# Hangxin Liu

Email: <u>liuhx111@ucla.edu</u> Mobile: 703-650-8781 Website: <u>liuhx111.github.io</u>

# **EDUCATION**

# University of California, Los Angeles

M.S. in Mechanical Engineering

Los Angeles, CA

09/2016 - Present

# Virginia Polytechnic Institute & State University (Virginia Tech)

Overall GPA 3.78/4.00, Magna Cum Laude, Honors Scholar

**Blacksburg, VA** 08/2012 – 05/2016

# **B. S. in Mechanical Engineering**

 Concentrated in Robotics. Courses Taken: Vibrations, Control, Robotics&Automation, Bayesian Robotics, Linear&Nonlinear Vibrations

#### **B. S. in Computer Science**

• Concentrated in Scientific Computing. Courses Taken: Data Structure&Algorithms, Computer System, Numerical Method, Theory of Computation, Issues in Scientific Computing, Machine Learning, Numerical Analysis

**Minor: Mathematics** 

# **Shanghai Jiao Tong University** (University of Michigan-SJTU Joint Institute)

Shanghai, China

Exchange Student
Courses Taken: Thermodynamics, Heat Transfer, Intermediate Dynamics and Vibration

05/2014 - 08/2014

# **APPOINTMENTS**

# Computational Multi-physics Systems (CMS) Laboratory

01/2015 - 09/2016

# Undergraduate/Graduate Research Assistant, Advisor: Dr. Tomonari Furukawa

- Developed an infrastructural traffic monitoring design using Arduino, laser ranger finders, IR image senor with Raspberry Pi.
- Led the software sub-team of Self-Driving Vehicle Team (SDVT: http://www.me.vt.edu/sdvt/) and implemented way-point controls on a drive-by-wire goftcart in Robot Operating System (ROS) using Sick LiDAR, IMU, GPS, and RGB-D sensors.
- Assisted a Post-doc researcher in developing probabilistic approach to NLOS visual/ acoustical target estimation based on recursive Bayesian estimation framework, and conducting test on human/ mobile sensor platform for human-robot-interaction.
- Worked on motion tracking and feature detection using non-stationary camera that enabled UAV to locate, track and land on a moving ground vehicle for the Mohamed Bin Zayed International Robotics Challenge (MBZIRC 2017).
- Mentoring a senior design project, Self-Driving Vehicle Team, consisting of ten senior students.

# $Ipsen\ Industries\ Furnaces\ (Shanghai)\ Ltd.$

07/2014 - 08/2014

# **R&D** Internship

- 3D modeled furnace covers, pipes, flanges and standard parts using AutoDesk Inventor.
- Audited sketches and selected suitable parts (motors, valves) corresponding to China National Standard.

#### **PUBLICATIONS**

# Journal Paper:

1. K. Takami, **H. Liu**, T. Furukawa, M. Kumon, G. Dissanayake, "Reflection and Diffraction Signals based Recursive Bayesian Estimation for Non-Field-of-View Target," (in preparation).

#### **Conference Paper:**

1. Y. Tian, **H. Liu**, T. Furukawa, "Reliable Infrastructural Urban Traffic Monitoring Via Lidar and Camera Fusion," WCX17: SAE World Congress Experience, 2017 [Submitted]

- 2. K. Takami, **H. Liu**, T. Furukawa, M. Kumon, G. Dissanayake, "Non-Field-of-View Sound Source Localization Using Diffraction and Reflection Signal," IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2016 [accepted]
- 3. **H. Liu**, Y. Tian, T. Furukawa, "Design of Highly Reliable Infrastructural Traffic Monitoring Using Laser and Vision Sensors," ASME IDETC/CIE, 2016
- 4. K. Takami, **H. Liu**, T. Furukawa, M. Kumon, G. Dissanayake, "Recursive Bayesian Estimation of NFOV Target Using Diffraction and Reflection Signals," ISIF International Conference on Information Fusion, 2016

### **HONORS & AWARDS**

• Pratt Engineering Scholarship (\$5000 each academic year) from Collage of Engineering

2013 - 2016

Dean's Scholarship (\$3000) from Collage of Engineering

Spring 2013

• Dean's List (Two semesters).

Spring 2015– Fall 2015

• Dean's List with Distinction (Six semesters).

Fall 2012 - Fall 2014, Spring 2016

• University Honor Student at Virginia Tech.

Summer 2014 – Spring 2016

# LANGUAGES & SKILLS

Language: Native in Chinese Mandarin and Chinese Cantonese; Fluent in English.

**Skills**: Computer Languages: Java, C/C++, Python Software: Robot Operating System (ROS), MATLAB, Eclipse

Operating Systems: Windows, Linux CAD: AutoDesk Inventor

# **MEMBERSHIPS & AFFILIATION**

• Member of **Phi Beta Kappa** Honor Society. 04/2016 - Present

• Student Member of ASME. 01/2016 - Present

Member of **Tau Beta Pi** National Engineering Honor Society. 04/2014 - Present