

Research Interest

My research focuses on Computer Vision & Robotics. My goal is to develop embodied, active and intelligent agents in the real and open world through interactive learning. I am actively looking for a PhD position starting from 2024 Fall.

Education

Tongji University Shanghai, China

B.ENG. IN COMPUTER SCIENCE, COLLEGE OF ELECTRONIC & INFORMATION ENGINEERING

Sep. 2019 - Jun. 2024 (expected)

University of California San Diego

VISITING STUDENT SCHOLAR AT SU LAB, JACOBS SCHOOL OF ENGINEERING

• Advisor: Prof. Hao Su

California, USA Mar. 2023 - Present

Beijing, China

Peking UniversityVisiting Student Scholar at Center on Frontiers of Computing Studies

· Advisor: Prof. He Wang

Mar. 2022 - Present

Publication

*: equivalent contribution, †: corresponding author(s)

[C2] 3D-Aware Object Goal Navigation via Simultaneous Exploration and Identification [Paper Link]

Jiazhao Zhang*, **Liu Dai***, Fanpeng Meng, Qingnan Fan, Xuelin Chen, Kai Xu, He Wang[†]

Accepted to IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR) 2023

[C1] Discovering Novel Categories in SAR Images in Open Set Conditions [Paper Link]

Liu Dai, Weiwei Guo[†], Zenghui Zhang, Wenxian Yu

Accepted to IEEE/GRSS International Geoscience and Remote Sensing Symposium (IGARSS) 2022, Oral

Research Experience _____

University of California San Diego

California, USA

RESEARCH INTERN AT SU LAB, ADVISED BY PROF. HAO SU

Mar. 2023 - Present

Project: Environment Generation and Construction for Full-Physical Simulation of Embodied AI Tasks [On-Going]

· Aim to develop interactive simulation environment which is rich in scene layouts and object diversity for full-physical embodied AI tasks.

Peking University Beijing, China

RESEARCH INTERN AT EPIC LAB, ADVISED BY PROF. HE WANG

Mar. 2022 - Present

Project: Active 3D Scene Understanding & Object Goal Navigation [C2]

- Proposed the first 3D-aware framework for the challenging Object Goal Navigation task, empowered by two simultaneously running subpolicies: corner-guided exploration policy and category-aware identification policy. By this dedicated design, we overcame the challenge of low sample efficiency in RL and high computational cost when leveraging 3D data for training navigation skills.
- I conducted part of method design, coding, writing and the most of plotting. This project piqued my interest in Embodied-Al and comprehensively improved my ability in coding, writing and plotting.

Project: Mobile Manipulation in Real World [On-Going]

• Aim to build active agents with strong navigation and manipulation skills in the real world.

Tongji-MIT City Science Lab

Shanghai, China

Sep. 2021 - Mar. 2022

RESEARCH INTERN, ADVISED BY PROF. WEIWEI GUO Project: Remote Sensing Image Interpretation in the Open & Challenging World [C1]

- Proposed a multi-stage framework for Novel Category Discovery of remote sensing images: first self-supervisedly train a representation extractor, taking the best of both worlds of the labelled and unlabelled data, and then estimate the number of novel classes and cluster the unknown data based on open-set detection.
- This is the first research project I had and it piqued my research interest in the setting of Open-World. I undertook the most of coding, writing and plotting independently.



Course 55010501: Opensource Hardware and Programming

Tongji University

TEACHING ASSISTANT FOR PROF. XIAOHUA SUN IN COLLEGE OF DESIGN AND INNOVATION

2021 Fall

· Delivered courses on Python & Arduino, guided undergraduate students to design and implement their Art projects through coding.

Honors & Awards

PERSONAL HONORS

2023 Pursuit of Excellence Scholarship with 50000¥ (\approx 7000\$)

Tongji University

- Highest Honor for All Members of Tongji University (10/43106, among faculty, students & admin staff).

2022 **SenseTime Scholarship** with 20000¥ (\approx 3000\$)

SenseTime Co.,Ltd.

- Nationwide Selected 30 Undergraduates in the Field of Al.

2022 Tongji Academic Star

Tongji University

- Highest Honor for All Undergrads at Tongji University (15/18536).

COMPETITION ACHIEVEMENTS

2021 National First Prize of Challenge Cup Competition: Research Track

Project: We built a pest detection system based on deep learning to help the agricultural workers in the less-developed rural area in China, where there is a great lack of experts on pest detection and the farmhand could only diagnose based on some folk prescription before.

- Most Influential Research Competition among University Students in China.
- Best Record in College History.
- Team Leader.
- 2023 National Silver Award of Challenge Cup Competition: Entrepreneurship Track
 - Best Record in College History.
 - Team Leader.
- 2022 **Gold Award in Shanghai** of *Internet*+ Competition
 - Team Leader.
- 2020 **University Champion** of FLTRP Cup National English Public Speaking Contest

Skills

Programming C/C++, Python, LaTex, HTML & CSS, SQL, Arduino, Bash

Frameworks Pytorch, NumPy, OpenCV, Open3D, trimesh, Habitat Simulator

Others Public Speaking and Presentation

Languages _

Chinese Native
English Fluent
French Preliminary