justification should be  $\theta_A > \theta_B$ .

(c) Assume the 3D plane is a glossy surface. If the light source is a point light source, what is the relationship between the specular reflections at point B observed by viewers 1 and 2? Please justify your answer. [7 points]

Let  $I_s^1$  and  $I_s^2$  be the specular reflections at viewpoints 1 and 2, respectively. Let  $\theta_1$  be the angle between the ideal reflected ray and viewing direction towards Viewer 1, and  $\theta_2$  the angle between the ideal reflected ray and viewing direction towards Viewer 1. If your answer is  $I_s^1 > I_s^2$ , your justification is  $\theta_1 < \theta_2$ . If your answer is  $I_s^1 < I_s^2$ , your justification is  $\theta_1 > \theta_2$ .

10. The following figure shows a 2D house model and a 2D affine transformation matrix **M**. Sketch the transformed house and label the coordinates of all vertices.

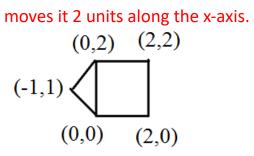
[8 points]



$$\mathbf{M} = \begin{bmatrix} 0 & -1 & 2 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Observe that 
$$\mathbf{M} = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

So this transformation first rotates the house 90 degree around the origin and then



--End--