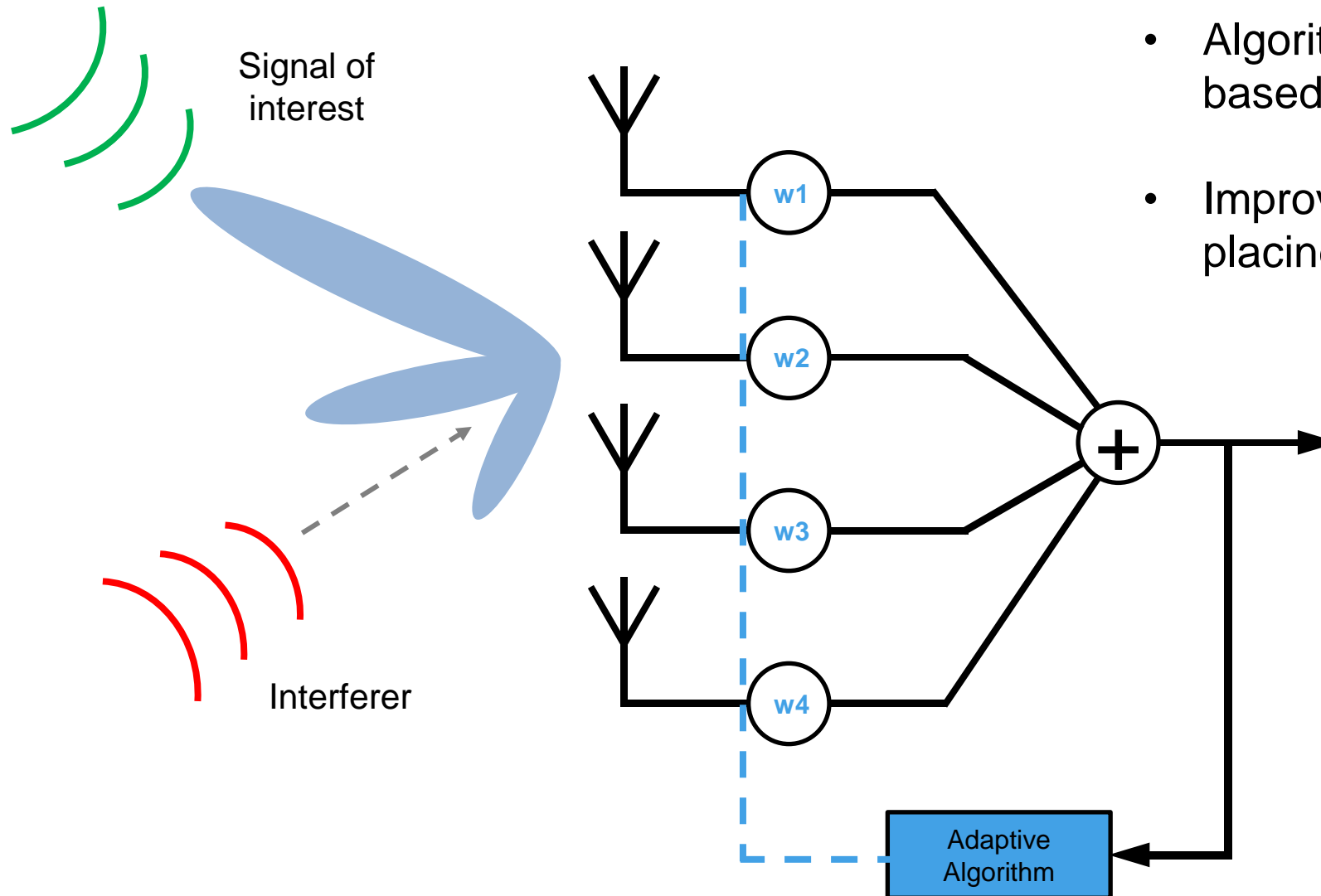


Hardware-Efficient Linear Algebra for Radar and 5G

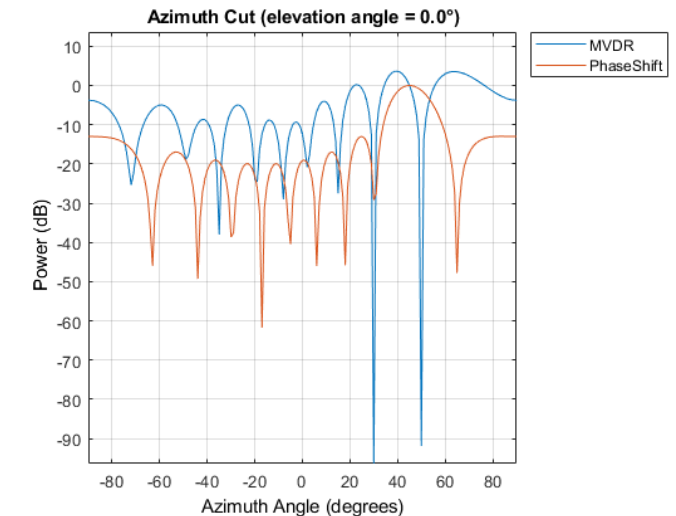
Agenda

- Introduction
 - Applications: Radar, Comms and Wireless
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- Theory and Implementation
 - Linear algebra
 - Matrix decomposition: QR vs Cholesky
 - Latency vs. area tradeoffs
- HDL Coder Implementation
 - HDL Coder implementation
 - Resource mapping and utilization

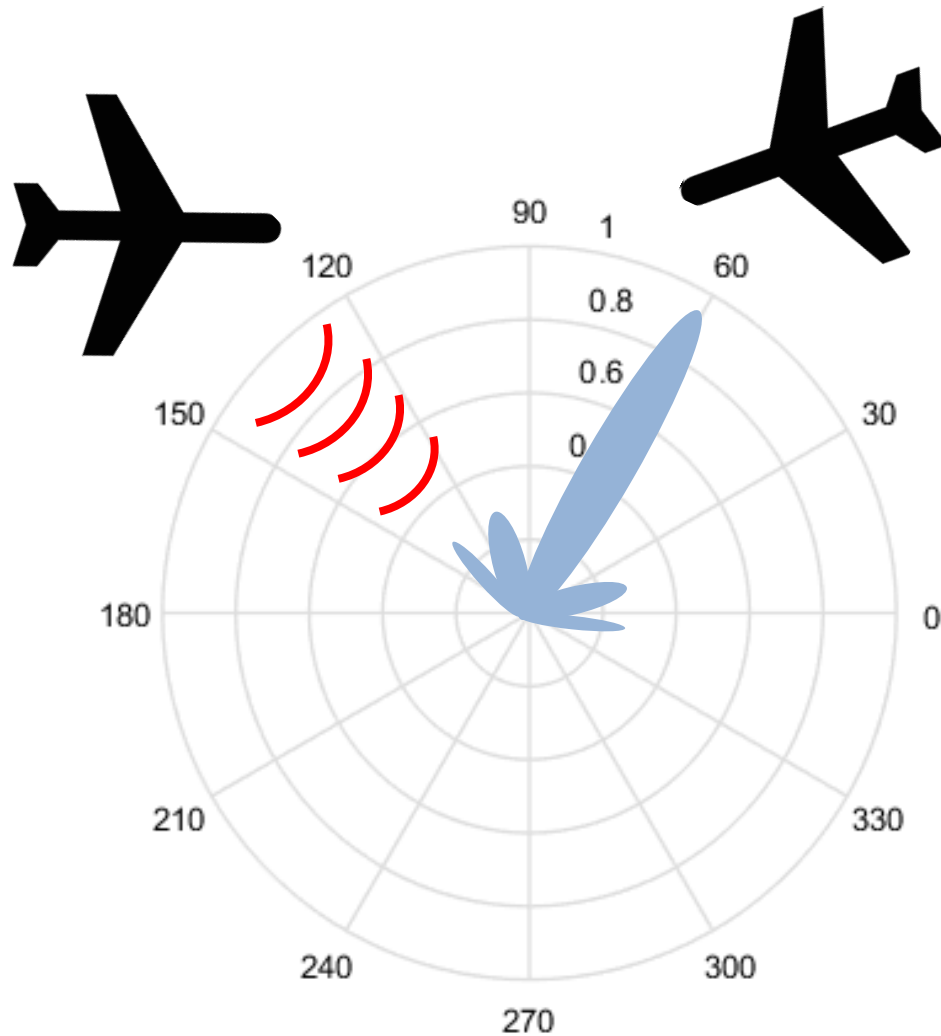
Adaptive Beamforming



- Algorithm chooses optimal weights based on receive data statistics
- Improve SNR by automatically placing nulls at interference angles



Applications: Radar

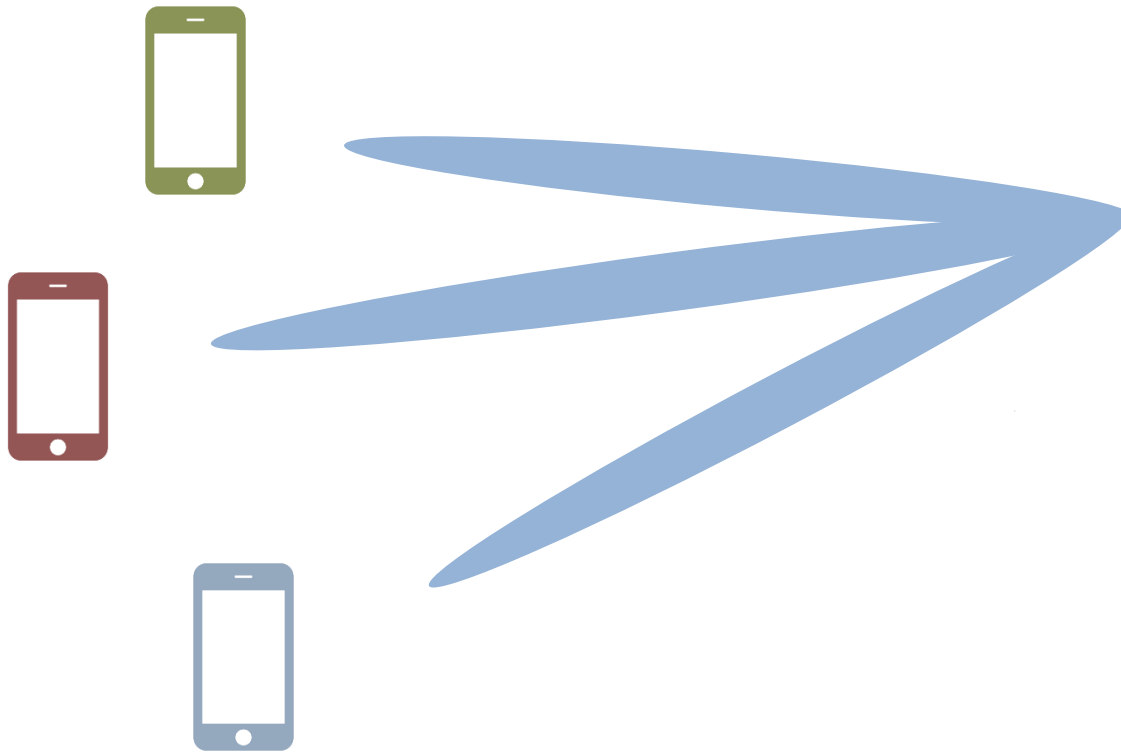


- Increase angular resolution
- Suppress interference



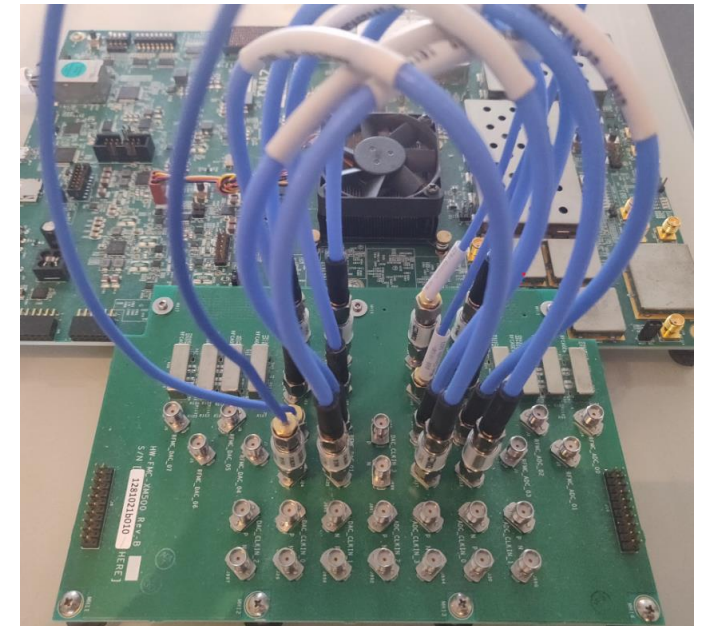
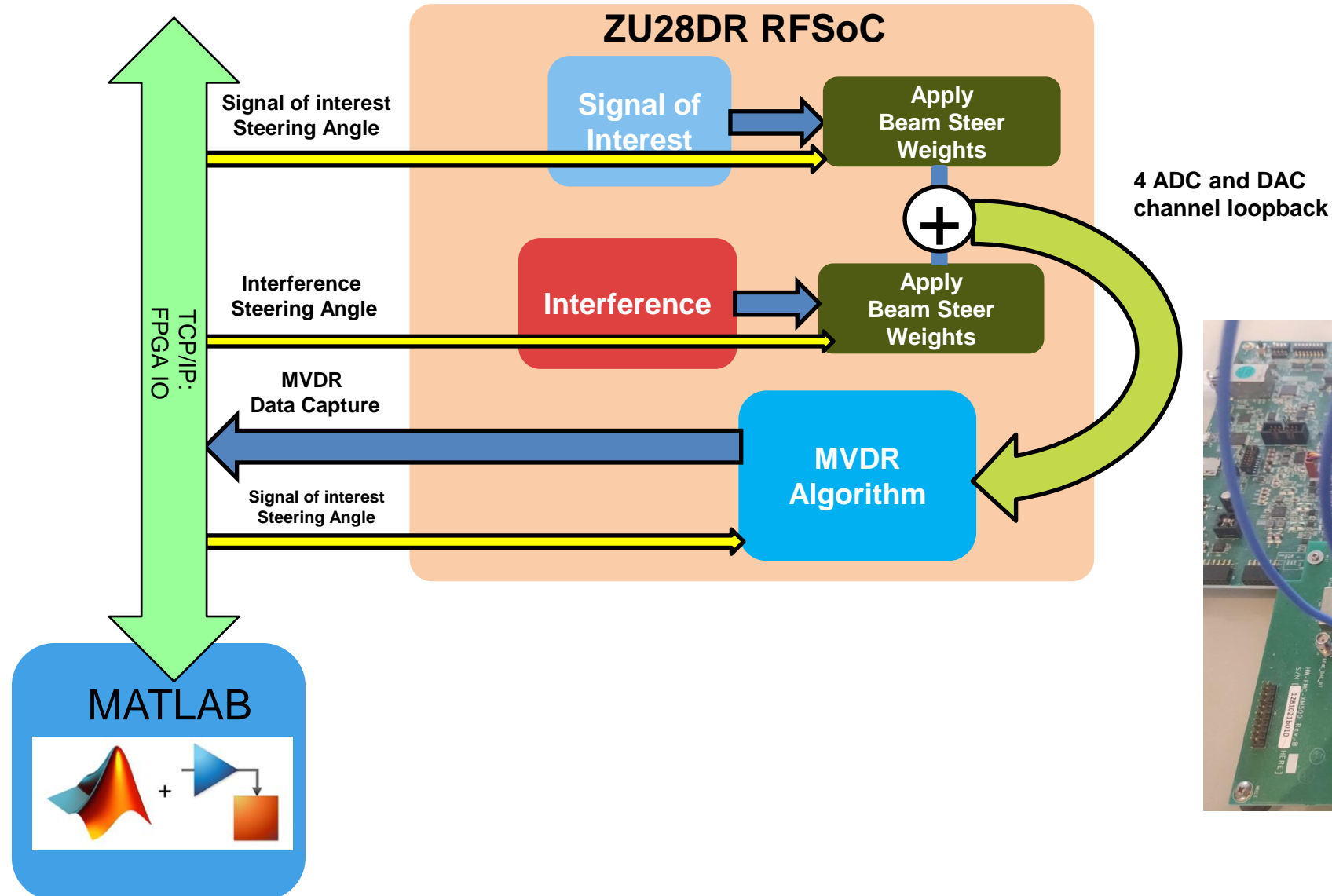
Applications: 5G

- Increase number of simultaneous users
- Improve throughput and coverage



Beamforming Demonstration

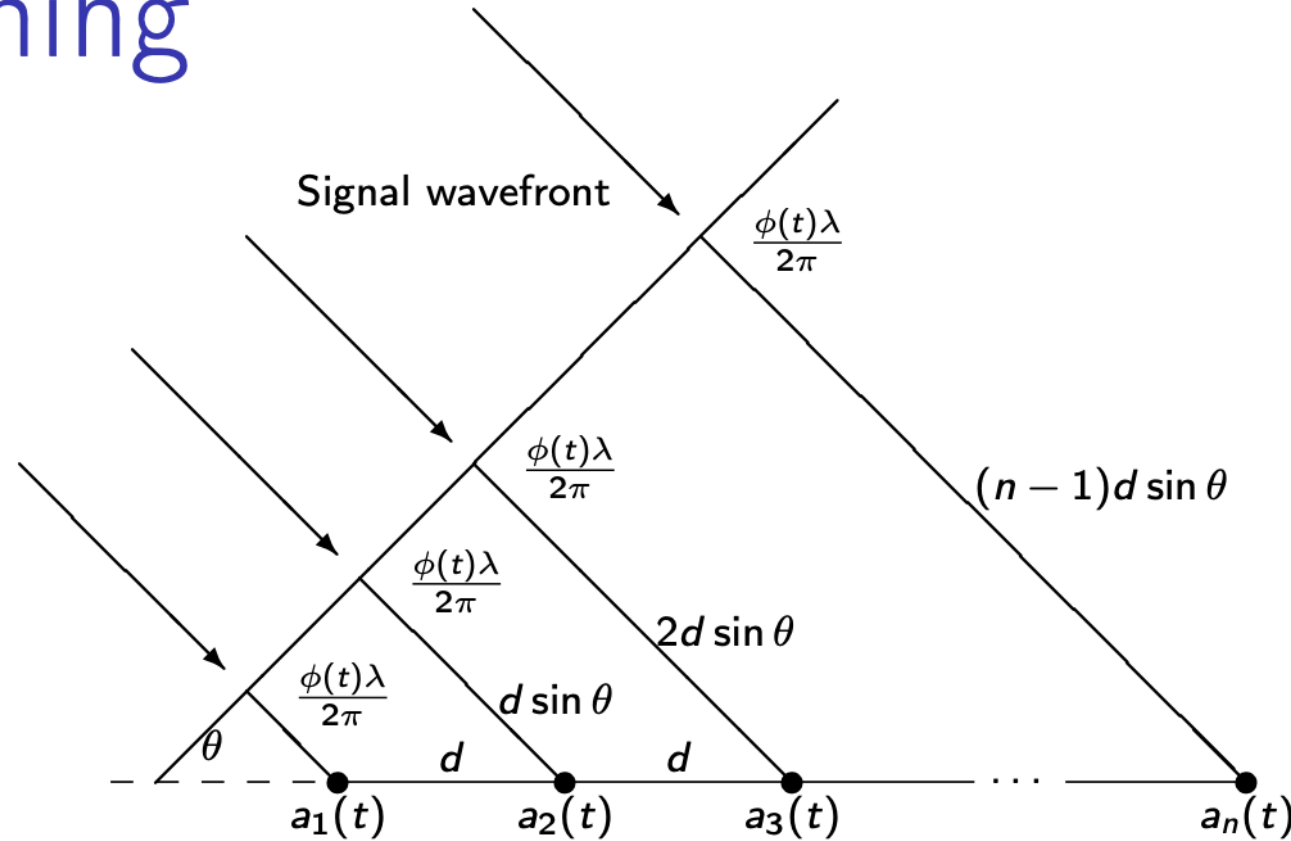
Test Setup



Agenda

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- **Theory and Implementation**
 - Linear algebra
 - Matrix decomposition: QR vs Cholesky
 - Latency vs. area tradeoffs
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 - HDL Coder implementation
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Beamforming



m samples, n antenna elements, $m \gg n$.

m -by- n data matrix A .

$a(t)$ is an n -by-1 column vector. $a(t)^H$ form the rows of A .

Unified notation

- A is the m -by- n data matrix
- $m \gg n$
- $A^H A$ is the n -by- n estimate of the covariance matrix

- $b = \begin{bmatrix} 1 \\ e^{(2\pi d/\lambda) \sin(\theta)i} \\ e^{2(2\pi d/\lambda) \sin(\theta)i} \\ \vdots \\ e^{(n-1)(2\pi d/\lambda) \sin(\theta)i} \end{bmatrix}$ is the steering vector

Minimum Variance Distortionless Response (MVDR) Beamformer

Covariance matrix solve
 $(A^H A)x = b$

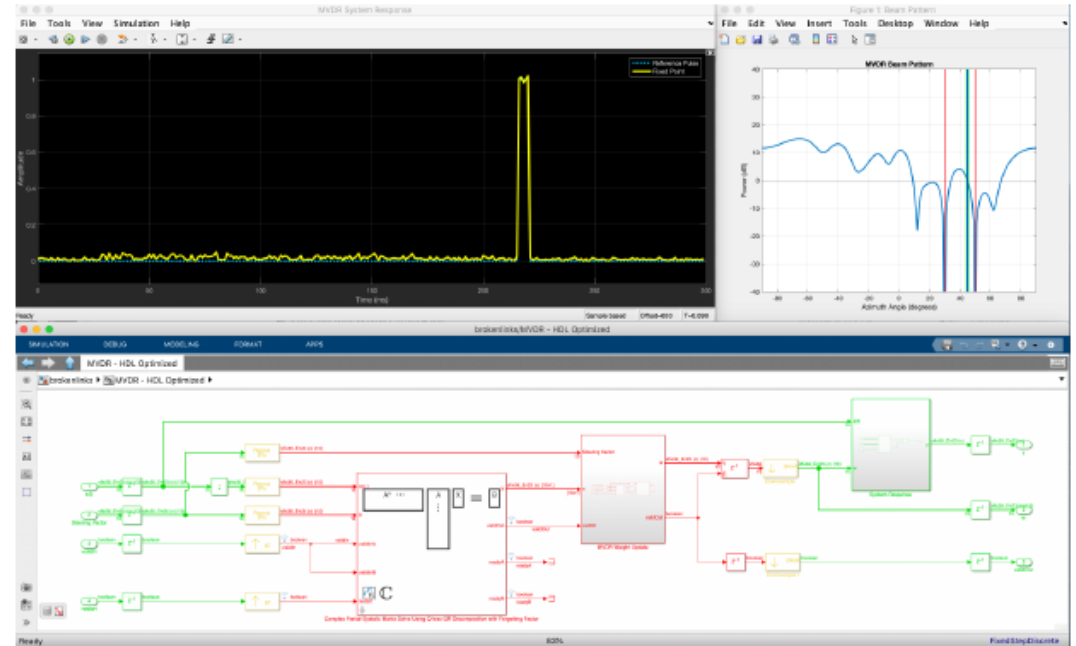
Example

MVDR weight vector

$$w = \frac{A^H x}{b^H x}$$

MVDR response

$$y = w^H a(t)$$



MVDR Beamformer in MATLAB

Covariance matrix solve

$$(A^H A)x = b$$

MATLAB

$$x = (A' * A) \backslash b;$$

MVDR weight vector

$$w = \frac{x}{b^H x}$$

$$w = x / (b' * x);$$

MVDR response

$$y = w^H a(t)$$

$$y = w' * a$$

Resist the urge to use inverse

Covariance matrix solve

$$(A^H A)x = b$$

MATLAB

$$x = (A' * A) \backslash b;$$

~~$$x = \text{inv}(A' * A) * b;$$~~

Inverses have problems with roundoff errors and high dynamic range.

- Roundoff errors. $3x = 21 \rightarrow x = 0.3333 \cdot 21 = 6.9993$
- Big numbers get small and may underflow. $10000x = 20000 \rightarrow x = 0.0001 \cdot 2000$
- Small numbers get big and may overflow. $0.0001x = 0.0002 \rightarrow x = 10000 \cdot 0.0002$

Cholesky factorization

Covariance matrix solve

$$(A^H A)x = b$$

MATLAB

$$R = \text{chol}(A' * A)$$

Forward and backward substitute

$$x = R \setminus (R' \setminus b)$$

Cholesky requires symmetric positive definite input, which $A^H A$ is.

$$R = \text{chol}(A' * A) \Rightarrow R \text{ is upper triangular and } R' * R = A' * A$$

Using QR decomposition without computing Q

Covariance matrix solve
 $(A^H A)x = b$

MATLAB

$[\sim, R] = \text{QR}(A, 0)$

Forward and backward substitute

$x = R \setminus (R' \setminus b)$

QR vs. Cholesky

Computing $A^H A$ squares the condition number of A ,
but may be better for faster updates in some hardware applications.

<code>R = fixed.qlessQR(A)</code>	<code>R = chol(A'*A)</code>
5.6648 2.3256 -0.8496	5.6648 2.3256 -0.8496
0 3.5967 -0.9131	0 3.5967 -0.9131
0 0 2.4822	0 0 2.4822

$$R = \text{chol}(A'A) \rightarrow A'A = R'R$$

$$[Q, R] = \text{qr}(A, 0) \rightarrow A'A = R'Q'QR = R'R$$

MATLAB Fixed-Point using Q-less QR

MATLAB

```
[~,R] = QR(A,0)
```

```
x = R\'(R\' \ b)
```

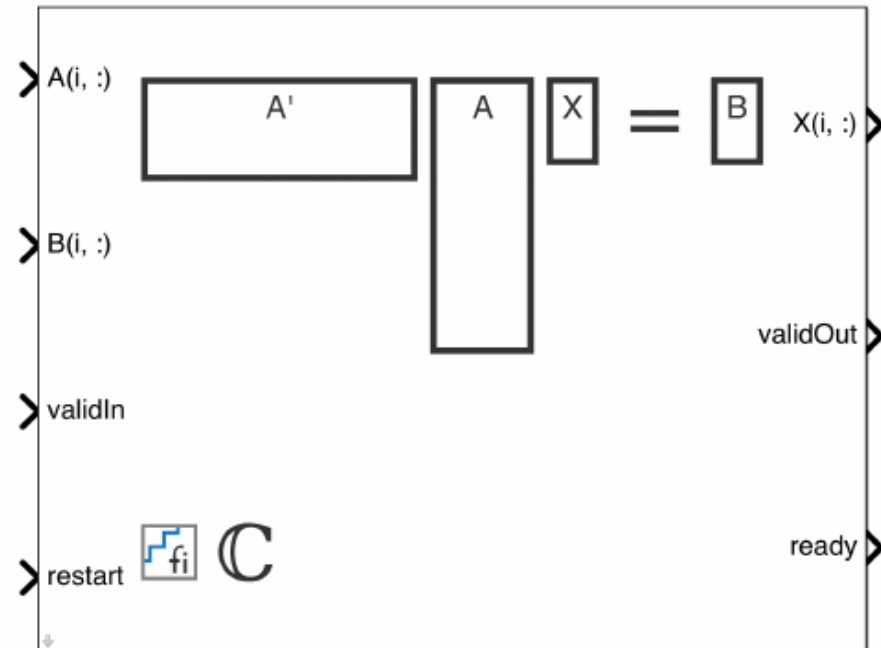
Fixed point

```
x = fixed.qlessQRMatrixSolve(A,b)
```

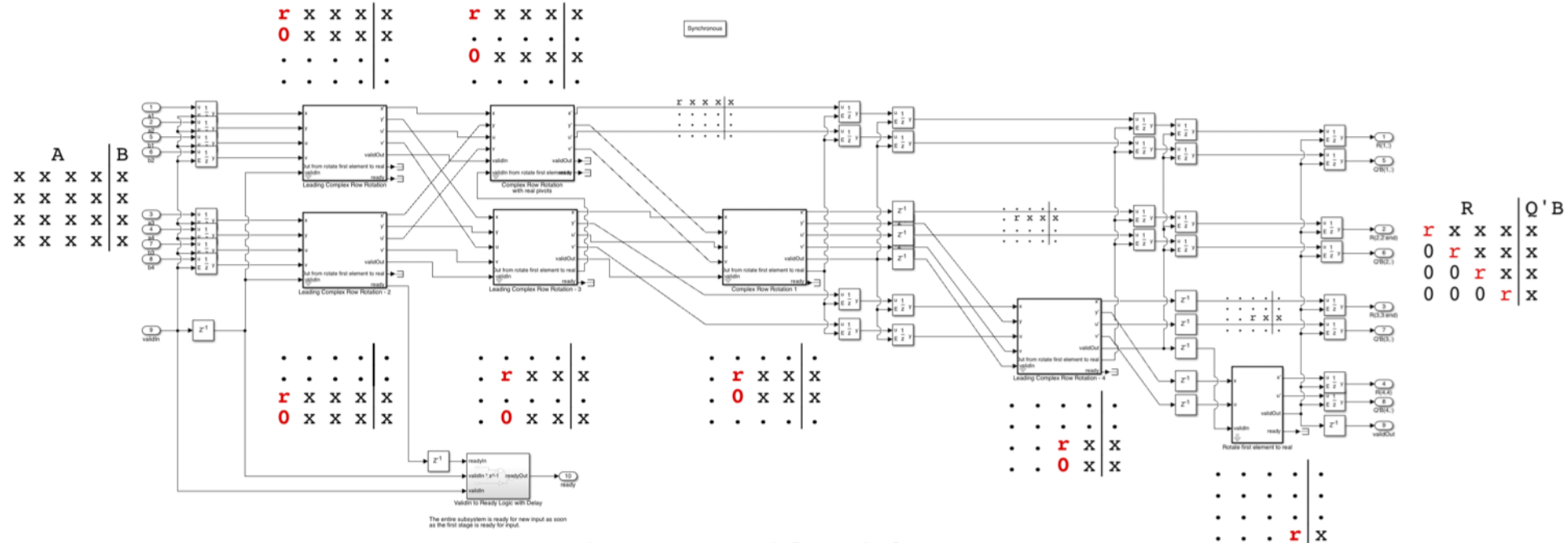

HDL-Optimized Simulink

Matrix Solve Using Q-less QR Decomposition

$$(A^H A)x = b$$



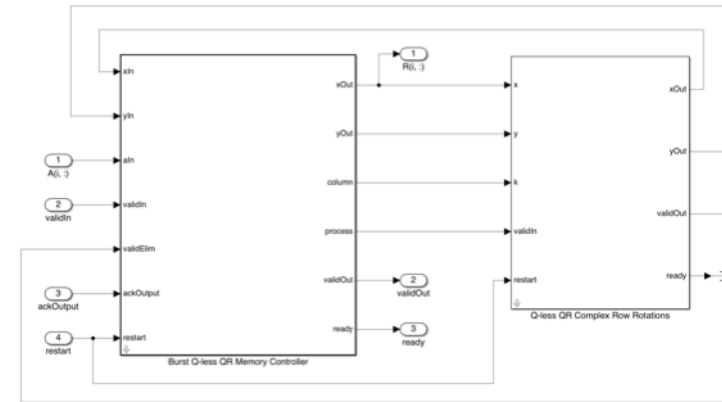
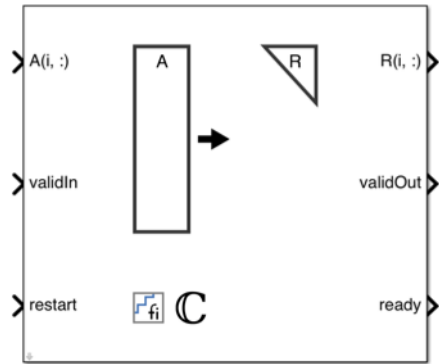
Systolic: One cell for each zero ($\mathcal{O}(mn)$ cells). High area, Low latency.



Complex 4x4 CORDIC Q'B, R

	Method	Input	Ready	Latency	Area	Release
	Systolic	Matrix	C	$\mathcal{O}(n)$	$\mathcal{O}(mn^2)$	R2019a Example
	Burst	Row	$\mathcal{O}(n)$	$\mathcal{O}(mn^2)$	$\mathcal{O}(n)$	R2020a Library blocks
	Partial-Systolic	Row	C	$\mathcal{O}(m)$	$\mathcal{O}(n^2)$	R2020b Library blocks
	Partial-Systolic with Forgetting Factor	Row	C	$\mathcal{O}(n)$	$\mathcal{O}(n^2)$	R2020b Library blocks

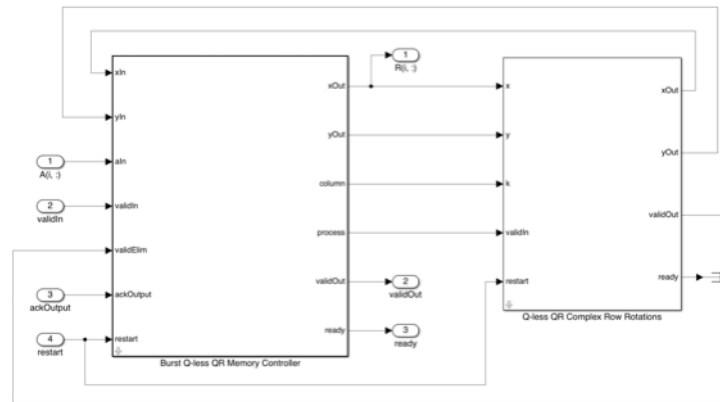
Burst: One cell for all zeros (1 cell). Low area, High latency.



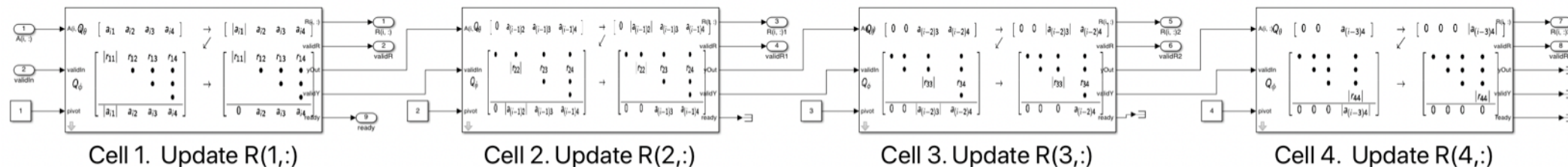
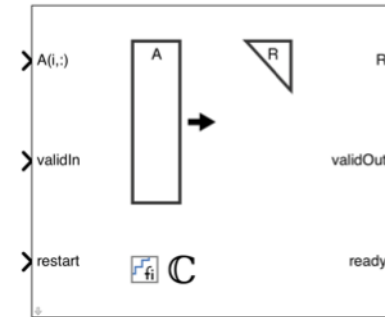
	<i>Method</i>	<i>Input</i>	<i>Ready</i>	<i>Latency</i>	<i>Area</i>	<i>Release</i>
	Systolic	Matrix	C	$\mathcal{O}(n)$	$\mathcal{O}(mn^2)$	R2019a Example
	Burst	Row	$\mathcal{O}(n)$	$\mathcal{O}(mn^2)$	$\mathcal{O}(n)$	R2020a Library blocks
	Partial-Systolic	Row	C	$\mathcal{O}(m)$	$\mathcal{O}(n^2)$	R2020b Library blocks
	Partial-Systolic with Forgetting Factor	Row	C	$\mathcal{O}(n)$	$\mathcal{O}(n^2)$	R2020b Library blocks

Partial-Systolic: (n cells). Medium area, Medium latency.

Cell internals



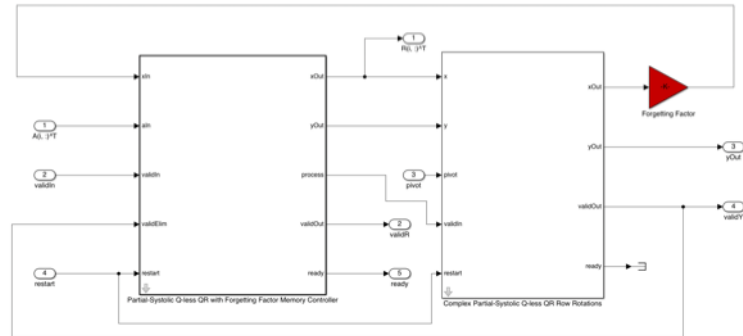
Block



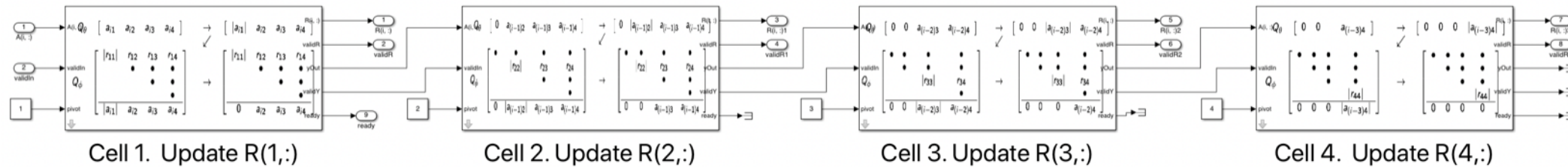
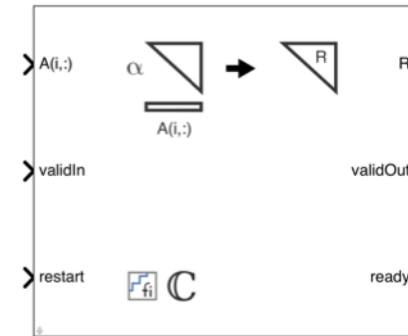
	Method	Input	Ready	Latency	Area	Release
	Systolic	Matrix	C	$\mathcal{O}(n)$	$\mathcal{O}(mn^2)$	R2019a Example
	Burst	Row	$\mathcal{O}(n)$	$\mathcal{O}(mn^2)$	$\mathcal{O}(n)$	R2020a Library blocks
	Partial-Systolic	Row	C	$\mathcal{O}(m)$	$\mathcal{O}(n^2)$	R2020b Library blocks
	Partial-Systolic with Forgetting Factor	Row	C	$\mathcal{O}(n)$	$\mathcal{O}(n^2)$	R2020b Library blocks

Partial-Systolic with Forgetting Factor (n cells): Continuously update

Cell internals with forgetting factor

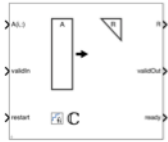


Block

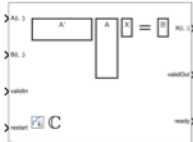


	<i>Method</i>	<i>Input</i>	<i>Ready</i>	<i>Latency</i>	<i>Area</i>	<i>Release</i>
	Systolic	Matrix	C	$\mathcal{O}(n)$	$\mathcal{O}(mn^2)$	R2019a Example
	Burst	Row	$\mathcal{O}(n)$	$\mathcal{O}(mn^2)$	$\mathcal{O}(n)$	R2020a Library blocks
	Partial-Systolic	Row	C	$\mathcal{O}(m)$	$\mathcal{O}(n^2)$	R2020b Library blocks
	Partial-Systolic with Forgetting Factor	Row	C	$\mathcal{O}(n)$	$\mathcal{O}(n^2)$	R2020b Library blocks

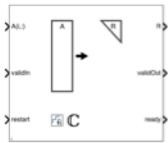
MATLAB functions



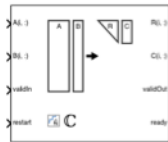
`fixed.qlessQR`



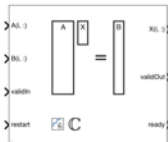
`fixed.qlessQRMatrixSolve`



`fixed.qlessQRUpdate`

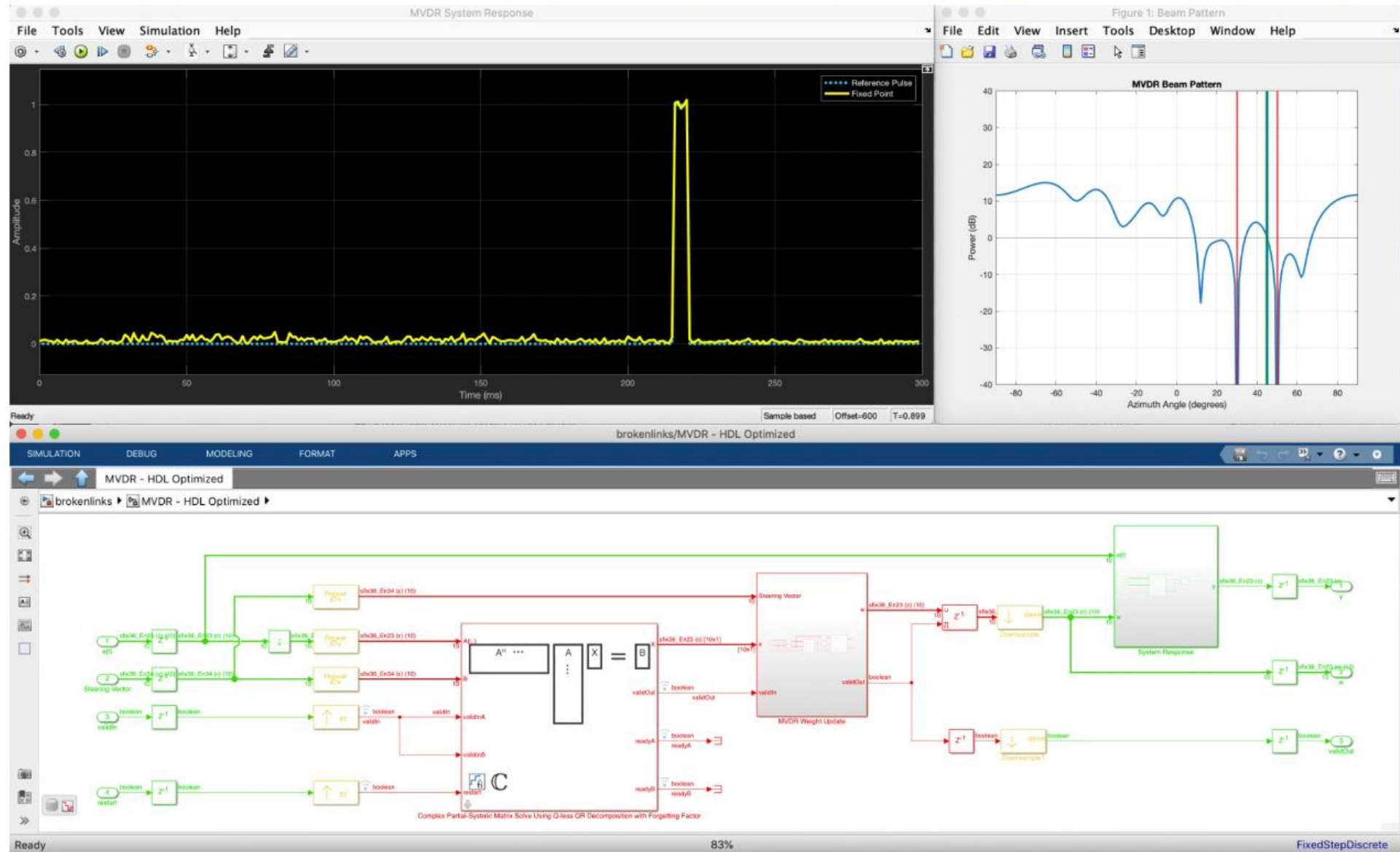


`fixed.qrAB`



`fixed.qrMatrixSolve`

White-box MVDR reference model in doc



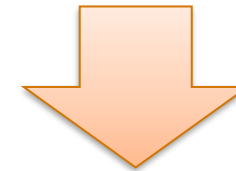
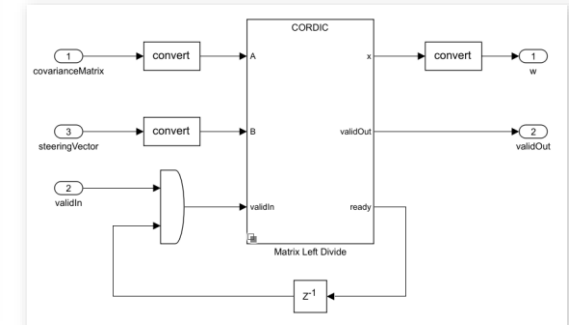
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- **HDL Coder Implementation**
 - HDL Coder implementation
 - Resource mapping and utilization

FPGA Implementation Challenges

- Fixed-Point Math
- Performance vs Area tradeoffs
- Data Rate vs Clock Rate
- Project Timeline

```
% the covariance matrix is defined as E{x.*conj(x)}
if size(C,2) == 1
    % MVD
    temp = qr(linsolve(x.',C));
    w = G*temp/(C'*temp);
else
    % LCMV
    if m >= n
        [temp,F] = qr(linsolve(x.',C));
        w = temp*qr(linsolve(F',G));
    else
        % when matrix is fat, F is no longer square and we cannot play the
        % trick of thin matrix. Therefore, we have to form R2 and use LU.
        temp = qr(linsolve(x.',C));
        R2 = C'*temp; % R2 = C'*R*(-1)*C
        [L2, U2] = lu(R2);
        temp2 = U2\((L2\G));
        w = temp*temp2;
    end
end
```



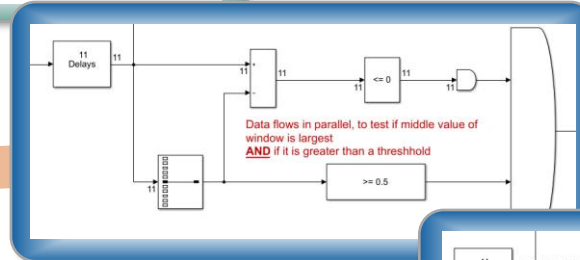
HDL Implementation Workflow

MATLAB
Reference

```
%% MATLAB reference detector
% this uses high level MATLAB functions
% computing a global maximum requires holding the entire signal at once
% this is impractical in a hardware implementation but serves as a golden
% reference

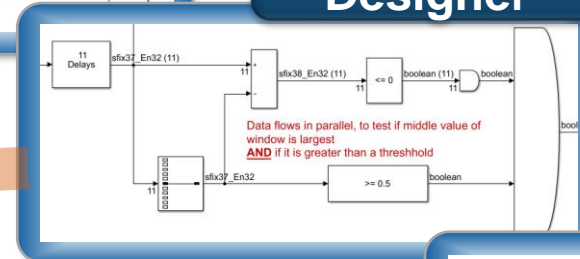
y=filter(CorrelationFilter,1,RxSignal); % correlate against the pulse
[peak, location]=max(abs(y).^2);
fprintf('Found Global Maximum at location %d Value %3.3f \n',location, peak)
```

Hardware
Architecture



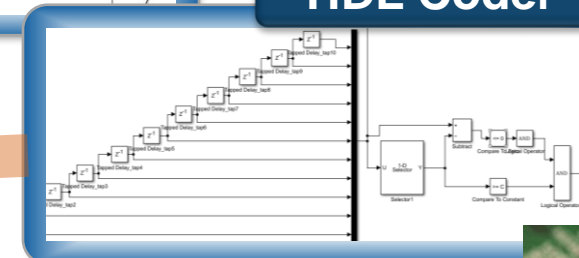
**Fixed Point
Designer**

Fixed-point
Implementation



HDL Coder

HDL Code Generation
and Optimization

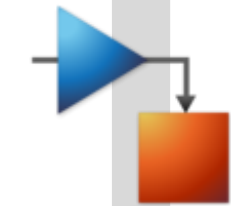


HDL Verification
and Targeting

Integrated Verification



MATLAB



Simulink



MATLAB MVDR reference code

```
function Y = mvdr_beamform(X, sv)
```

```
% form covariance matrix
```

```
EcX = X.'*conj(X);
```

```
% compute weight vector
```

```
wp = EcX\sv;
```

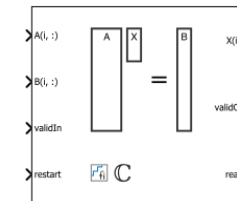
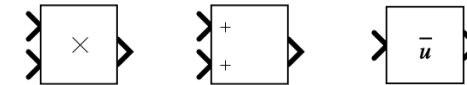
```
% normalize response
```

```
w = wp/(sv'*wp);
```

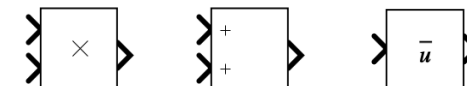
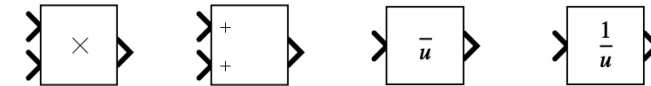
```
% form output beam
```

```
Y = X*w*conj(w);
```

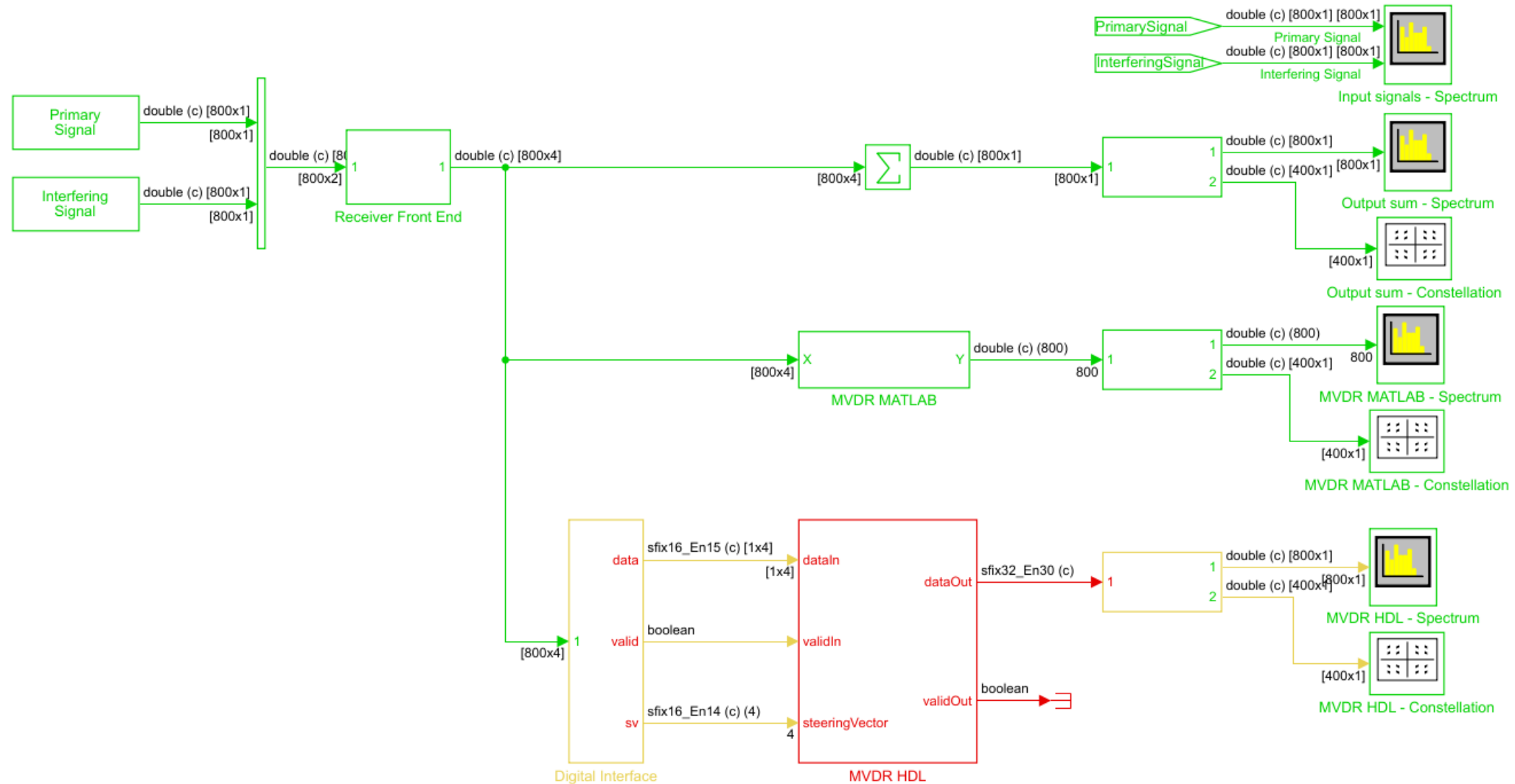
```
end
```



**100+ hours of
design time saved!**



HDL Implementation of MVDR Beamforming

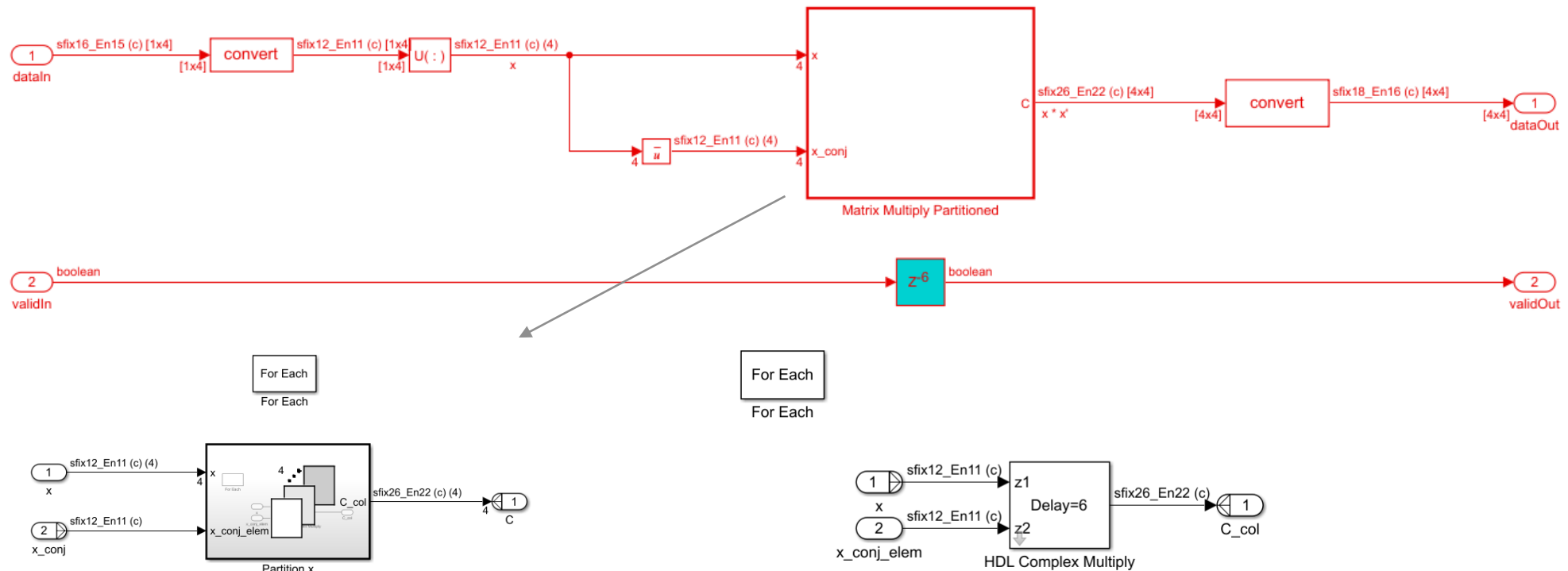




Form Covariance Matrix

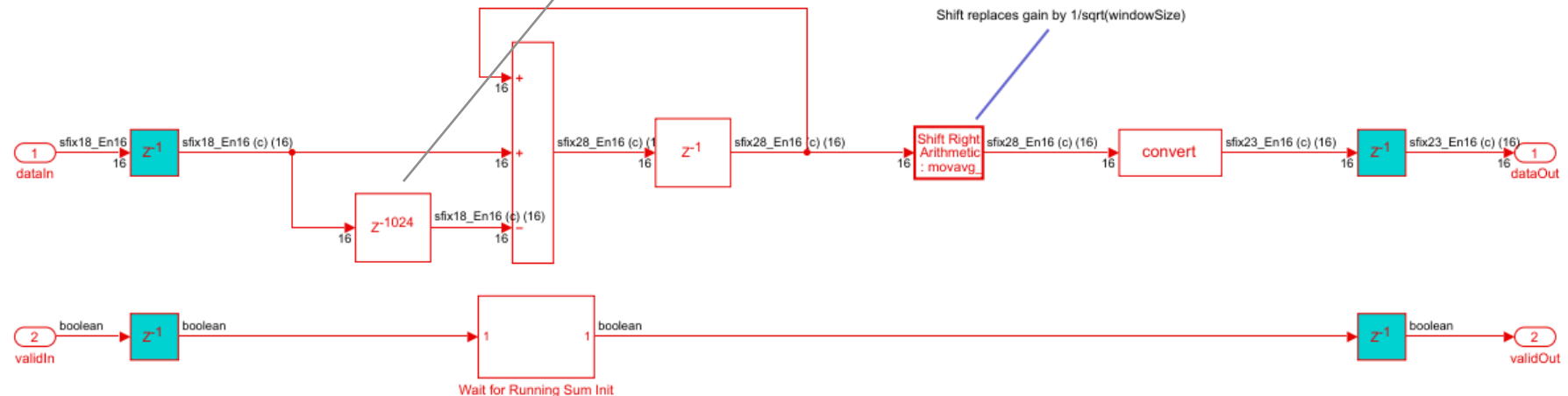
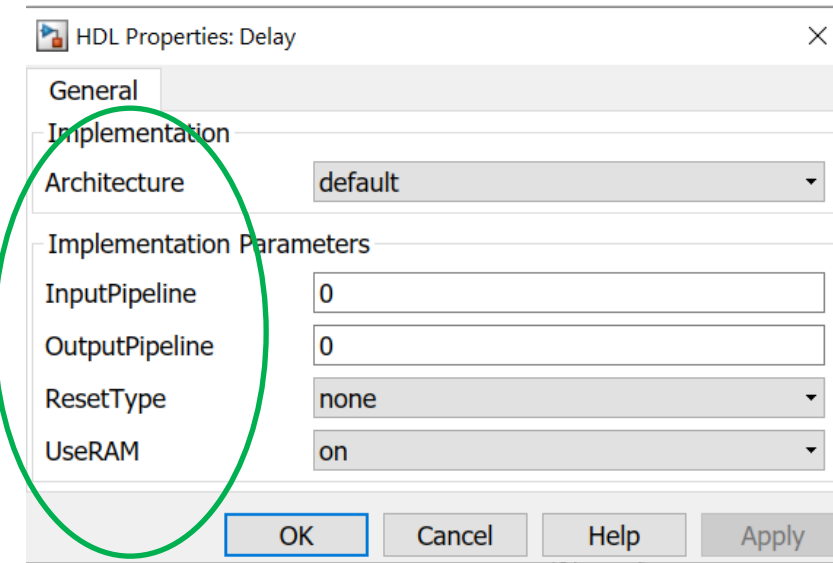
- For Each subsystem
 - Process elements independently
 - Concatenate results into outputs

```
% form covariance matrix
EcX = X.'*conj(X);
```



Moving Average

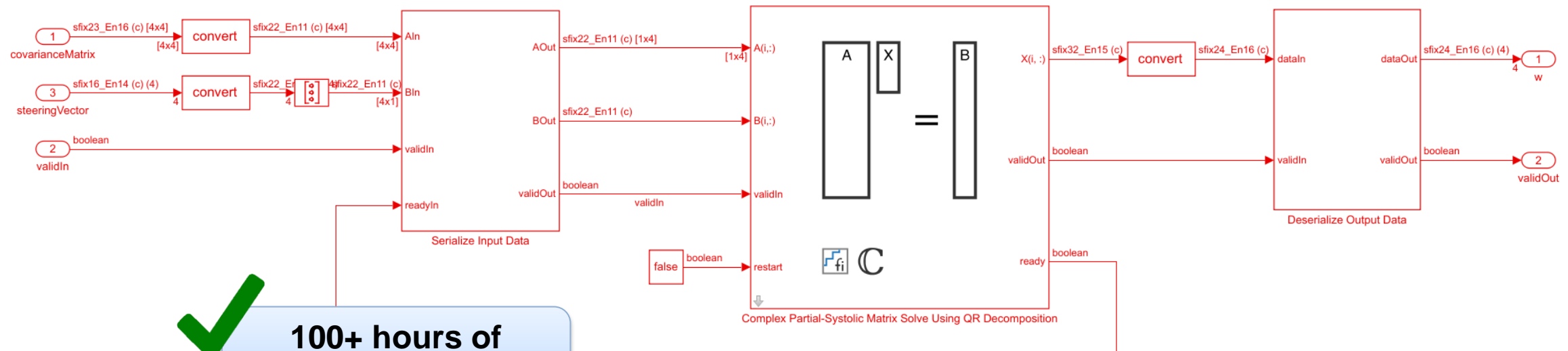
- Use HDL Implementation properties to map large delays to Block RAM



Compute Weight Vector

- Use Complex Matrix Solve block from Fixed-Point Matrix Linear Algebra Library

```
% compute weight vector
wp = Ecx\sv;
```



**100+ hours of
design time saved!**

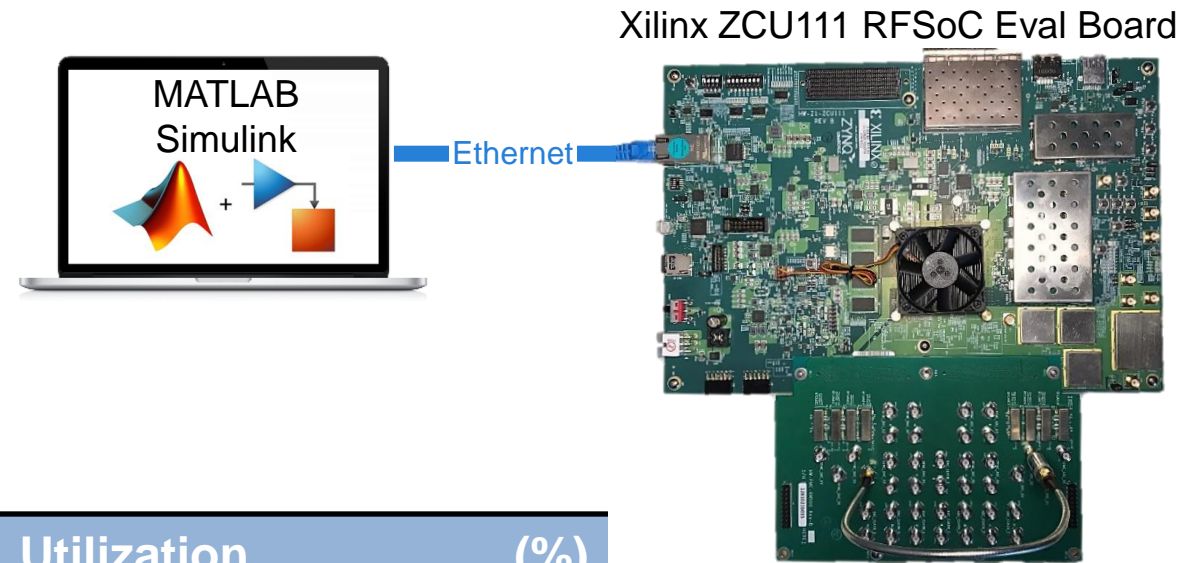
- ```
% normalize response
w = wp/(sv'*wp);
```



# Implementation Results

- Device: xczu28dr (ZCU111)
- Maximum frequency: 452 MHz
- Resource utilization:

| Resource | Utilization | (%)   |
|----------|-------------|-------|
| LUT      | 47K         | 11.13 |
| LUTRAM   | 989         | 0.5   |
| FF       | 40K         | 4.7   |
| BRAM     | 2           | 0.2   |
| URAM     | 10          | 12.5  |
| DSP      | 92          | 3.5   |



# Resources to Get Started and Speed Adoption

- Getting started:
  - [MATLAB Onramp](#)
  - [Simulink Onramp](#)
  - [HDL pulse detector self-guided tutorial](#) and [videos](#)
- Proof-of-concept guided evaluations
  - **FREE** support via weekly WebEx meetings using custom sample designs
  - MathWorks coaches customers on “how to fish” through weekly WebEx sessions
- Training & consulting services
  - [HDL code generation](#), [FPGA signal processing](#) & [Zynq programming](#) training courses
  - Consulting service on deep technical coaching, custom design / hardware and more

**INTRODUCING HDL CODER INTO WORKFLOW**

Training period, ~2 months

- Learning Simulink
- Testing HDL Coder
- Finding limitations in synthesis
- Finding workarounds for limitations

Implementation, 1 month

- Design of custom components
- High level design of signal processing ch

Integration, 1 week

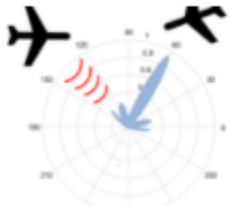
- Include generated code in FPGA framev
- Resolve timing issues

**BENEFITS**

- › A single model for simulation and code generation
  - No hand offs between systemization and implementation
  - Ready for FPGA as soon as simulation works
- › Short iterations for changes in design
- › Simulink block diagram resembles “manager level” power points
  - Drawback: makes it look a bit too easy
- › FPGA implementation done by person with limited VHDL competence

Tomas Andersson  
Ericsson

# Beamforming Demonstration



## FPGA-Adaptive-Beamforming-and-Radar-Examples

version 1.0.0.0 (6.87 MB) by Daren Lee **STAFF**

FPGA/HDL demonstrations for beamforming and radar designs.

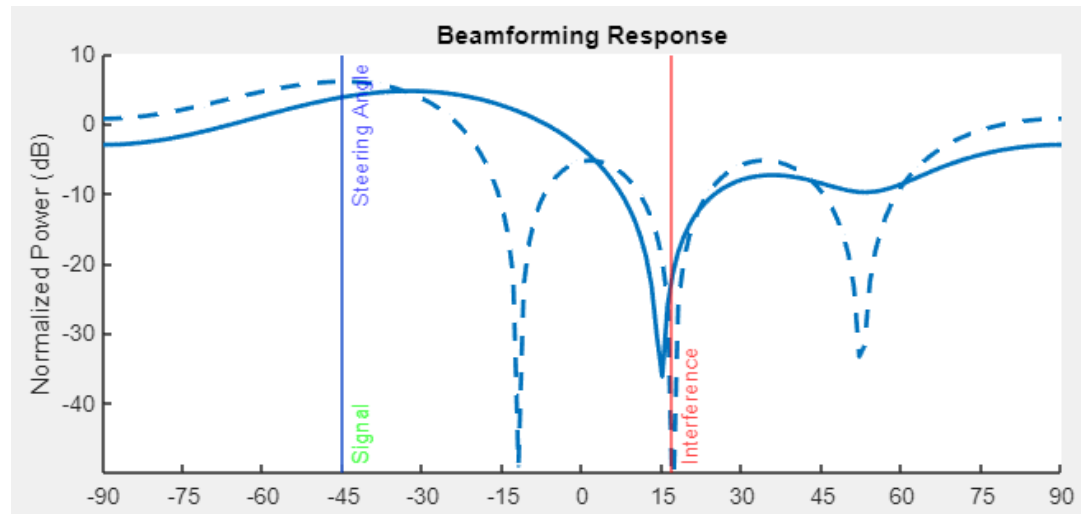
★★★★★ 2 Ratings

30 Downloads ⓘ

Updated 31 Mar 2021

From GitHub

- ZCU111 RFSoc Adaptive Beamformer demo for 4x4 matrix solve for 4 channel ADC/DAC
- Places nulls in interference locations and maximizes beam pattern for steering direction
- Interactively steer angles for interference and beam pattern at run-time



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