Mass properties of motorR3
Configuration: Default
Coordinate system: -- default --

Mass = 0.095 kilograms

Volume = 0.000 cubic meters

Surface area = 0.061 square meters

Center of mass: (meters)
X = 0.000
Y = 0.004
Z = 0.000

Principal axes of inertia and principal moments of inertia: (kilograms * square meters)
Taken at the center of mass.

Ix = (0.000, 0.001, 1.000)	Px = 0.000
Iy = (-0.001, -1.000, 0.001)	Py = 0.000
Iz = (1.000, -0.001, 0.000)	Pz = 0.000

Moments of inertia: (kilograms * square meters)
Taken at the center of mass and aligned with the output coordinate system.

Lxx = 0.000	Lxy = 0.000	Lxz = 0.000
Lyx = 0.000	Lyy = 0.000	Lyz = 0.000
Lzx = 0.000	Lzy = 0.000	Lzz = 0.000

Moments of inertia: (kilograms * square meters)
Taken at the output coordinate system.

Ixx = 0.000	Ixy = 0.000	Ixz = 0.000
Iyx = 0.000	Iyy = 0.000	Iyz = 0.000
Izx = 0.000	Izy = 0.000	Izz = 0.000

One or more components have overridden mass properties:
Bevel gear new<2><R3 Sides>
Side Plate<1><Default>
Side Shaft<1><Default>
Side Shaft<2><Default>
Bevel gear new<3><R3 Sides>
Top Plate<1><Default>
Side Plate<3><Default>