

# ETHAN LEITNER

[github.com/litehed](https://github.com/litehed) — [gitlab.com/litehed](https://gitlab.com/litehed)  
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## EDUCATION

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### Kennesaw State University

*June 2022 - Present*

B.S. in Computer Science

Member of Electric Vehicle Team

Member of Upsilon Pi Epsilon Honor Society

## EXPERIENCE

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### KSU Electric Vehicle Team (EVT)

*August 2022 - May 2023*

*Member*

#### Skills: C++, Python, ROS 2, GitLab, Docker

- Led the switch to real-time object detection using Darknet YOLOv4 and depth estimation utilizing a binocular camera
- Trained a TensorFlow U-Net model to segment the track from the rest of the camera image
- Created ROS nodes relating to object detection utilizing our depth camera within other parts of our kart
- Created multiple guides to set up our simulator environment and depth camera with computer vision
- Worked on lidar z-crop to get borders of track

### Skaivision

*September 2023 - March 2024*

*AI Intern*

#### Skills: Python, TensorFlow, PyTorch, OpenCV, GitHub, Jira

- Meticulously annotated videos of vehicles to train networks with
- Learned more about building basic neural networks deepening understanding of fundamentals
- Created an OpenCV-based arm-sign detection algorithm
- Learned more about segmentation neural networks such as SAM

## PROJECTS

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### PastEven

*Current*

*Co-Creator*

#### Skills: Python, OpenCV, PySide

- Working with a friend on a paint application aimed at improving Python skills and exploring creative ideas
- Implemented features like an OpenCV-based tool for drawing borders around illustrations and a history slider for easier undoing and redoing functionality
- Learned a lot about software UX design and making an application friendly to the user

## TECHNICAL STRENGTHS

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### Computer Languages

Java, Python, C/C++, Javascript, GoLang

### Frameworks

ROS2, .NET, Qt, JavaFX

### Tools

VSCode, IntelliJ, Git, Docker