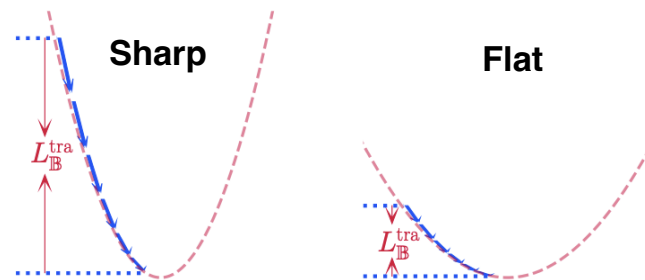


Question
How can we add more **Challenge Operators** in GTs without considering differentiability?

Challenge
Naive ZOO ---> sharp loss landscape
Objective: seek for an optimization scheme with flat loss landscape



Challenge Operators
Expert A: add rewiring
Expert B: add sparsity
Expert C: add shortest path

Unveiling the Power of SZO in Graph Transformers

