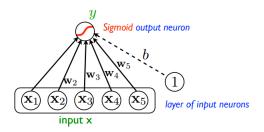
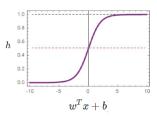
Basics of Training Neural Nets

Logistic Regression - Simplest Network

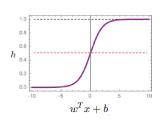


$$h(w^Tx+b)=rac{1}{1+e^{-(w^Tx+b)}}$$



Logistic Regression - Simplest Network

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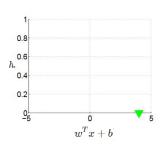
$$P(y=1|w,b,x) = h(w^Tx+b)$$

$$P(y = 0|w, b, x) = 1 - h(w^T x + b)$$

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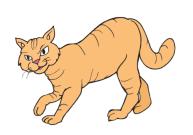
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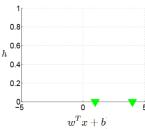




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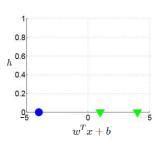




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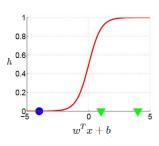




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Can model class probabilities

$$P(y=1|w,b,x) = h(w^Tx+b)$$

$$P(y = 0|w, b, x) = 1 - h(w^T x + b)$$

The above two equations can be combined as:

$$P(y|w,b,x) = (h(w^Tx+b))^y (1 - h(w^Tx+b))^{1-y}$$

Can model class probabilities

$$P(y=1|w,b,x) = h(w^Tx+b)$$
 y=1 => Cat y=0 => Dog $P(y=0|w,b,x) = 1-h(w^Tx+b)$

The above two equations can be combined as:

$$P(y|w,b,x) = (h(w^Tx+b))^y (1 - h(w^Tx+b))^{1-y}$$

The overall probability for M training examples:

$$P(Y|w,b,X) = \prod_{i=1}^{M} (h(w^Tx_i+b))^{y_i} \; (1-h(w^Tx_i+b))^{1-y_i}$$

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The goal of Logistic Regression:

$$\max_{w,b} \ P(Y|w,b,X)$$

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If we do it correctly, we know, *h* would be <u>high for cats and low for dogs</u>

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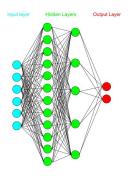
$$\max_{w,b} \ P(Y|w,b,X)$$

If we do it correctly, we know, h would be high for cats and low for dogs

For a new example, x, we compute $h(w^Tx + b)$ to get its probability for being a cat

Multiple Layers

To model more complex relations – we can go deep



Sometimes called Multilayer Perceptron (MLP)

How to Learn

Rumelhart, D.E., Hinton G.E, and Williams R.J. Learning representations by back-propagating errors. Nature 323 (Oct. 9, 1986), 533–536.

Werbos P. Beyond regression: New tools for prediction and analysis in the behavioral sciences. Ph.D. thesis, Harvard University, 1974

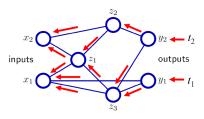
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Intuitive explanation:

- Compute approximation error at the output
- Propagate error back by computing individual contributions of parameters to error



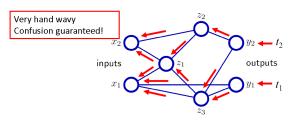
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Intuitive explanation:

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Gradient Descent

$$\max_{w} \ f(w) \ or \ \min_{w} \ e(w)$$

Gradient descent $\min_{w} e(w)$

Algorithm: start with w_0 , t = 0

- lack 0 Compute gradient $g_t = rac{\partial e}{\partial w}ig|_{w=w_t}$
- 2 Update $w_{t+1} = w_t \eta g_t$
- **3** Set $t \leftarrow t + 1$

How to get gradients

1. Analytically Compute Gradients

$$\nabla e(w) = \frac{\partial e}{\partial w}$$

If you can do it, that's the best option!

Fast, Accurate, Exact!

BUT

Tedious to derive Tedious to Implement Error prone Tedious to debug

How to get gradients

2. Numerically Compute Gradients

$$rac{\partial e}{\partial w_i} = rac{e(w_i + \epsilon \mid w ackslash w_i) - e(w_i - \epsilon \mid w ackslash w_i)}{2\epsilon}$$

Trivially Easy to Implement

BUT

Slow and Approximate

2N function calls if N parameters for every gradient descent step (Not Good)

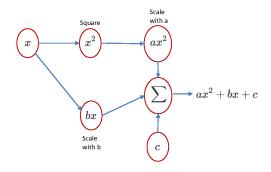
Exploiting Chain Rule

3. Automatic Differentiation (Exploit Chain Rule)

$$\frac{\partial}{\partial x}g(f(x)) = \frac{\partial g}{\partial f}.\frac{\partial f}{\partial x}$$

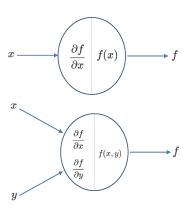
Computation Graph

$$f(x) = ax^2 + bx + c$$



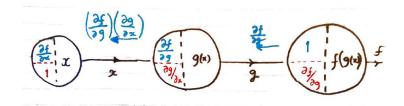
A function can be represented as a directed acyclic Computation Graph in terms of primitive functions. Once a function is represented as a computation graph, implementing chain rule becomes an exercise in memoization...

Memoization of Derivatives



While computing a node function in the graph store the derivative of the node output with respect of its input.

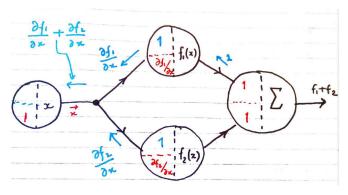
Memoization Example: Composition of Functions



Function Composition

- The terms in red represent the memoized derivatives stored during the forward pass. They are the derivatives of the respective node's output with respect to its input.
- The terms in blue flow and get collected during the backward pass. They represent the derivative of the main output function with respect to the output of the respective node.

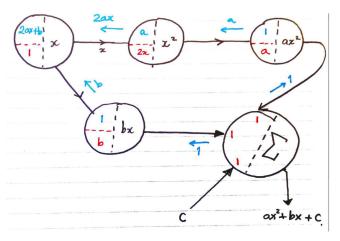
Memoization Example: Addition of functions



Function Summation

The red and blue terms represent the same quantities as in the previous slide. In this example, when two paths merge during backward pass, the sum of the two quantities flow backwards.

Memoization Example: Quadratic



Chain Rule on our Quadratic Example

Now we know how to compute gradients

- so run Gradient Descent

$$\max_{w} \ f(w) \ or \ \min_{w} \ e(w)$$

Gradient descent $\min_{w} e(w)$

Algorithm: start with w_0 , t = 0

- **①** Compute gradient $g_t = \left. rac{\partial e}{\partial w} \right|_{w=w_t}$
- 2 Update $w_{t+1} = w_t \eta g_t$
- ③ Set $t \leftarrow t + 1$

Problems with Back Propagation

Back propagation doesn't work well for deep sigmoid networks:

- Diffusion of gradient signal (multiplication of many small numbers)
- Attractivity of many local minima (random initialization is very far from good points)
- Requires a lot of training samples
- Need for significant computational power

Tricks to handle problems

To obtain more flexibility/non-linearity we use additional function prototypes:

- Sigmoid
- Rectified linear unit (ReLU)
- Pooling
- Dropout
- Convolutions

Tricks to handle problems

Rectified Linear Unit (ReLU)

- Drop information if smaller than zero
- Fixes the problem of vanishing gradients to some degree

Dropout

- Drop information at random
- Kind of a regularization

Next Time: Indexing for Fast Retrieval