

Roll No

MEVD - 104**M.E./M.Tech. I Semester**

Examination, December 2014

Digital Signal Processing*Time : Three Hours***RGPVONLINE.COM****Maximum Marks : 70**

Note : 1. Attempt any five questions out of the following.
2. Each questions carries equal marks.

1. a) Find the Impulse Response for the system given by

$$y(n) + 4y(n-1) + 4y(n-2) = x(n)$$
 b) Verify whether the following Impulse responses describe Causal, stable or LTI systems. Give reasons for your answers.
 i) $h(n) = e^{-0.6n} u(n)$ ii) $h(n) = u(n-2) - u(n+3)$
2. a) Write the properties of Z-transform. Also give the necessary proofs for them.
 b) Determine the cross-correlation sequence $rx_1, x_2(l)$ of the sequences
 $x_1(n) = (1, 2, 3, 4)$
 $x_2(n) = (4, 3, 2, 1)$
 Determine the Z-transform and its ROC of the sequence given by

$$x(n) = \begin{cases} 2^n & n < 0 \\ \left(\frac{1}{2}\right)^n & n = 0, 2, 4, \dots \\ \left(\frac{1}{3}\right)^n & n = 1, 3, 5, \dots \end{cases}$$

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3. Given $x(n) = \{1, 2, 3, 4, 4, 3, 2, 1\}$ find $X(k)$ using DIT and DIF FFT algorithm.
4. The following transfer function characteristics FIR filter ($M = 11$). Determine the magnitude response and show that the phase and group delays are constant.

$$H(z) = \sum_{n=0}^{M-1} h(n) z^{-n}$$

5. A low pass filter is to be designed with the following desired frequency response

$$H_d(e^{j\omega}) = \begin{cases} e^{-j2\omega} & -\pi/4 \leq \omega \leq \pi/4 \\ 0 & \pi/4 < |\omega| \leq \pi \end{cases}$$

Determine the filter coefficients $h_d(n)$ if the window function is defined as

$$\omega(n) = \begin{cases} 1 & 0 \leq n \leq 4 \\ 0 & \text{otherwise} \end{cases} \quad \text{RGPVONLINE.COM}$$

6. a) Determine $H(z)$ using the impulse Invariant technique for the analog system function

$$H(s) = \frac{1}{(s+0.5)(s^2+0.55s+2)}$$

- b) Convert the analog filter with system function

$$H(s) = \frac{s+0.1}{(s+0.1)^2+9} \text{ into digital IIR filter using bilinear transformation the digital filter should have a resonant frequency of } \omega_r = \pi/4.$$

7. a) Explain signal design and ambiguity functions.
 b) Explain Airborne surveillance Radar for Air traffic control.
