



15 April 2019

RE: The 9th Annual IEEE International Conference on CYBER Technology in Automation, Control, and Intelligent Systems (IEEE-CYBER 2019)

Dear Author(s),

Congratulations! Your paper has been accepted for Oral/Poster presentation at the 9th Annual IEEE International Conference on CYBER Technology in Automation, Control, and Intelligent Systems (IEEE-CYBER 2019). On behalf of the IEEE-CYBER 2019 Program Committee, it is my great pleasure to invite you to participate in IEEE-CYBER 2019.

- Title: A Quasi-Elliptic Foot Trajectory Planning Approach Based on the Stochastic Linear Complementarity Problem for Electrical Quadruped Robots
- Author(s): Tianfa Li, Lelai Zhou, Wenlong Xuan, Xuewen Rong, Hui Chai and Yibin Li

This year's IEEE-CYBER will be held from 29 July – 2 August 2019 at Jinke Grand Hotel, Suzhou, China (Address: No.67 Tiancheng South Road, Xiangcheng District, Suzhou, China). The CYBER 2019 is organized by an international committee of experts in the field of CYBER Technology in Automation, Control, and Intelligent Systems and it is sponsored by IEEE Robotics and Automation Society (RAS). The conference will last for five days, featuring technical workshops, and three days for technical presentations including plenary speeches, technical and non-technical tours, and attractive social events.

We are very much looking forward for a very fruitful IEEE-CYBER 2019 with your presence in July 2019! Should you have any questions, please do not hesitate to contact with us. Also if you need more information about the conference, please visit the conference website for program and details of the conference: http://www.ieee-cyber.org/2019/

We sincerely look forward to seeing you in Suzhou, China!

Best Regards,

Xın-Jun Lıu

General Chair of IEEE-CYBER 2019

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