# The Long Short-Term Memory (LSTM) architecture

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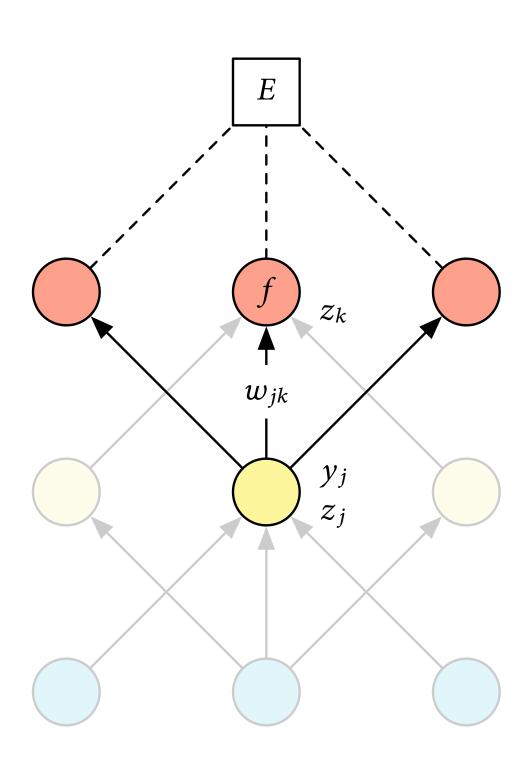
Department of Computer and Information Science



#### Challenges with recurrent neural networks

- In principle, recurrent neural networks are capable of learning long-distance dependencies in input sequences.
- In practice, training recurrent neural networks is challenging due to the large depth of the unrolled networks.

## Vanishing and exploding gradients



$$\delta_k = \frac{\partial E}{\partial z_k} = \frac{\partial E}{\partial y_k} \frac{\partial y_k}{\partial z_k} = \frac{\partial E}{\partial y_k} f'(z_k)$$

$$\delta_{j} = \frac{\partial E}{\partial z_{j}} = \frac{\partial y_{j}}{\partial z_{j}} \sum_{k} \frac{\partial E}{\partial z_{k}} \frac{\partial z_{k}}{\partial y_{j}} = f'(z_{j}) \sum_{k} \delta_{k} w_{jk}$$

#### Vanishing and exploding gradients

- In backpropagation there is a risk of gradients either vanishing or exploding, depending on the magnitude of the weights.
- This problem is exacerbated in recurrent networks, whose unrolled computation graphs can be very deep.
- Research on recurrent networks has proposed various methods to mitigate this problem.

weight scaling and clipping, specialised architectures

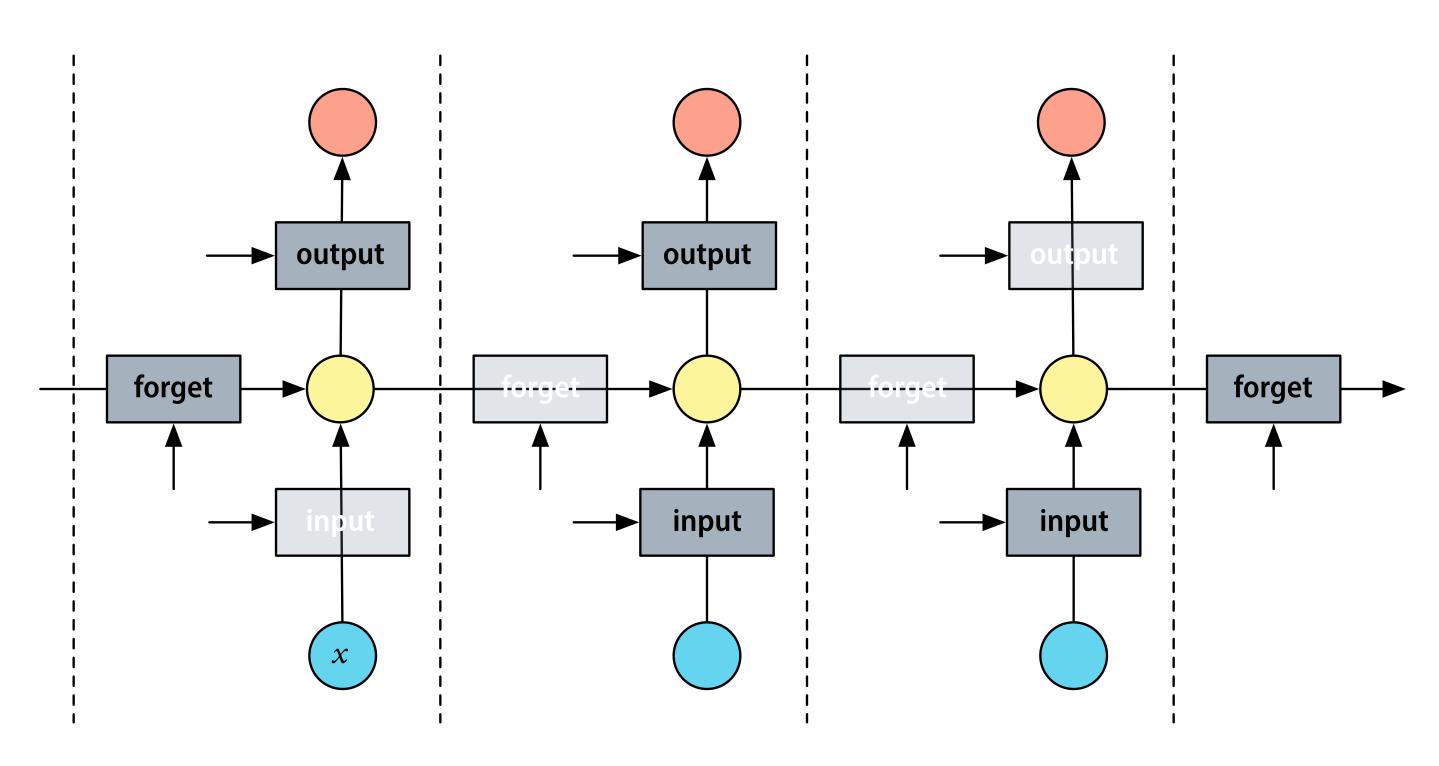
### Long Short-Term Memory (LSTM)

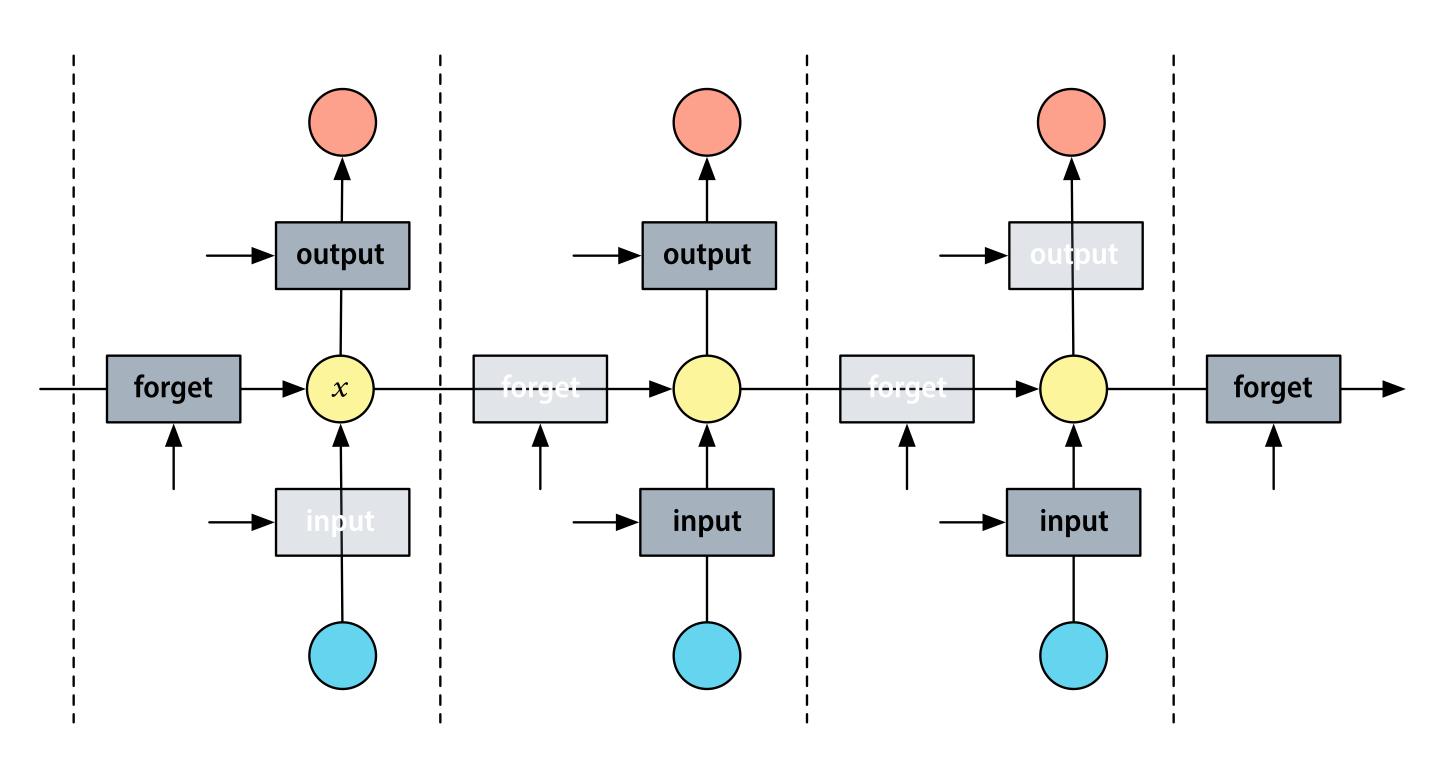
- The Long Short-Term Memory (LSTM) architecture was specifically designed to adress the vanishing gradients problem.
- Metaphor: The hidden state of the neural network can be considered as a short-term memory.
- The LSTM architecture tries to make this short-term memory last as long as possible by preventing vanishing gradients.

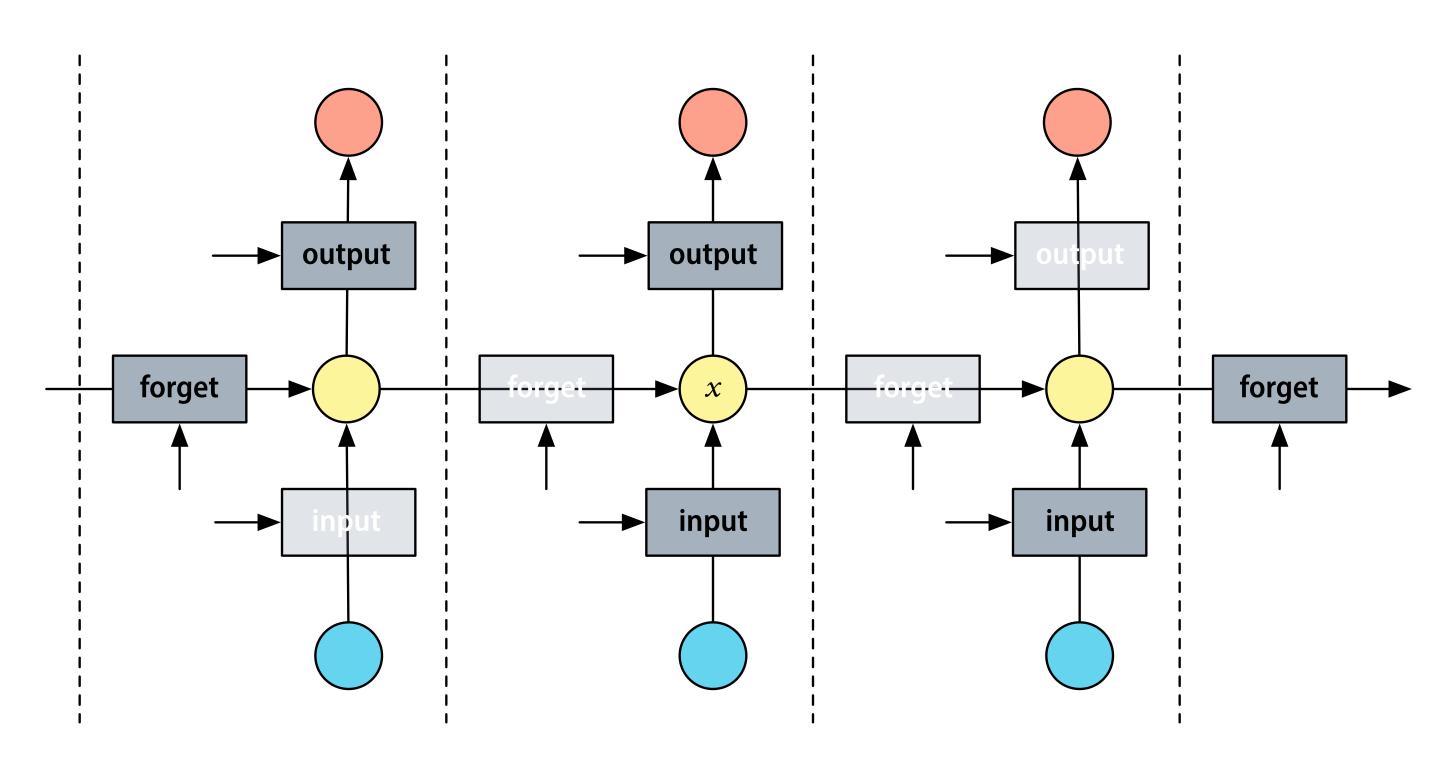
#### Memory cell and gating mechanism

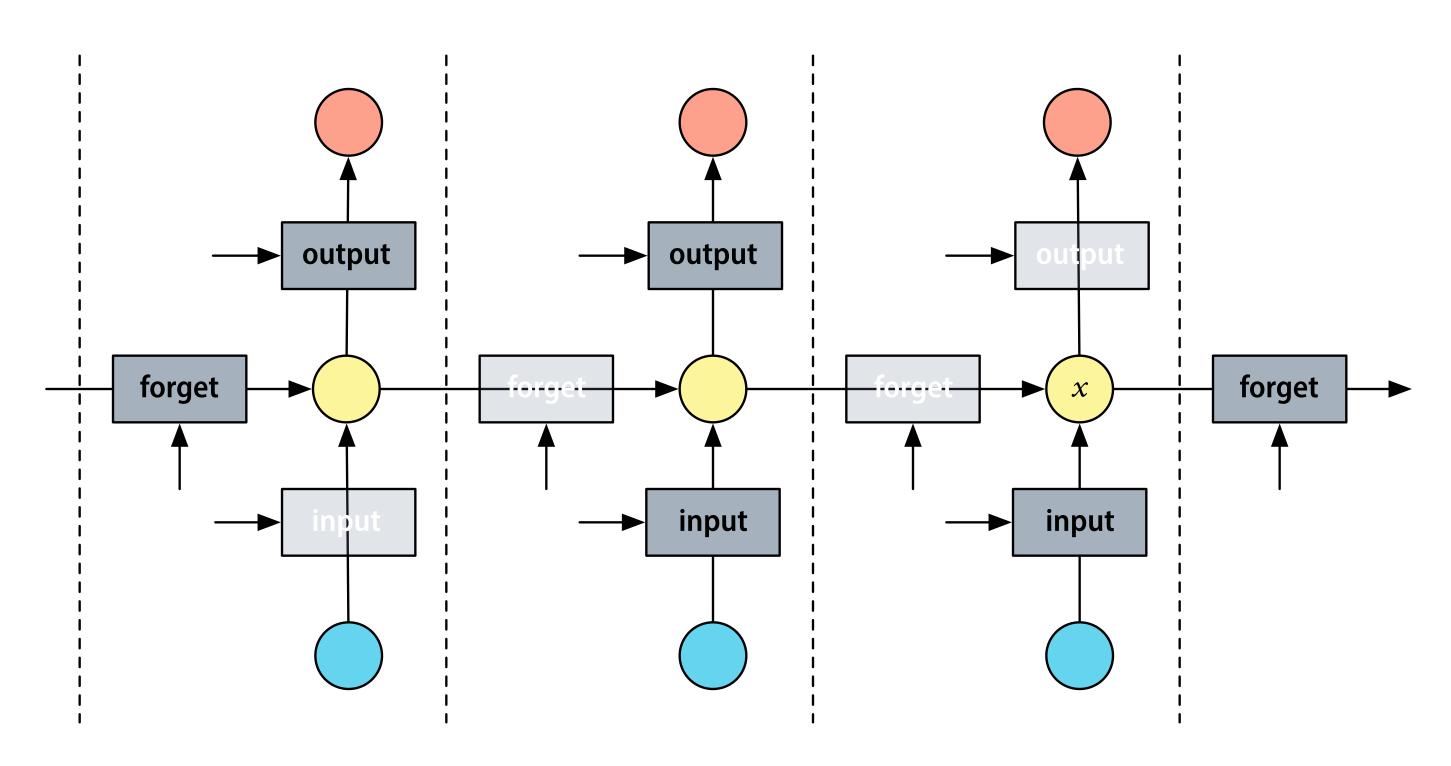
The crucial innovation in an LSTM is the design of its memory cell.

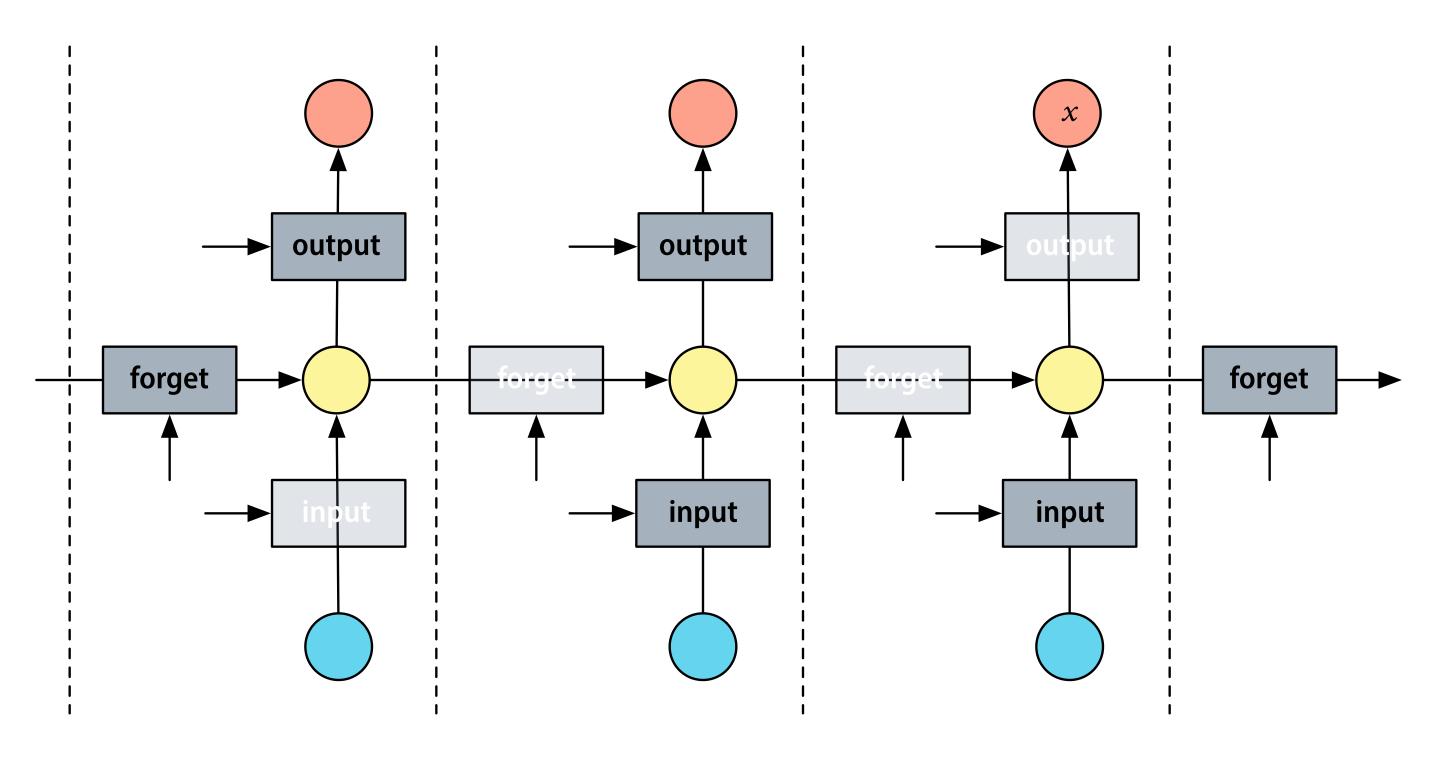
- Information is written into the cell if its INPUT gate is open.
- Information stays in the cell as long as its forget gate is closed.
- Information is read from the cell if its READ gate is open.











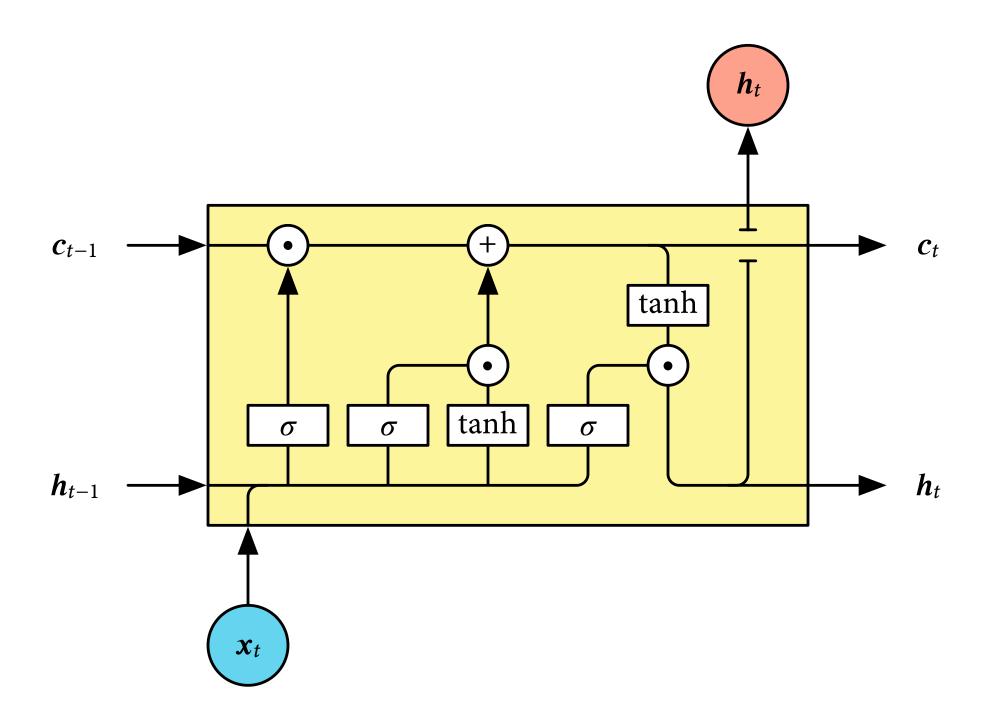
#### Gating mechanism

$$\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} \odot \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 5 \\ 6 \\ 7 \\ 8 \end{bmatrix} \odot \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \\ 3 \\ 8 \end{bmatrix}$$

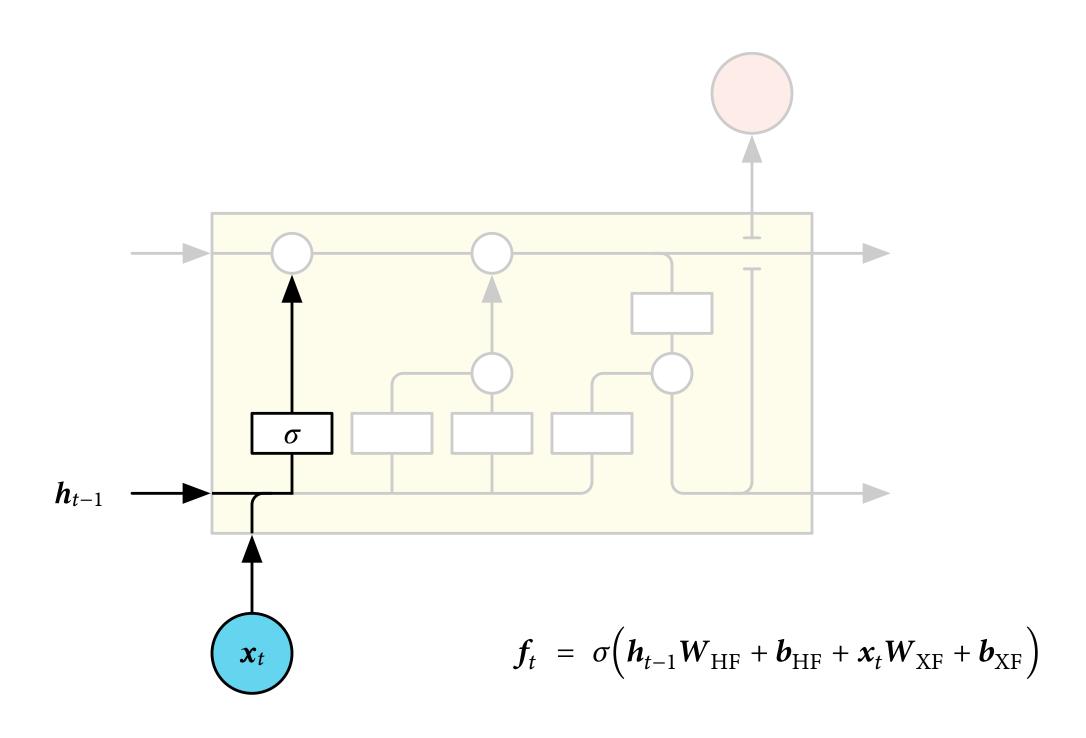
$$h_{t-1} \quad g \quad x_t \quad 1-g \quad h_t$$

The gating masks g are learned values between 0 and 1.

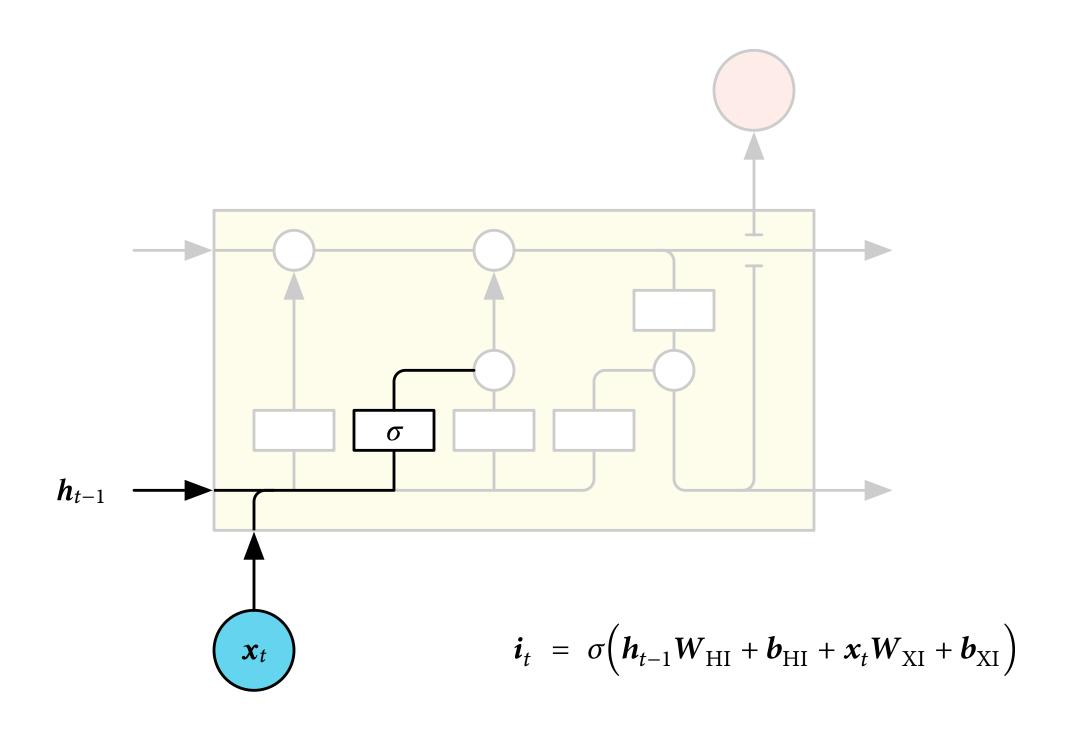
#### A look inside an LSTM cell



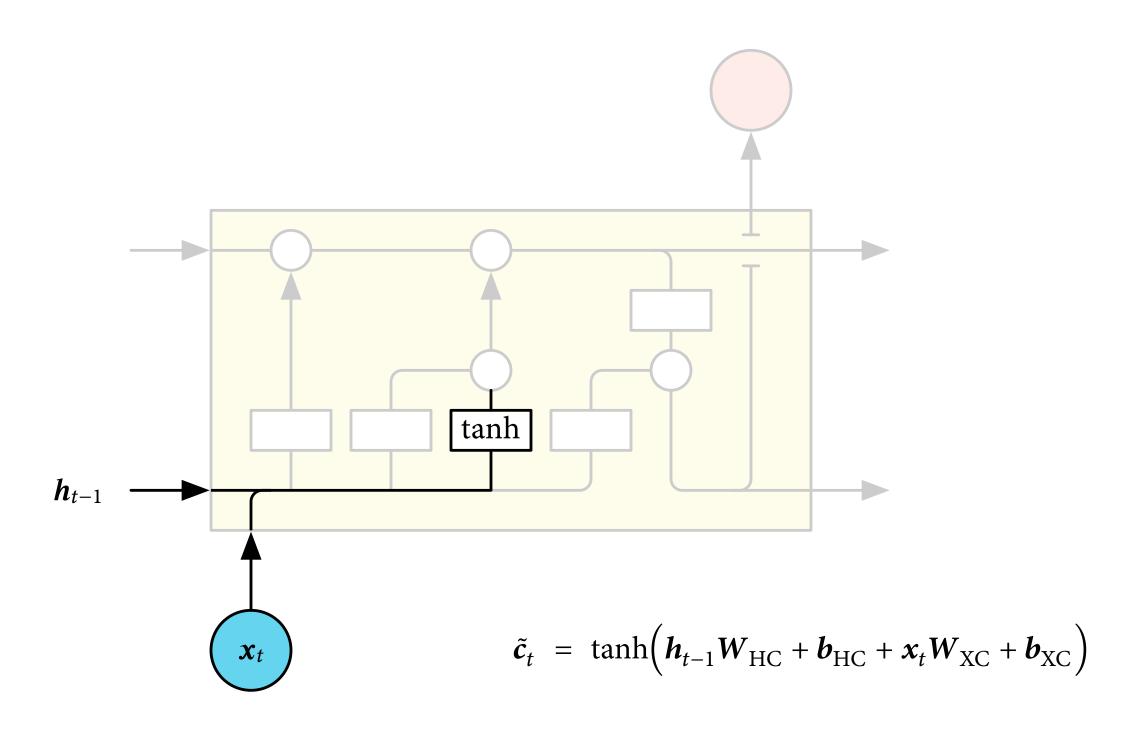
## Forget gate



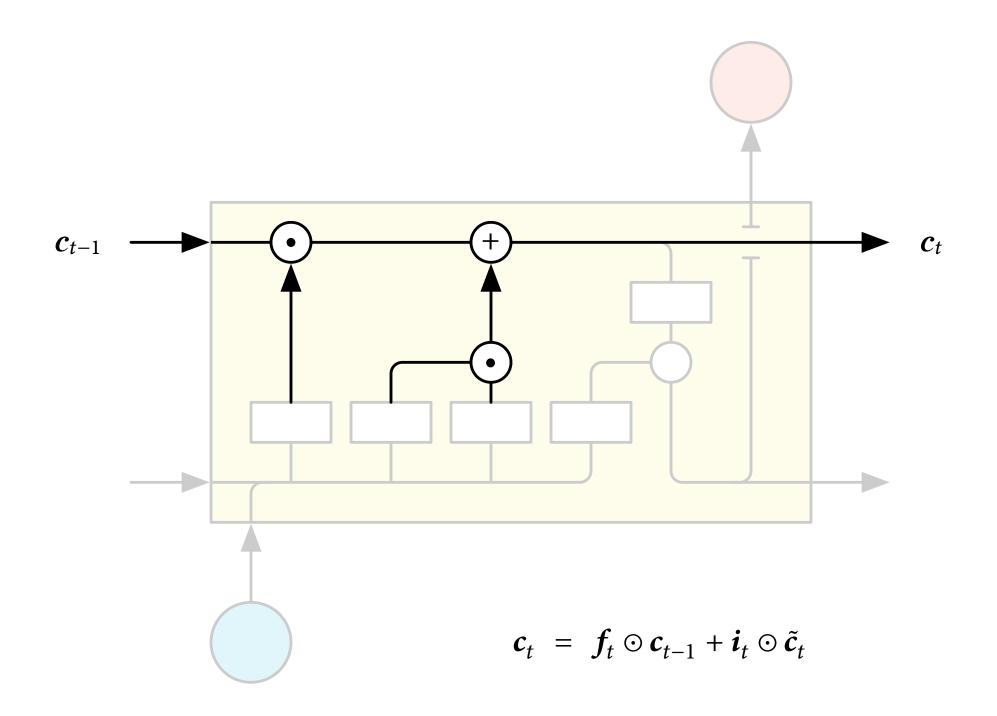
# Input gate



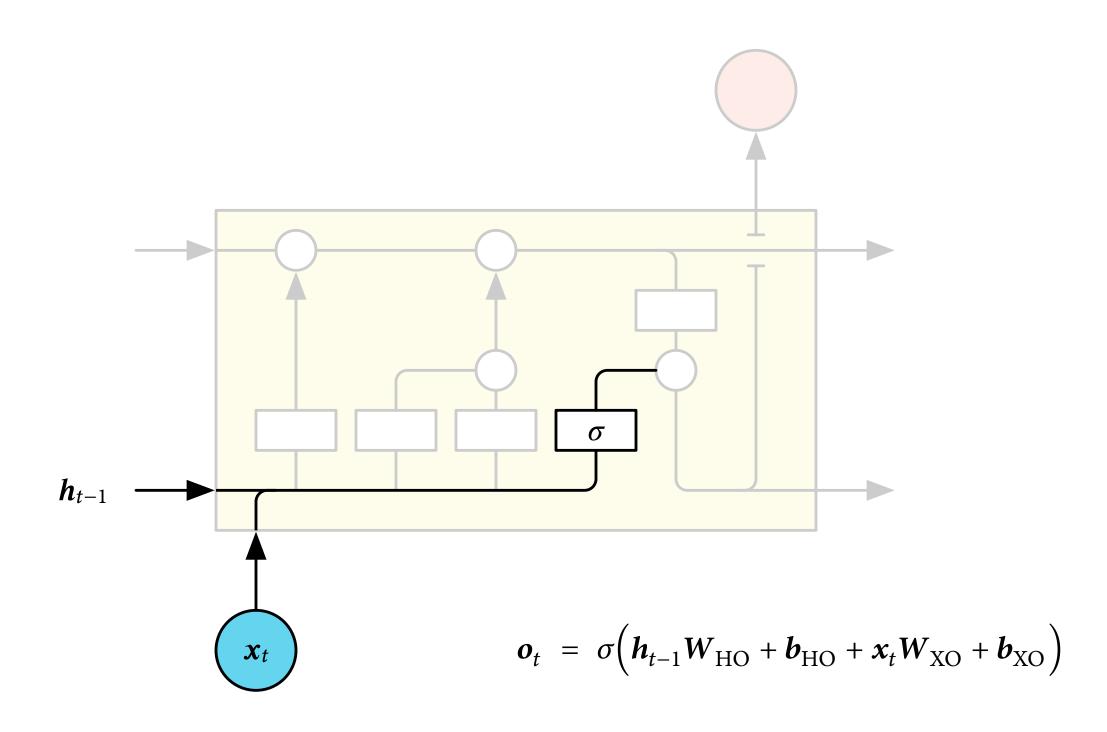
# Update candidate



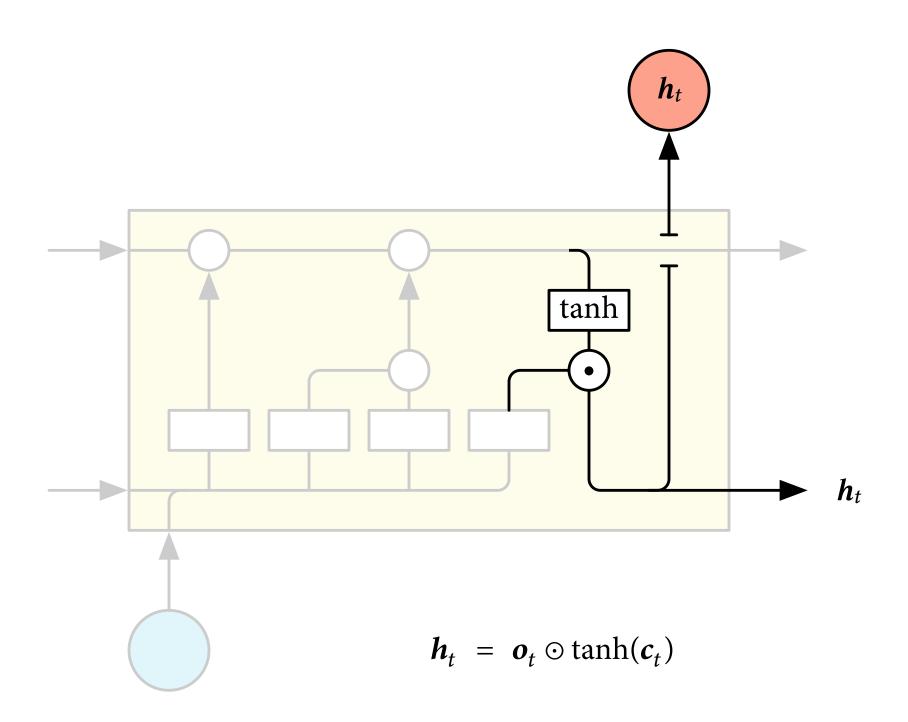
# Memory cell update



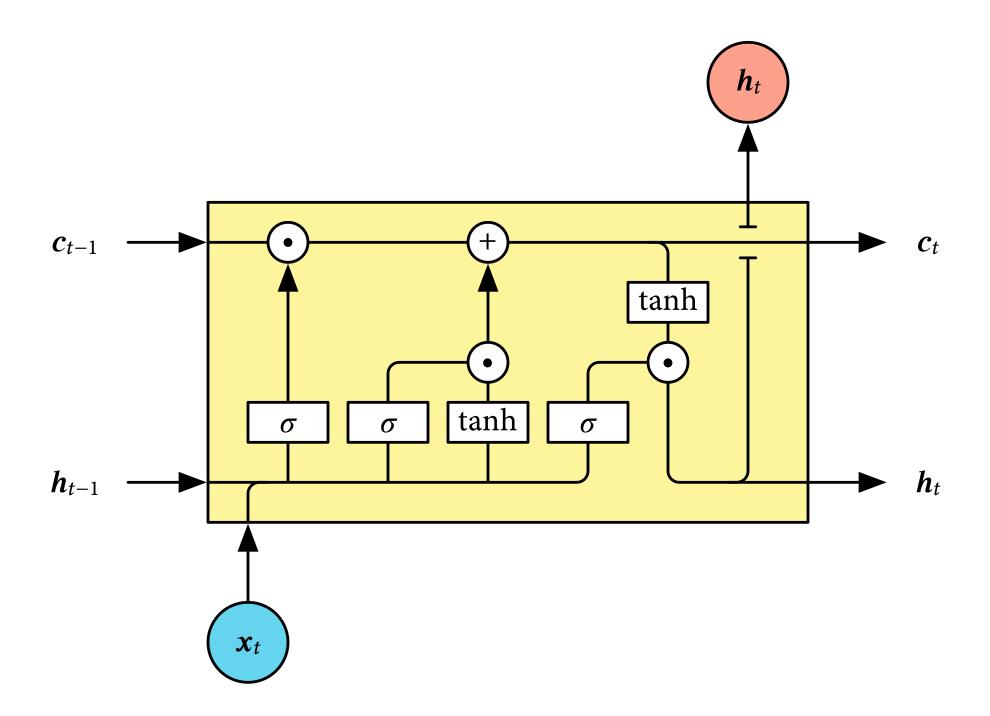
# Output gate



# Output



#### A look inside an LSTM cell



# Gated Recurrent Unit (GRU)

