ME-701 Elective –I ME-701 (C) – Industrial Robotics

Unit I Introduction: Need and importance, basic concepts, structure and classification of industrial robots, terminology of robot motion, motion characteristics, resolution, accuracy, repeatability, robot applications.

Unit II End Effectors and Drive systems: Drive systems for robots, salient features and comparison, different types of end effectors, design, applications.

Unit III Sensors: Sensor evaluation and selection Piezoelectric sensors linear position and displacement sensing, revolvers, encoders, velocity measurement, proximity, tactile, compliance and range sensing. Image Processing and object recognition.

Unit IV Robot Programming: Teaching of robots, manual, walk through, teach pendant, off line programming concepts and languages, applications.

Unit V Safety and Economy of Robots: Work cycle time analysis, economics and effectiveness of robots, safety systems and devices, concepts of testing methods and acceptance rule for industrial robots.

References:

1. Mittal RK, Nagrath IJ; Robotics and Control; TMH
2. Groover M.P,Weiss M, Nagel,OdreyNG; Industrial Robotics-The Appl; TMH
3. Groover M.P; CAM and Automation; PHI Learning
4. Spong Mark and Vidyasagar; Robot Modelling and control; Wiley India
5. Yoshikava ; Foundations of Robotics- analysis and Control; PHI Learning;
6. Murphy ; Introduction to AI Robotics; PHI Learning
7. FU KS, Gonzalez RC, Lee CSG; Robotics Control, sensing; TMH
8. Shimon, K; Handbook of Industrial Robots; John Wiley & Sons,.
9. Ghosal Ashitava; Robotics Fundamental concepts and analysis; Oxford
10. Saha S; Introduction to Robotics; TMH
11. Yu Kozyhev; Industrial Robots Handbook; MIR Pub.