

3.3 COMPLETE SOLUTION TO $A\vec{x} = \vec{b}$

• Solution to $A\vec{x} = \vec{b}$ takes the form $\vec{x} = \vec{x}_p + \vec{x}_n$ where \vec{x}_p = one particular solution to $A\vec{x} = \vec{b}$, \vec{x}_n = any solution to $A\vec{x} = \vec{0}$

• This expression is obtained by

augmented matrix $[A \ \vec{b}] \longrightarrow [R \ \vec{d}]$ ^{REF of A}

↑
comes from null space

• Two extreme cases: What if $\text{rank } A = n$ or m ? \rightarrow extreme case
 _{$m \times n$}

COMPLETE SOLUTION TO $A\vec{x} = \vec{b}$

EXAMPLE: Find all solutions to $A\vec{x} = \vec{b}$ where

$$A = \begin{bmatrix} 1 & 2 & 1 & 0 \\ 2 & 4 & 4 & 8 \\ 4 & 8 & 6 & 8 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 4 \\ 2 \\ 10 \end{bmatrix}$$

#1) row reduce the augmented matrix

• Remember REF, all 0's above pivots

$$\begin{aligned} [A \ \vec{b}] &= \begin{bmatrix} 1 & 2 & 1 & 0 & 4 \\ 2 & 4 & 4 & 8 & 2 \\ 4 & 8 & 6 & 8 & 10 \end{bmatrix} \xrightarrow[\substack{R_3 - 4R_1 \\ R_2 - 2R_1}]{R_2 - 2R_1} \begin{bmatrix} 1 & 2 & 1 & 0 & 4 \\ 0 & 0 & 2 & 8 & -6 \\ 0 & 0 & 2 & 8 & -6 \end{bmatrix} \xrightarrow{R_3 - R_2} \begin{bmatrix} 1 & 2 & 1 & 0 & 4 \\ 0 & 0 & 2 & 8 & -6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \\ &\xrightarrow{R_3 \cdot R_2} \begin{bmatrix} 1 & 2 & 1 & 0 & 4 \\ 0 & 0 & 2 & 8 & -6 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\frac{1}{2} R_2} \begin{bmatrix} 1 & 2 & 1 & 0 & 4 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 - R_2} \begin{bmatrix} 1 & 2 & 0 & -4 & 7 \\ 0 & 0 & 1 & 4 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = [R \ \vec{d}] \end{aligned}$$

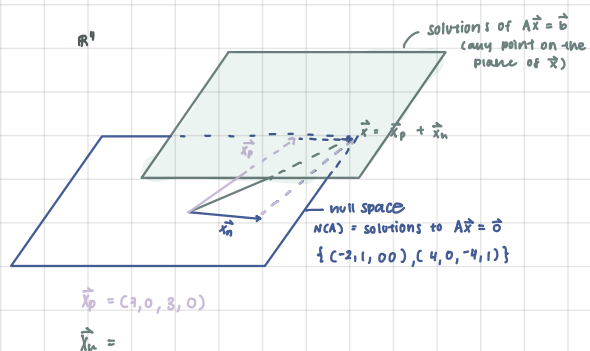
#2) Set pivots = free vars

$$\Rightarrow \begin{cases} x_1 + 2x_2 = -4x_4 = 7 \\ x_3 + 4x_4 = -3 \end{cases} \Rightarrow \begin{cases} x_1 = 7 - 2x_2 \\ x_3 = -3 - 4x_4 \end{cases}$$

$$\vec{x} = \begin{bmatrix} 7 - 2x_2 + 4x_4 \\ x_2 \\ -3 - 4x_4 \\ x_4 \end{bmatrix} = \begin{bmatrix} 7 \\ 0 \\ -3 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 4 \\ 0 \\ -4 \\ 1 \end{bmatrix}$$

\vec{x}_p \vec{x}_n

where $A\vec{x}_p = \vec{b}$ and $\vec{x}_n \in N(A)$ i.e. $A\vec{x}_n = \vec{0}$



EXTREAM CASES

#1 Full Column Rank Case

EXAMPLE:

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 5 \\ 1 & 4 \end{bmatrix}$$

a) Does $A\vec{x} = \vec{b}$ have solutions for any $\vec{b} \in \mathbb{R}^3$? If NOT, find a condition on \vec{b} so that $A\vec{x} = \vec{b}$ has a solution.

recall $A\vec{x} = \vec{b}$ has a solution means $\vec{b} \in C(A)$

$$C(A) = \text{span}\{(1, 2, 1), (2, 5, 4)\} = \text{plane} \neq \mathbb{R}^3$$

↳ so $A\vec{x} = \vec{b}$ does not have a solution for some $\vec{b} \in \mathbb{R}^3$

$$[A \mid \vec{b}] = \begin{bmatrix} 1 & 2 & b_1 \\ 2 & 5 & b_2 \\ 1 & 4 & b_3 \end{bmatrix} \xrightarrow[R_3 - R_1]{R_2 - 2R_1} \begin{bmatrix} 1 & 2 & b_1 \\ 0 & 1 & b_2 - 2b_1 \\ 0 & 2 & b_3 - b_1 \end{bmatrix} \xrightarrow{R_3 - 2R_2} \begin{bmatrix} 1 & 2 & b_1 \\ 0 & 1 & b_2 - 2b_1 \\ 0 & 0 & 3b_1 - 2b_2 + b_3 \end{bmatrix} \xrightarrow{R_1 - 2R_2} \begin{bmatrix} 1 & 0 & 5b_1 - 2b_2 \\ 0 & 1 & b_2 - 2b_1 \\ 0 & 0 & 3b_1 - 2b_2 + b_3 \end{bmatrix}$$

$$A\vec{x} = \vec{b} \text{ has a solution when } 3b_1 - 2b_2 + b_3 = 0$$

b are constants in general

b) find all solutions to $A\vec{x} = \vec{b}$ under the condition found in (a). \vec{x}_p ? \vec{x}_h ?

$$\text{Assuming } 3b_1 - 2b_2 + b_3 = 0$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5b_1 - 2b_2 \\ b_2 - 2b_1 \end{bmatrix} = \underbrace{\begin{bmatrix} 5b_1 - 2b_2 \\ b_2 - 2b_1 \end{bmatrix}}_{\vec{x}_p} + \underbrace{\begin{bmatrix} 0 \\ 0 \end{bmatrix}}_{\vec{x}_h}$$

there's only one solution

c) rank of A ? # of free variables?

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 5 \\ 1 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} x_1 & x_2 \\ 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \Rightarrow \text{rank } A = 2$$

↳ 0 free variable → so $N(A) = \{\vec{0}\}$

EXPLAINS THIS

FULL COL. RANK GENERAL CASE

In general:

rank $A = n$ (# of columns) means # of pivots = # of columns in A (EVERY COLUMN HAS A PIVOT)

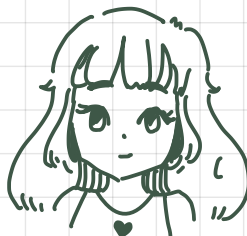
then...

rank A implies:

i) there are no free variables, $\vec{x}_h = \vec{0}$, $N(A) = \{\vec{0}\}$

ii) $A\vec{x} = \vec{b}$, if solvable, has only 1 solution

since $\vec{x}_p + \vec{x}_h = \vec{x}$, but $\vec{x}_h = \vec{0}$, there's no wiggle room for our solution



#2 FULL ROW RANK CASE

$$\text{Rank } A = m \text{ (\# of rows)}$$

EXAMPLE:

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 7 \end{bmatrix}$$

a) Does $A\vec{x} = \vec{b}$ have solutions for any $\vec{b} \in \mathbb{R}^2$? If NOT, find a condition on \vec{b} so that $A\vec{x} = \vec{b}$ has a solution.

$\text{CCA} = \text{span}\{(1,2), (2,4)\}$ this span is in \mathbb{R}^2
scalar

↳ THIS MEANS $A\vec{x} = \vec{b}$ HAS SOLUTION $\forall \vec{b} \in \mathbb{R}^2$, IN FACT:

$$\left[A \quad \vec{b} \right] = \left[\begin{array}{ccc|c} 1 & 2 & 3 & b_1 \\ 2 & 4 & 7 & b_2 \end{array} \right] \xrightarrow{R_2 - 2R_1} \left[\begin{array}{ccc|c} 1 & 2 & 3 & b_1 \\ 0 & 0 & 1 & b_2 - 2b_1 \end{array} \right] \rightarrow \text{NO INCONSISTENCIES}$$

$$\xrightarrow[\text{REF}]{R_1 - 3R_2} \left[\begin{array}{ccc|c} 1 & 2 & 0 & 7b_1 - 3b_2 \\ 0 & 0 & 1 & b_2 - 2b_1 \end{array} \right]$$

b) find all solutions to $A\vec{x} = \vec{b}$ under the condition found in (a). \vec{x}_p ? \vec{x}_h ?

$$\left. \begin{array}{l} x_1 = 7b_1 - 3b_2 - 2x_2 \\ x_3 = b_2 - 2b_1 \end{array} \right\} \text{tells us our } \vec{x} \text{ would be: } \begin{bmatrix} 7b_1 - 3b_2 - 2x_2 \\ x_2 \\ b_2 - 2b_1 \end{bmatrix} \rightarrow x_2 \text{ is a free variable}$$

$$= \underbrace{\begin{bmatrix} 7b_1 - 3b_2 \\ 0 \\ b_2 - 2b_1 \end{bmatrix}}_{\vec{x}_p} + x_2 \underbrace{\begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}}_{\vec{x}_h}$$

c) rank of A? # of free variables?

$$A = \begin{bmatrix} x_1 & x_2 & x_3 \\ 1 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \text{rank } A = 2, 1 \text{ free variable}$$

becomes \vec{x}_h ,
so there are
infinite solutions

FULL ROW RANK GENERAL CASE

IN GENERAL:

Rank $A = m$ means # of pivots = # of rows in A = every row has a pivot

$$A \rightarrow R = \left[\begin{array}{ccc|c} & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \\ & & & & 1 \end{array} \right] \rightarrow \text{rank } A = m \text{ implies}$$

(i) $A\vec{x} = \vec{b}$ has solutions for any $\vec{b} \in \mathbb{R}^m$

(ii) $\text{CCA} = \mathbb{R}^m$