# CNN vs Dense Layers

In the proposed approach, we employ a Dense to handle the code metrics. We hava also tried to replace it with CNN layers, and the resulting approach is presented in Fig.1. We call it CNN-based approach, and call the original one(introduced in the journal paper) as Dense-based approach.

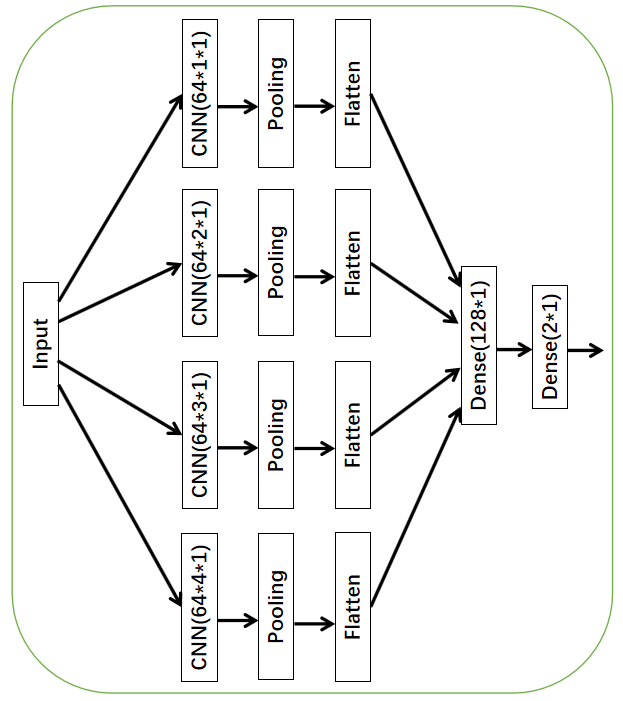


Figure 1. Replacing Dense with CNN Layer

The source code of the algorithm is presented as follows:

*conv1=Sequential()*

*conv2=Sequential()*

*conv3=Sequential()*

*conv4=Sequential()*

*conv1.add(Conv1D(64,1,padding="same",input\_shape=(9,1),activation="relu"))*

*conv1.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv1.add(Conv1D(64,1,padding="same",activation="relu"))*

*conv1.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv1.add(Conv1D(64,1,padding="same",activation="relu"))*

*conv1.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv1.add(Flatten())*

*conv2.add(Conv1D(64,2,padding="same",input\_shape=(9,1),activation="relu"))*

*conv2.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv2.add(Conv1D(64,2,padding="same",activation="relu"))*

*conv2.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv2.add(Conv1D(64,2,padding="same",activation="relu"))*

*conv2.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv2.add(Flatten())*

*conv3.add(Conv1D(64,3,padding="same",input\_shape=(9,1),activation="relu"))*

*conv3.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv3.add(Conv1D(64,3,padding="same",activation="relu"))*

*conv3.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv3.add(Conv1D(64,3,padding="same",activation="relu"))*

*conv3.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv3.add(Flatten())*

*conv4.add(Conv1D(64,4,padding="same",input\_shape=(9,1),activation="relu"))*

*conv4.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv4.add(Conv1D(64,4,padding="same",activation="relu"))*

*conv4.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv4.add(Conv1D(64,4,padding="same",activation="relu"))*

*conv4.add(pooling.MaxPooling1D(pool\_size=2,padding="same"))*

*conv4.add(Flatten())*

*output=merge.Concatenate()([conv1.output,conv2.output,conv3.output,conv4.output])*

*output=Dense(128, activation='relu')(output)*

*output=Dense(2,activation='sigmoid')(output)*

*input1=conv1.input*

*input2=conv2.input*

*input3=conv3.input*

*input4=conv4.input*

*model=Model([input1,input2,input3,input4],output)*

*model.compile(loss='binary\_crossentropy',optimizer='Adadelta',metrics=['accuracy'])*

With the algorithm, we repeat the evaluation and results are presented on Table 2. From this table, we observe the resulting precision and recall is both slightly smaller than the ones of the Dense-based approach (as presented in Table 1). In summary, the performance of the dense-based approach is better than that of the CNN-based approach by comparing the F1 value. Consequently, we keep the original Dense-based approach.

Table 1: Result of Dense-based Approach

|  |  |  |  |
| --- | --- | --- | --- |
| Applications | Precision | Recall | F1 |
| Areca | 33.89% | 80.17% | 47.64% |
| Freeplane | 36.72% | 75.77% | 49.47% |
| jEdit | 36.95% | 72.79% | 49.02% |
| JExcelAPI | 19.74% | 62.72% | 30.03% |
| JUnit | 45.30% | 46.49% | 45.89% |
| PMD | 27.92% | 74.57% | 40.63% |
| Weka | 33.13% | 78.82% | 46.65% |
| Average | 33.80% | 75.91% | 46.77% |

Table 2: Result of CNN-based Approach

|  |  |  |  |
| --- | --- | --- | --- |
| Applications | Precision | Recall | F1 |
| Areca | 31.66% | 86.61% | 46.37% |
| Freeplane | 36.6% | 70.96% | 48.3% |
| jEdit | 36.43% | 79.38% | 49.94% |
| JExcelAPI | 17.94% | 55.62% | 27.13% |
| JUnit | 43.36% | 54.39% | 48.25% |
| PMD | 27.71% | 82.66% | 41.51% |
| Weka | 32.67% | 73.3% | 45.2% |
| Average | 33.14% | 74.91% | 45.95% |