

Tree Depth in a Forest

Mark Segal

Center for Bioinformatics & Molecular Biostatistics

Division of Bioinformatics

Department of Epidemiology and Biostatistics

UCSF



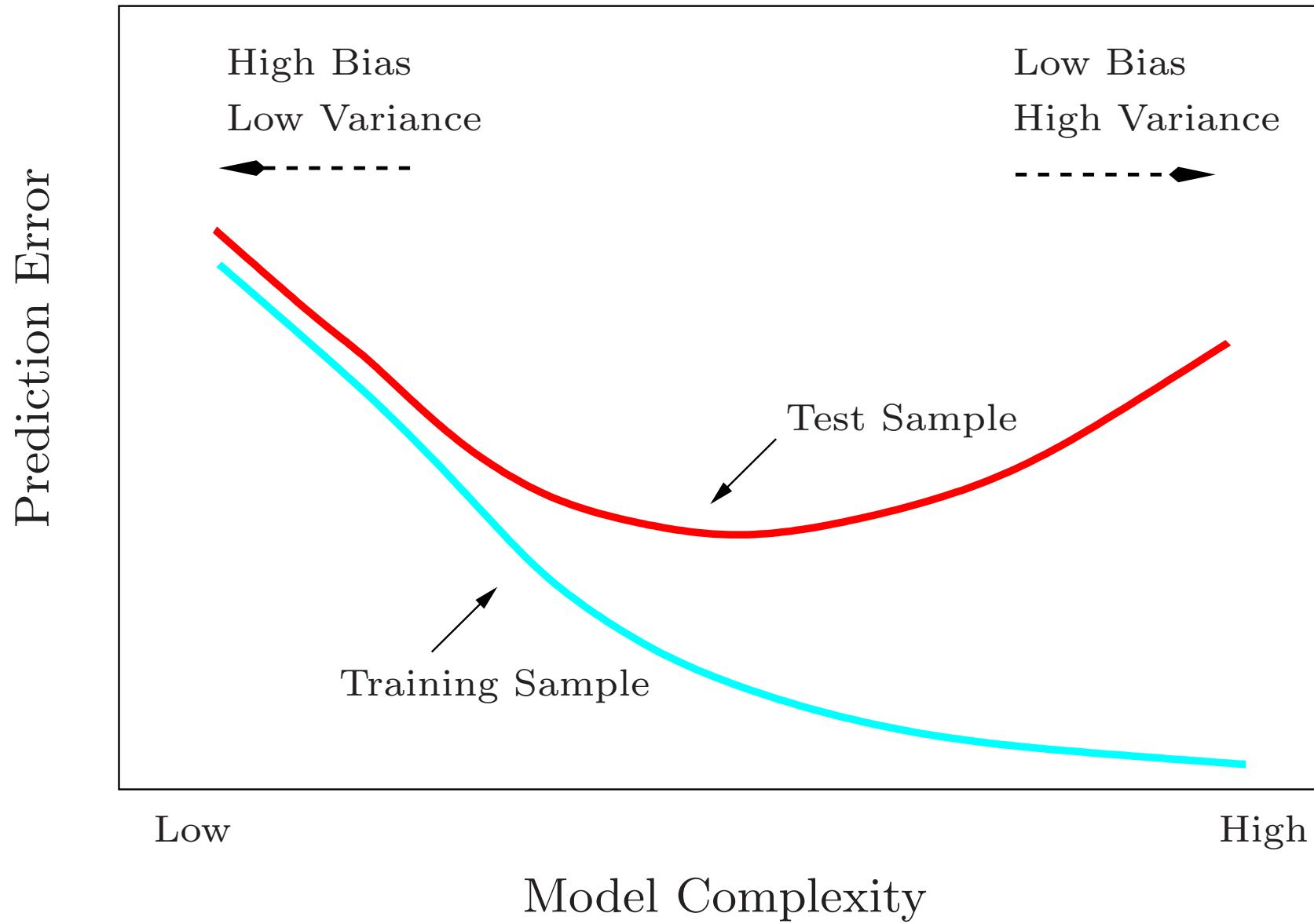
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**NUS / IMS Workshop on
Classification and Regression Trees**

CART

- Breiman, Friedman, Olshen, Stone (1984)
- Popularized tree-structured techniques
- Primary distinction with earlier approaches?
 - Means for determining tree size
 - Grow large / maximal initial tree
 - capture all potential action
 - Cost-complexity pruning
 - Cross-validation based selection
 - Size determination critical consideration
 - Why??

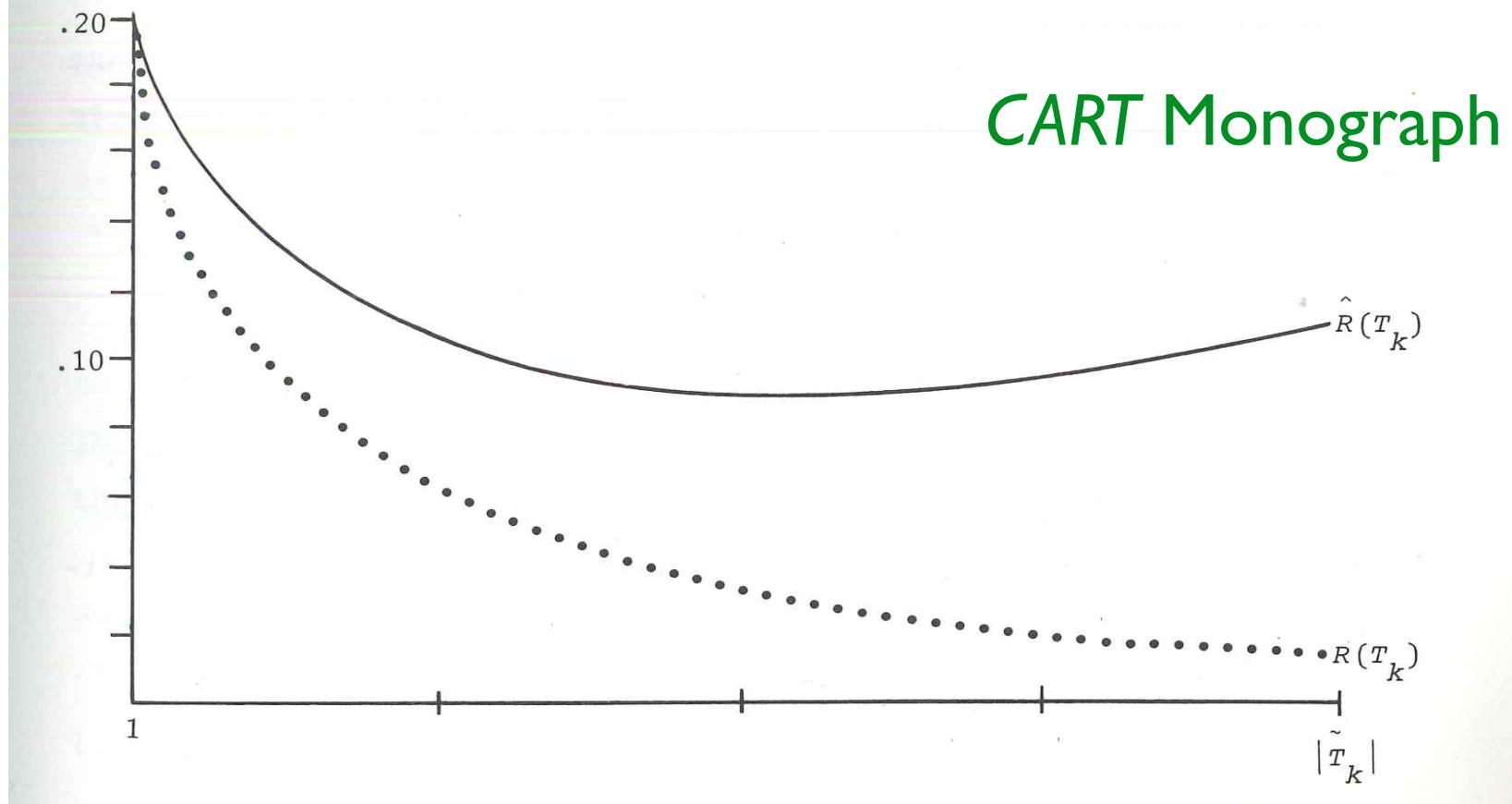
Predictive Performance



Predictive Performance

Heuristics of Bias Versus Variance

In those examples where $|\tilde{T}_1|$ is large, when the cross-validated or test sample estimates $\hat{R}(T_k)$ are graphed as a function of $|\tilde{T}_k|$, similar-shaped curves result. A typical graph, including the re-substitution estimate $R(T_k)$, is shown in Figure 3.3.



- **CART** lived happily ever after
 - widespread uptake in diverse fields
 - many methodological refinements
 - this workshop (thanks Wei-Yin!)
- But, what about predictive performance??

Breiman Mantra

- Better the model fits, the more sound the inference
- Conventional models and **CART** tend to fit very poorly
- Fit measured by prediction error (**PE**)
- Substantial gains in **PE** can be achieved by using ensembles of (weak) predictors
 - in particular, individual trees

Random Forests

- Breiman (2001a,b)
- Have become a forefront prediction technique
- Notable gains in prediction performance over individual trees
 - PE variance reduced by averaging over the randomness-injected ensemble
 - Individual trees grown to large / maximal depth
 - Major departure from CART paradigm
 - Seemingly, averaging over the ensemble *more than* compensates for increased individual tree variability

A **RF** is a collection of tree predictors
 $h(\mathbf{x}; \boldsymbol{\theta}_t), t = 1, \dots, T$; $\boldsymbol{\theta}_t$ iid random vectors
For regression, the forest prediction is the
unweighted average over the collection: $\bar{h}(\mathbf{x})$

As $t \rightarrow \infty$ the Law of Large Numbers ensures
 $E_{\mathbf{X}, Y}(Y - \bar{h}(X))^2 \rightarrow E_{\mathbf{X}, Y}(Y - E_{\boldsymbol{\theta}} h(\mathbf{X}; \boldsymbol{\theta}))^2$
 $\equiv PE_f^*$ the forest prediction error

Convergence implies forests *don't* overfit

Average prediction error for a single tree is

$$PE_t^* = E_{\boldsymbol{\theta}} E_{\mathbf{X}, Y} (Y - h(\mathbf{X}; \boldsymbol{\theta}))^2$$

Assume $EY = E_{\mathbf{X}} h(\mathbf{x}; \boldsymbol{\theta}) \forall \boldsymbol{\theta}$

Then $PE_f^* \leq \bar{\rho} PE_t^*$ where $\bar{\rho}$ is weighted corrⁿ between residuals for independent $\boldsymbol{\theta}', \boldsymbol{\theta}''$

Inequality pinpoints needs for accurate **RF**:
low residual corrⁿ; low PE for individual trees

Low corrⁿ sought via injected randomization

But what about low PE_t^* ?

- Growing trees to maximal depth minimizes bias
 - But potentially incurs prediction variance cost
 - Averaging over ensemble putatively handles this
- But how was it established that such averaging (more than) compensates for increased individual tree variability??
 - Hard to address theoretically ([will try later](#))
- Breiman (2001a,b) addressed empirically using
 - UCI Irvine machine learning benchmark datasets
 - Includes classification and regression problems
 - Simulated and (predominantly) real data
 - Exported to R mlbench library

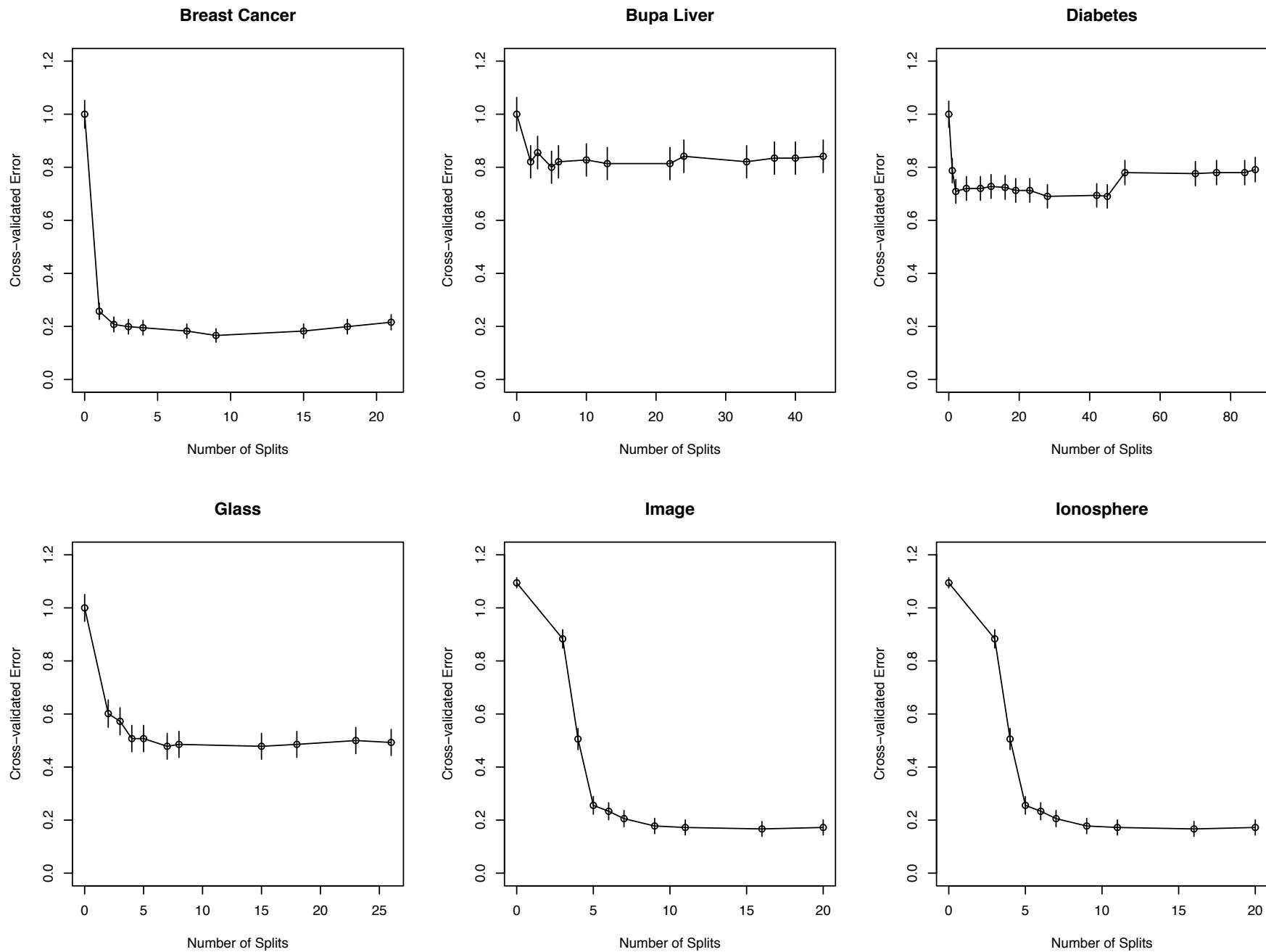
Some classification results from UCI Irvine machine learning benchmark datasets:

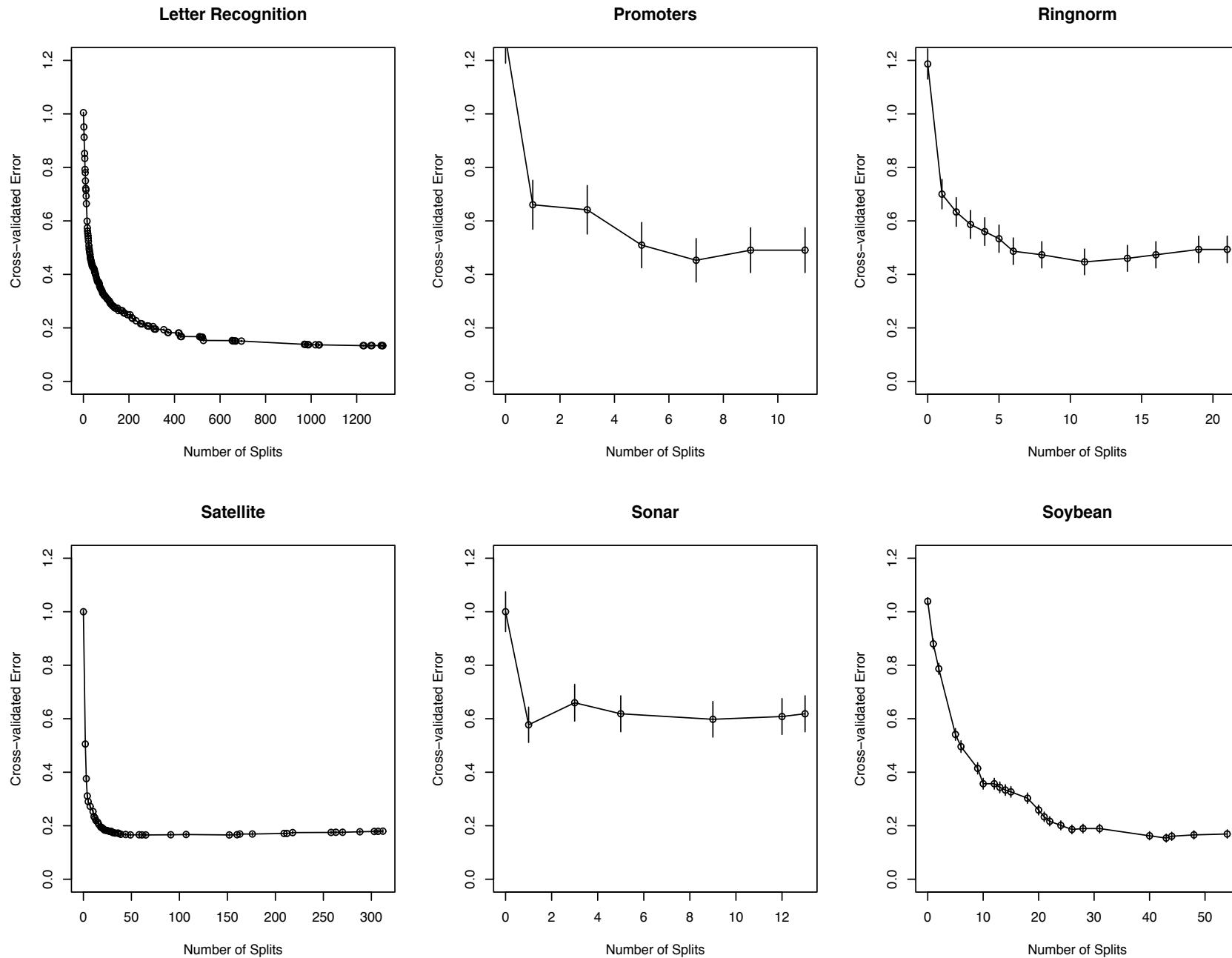
<i>Data set</i>	Forest	Single tree
Breast cancer	2.9	5.9
Ionosphere	5.5	11.2
Diabetes	24.2	25.3
Glass	22.0	30.4
Soybean	5.7	8.6
Letters	3.4	12.4
Satellite	8.6	14.8
Shuttle $\times 10^3$	7.0	62.0
DNA	3.9	6.2
Digit	6.2	17.1

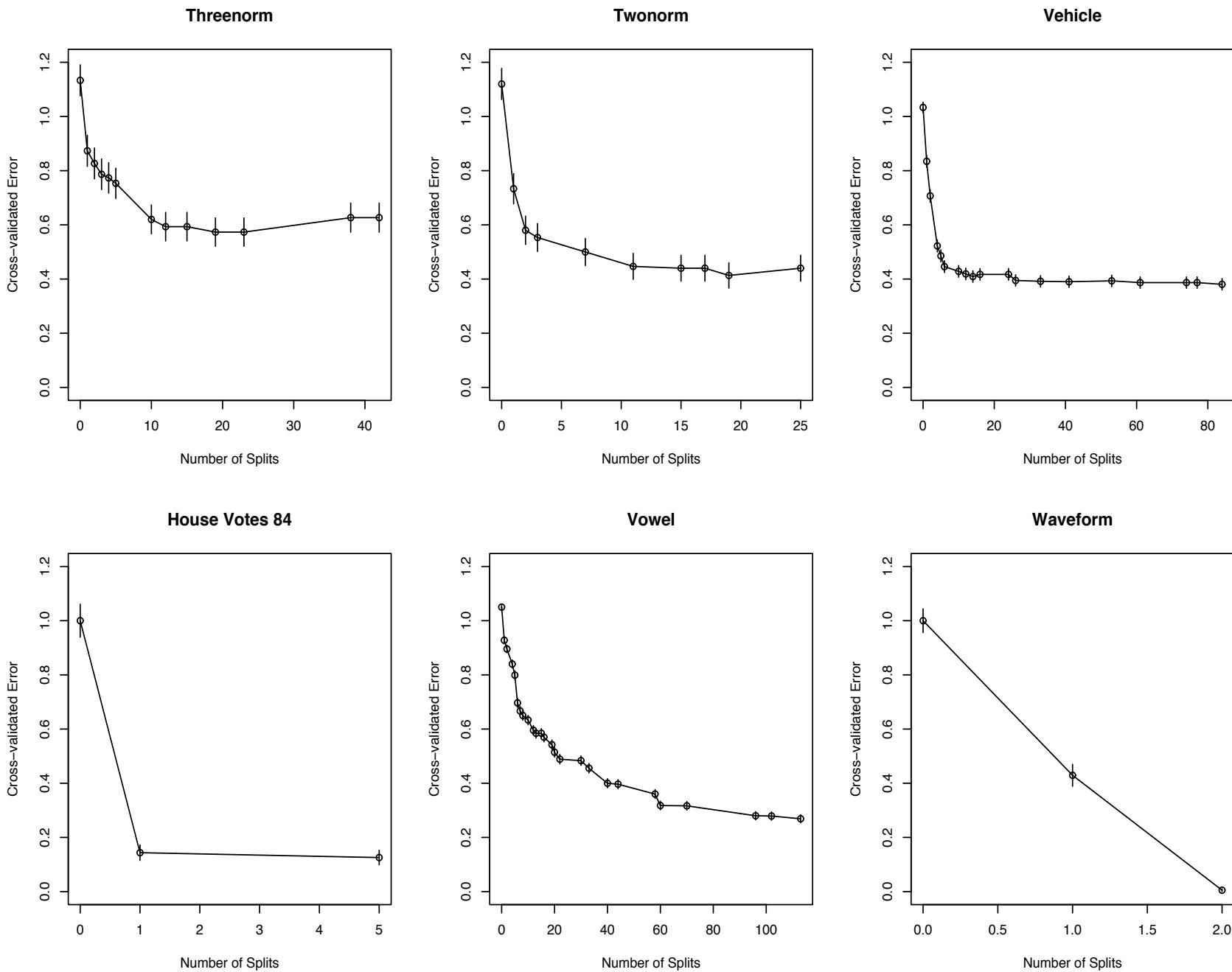
Breiman (2001a,b)

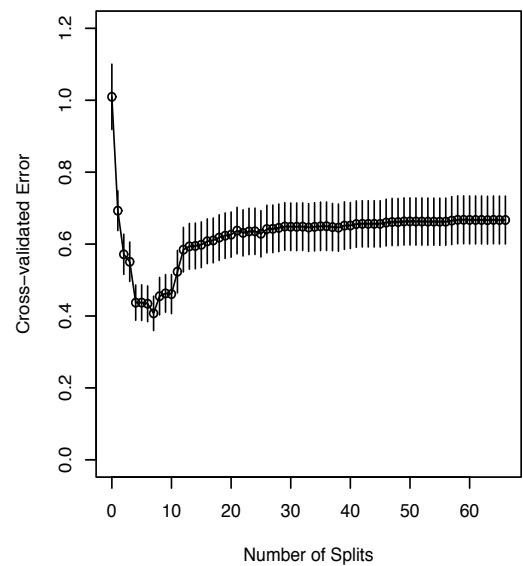
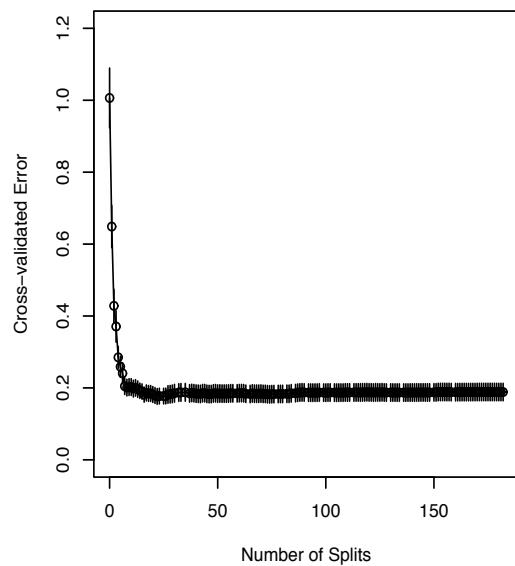
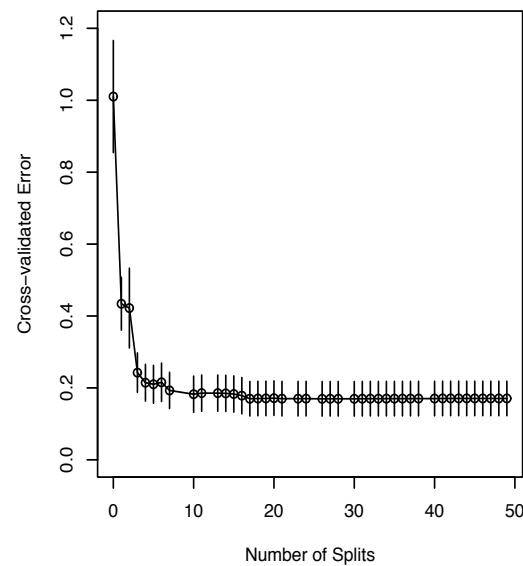
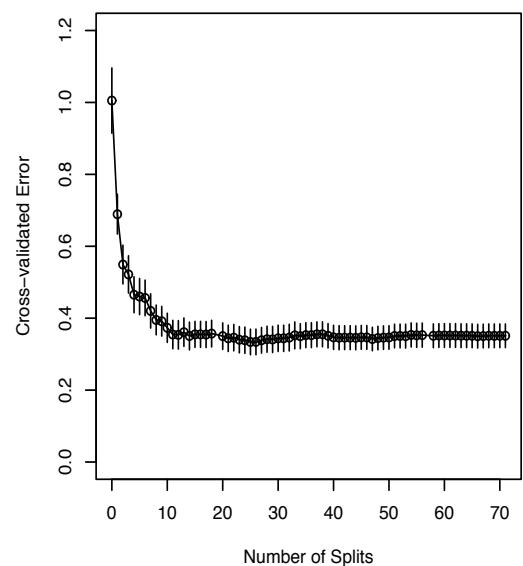
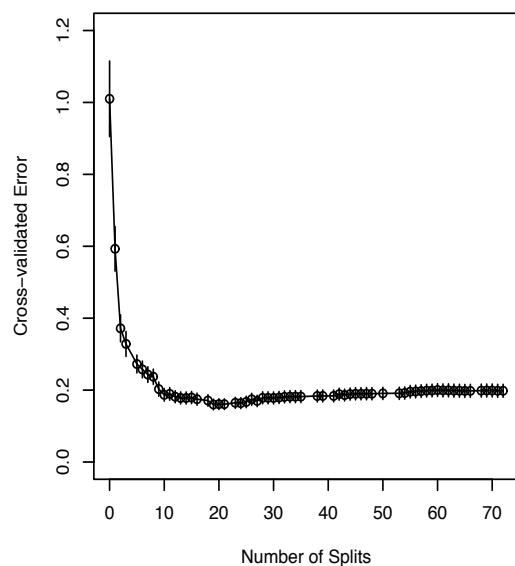
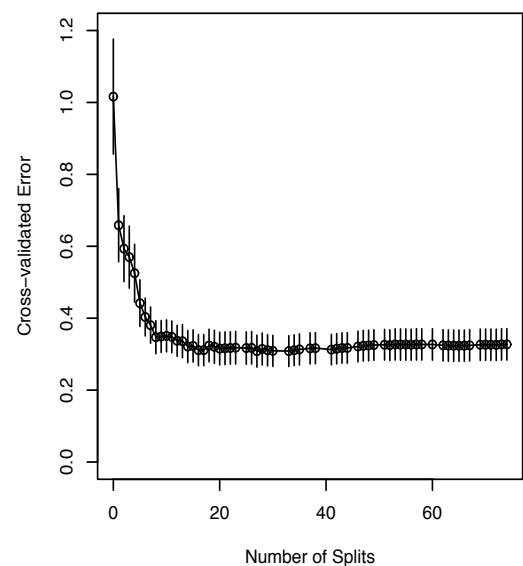
- Many further comparisons using the UCI Irvine / mlbench repository datasets:
 - several modeling / prediction frameworks:
 - CART, ANNs, LDA, QDA, kNNs...
 - regression and classification problems
 - Conclusion: “Random Forests are A+ predictors”
 - Discussion (Efron): Lots of knobs (tuning parameters)
 - Rejoinder (Breiman): Essentially only one (*mtry*)

- Random Forests have lived happily ever after
- But, lets take a closer look at the UCI Irvine / mlbench repository datasets

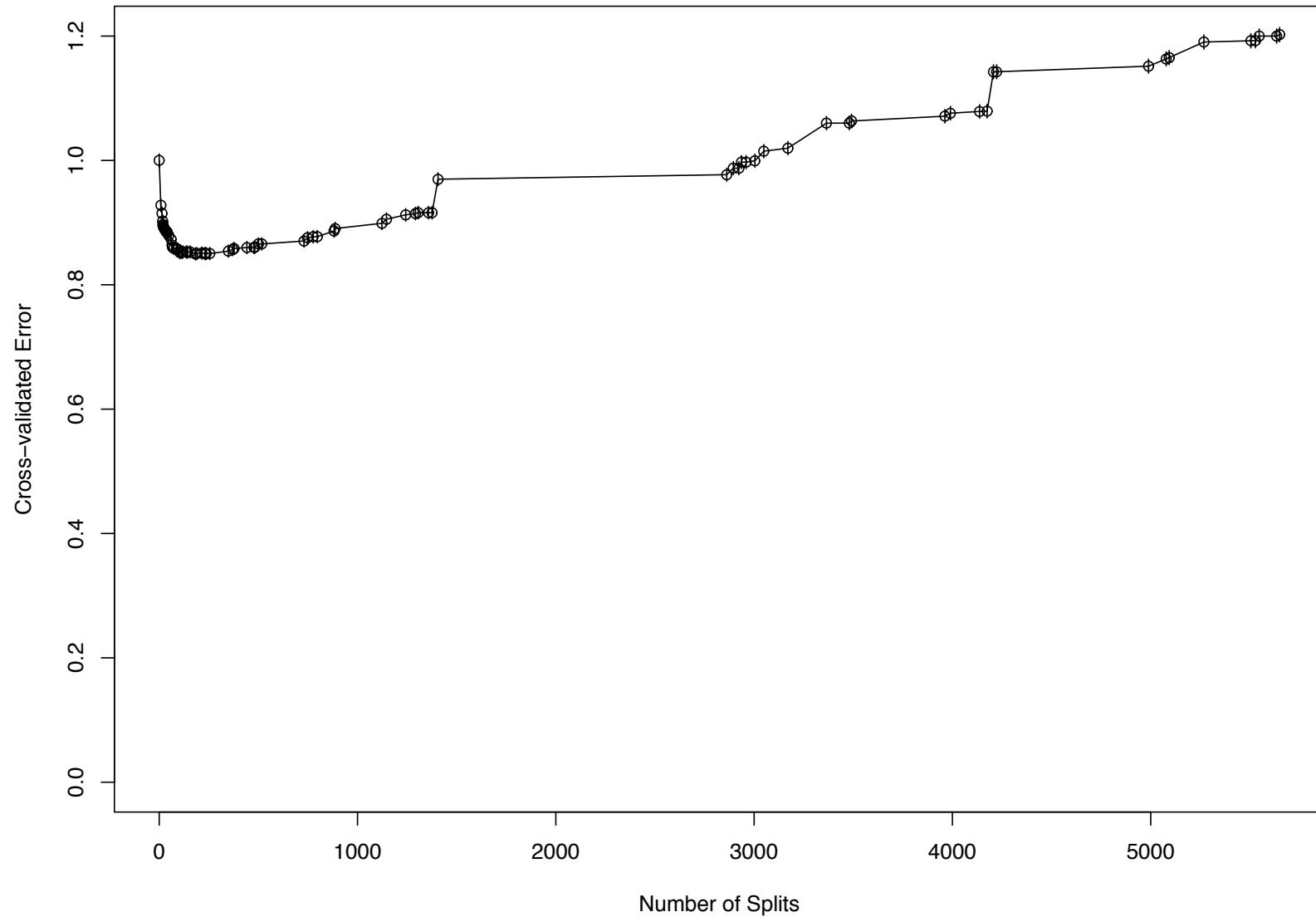






Augmented Friedman #1**Boston Housing****Servo****Friedman #1****Friedman #2****Friedman #3**

- Almost all UCI Irvine machine learning benchmark datasets exhibit this behaviour:
 - they are hard to *overfit* {not just with trees}
 - This will make the Random Forest strategy of growing trees to maximal depth look good
 - “Benchmarks” are not representative of what is at least thought to be prototypic
 - Will next showcase such an example
 - Then offer some theory and characterizations



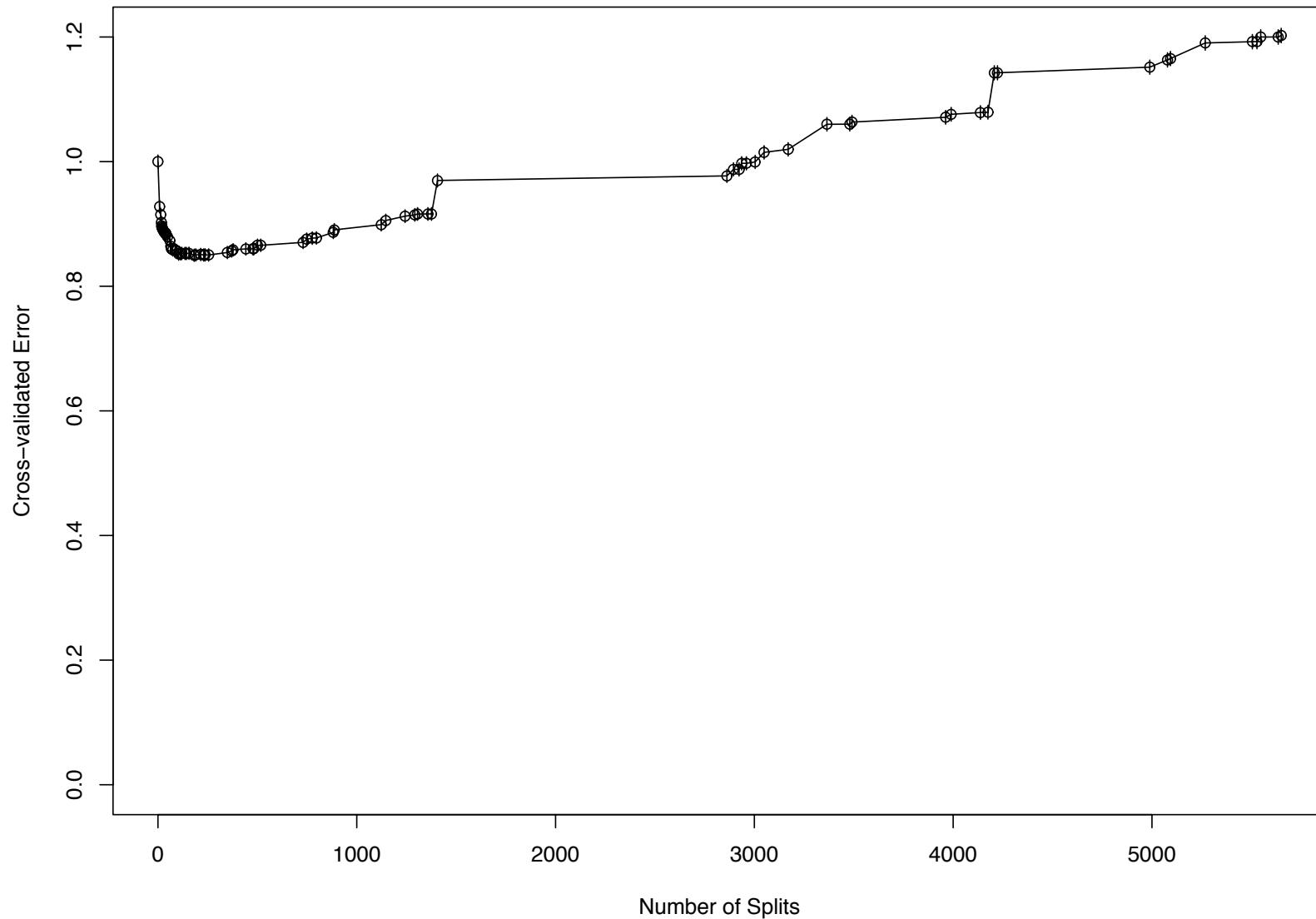
Basal Splicing Signals

- Pre-messenger RNA splicing - responsible for precise removal of introns - is an essential step in expression of most genes
- Exons defined by short, degenerate splice site sequences at intron/exon boundaries: 5' splice site (**5'ss**, donor); **3'ss**, acceptor
- Each **ss** has a consensus sequence motif: essential nucleotides plus base usage preferences in flanking positions

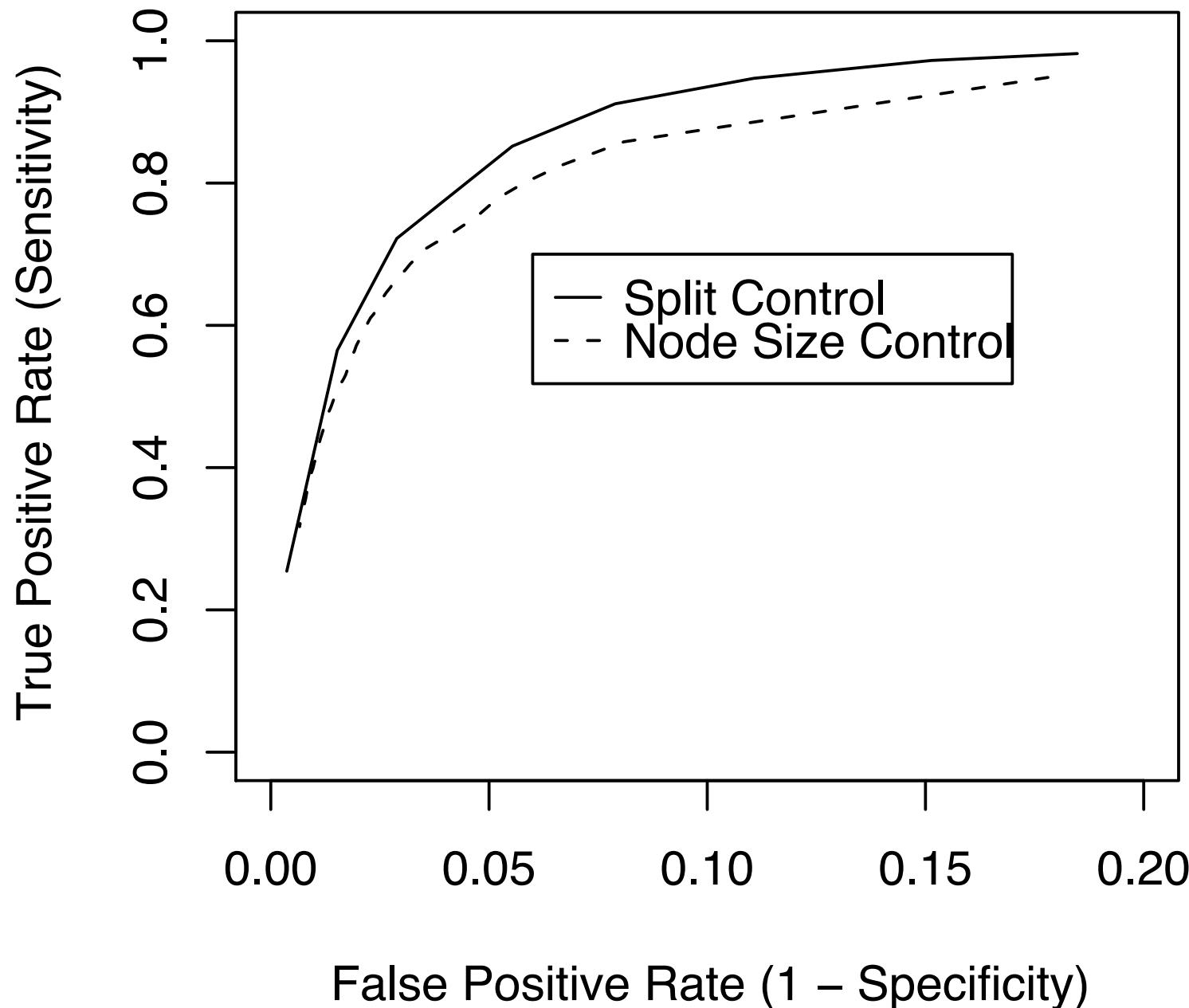
- Despite requirement for accurate splicing, human **ss** only moderately conserved
 - Implies an abundance of **decoy ss**
- Further, strong and complex dependencies between **ss** nucleotides exist
- Improved understanding of basal **ss** is important for exon recognition and, ultimately, disease impact of splicing defects
- Approach as a classification problem -- **real** vs **decoy ss** -- using large database

- Objective: predict 3' splice site sequences
- Large n , small p datasets:
 - training 8465 real; 180957 decoy
 - test 4233 real; 90494 decoy
 - ATTCTTACAAGTCCAATAAGGTT real
 - GAATCGCTTGAACCTGGGAGGTG real
 - CTGAAATGTCTCATCTGCAGTAC decoy
 - ATTTTATTTTAAATTGCAGGTA decoy
 - each (non-degenerate, aligned) position constitutes an unordered covariate ($p = 21$)
 - data generation: Yeo and Burge (2003).

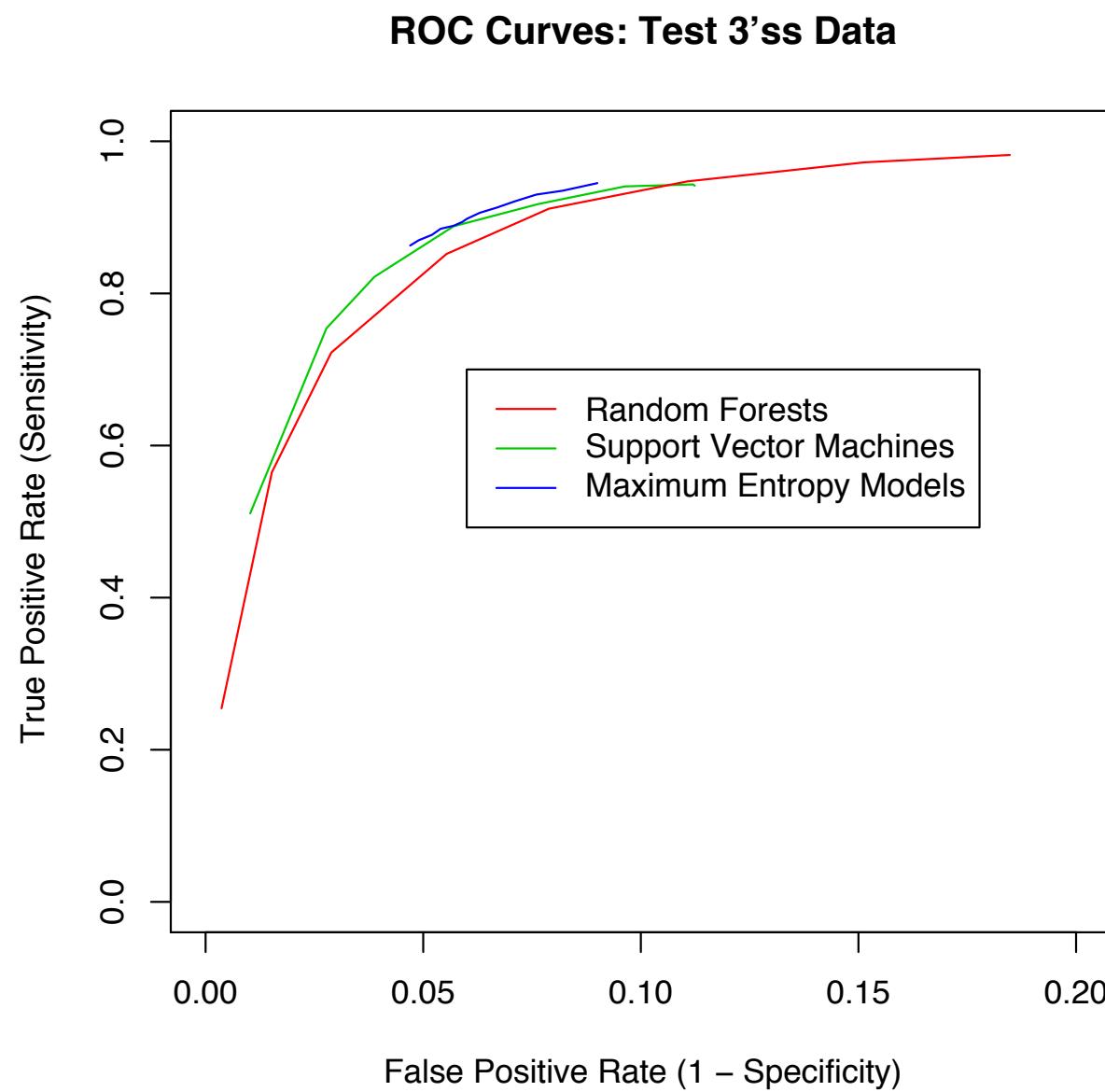
3'ss: CV error for a single tree



Random Forest ROC Curves: Test 3'ss Data



{Aside: comparisons}



Tree Depth in a Forest

- Individual tree size determined by *inter-related* tuning parameters that govern (terminal) node size, number of splits, depth, split improvement
- A priori regulation via node size specifications problematic in large n situations
- Guidelines, rules-of-thumb as function of n are lacking (cf defaults for m)
- Leekasso

Potential Nearest Neighbours

- Lin and Jeong (2006, JASA)
- Develop construct of **k -PNNs**
- Establish connections between **Random Forests** and **k -PNNs** where k is terminal node size
 - $k = 1$ for trees grown to maximal depth
- Enables analysis of role of tree depth

RF grown on original training data $\{(\mathbf{x}_i, y_i)\}_1^n$

Prediction from tree t at target \mathbf{x}_0 : $\sum W_{it}y_i$

$W_{it} = 1/k$ if \mathbf{x}_i is among the k points in terminal node containing \mathbf{x}_0 ; zero otherwise.

Averaging over T trees the **RF** prediction at \mathbf{x}_0 is $\sum_{i=1}^n \bar{W}_i y_i$ with $\bar{W}_i = 1/T \sum_{t=1}^T W_{it}$.

RF is a weighted average of y_i 's with weights depending on training data and θ_t .

Clearly $\bar{W}_i = 0$ for most sample points i .
Points with $\bar{W}_i > 0$ are called **voting points**.
In general, **voting points** are *not* NNs of \mathbf{x}_0 for any single distance metric.
However, **voting points** *are* k **potential** NNs:
there exists a distance under which they are among the k closest sample points to \mathbf{x}_0
(from hyper-rectangular partitioning of **RFs**).

Thus **RFs** are a weighted k **PNN** method.

Under simplifying assumptions Lin and Jeon show that a lower bound on the rate of convergence of RF MSE is $k^{-1}(\log n)^{-(p-1)}$. Much inferior to standard rate $n^{-2d/(2d+p)}$ (where d is degree of target smoothness) attained by many nonparametric methods. To achieve competitiveness terminal node size k should increase with sample size n .

Intuitively: largest trees use 1-PNNs at \mathbf{x}_0 #1-PNNs $\sim O_p[(\log n)^{p-1}]$ which is too small.

Lin and Jeon: “growing large trees (k small) does not always give the best performance”

But, asymptotics require $n \gg p$ and even when seemingly applicable may not pertain. Consider $p = 10, d = 2, n = 100000$. Then $(\log n)^{p-1}/(p - 1)! = 9793 \gg 27 = n^{2d/(2d+p)}$ Even more so the case for larger p , smaller n .

So, for high dimensional problems growing largest individual trees is often desirable.

Conclusions / Future Work

- UCI / mlbench data repositories are inadequate as representative testbeds
- **k -PNNs** provide a theoretic framework for (crudely) evaluating tree depth considerations
- In large sample settings (**Big Data**) growing the individual tree components of a **Random Forest** ensemble to maximal depth can be undesirable
- Approaches to developing guidelines, defaults, parameterizations, tuning strategies to address tree depth are yet to be developed

Acknowledgements

- Eugene Yeo
- Leo Breiman