

Research Interest

My research focuses on Embodied AI. My goal is to build active and intelligent agents in the real and open world, through developing both stronger agent skills and more powerful simulators for embodied tasks.

Education

Tongji University Shanghai, China

B.ENG. IN COMPUTER SCIENCE, COLLEGE OF ELECTRONIC & INFORMATION ENGINEERING

Sep. 2019 - Jun. 2024 (expected)

• GPA: 88.0 / 100, Overall Ranking: 10 / 120

University of California San Diego

California, USA

Mar. 2023 - Present

• Advisor: Prof. Hao Su

Peking University

Beijing, China

VISITING STUDENT SCHOLAR AT CENTER ON FRONTIERS OF COMPUTING STUDIES

VISITING STUDENT SCHOLAR AT SU LAB, JACOBS SCHOOL OF ENGINEERING

Mar. 2022 - Present

Advisor: Prof. He Wang

Publication

*: equivalent contribution, †: corresponding author(s)

[C2] 3D-Aware Object Goal Navigation via Simultaneous Exploration and Identification [Paper Link]

Jiazhao Zhang*, **Liu Dai***, Fanpeng Meng, Qingnan Fan, Xuelin Chen, Kai Xu, He Wang[†]

Accepted to IEEE/CVF Computer Vision and Pattern Recognition Conference (CVPR) 2023

[C1] Discovering Novel Categories in SAR Images in Open Set Conditions [Paper Link]

Liu Dai, Weiwei Guo[†], Zenghui Zhang, Wenxian Yu

Accepted to IEEE/GRSS International Geoscience and Remote Sensing Symposium (IGARSS) 2022, Oral

Research Experience _____

University of California San Diego

California, USA

RESEARCH INTERN AT SU LAB, ADVISED BY PROF. HAO SU

Mar. 2023 - Present

Project: Environment Generation and Construction for Full-Physical Simulation of Embodied AI Tasks [On-Going]

Aim to build interactive simulation environment which is rich in scene layouts and object diversity for full-physical embodied AI tasks.

Peking University Beijing, China

RESEARCH INTERN AT EPIC LAB, ADVISED BY PROF. HE WANG

Mar. 2022 - Present

Project: Active 3D Scene Understanding & Object Goal Navigation [C2]

- Proposed the first 3D-aware framework for the challenging Object Goal Navigation task, empowered by two simultaneously running subpolicies: corner-guided exploration policy and category-aware identification policy. By this dedicated design, we overcame the challenge of low sample efficiency in RL and high computational cost when leveraging 3D data for training navigation skills.
- I conducted part of method design, coding, writing and the most of plotting. This project piqued my interest in Embodied-AI and comprehensively improved my ability in coding, writing and plotting.

Project: Mobile Manipulation in Real World [On-Going]

• Aim to build active agents with strong navigation and manipulation skills in the real world.

Tongji-MIT City Science Lab

Shanghai, China

RESEARCH INTERN, ADVISED BY PROF. WEIWEI GUO Sep. 2021 - Mar. 2022

Project: Remote Sensing Image Interpretation in the Open & Challenging World [C1]

- Proposed a multi-stage framework for Novel Category Discovery of remote sensing images: first self-supervisedly train a representation extractor, taking the best of both worlds of the labelled and unlabelled data, and then estimate the number of novel classes and cluster the unknown data based on open-set detection.
- This is the first research project I had and it piqued my research interest in the setting of Open-World. I undertook the most of coding, writing and plotting independently.



Course 55010501: Opensource Hardware and Programming

Tongji University

TEACHING ASSISTANT FOR PROF. XIAOHUA SUN IN COLLEGE OF DESIGN AND INNOVATION

2021 Fall

· Delivered courses on Python & Arduino, guided undergraduate students to design and implement their Art projects through coding.

Honors & Awards

PERSONAL HONORS

2023 **Pursuit of Excellence Scholarship** with $50000 \text{¥} (\approx 7000 \text{\$})$

Tongji University

- Highest Honor for All Members of Tongji University (10/43106, among faculty, students & admin staff).

2022 **SenseTime Scholarship** with 20000¥ (\approx 3000\$)

SenseTime Co.,Ltd.

- Nationwide Selected 30 Undergraduates in the Field of Al.

2022 Tongji Academic Star

Tongji University

- Highest Honor for All Undergrads at Tongji University (15/18536).

COMPETITION ACHIEVEMENTS

2021 National First Prize of Challenge Cup Competition: Research Track

Project: We built a pest detection system based on deep learning to help the agricultural workers in the less-developed rural area in China, where there is a great lack of experts on pest detection and the farmhand could only diagnose based on some folk prescription before.

- Most Influential Research Competition among University Students in China.
- Best Record in College History.
- Team Leader.
- 2023 National Silver Award of Challenge Cup Competition: Entrepreneurship Track
 - Best Record in College History.
 - Team Leader.
- 2022 **Gold Award in Shanghai** of *Internet*+ Competition
 - Team Leader.
- 2020 University Champion of FLTRP Cup National English Public Speaking Contest

Skills

Programming C/C++, Python, LaTex, HTML & CSS, SQL, Arduino, Bash

Frameworks Pytorch, NumPy, OpenCV, Open3D, trimesh, Habitat Simulator

Others Public Speaking and Presentation

Languages_

Chinese Native
English Fluent
French Preliminary

Entrepreneurship

I am the co-founder of **LunarAI**, an AI-Empowered Start-Up for Modern Agriculture.