

一点课 One Point Lesson

分类： 基础知识 ☐ 工作技巧 ☒ 改善提案 ☐ 问题解决 ☐ 设备保养维护 ☐ 其他 ☐

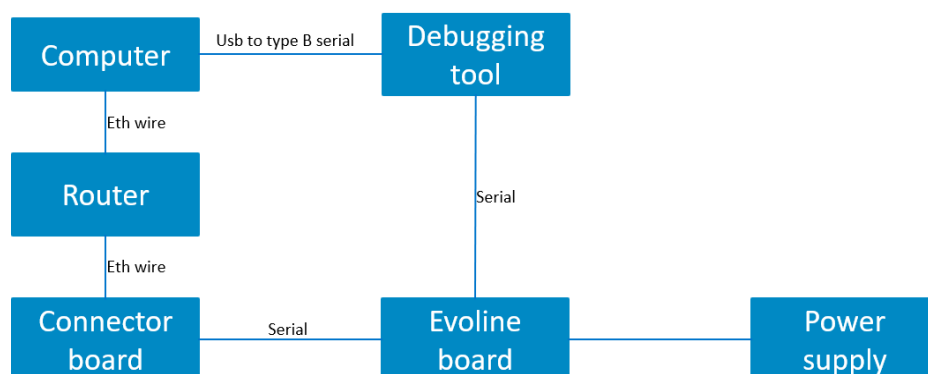
编号		部门	RD
主题	如何烧录 UBOOT 和 YOCTO 进 EVOLINE 主板并配置主 板	制作人	Louris
		批 准	

Equipment requirements

- Evoline main board
- Connector board
- Power supply
- Debugging tool
- Router

Equipment setup

- Power supply set to 18V and 2A output
- Connect equipments as following picture:



- Download tftpd-hpa in ubuntu by `sudo apt-get install tftpd-hpa`
open file `sudo vim /etc/default/tftpd-hpa` to check your default TFTP_DIRECTORY
modify the permission of TFTP_DIRECTORY to 777 by `chmod 777 your_TFTP_DIRECTORY`
- Save your U-BOOT and Yocto images in the TFTP_DIRECTORY, here taking `u-boot-dtb-mx6evomon_dev.imx` and `iv.wicas` an example: (`/srv/tftp` is my

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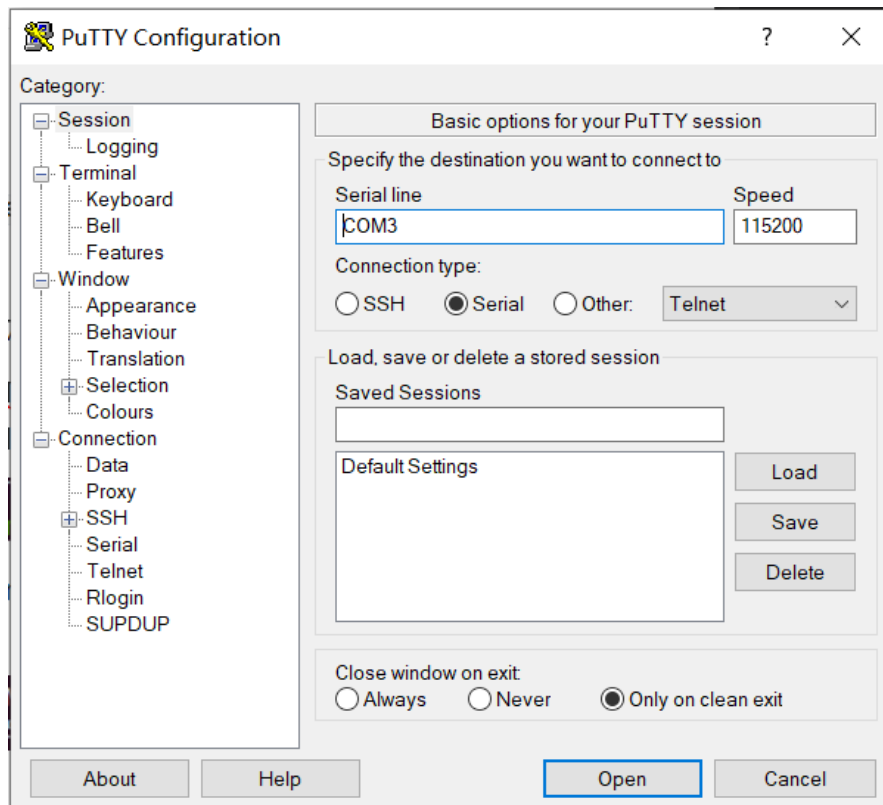
TFTP_DIRECTORY)

```
liu@liu:/srv/tftp$ ls
iv.wic  u-boot-dtb-mx6evomon_dev.imx
```

- Check your VM IP by typing `ifconfig` in terminal, taking it as the `serverip` (192.168.72.131 is my `serverip`)

```
ens38: flags=4163<UP,BROADCAST,RUNNING,MULTICAST>  mtu 1500
        inet 192.168.72.131  netmask 255.255.255.0  broadcast 192.168.72.255
```

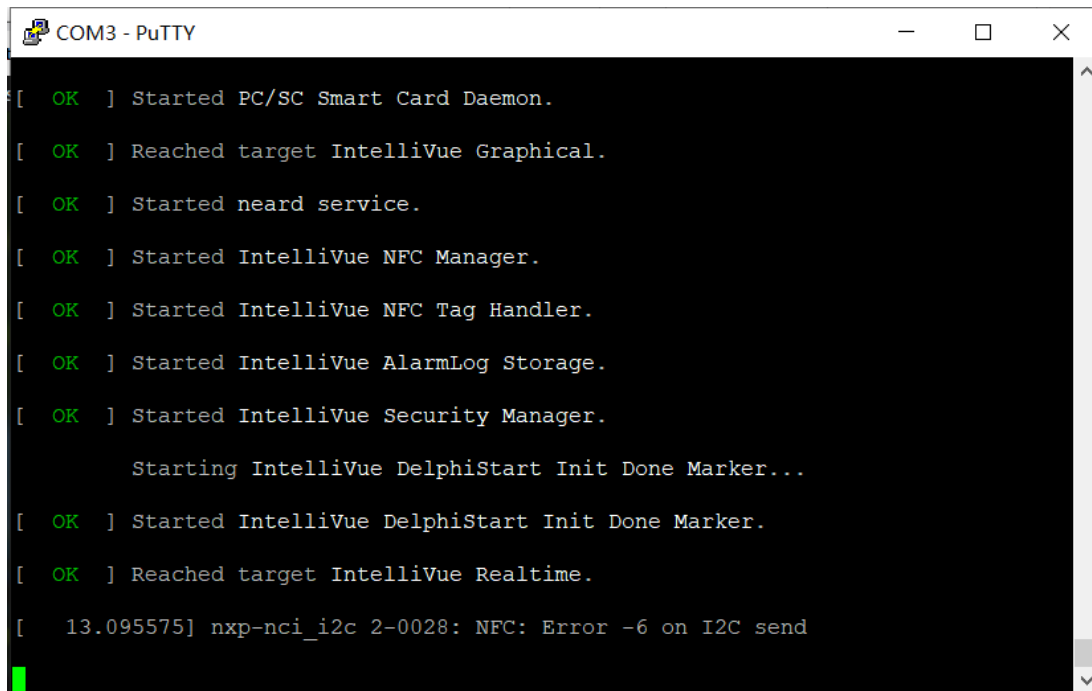
- Download `PUTTY` and setup as following:



where the Serial line `COM3` is the PC USB port which connected to the debugging tool `console to computer` and it could be different from each other's PC.

- Turn on the power supply and open the `PUTTY` and you should see rolling information in `PUTTY` :

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```
COM3 - PuTTY

[ OK ] Started PC/SC Smart Card Daemon.
[ OK ] Reached target IntelliVue Graphical.
[ OK ] Started neard service.
[ OK ] Started IntelliVue NFC Manager.
[ OK ] Started IntelliVue NFC Tag Handler.
[ OK ] Started IntelliVue AlarmLog Storage.
[ OK ] Started IntelliVue Security Manager.

Starting IntelliVue DelphiStart Init Done Marker...
[ OK ] Started IntelliVue DelphiStart Init Done Marker.
[ OK ] Reached target IntelliVue Realtime.
[ 13.095575] nxp-nci_i2c 2-0028: NFC: Error -6 on I2C send
```

- Once the rolling is stop and showing `restart at 3 seconds`, you should key `osum` to enter bootloader command-line **AS SOON AS POSSIBLE**. Once enter the command-line, there will be a time limit for operation, if you meet the time limit, the system will be reboot.

Images Flashing

- Enter the command line of EVOLINE board, keying `usb start`
- Set up the environment by using

```
setenv ipaddr 192.168.1.102 setenv gatewayip 192.168.1.1 setenv serverip
192.168.72.131
```

the `ipaddr` is the ip address for your main board and it can be modify by yourself `192.168.1.xxx`, here `102` is for example.

`serverip` is the ip for your VM as mentioned above.

- Key `saveenv` to save environment and `printenv` can check your environment setting
- To flash your UBOOT image, keying `tftp`

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192.168.72.131:u-boot-dtb-mx6evomon_dev.imx

the UBOOT image in your TFTP_DIRECTORY will be transmitted to the main board.

Then, keying `sf probe 2:0; sf erase 0 70000; sf write ${loadaddr} 400 70000`

- To flash Yocto, keying `tftp 192.168.72.131:iv.wic mmc write ${loadaddr} 0 0x457fe`

`0x457fe` is the size of your yocto image divided to 512 and changed to hex, and it should be dividable to 512.

There should be some information showing that flashing is done.

- If flash successfully, restart you board, the UBOOT should be able to jump to linux kernal, if not, please keying

```
setenv bootcmd 'run basicargs; run mmcargs; ext2load mmc 0:1 ${loadaddr} zImage;
ext2load mmc 0:1 ${fdt_addr} imx6dp-calimon.dtb; bootz ${loadaddr} - ${fdt_addr}'
setenv mmcrootfstype ext4 rootwait saveenv
```

- `printenv` to check the following variables are correct:
 - `mmcargs=setenv bootargs ${bootargs} root=${mmcroot}`
 - `rootfstype=${mmcrootfstype}`
 - `mmcroot=/dev/mmcblk0p2 ro`
 - `mmcrootfstype=ext4 rootwait`
 - `bootcmd=run basicargs; run mmcargs; ext2load mmc 0:1 ${loadaddr} zImage; ext2load mmc 0:1 ${fdt_addr} imx6dp-calimon.dtb; bootz ${loadaddr} - ${fdt_addr}`

if not the same, can use `setenv` to setup.

- `saveenv` to save all once modify.

Linux system setup in board

- Once all images flashed successfully, it will jump to linux kernel, and when it stops, you need to key in `root`

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```
root@genericiv32:
```

then you enter the linux system on board.

- Keying `ip a` to check all available netcard, select your netcard and key `cd /etc/systemd/network`, then `vi 10-wired-static.network` and input the content as follow:

```
[Match]
```

```
Name= the available netcard name you choose
```

```
[Network]
```

```
DHCP=ipv4
```

if system output `Read file system only`, key `mount -o remount,rw /` to overwrite the system.

Keying `systemctl restart systemd-networkd` and `systemctl enable systemd-networkd` to restart and enable your setup.

- Generate ssh keys with command:

```
cd /etc/ssh
```

```
ssh-keygen -t rsa -f ssh_host_rsa_key
```

```
ssh-keygen -t ecdsa -f ssh_host_ecdsa_key
```

```
ssh-keygen -t ed25519 -f ssh_host_ed25519_key
```

- `vi /etc/ssh/sshd_config_readonly` and modify the following content:

```
#HostKey /etc/ssh/ssh_host_rsa_key
#HostKey /etc/ssh/ssh_host_ecdsa_key
#HostKey /etc/ssh/ssh_host_ed25519_key
```

- `cd /etc/systemd/system/multi-user.target.wants`

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```
ls -l systemd-networkd.service
```

save the output path `../../../../../lib/systemd/system`

- Create two soft connections by

```
cd /ect/systemd/system/getty.target.wants
```

```
ln -s ../../../../../lib/systemd/system/systemd-networkd.service systemd-networkd.service
```

```
ln -s ../../../../../lib/systemd/system/sshd.socket sshd.socket
```

- `reboot` the system
- `ifconfig` to check the ip address of the board
- Open windows powershell in your windows system, input `ssh root@the ip address of your evoline board` to connect to the board.

实施日期	10-Mar-2022																																																											
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【评价】1、知道但是不会做；2、能做到一定程度；3、能够有自信的做到；4、可以教别人

【说明】一点课编号规范：部门名称(第一个字母大写)-XXXX(年月缩写)-序号，品质部 12 年 11 月第 3 个一点课编号为：PZB-1211-003