Mass properties of motorT2
Configuration: v2
Coordinate system: -- default --

Mass = 2.071 kilograms

Volume = 0.001 cubic meters

Surface area = 0.456 square meters

Center of mass: (meters)
X = 0.000
Y = 0.114
Z = 0.000

Principal axes of inertia and principal moments of inertia: (kilograms * square meters)
Taken at the center of mass.

Ix = (0.001, 1.000, 0.002)	Px = 0.003
Iy = (0.000, -0.002, 1.000)	Py = 0.014
Iz = (1.000, -0.001, 0.000)	Pz = 0.015

Moments of inertia: (kilograms * square meters)
Taken at the center of mass and aligned with the output coordinate system.

Lxx = 0.015	Lxy = 0.000	Lxz = 0.000
Lyx = 0.000	Lyy = 0.003	Lyz = 0.000
Lzx = 0.000	Lzy = 0.000	Lzz = 0.014

Moments of inertia: (kilograms * square meters)
Taken at the output coordinate system.

Ixx = 0.042	Ixy = 0.000	Ixz = 0.000
Iyx = 0.000	Iyy = 0.003	Iyz = 0.000
Izx = 0.000	Izy = 0.000	Izz = 0.041

One or more components have overridden mass properties:
NEMA23<1><2.83 Nm>
UpperArm v3<1><Default>
Connecting Plate<1><Top Side>
Connecting Plate<2><Bot Side>
Stepper Motor Heatsink<1><Default>
Stepper Motor Heatsink<2><Default>
LowerArm Inner<4><Default>
LowerArm Outer<5><Default>
LowerArm Connector<1><Default>
5P 90T 9W GT Pulley<2><Mid>
LowerArm Inner<5><Default>
LowerArm Outer<6><Default>
5P 90T 9W GT Pulley<3><Mid>