# LIU Hongji

Robotics and Multiperception Lab Cheng Kar Shun Robotics Institute

The Hong Kong University of Science and Technology, Hong Kong SAR, China.

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★ Homepage

Google Scholar

### EDUCATION

The Hong Kong University of Science and Technology, Hong Kong SAR, China

2020 - present

PhD student in Robotics & Autonomous Systems

Advisors: Prof. Ming Liu & Prof. Qifeng Chen

Sun Yat-sen University

2015 - 2019

B.Eng in Software Engineering GPA: 3.8/5 Advisor: Prof. Hui Cheng

# PUBLICATIONS \_\_\_\_\_

#### **Conference Publications**

2. V2HDM-Mono: A Framework of Constructing a Marker-and-Lane Level High-definition Map Online Using One or More Monocular Cameras.

Hongji Liu, Linwei Zheng, Xiaoyang Yan, Bohuan Xue, Zhenhua Xu and Ming Liu.

Under Review.

1. 360ST-Mapping: An Online Semantics-Guided Topological Mapping Module for Omnidirectional Visual SLAM.

Hongji Liu, Huajian Huang, Sai-Kit Yeung and Ming Liu.

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2022

#### Patents \_\_\_\_\_

1. A robust and accurate unmanned vehicle positioning system integrating gyroscope, encoder, GNSS, visual detection and high-definition map.

Hongji Liu, Ming Liu, Lujia Wang.

Shenzhen Unity-Drive Innovation Technology Co., Ltd., 6/28/2022 - present.

2. A robust positioning scheme of unmanned vehicle integrating gyroscope, encoder and GNSS.

Hongji Liu, Ming Liu, Lujia Wang.

Shenzhen Unity-Drive Innovation Technology Co., Ltd., 7/12/2021 - present.

3. An efficient method of calibrating the position and heading angle of unmanned vehicle by using high-definition map and visual detection.

Hongji Liu, Ming Liu, Lujia Wang.

Shenzhen Unity-Drive Innovation Technology Co., Ltd., 7/12/2021 - present.

#### Selected Awards and Honors

• Baosteel outstanding student scholarship.	Nov 2018
• The Seventeenth National College Student robot contest, Third prize in the south race area.	$May\ 2018$
• American Mathematical Contest In Modeling, Honorable Mention.	Apr 2018
• Contemporary Undergraduate Mathematical Contest In Modeling, Second prize in Guangdong	Jan 2018
• Undergraduate Second-class Scholarship	Nov 2017
• The fourteenth Challenge Cup, Guangdong college students' extracurricular academic and technological works competition, Second prize.	Jun 2017
• The Sixteenth National College Student robot contest, Third prize in the south race area.	May~2017
• American Mathematical Contest In Modeling, Honorable Mention.	Apr 2017
• The twelfth Sun Yat-sen university Programming Competition, Third prize.	Apr 2017
• The eighth Sun Yat-sen university Programming Novice Competition, Third prize.	Dec 2016
• Undergraduate Second-class Scholarship.	Dec 2016

## SELECTED RESEARCH PROJECTS

R & D and test of the first driverless logistics vehicle in Hong Kong that has obtained the operation license from the transport department.

Sept 2021 - present

Advisor: Prof. Ming Liu, The Hong Kong University of Science and Technology, Hong Kong SAR, China.

- Establishment, maintenance, editing and modification of high-precision maps within the campus.
- Long-term test under complex road conditions such as obstacle avoidance, fixed station parking, traffic interaction, and operation according to traffic rules.

#### R & D of port unmanned container truck visual localization system.

Dec 2019 - Aug 2021

Advisor: Prof. Ming Liu, Shenzhen Unity-Drive Innovation Technology Co., Ltd. Shanghai, China, Guangzhou, China

- Efficient and robust detection of ground markers.
- Dynamic extrinsic parameter calibration of camera.
- Development of sensor and system resource anomaly detection system.