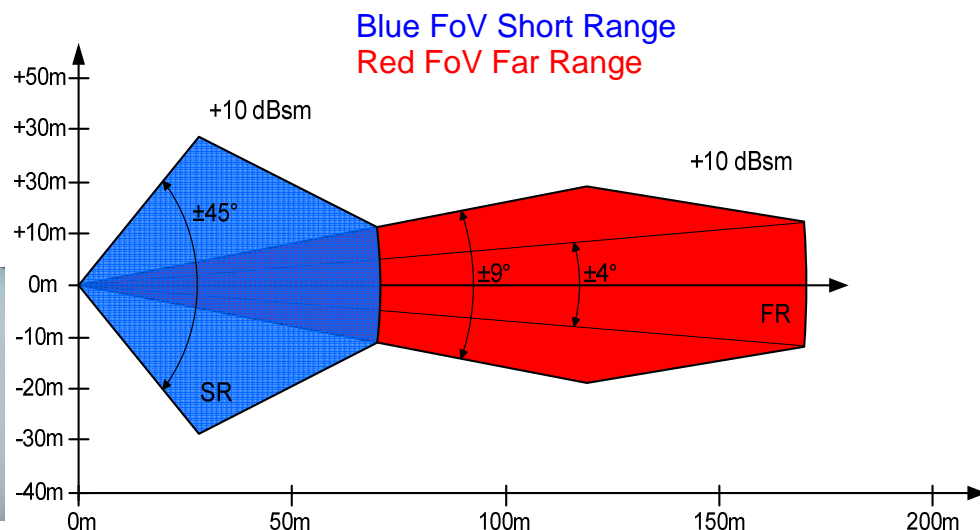


# ARS 404-21 Entry

## Long Range Radar Sensor 77 GHz



### Safe - reliable - robust – very small design

The A.D.C. GmbH offers a new type of radar sensor, the ARS 404-21, as a possible adaption in different application and as entry version of the series 40X.

#### Typical areas of application:

- **Anti-collision protection for vehicles of every description (particul. autonomous)**
- Headway control also for far range (vehicles of every description, particularly autonomous)
- Area monitoring system for far range, e.g. of hazardous or non-accessible areas
- Classification of objects
- Object detection, e.g. in confusing or unclear areas
- Unremarkable object detection by affix a protection cover before it (radome)

#### Measuring procedure:

The rugged ARS 404-21 sensor from Continental measures independent the distance and velocity (Doppler's principle) to objects without reflector in one measuring cycle due basis of FMCW (Frequency Modulated Continuous Wave) with very fast ramps, with a real time scanning of 20 / sec.. A special feature of the device is the simultaneously measurement of great distances **up to 170 m**, relative velocity and the angle relation between 2 objects.

#### Advantages:

- **Fast and safe:** The ARS 404-21 dispels with the apparent contradiction between excellent great measuring performance and a high degree of operational safety. The rugged ARS 404-21 radar sensor is capable of determining the distance to an object in real time scanning and dependent on the driving speed a possible risk of collision.
- **Reliable:** The ARS 404-21 radar sensor is fail-safe and able to recognize troubles of the sensor and sensor environment and display it automatically.
- **Robust and very small design:** By using a radar technology with less complex measuring principle and the development and mass production in automotive supply industry, the design is kept very robust and very small.

**Benefit from the unique features of the latest Continental technology!**



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## Long Range Radar Sensor 77 GHz

| Measuring performance   |  | to natural targets (non-reflector targets)   |
|---|--|--|
| Distance range  |  | 0.20...170m@0...±4° & 0.20...120m@±9° far range scan, 0.20...70m@0...±9° & 0.20...40m@±45° near range scan   |
| Resolution distance measuring   | point targets, no tracking                       | 0.40 m (0.75 m @ large v_ego for 170 m range<br>ability to separate targets and objects 1.5...2 x resolution   |
| Accuracy distance measuring   | point targets, no tracking                       | ±0.10 m (0.20 m @ large v_ego for 170 m range  |
| Azimuth angle augmentation  | (field of view FoV)                              | -9.0°...+9.0° far range, -45°...+45° near range  |
| Elevation angle augmentation  | (field of view FoV)                              | 18° at 6 dB two way for far and near range   |
| Azimuth beam width (3 dB)   | 6 dB values 1.4 x larger                         | 4.6° @0° far range, 9.2°@0°...13.0°@±45° near range  |
| Elevation beam width  | 6 dB two way                                     | 18° at 6 dB two way for far and near range   |
| Resolution azimuth angle  | point targets, no tracking                       | 3.3° far range, 6.6° @0°...9.3°@±45° near range<br>ability to separate targets and objects 1.5...2 x resolution  |
| Accuracy azimuth angle  | point targets, no tracking                       | 0.1°@±6°...0.2°@±9° far range<br>0.6°@0°...2.0°@±45° near range  |
| Velocity range  |  | -400 km/h...+200 km/h (- leaving objects...+approximation)   |
| Velocity resolution   | target separation ability                        | 0.28 km/h  |
| Velocity accuracy   | point targets                                    | ±0.1 km/h  |
| Sensitivity (min. RCS@x m)  |  | 10m <sup>2</sup> @170 m far range<br>1m <sup>2</sup> @40 m & 0°...±45° near range  |
| Cycle time  |  | app. 50 ms near and far measurement  |
| Antenna channels / -principle   | planar   | 6 channels = 2TX/2RX near + 2TX/1RX*+2RX far - *1RX double column = higher bundling / Digital Beam Forming   |
| Operating conditions  |  |  |
| Radar operating frequency band  | compliant ETSI & FCC                             | 76...77 GHz  |
| Transmission capacity   | average / peak EIRP                              | <12 dBm@77GHz / <35.5 dBm - sweep bandwidth 500 MHz  |
| Mains power supply  | at 12 V DC / 24 V DC                             | +8,0 V...32 V DC – B-Version for truck & passenger cars  |
| Power consumption   | at 12 V DC / 10 A fuse<br>at 24 V DC / 10 A fuse | 4.5 W / 375 mA typ. and 12 W / 1.0 A peak – sleep <100 µA<br>200 mA typ. – sleep <200 µA   |
| Load dump protection internal   |  | disconnection >60 V and re-start returning to <60 V  |
| Operating-/ storage temperature   |  | -40°C...+85°C / -40°C...+90°C  |
| Life time   | acc. LV124 part 2 - v1.3                         | 10000 h or 10 years (for passenger cars)   |
| Shock   | mechanical                                       | 500 m/s <sup>2</sup> @6 ms half-sine (10 x shock each in +/-X/Y/Z dir.)  |
| Vibration   | mechanical                                       | 20 [(m/s <sup>2</sup> )/Hz]@10 Hz / 0,14 [(m/s <sup>2</sup> )/Hz]@1000Hz (peak)  |
| Protection rating   | ISO 16750 Classification (Trucks)                | IP 6k 9k (dust, high-pressure cleaning)<br>IP 6k7 (10 cm under water), ice-water shock test,<br>salt fog resistant, mixed gas EN 60068-2-60                                    |
| Connections   |  |  |
| Monitoring function   |  | self monitoring (fail-safe designed)   |
| Interface   | up to 8 ID                                       | 1 x CAN - high-speed 500 kbit/s  |
| Housing   |  |  |
| Dimensions / weight   | L * W * H (mm) / (mass)                          | 136.25 * 68.4 * 33.75 / app. 172 g – B-type screw mounted  |
| Material  | housing front / rear side                        | PBT GF 30 black (BASF-Ultradur B4300G6 LS sw 15073) /<br>AC-47100 (AlSi12Cu1(Fe)) die cast aluminium or<br>EN AW 5754 (3.535) AlMg3 pressed-formed aluminium                   |
| Miscellaneous   |  |  |
| Measuring principle (Doppler's principle) in one measuring cycle due basis of FMCW with very fast ramps |  | independent measurement of distance and velocity   |
| Version ARS 404-21  | sensor for the industry                          | CAN protocol for free communication  |
|   |  | The version -21 allows to set maximum 8 ID's and maximum 8 collision avoidance regions and to change the sensitivity between low and high sensitivity by the user continuously |

### Interfaces:

The device is fitted with one CAN bus interface. Further interfaces as converter, software adaption are possible on demand and in case of assumption of costs.