Mass properties of motorR2 v2
Configuration: Default
Coordinate system: -- default --

Mass = 0.658 kilograms

Volume = 0.000 cubic meters

Surface area = 0.188 square meters

Center of mass: (meters)
X = 0.002
Y = 0.010
Z = 0.000

Principal axes of inertia and principal moments of inertia: (kilograms * square meters)
Taken at the center of mass.

Ix = (0.012, 1.000, 0.000)	Px = 0.001
Iy = (0.000, 0.000, 1.000)	Py = 0.001
Iz = (1.000, -0.012, 0.000)	Pz = 0.001

Moments of inertia: (kilograms * square meters)
Taken at the center of mass and aligned with the output coordinate system.

Lxx = 0.001	Lxy = 0.000	Lxz = 0.000
Lyx = 0.000	Lyy = 0.001	Lyz = 0.000
Lzx = 0.000	Lzy = 0.000	Lzz = 0.001

Moments of inertia: (kilograms * square meters)
Taken at the output coordinate system.

Ixx = 0.001	Ixy = 0.000	Ixz = 0.000
Iyx = 0.000	Iyy = 0.001	Iyz = 0.000
Izx = 0.000	Izy = 0.000	Izz = 0.001

One or more components have overridden mass properties:
3P 80T 6W GT Pulley<1><Side>
motorR2 Shell v2<1><Default>
3P 80T 6W GT Pulley<4><Side>