Mass properties of motorT3
    Configuration: Default
    Coordinate system: -- default --

* Includes the mass properties of one or more hidden components/bodies.

Mass = 0.448 kilograms

Volume = 0.000 cubic meters

Surface area = 0.165 square meters

Center of mass: (meters)
            X = 0.000
            Y = 0.089
            Z = 0.000

Principal axes of inertia and principal moments of inertia: (kilograms * square meters)
Taken at the center of mass.
            Ix = (0.000, 1.000, 0.000)   Px = 0.000
            Iy = (0.000, 0.000, 1.000)   Py = 0.001
            Iz = (1.000, 0.000, 0.000)   Pz = 0.001

Moments of inertia: (kilograms * square meters)
Taken at the center of mass and aligned with the output coordinate system.
            Lxx = 0.001   Lxy = 0.000   Lxz = 0.000
            Lyx = 0.000   Lyy = 0.000   Lyz = 0.000
            Lzx = 0.000   Lzy = 0.000   Lzz = 0.001

Moments of inertia: (kilograms * square meters)
Taken at the output coordinate system.
            Ixx = 0.005   Ixy = 0.000   Ixz = 0.000
            Iyx = 0.000   Iyy = 0.000   Iyz = 0.000
            Izx = 0.000   Izy = 0.000   Izz = 0.004

One or more components have overridden mass properties:
            BLDC<1><Tiger Motor MN 3508-20 580kV>
            EncoderAMT102<1><Default>
            MainArm<1><Encoder on Input>
            EncoderAMT102<2><Default>
            3P 80T 6W GT Pulley<1><Mid>
            BLDC<3><Tiger Motor MN 3508-20 580kV>