Mass properties of end_effector
    Configuration: Default
    Coordinate system: -- default --

Mass = 0.008 kilograms

Volume = 0.000 cubic meters

Surface area = 0.005 square meters

Center of mass: (meters)
      X = 0.000
      Y = -0.005
      Z = 0.000

Principal axes of inertia and principal moments of inertia: (kilograms * square meters)
Taken at the center of mass.
      Ix = (0.997, 0.000, -0.080)   Px = 0.000
      Iy = (-0.080, 0.000, -0.997)   Py = 0.000
      Iz = (0.000, 1.000, 0.000)   Pz = 0.000

Moments of inertia: (kilograms * square meters)
Taken at the center of mass and aligned with the output coordinate system.
      Lxx = 0.000   Lxy = 0.000   Lxz = 0.000
      Lyx = 0.000   Lyy = 0.000   Lyz = 0.000
      Lzx = 0.000   Lzy = 0.000   Lzz = 0.000

Moments of inertia: (kilograms * square meters)
Taken at the output coordinate system.
      Ixx = 0.000   Ixy = 0.000   Ixz = 0.000
      Iyx = 0.000   Iyy = 0.000   Iyz = 0.000
      Izx = 0.000   Izy = 0.000   Izz = 0.000

One or more components have overridden mass properties:
      Top Shaft<1><Default>
      Bevel gear new<1><R3 Sides>