First order Tailor series approximation
$$h(\omega) = g(\omega^{\circ}) + \overline{d}\omega g(\omega) \cdot (\omega - \omega^{\circ})$$

$$h(\overline{\omega}) = g(\overline{\omega}^{\circ}) + \overline{7}g(\overline{\omega}^{\circ})^{T}(\overline{\omega} - \omega^{\circ})$$
Gradient descent
$$\overline{\omega}^{k} = \overline{\omega}^{k+1} - \alpha \overline{7}g(\overline{\omega}^{k+1})$$
we

Second order Taylor series approximation
$$h(\omega) = g(\overline{v}) + (\overline{d}ug(v))(\omega - v) + \frac{1}{2}(\overline{d}u^{2}g(v))(\omega - v)^{2}$$

$$h(\overline{\omega}) = g(\overline{v}) + \overline{7}g(\overline{v})^{T}(\overline{\omega} - \overline{v}) + \frac{1}{2}(\overline{\omega} - \overline{v})^{T} \overline{7}g(\overline{v})(\overline{\omega} - v)^{2}$$

$$h(\overline{\omega}) = g(\overline{v}) + \overline{7}g(\overline{v})^{T}(\overline{\omega} - \overline{v}) + \frac{1}{2}(\overline{\omega} - \overline{v})^{T} \overline{7}g(\overline{v})(\overline{\omega} - v)^{2}$$

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Mourton's mothed. h(w)=9(wk-1)+(dug(wk-1))(w-wk-1)+2(dw-g(wk-1))

1 (w-wk-1)2

$$h(w) = g(w^{k-1}) + \left(\frac{d}{dw}g(w^{k-1})\right)(w-w^{k-1}) + \frac{1}{2}\left(\frac{d}{dw}g(w^{k-1})\right)$$

$$\Rightarrow w^{k} = w^{k-1} - \frac{d}{dw}g(w^{k-1})$$

$$= \frac{d^{2}}{dw^{2}}g(w^{k-1})$$

h(w)= g(wk1) + 89(wk-1) (w-wk1)+ 1/2(w-wk1)T ¥9(w*+)(w-wk+) => wk= wk-1-(vg(wk-1))-1vg(wk-1)

Newton's method produces a sequence of points \overline{w}^1 , \overline{w}^2 , that minimize cost function g by repeatedly creating the second order Taylor series quadratic approximation to the function, and traveling to a stationary point of this quadratic. Because Newton's method uses quadratic as opposed to linear approximation at each step, with a quadratic more closely mimicking the associated function, it is often much more effective than gradient descent in the sense that it requires for fewer steps for convergence.

arxu symmetric If it satisfies ZTQZ >0 For all Z then it-must have all non-negative eigenvalues. Proof: Q= ZXiXiT ZT (ZX,X,T) ZT = Z ZTX, X,TZ if $\vec{b}_i = \vec{x}_i \vec{z}$ = \(\bar{b}_1 \bar{b}_1 = \bar{b}_1 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_1 \bar{b}_2 \bar{b}_2 \bar{b}_1 \bar{b}_2 \bar{b}_1 \bar{b}_2 \bar{b}_2 \bar{b}_2 \bar{b}_1 \bar{b}_2 .. Q positive definite. Take the general multi-imput quadrative function. g(w) = a+ bTn+ WCn Where C is an NXN symmetric matrix, I'v. an NXI rector, and a is a scalar. Computing the first derivative (gradhent) we have との(W=2cn+b (cm=-もり) $\nabla^2 g(\bar{w}) = 2\bar{C}$.