

Roll No

ME - 503**B.E. V Semester**

Examination, June 2016

Mechanical Measurement and Control*Time : Three Hours**Maximum Marks : 70*

Note: i) Answer five questions. In each question part A, B, C is compulsory and D part has internal choice.

- ii) All parts of each questions are to be attempted at one place.
- iii) All questions carry equal marks, out of which part A and B (Max.50 words) carry 2 marks, part C (Max.100 words) carry 3 marks, part D (Max.400 words) carry 7 marks.
- iv) Except numericals, Derivation, Design and Drawing etc.

1. a) Compare static and dynamic calibration.
- b) Write about zero order, first order and second order systems.
- c) Define the term: Phase linearity.
- d) Explain the following measurement terms:
Range, accuracy, bias error, sequential and random tests

OR

Draw and Discuss general model for a dynamic measurement system.

2. a) Define error propagation.
- b) Write about the concept of standard deviation in measurement.
- c) Define the term: Data outlier detection.
- d) Discuss the least square regression analysis with examples.

OR

Describe the different types of errors encountered in measurement with examples.

3. a) What do you mean by transducers?
- b) Write about Relative Pressure Scales.
- c) State the working of bimetallic thermometers.
- d) Write short note on following (any two)
 - i) Orifice meter
 - ii) Flow meter
 - iii) Rotameter.

OR

Discuss the construction and working of resistance temperature detector.

4. a) What do you mean by angular velocity measurements?
- b) Write about potentiometers.
- c) State the working of LVDT.
- d) Discuss Measurement of Torque on rotating shaft.

OR

Explain the working of Rotary Variable Differential Transformer.

5. a) What do you mean by Transfer function?
- b) Write about Signal flow graphs.
- c) State brief about Transient and steady state response analysis.
- d) Discuss the Modelling of fluid systems or mechanical systems.

OR

Explain the following:

- i) Liquid level systems.
- ii) Impulse response function.
