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**MEDC-103****M.E./M.Tech., I Semester**

Examination, December 2013

**DSP Application***Time : Three Hours*

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**Maximum Marks : 70**

- Note:** 1. Attempt any five questions.  
2. All questions carry equal marks.

1. Examine the following systems with respect to the properties such as static or dynamic, linear or non-linear, Time invariant or time varying, causal or non-causal and stable or unstable.

a)  $y(n) = \sum_{k=-\infty}^{n+1} x(k)$       b)  $y(n) = \text{sign}[x(n)]$

c)  $y(n) = x(-n+2)$       d)  $y(n) = x(n^2)$

2. a) Determine the zero input response of the system described by the second-order difference equation

$$x(n) - 3y(n-1) - 4y(n-2) = 0$$

- b) Consider the discrete time system shown in Fig. 1

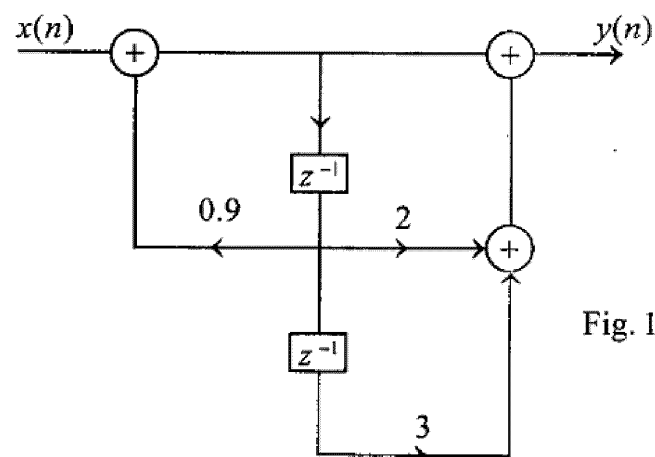


Fig. 1

- Compute the first six values of the impulse response of the system. RGPVONLINE.COM
- Determine an analytical expression for the impulse response of the system.

3. a) Determine the response of the system

$$y(n) = \frac{5}{6}y(n-1) - \frac{1}{6}y(n-2) + x(n)$$
 to the input signal

$$x(n) = \delta(n) + \frac{1}{3}\delta(n-1).$$

- b) A LTI system is characterized by the system function

$$H(z) = \frac{3-4z^{-1}}{1-3.5z^{-1}+1.5z^{-2}}.$$

Specify ROC of  $H(z)$  and determine  $h(n)$  for the following conditions

- System is stable
- System is causal
- System is anticausal

4. Determine the causal signal  $x(n]$  if its  $z$  transform is given by

a)  $X(z) = \frac{1+2z^{-2}}{1+z^{-2}}$

b)  $X(z) = \frac{1+6z^{-1}+z^{-2}}{4(1-2z^{-1}+2z^{-2})(1-0.5z^{-1})}$

c)  $X(z) = \frac{z^{-6}+z^{-7}}{1-z^{-1}}$

5. Determine the  $N = 8$  point DFT using decimation in frequency. RGPVONLINE.COM

- Explain the designing of FIR filter using Kaiser window.
- Explain bilinear transformation method for designing of IIR filter.

- Discuss the basic principle of spectrum estimation.
- Explain briefly about multirate signal sampling

8. Write Short notes on any two of the following

- Effect of finite register length in filter design
- Wavelet Transform
- Infinite invariance method

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