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Examination, June 2017

DSPApplication

Time: Three Hours

Maximum Marks: 70

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Note: i) Attempt any five questions.

- ii) All questions carry equal marks.
- 1. a) What is a LTI system? Explain giving some examples what is the importance of impulse response to LTI system?
 - b) Define convolution. Compute the convolution of following signals

$$x_1(n) = [4, -2, 1]$$

$$x_2(n) = \begin{cases} 1 & 0 \le n \le s \\ 0 & otherwise \end{cases}$$

- What do you understand by ROC of Z transforms? Write properties of ROC for various types of signals.
 - b) Determine Z transform of the following system.
 - i) $a^n u(n)$
 - ii) $(\cos w_0 n) u(n)$ www.rgpvonline.com
- Determine the causal signal x(n) whose Z transform is

given by
$$X(z) = \frac{1+z^{-1}}{1-z^{-1}+0.5z^{-2}}$$

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Define, explain and differentiate recursive and nonrecursive system.

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- Differentiate:
 - Linear and circular convolution
 - ii) DFT and DCT
 - Obtain DFT of the following sequence

i)
$$x(n) = (1, 0, -1, 2)$$

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ii) $x(n) = (1, -1, 0, 2, 1, -2, -1, 1)$

- Define FIR and IIR system compare them and give their basic structure.
 - Explain Bilinear transformation method for designing digital filters.
- Describe designing of FIR filter using Kaiser window.
 - Discuss the effect of finite register length in filter design.
- Describe response of linear system to random signals.
 - Explain wavelet transform and discuss various applications of wavelet transform.
- 8. Write short notes on any two of the following:
 - a) Decimation in Time FFT algorithm
 - b) Butterworth filter www.rqpvonline.com
 - Basic principals of spectrum estimation
 - Multi rate signal processing

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