Unit - II

For the given signal flow graph related y and x using matrix 3. representation.

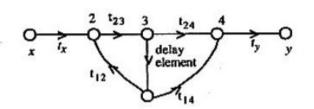


Figure given below represents the system. Find the difference equation and transfer function of the system.

x(n)-3/8

OR

Consider the LSIV system defined by the difference equation.

$$y(n) = (\frac{3}{4})y(n-1) - (\frac{1}{8})y(n-2) + x(n) + (\frac{1}{3})x(n-1)$$

Draw a canonic realization for this system using continued fraction expansions method described above.

Explain Tellegen's theorem and Intereciprocity.

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Total No. of Questions: 10]

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Roll No

EI/IC-603

B.E. VI Semester

Examination, June 2017

Digital signal Processing

Time: Three Hours

Maximum Marks: 70

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Note: i) Attempt all questions.

ii) Each question carries equal marks.

Unit - I

- How do we derive DFT from DFS. Explain in detail.
 - How does DFT differs from DTFT. Explain and justify the answer.

OR

Convolve following sequences using DFT.

$$x(n) = \left\{ \frac{1}{1}, 2, 3, 4 \right\}$$
$$h(n) = \left\{ 1, 1, \frac{2}{1}, 1 \right\}$$

$$h(n) = \left\{1, 1, 2, 1\right\}$$

State and prove the following:

- Frequency shifting property
- Time sealing
- iii) Symmetry

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Unit - III

- 5. a) Make comparison of IIR and FIR digital filters.
 - Explain matched Z-transform method of IIR filter design.

OR

- 6. a) Explain the following terms:
 - i) Window function
 - ii) Gibbs phenomenon
 - iii) Stable and casual filter
 - b) Explain the following:
 - i) Aliasing error
 - ii) Prewarping
 - iii) Impulse invariance

Unit-IV

- a) Explain periodicity and symmetry property of phase rotation factor.
 - b) If $x(n) = 2^n$ for n = 0, 1, 2, 3 find DFT X(K) of x(n) using DIT algorithm.

OR

Consider two 4-point sequences x(n) and h(n) defined as follow:

$$x(n) = \cos(n \frac{\pi}{2}), n = 0, 1, 2, 3 \text{ and}$$

$$h(n) = 2^n$$
, $n = 0, 1, 2, 3$.

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- a) Calculate the 4-point DFT of x(n) that is x(k)
- b) Calculate the 4-point DFT of h(n), that is H(k)

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- c) Calculate y(n) = IDFT of [X(k) H(k)]
- Verify the sequence values y(n) by performing circular convolution.

Unit - V

-) Explain basic principle of power speeding estimation. 7
- Find out the response of linear system to random signals.

OR

Write short notes on any two of the following: 14

-) Correlation
-) Covariance

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- :) Cross covariance
- l) Average spectrum
- :) Chirp Z Transform

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