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Towards Optimal Lower Bounds for *k*-median and *k*-means Coresets

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**Abstract**

Given a set of points in a metric space, the (*k, z*)-clustering problem consists of finding a set of *k* points called centers, such that the sum of distances raised to the power of *z* of every data point to its closest center is minimized. Special cases include the famous *k*-median problem (*z* = 1) and *k*-means problem (*z* = 2). The *k*-median and *k*-means problems are at the heart of modern data analysis and massive data applications have given raise to the notion of coreset: a small (weighted) subset of the input point set preserving the cost of any solution to the problem up to a multiplicative (1 *ε*) factor, hence reducing from large to small scale the input to the problem.

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While there has been an intensive effort to understand what is the best coreset size possible for both problems in various metric spaces, there is still a significant gap between the state- of-the-art upper and lower bounds. In this paper, we make progress on both upper and lower bounds, obtaining tight bounds for several cases, namely:

* In finite *n* point general metrics, any coreset must consist of Ω(*k* log *n/ε*2) points. This improves on the Ω(*k* log *n/ε*) lower bound of Braverman, Jiang, Krauthgamer, and Wu

[ICML’19] and matches the upper bounds proposed for *k*-median by Feldman and Langberg [STOC’11] and *k*-means by Cohen-Addad, Saulpic, and Schwiegelshohn [STOC’21] up to polylog factors.

* For doubling metrics with doubling constant *D*, any coreset must consist of Ω(*kD/ε*2) points. This matches the *k*-median and *k*-means upper bounds by Cohen-Addad, Saulpic,

and Schwiegelshohn [STOC’21] up to polylog factors.

* In *d*-dimensional Euclidean√space, any coreset for (*k, z*) clustering requires Ω(*k/ε*2) points.

This improves on the Ω(*k/ ε*) lower bound of Baker, Braverman, Huang, Jiang, Krauthgamer,

and Wu [ICML’20] for *k*-median and complements the Ω(*k* min(*d,* 2*z/*20)) lower bound of Huang and Vishnoi [STOC’20].

We complement our lower bound for *d*-dimensional Euclidean space with the construction of a coreset of size *O*˜(*k/ε*2 min(*ε−z, k*)). This improves over the *O*˜(*k*2*ε−*4) upper bound for general power of *z* proposed by Braverman Jiang, Krauthgamer, and Wu [SODA’21] and over the *O*˜(*k/ε*4) upper bound for *k*-median by Huang and Vishnoi [STOC’20]. In fact, ours is the first construction breaking through the *ε−*2 min(*d, ε−*2) barrier inherent in all previous coreset constructions. To do this, we employ a novel chaining based analysis that may be of independent

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interest. Together our upper and lower bounds for *k*-median in Euclidean spaces are tight up to a factor *O*(*ε−*1polylog *k/* ).

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# Introduction

A clustering is a partition of a data set *P* such that data points in the same cluster are similar and points in different clusters are dissimilar. Various clustering problems have become important cornerstones in combinatorial optimization and machine learning problems. Among these, center- based clustering problems are arguably the most widely studied and used. Here, the data elements lie in a metric space, every cluster is associated with a center point and the cost of a data point is some function of the distance between data point and its assigned cluster. The (*k, z*) problem captures this and other important objectives via the cost function

cost(*P,* S) :=

*p*∈*P*

min

*s*∈S

*d*(*p, s*)*z,*

where *z* is a positive integer, |S| = *k* and *d*( *,* ) denotes the distance function. For *z* = 1, this is

*k*-median problem and for *z* = 2, this is the equally intensely studied *k*-means problem.

Datasets used in practice are often huge, containing hundred of millions of points, distributed, or evolving over time. Hence, in these settings classical heuristics (such as Lloyd or k-means++) are lapsed; the size of the dataset forbids multiple passes over the input data and finding a “compact representation” of the input data is of primary importance. This leads to a tradeoff: the smaller the dataset, the less storage we need and the faster we can run an algorithm on the data set, but conversely the smaller the data set the more information about the orginal data will be lost. *Coresets* formalize and study this tradeoff. Specifically, given a precision parameter *ε*, *k* and *z*, an (*ε, k, z*) coreset Ω is a subset of *P* with weights *w* : Ω → R that approximates the cost of *P* for any candidate solution S up to a (1 ± *ε*) factor, namely

∀S*,* (1 − *ε*)cost(*P,* S) ≤ *w*(*p*)cost(*p,* S) ≤ (1 + *ε*)cost(*P,* S)*.*

*p*∈Ω

A small (*ε, k, z*) coreset is therefore a good compression of the initial dataset, since it preserves the cost of any possible solution. Instead of storing the full dataset, one can simply store the coreset, saving on memory footprint and speeding up performances. We note that in some definitions, an offset ∆ is added to the coreset: in that case, the coreset cost of solution S is (1 ± *ε*)cost(*P,* S) +∆. In the case where the input space is infinite (e.g., Euclidean space), the coreset points may be chosen from the whole space, and are not restricted to be part of the input.

Although numerous great work focused on improving the size of coreset constructions, our under- standing of coreset lower bounds is comparatively limited, and there is a significant gap between the best upper and lower bounds on the possible coreset size. For example, even for Euclidean *k*-means, nothing beyond the trivial Ω(*k*) lower bound is known. In this work, we attempt to systematically obtain lower bounds for these problems.

We pay a particular attention to Euclidean Spaces. For those, we complement our lower bound with a new coreset construction that has an optimal dependency in 1*/ε*.

## Our Results

We settle the complexity of the problem for several cases. First, for finite *n*-point metrics, we prove the following theorem.

|  |  |  |  |
| --- | --- | --- | --- |
| Metric Space | Best upper bound | Best lower bound | Our result |
| Discrete Metrics | *O*(*kε*− max(2*,z*) log *n*) [[35]](#_bookmark118) | Ω(*kε*−1 log *n*) [[6]](#_bookmark89) | Ω(*kε*−2 log *n*)\* |
| with doubling dimension *D* | *O*(*kε*− max(2*,z*)*D*) [[35]](#_bookmark118) | - | Ω(*kε*−2*D*)\* |
| Euclidean *k*-median | *O* (*kε*−4) [[55]](#_bookmark138) | Ω(*kε*−1*/*2) [[6]](#_bookmark89) | *O* (*kε*−3) Ω(*kε*−2) |
| Euclidean *k*-means | *O* (*kε*−4) [[35]](#_bookmark118) | - | Ω(*kε*−2) |
| Euclidean | *O* (*kε*−2−max(2*,z*)) [[35]](#_bookmark118)  *O* (*k*2*ε*−4) [[17]](#_bookmark100) | Ω(*k*2*z/*100) [[55]](#_bookmark138) | *O* *z* (*kε*−2 · min(*ε*−*z, k*)) Ω(*kε*−2) |

Figure 1: Comparison between the state-of-the-art bounds and our results. Results marked with \* are tight for *k*-median and *k*-means.

**Theorem 1.** *For any* 0 *< ε <* 1*/*2*, k and n* ≥ *ε*−5 *such that* log *k* = *O*(log *n*)*, the* *re exists* *a finite*

*n point metric such that any* (*ε, k, z*) *coreset using offset* ∆ *consists of at least* Ω

*ε*2

*points.*

*k* log *n*

Our result improves over the Ω(*kε*−1 log *n*) lower bound of Baker, Braverman, Huang, Jiang, Krauthgamer, and Wu [[6].](#_bookmark89) For the *k*-median and *k*-means objective matches the upper bounds proposed in Feldman and Langberg [[41]](#_bookmark124) and Cohen-Addad, Saulpic, and Schwiegelshohn [[35]](#_bookmark118) up to polylog(1*/ε*) factors.

For metric space with doubling dimension *D*, we present a lower bound similar to that of Theorem [1:](#_bookmark0)

**Corollary 2.** *For any ε, k, D such that D* ≥ 5 log 1*/ε and* log *k* = *O*(*D*)*, there exists* *a gr* *aph with*

*doubling dimension D on which any* (*ε, k, z*)*-coreset using offset* ∆ *must have size* Ω

*.*

*kD ε*2

This matches up to polylog(1*/ε*) factors the upper bound from [[35]](#_bookmark118) for *k*-median and *k*-means.

We also study Euclidean spaces more specifically. Here, the difficulty is that centers can be placed arbitrarily in the space, and not only at input points. Our main results for Euclidean spaces is the following.

**Theorem 3** (See Theorem [11](#_bookmark181) for the exact statement)**.** *For any* 0 *< ε <* 1*/*2 *and any k, there*

*exists a point set such that any* (*ε, k, z*) *coreset using offset* ∆ *consists of at least* Ω 2 *k* 4

*ε*

max{1*,z* }

*points.*

This lower bound holds for any selection of points (i.e. the coreset may use non-input points), and for any additive offset, which is a generalization initially proposed by Feldman, Schmidt, and Sohler

[[43]](#_bookmark125) and which has since been used in a number of other papers, see Cohen, Elder, Musco, Musco, and Persu [[25],](#_bookmark108) Sohler and Woodruff [[86]](#_bookmark169) and Cohen-Addad, Saulpic and Schwiegelshohn [[34].](#_bookmark116) The only previously known results are the Ω(*k/ ε*) bound for *k*-median by Baker, Braverman, Jiang,

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Krauthgamer, and Wu [[6],](#_bookmark89) and the Ω(*k* · min(*d,* 2*z/*20)) bound by Huang and Vishnoi [[55].](#_bookmark138) Thus, we obtain the first non-trivial lower bound for Euclidean *k*-means.

We complement the lower bound with the following theorem.

**Theorem 4.** *Given a set of points P in d-dimensional Euclidean space and any ε >* 0*, there exists*

*an* (*ε, k, z*) *coreset of size O*˜(*k* · *ε*−2 · 2*O*(*z* log *z*) · min(*ε*−*z, k*))*.*

This is the first coreset construction with an optimal dependency on *ε*, at the cost of a quadratic dependency on *k*. Previously, all upper bounds either had a dependency of at least *ε*−4 [[18,](#_bookmark101) [35,](#_bookmark118) [55]](#_bookmark138) or a dependency on *d* [[23,](#_bookmark106) [41].](#_bookmark124)

We note that for the special case of Euclidean *k*-median, we improve the best coreset size from

*O*(*k* · *ε*−4) to *O*(*k* · *ε*−3), taking a step to reduce the gap with the lower bound.

A complete overview of previous coreset bounds for Euclidean spaces and finite metrics is given in Table [1.](#_bookmark5) For further related work, we refer to Section [2.](#_bookmark4)

## Overview of our Techniques

Our results for the Euclidean setting require several important new technical insights and we thus review them first. We later review our approach for our lower bound for general metrics.

**Euclidean Lower Bounds** The lower bound proof consists of three separate steps which com- bined proves that any coreset for the point set *P* = {*e*1*, . . . , ed*} in R*d* (i.e., the standard basis of R*d*) must have size Ω(*k* · *ε*−2) (in this proof overview, we focus on *z* = 2) when *d* = Θ(*k* · *ε*−2). The basic approach is to show that any clustering of *P* with *k* centers has large cost, while at the same time, for any coreset Ω using *o*(*d*) weighted points, there is a low cost clustering. Combining the

two yields the lower bound. We carry out this proof in three steps. In √the first step, we show that

any clustering of *P* using unit norm centers has cost at least 2*d* − *O*( *dk*). In the next step, we

show that for any coreset Ω consisting of *t* points and a w eighing *w* : Ω → R+, there is a low-cost

with step one implies *w*(*p*) *p* = *O*(√*td*). In the final step, we show that any coreset Ω must have *w*(*p*) *p* = Ω(*d*) when *d* = Θ(*k ε*−2). Combining this with the previous two

steps finally yields √*td* = Ω(*d*) ⇒ *t* = Ω(*d*) ⇒ *t* = Ω(*k* · *ε*−2). In the following, we elaborate on the

2*p*∈Ω

·2*p*∈Ω

clustering using unit norm centers that has cost 2*d* − Ω(

*k/t* ·

*p*∈Ω *w*(*p*) *p* 2). Combining this

high level ideas needed for each of the steps:

1. First, we show that√any clustering of *P* using *k* cluster centers *c*1*, . . . , ck* of unit norm, must have

cost at least 2*d* − *O*( *dk*). To see this, notice that if *ei* is assigned to cluster center *cj*, then the

cost of *ei* is *ei* − *cj* 2 = *ei* 2 + *cj* 2 − 2 *ei, cj* = 2 − 2*cj,i*, where *cj,i* denotes the *i*’th coordinate of

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2

2

*cj*. Any cluster center *cj* can thus at most reduce the cost of the clustering below 2*d* by an additive

1. *i cj,i* ≤ 2 *cj* 1. Moreover, it is only “wasteful” to assign a value different from 0 to *cj,i* if *ei* is not assigned to center *cj* (wasteful since *cj* is required to have unit norm). Thus the *k* centers can be thought of as having disjoint supports. Thus on average, they only have *d/k* coordinates availa ble. By Ca uchy-S chwartz (i.e√. the maximum ratio between *cj* 1 and *cj* 2), we can argue

that

*j* *cj* 1 ≤

*d/k*

*j* *cj* 2 =

*dk* and the conclusion follows.

1. Next, we argue that for any coreset Ω consisting of *t* points and a weighing *w* : Ω → R+, we can find a low-cost clustering in terms of *p* Ω *w*(*p*) *p* 2 using unit norm centers. This is achieved by partitioning the points of the coreset into *k* groups of= *t/k* points each and using one center for each group. For a group ofpoints *r*1*, . . . , r*, we choose the center as something that resembles the

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mean scaled to have unit norm. More precisely, we consider a random vector *u* = *σiw*(*ri*)*ri*

*i*=1

for uniform random and independent signs *σi*. We can then argue that there is a fixing of the signs,

such that if *u* is scaled to have unit norm and this is repeated for all *k* groups, the resulting cluster cost is at most 2*d* − Ω( *k/t p*∈Ω *w*(*p*) *p* 2).

1. In the last step, we need to argue that any coreset Ω and weighing *w* : Ω → R+ must have *p* Ω *w*(*p*) *p* 2 = Ω(*d*) when *d* = Θ(*k* · *ε* ). This is the technically most challenging part of the proof. The basic idea for arguing this, is to exploit that Ω must be a coreset for many different clusterings of *P* = {*e*1*, . . . , ed*}. In particular, we consider the Hadamard basis over *q* = *d/k* coor-

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dinates. The Hadamard basis consists of *q* orthogonal vectors with coordinates in 1*/ q,* 1*/ q* , all having at least half of the coordinates equal to 1*/*√*q*. For each vector *v* in the basis, we

consider a clustering where we use *k* centers *c*1*, . . . , ck* that are all copies of *v* shifted to take up either the first *q* coordinates in R*d*, the next *q* coordinates and so on. Since half of the coordi-

nates of any *v* are 1*/*√*q*, the cost of this clustering on *P* is 2*d* − Ω(*d/*√*q*) (if *ei* is assigned to

a center with the *i*’th coordinate is equal to 1*/*√*q* then the cost of *ei* is 2 − 2*/*√*q*). Thus in-

tuitively, the points *r*1*, . . . , rt* in any coreset Ω also must have *t*

*i*=1

max

*k*

*j*=1

*ri, cj* = Ω(*d/*√*q*).

This means that on average over all *ri*, we have max*k w*(*ri*) *ri, cj* = Ω(*d/*(*t*√*q*)). The cru-

*k*=1

cial observation is that we can repeat this argument for every *v* in the basis. There are *q* such

*v*’s. Moreover, for any point *ri* in the coreset, the set of *q* centers *c*1 *, . . . , cq*

it is assigned to in

*i*1 *iq*

these *q* different clusterings are all orthogonal vectors. Thus by Cauchy-Schwartz, we must have

√*qd/t* ≤ *q*  *w*(*ri*)*ri, c* = *w*(*ri*)*ri,* *q cj* ≤ *w*(*ri*)*ri* 2 *q cj* 2 = *w*(*ri*) *ri* 2√*q*. That

*j*

*j*=1

*i,j*

*j*=1

*ij*

*j*=1

*i,j*

is, *w*(*ri*) *ri* 2 = Ω(*d/t*). Summing over all *ri* completes the proof. Finally, let us remark where

the requirement *d* = Θ(*k ε*−2) enters the picture. We argued that the cost of clustering *P* using the Hadamard basis was 2*d* − Ω(*d/*√*q*). In the coreset, the clustering is allowed to be a factor (1 + *ε*) larger. We thus require that (2*d* − Ω(*d/*√*q*))(1 + *ε*) ≤ 2*d* − Ω(*d/*√*q*), which is satisfied when *dε* = *O*(*d/*√*q*) ⇔ *q* = *O*(*ε*−2). But *q* = *d/k* and thus this translates into *d* = *O*(*k* · *ε*−2).

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**Upper Bounds** Our main technical contribution is an application of chaining techniques used to analyse Gaussian processes for coreset construction, see Talagrand for an extensive introduction [[87].](#_bookmark170) To the best of our knowledge, we are not aware of any prior attempts of using chaining to improve coreset bounds directly.

For readers that may not be familiar with the technique, we now highlight how it allows us to improve over previous constructions. For every candidate solution S, we say that *v*S is the cost vector associated with S, where *vp*S is simply the cost of point *p* in S. A sampling based coreset now

picks rows of *v*S according to some distribution and approximates *v*S 1 = *vp*S as the weighted

average of the costs of the picked points. To show that this weighted average is concentrated, we

require two ingredients. First, we bound the variance for approximating any *v*S 1. Suppose we make the simplifying assumption that all points less than 1 and that we are aiming for an additive error of at most *ε* · *n*. In this case, the variance is constant, upon which applying a Chernoff bound requires only **Var** · *ε*−2 samples to approximate any single *v*S 1.

Second, we have to apply a union bound over all *v*S. In Euclidean spaces, a naive union bound is useless, as there are infinitely many candidate solutions. To discretize S, previous work, either implicitly or explicitly, showed that there exists a small set of vectors N*ε*, henceforth called a net, such that for every *v*S there exists *v*S*,ε* ∈ N*ε* with |*vp*S*,ε* − *v*S| ≤ *ε*. Thus, an accurate estimation of

*p*

*v* 1 for all *v* ∈ N*ε* is sufficient to achieve an estimation for all *v*S. Unfortunately, the only known bounds of N*ε* are of the order exp(*k* min(*d, ε*−2)), which combined with bound of the variance leads

to log |N*ε*| · **Var** · *ε*−2 = *k* · *ε*−2 · min(*ε*−2*, d*) many samples.

To improve upon this idea, we use nets at different scales, i.e. we have nets N1, N1*/*2, N1*/*4 and so on. These nets allow us to write every *v*S as a telescoping sum of net vectors at different scales, that is

−(*h*+1) −*h,*2 *,*2

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*v*S = *v*S − *v*S *,*

*h*=0

where *v*S*,*2−*h* is an element of N2−*h* . Instead of applying the union bound for all vectors in N*ε* at once, we apply the union bound for all difference vectors at various scales, i.e. we show that for all

difference vectors *v*S*,*2−(*h*+1) − *v*S*,*2−*h*

P |*v*S*,*2−(*h*+1) − *v*S*,*2−*h* − E[*v*S*,*2−(*h*+1) − *v*S*,*2−*h* |] ≥ *ε* · *n*

is small.

The reason why this improves over the naive discretization is that as the nets get finer, the difference also gets smaller, i.e. |*v*S*,*2−(*h*+1) − *v*S*,*2−*h* | ≤ 2 · 2−*h*. This difference directly affects the bound

*p*

*p*

on the variance, which decreases from a constant to roughly 2−2*h* · *O*(1). Since there are only

|N2−(*h*+1) | · |N2−*h* | ∈ exp(*k* · 2−2*h* · *O*(1)) many difference vectors, we can compensate the increase in net size by a decrease in variance, i.e. we require only

log(|N2−(*h*+1) | · |N2−*h* |) · **Var** · *ε*−2 ≈ *k* · 2−2*h* · *O*(1) · 2−2*h* · *ε*−2 = *k* · *ε*−2 · *O*(1)

many samples. Applying this idea to every successive summand of the telescoping sum (or rather to every link of the chain of net vectors), leads to an overall number of samples of the order *k* · *ε*−2, ignoring polylog factors.

Unfortunately, improving the analysis from an additive approximation to a multiplicative approx- imation leads to several difficulties. Without using the assumption that all points cost less than 1, the variance increases. Indeed, contrasting to the previous work [[34]](#_bookmark116) that used a chaining-based analysis to obtain coreset bounds for a single center and previous work [[35]](#_bookmark118) that used a chaining- inspired variance reduction technique, both of which managed to obtain constant variance, bounding the variance in this setting is highly non-trivial and requires a number of new ideas. The lowest

variance we could show for estimating *v*S 1 is only of the order min(*ε*−*z, k*), leading to the (likely suboptimal) bound of *O*˜(*k* · *ε*−2 · min(*ε*−*z, k*)) and moreover this bound on the variance is tight. Further ideas will be necessary to reach the (conjectured) optimal bound of Θ(*k* · *ε*−2).

**Lower Bound for discrete metric spaces** The general idea behind our lower bound is to use the tight concentration and anti-concentration bounds on the sum of random variables.

We first build an instance for *k* = 1, and combines several copies of it to obtain a lower bound for any arbitrary *k*. Our instance for *k* = 1 is such that: (1) when |Ω| ≤ *ε*−2 log |*C*| there exists a center with cost(Ω*, c*) *>* (1 + 100*ε*)cost(*c*), and (2): for any |Ω| *> ε*−2 log |*C*| there exists a center *c* with cost(Ω*, c*) ∈ (1 ± *ε*)cost(*c*).

To show the existence of such an instance, we consider a complete bipartite graph with nodes *P* ∪ *C*

where there is an edge between each point of *P* and each point of *C*, with length 1 with probability

1*/*4 and 2 otherwise. The set of clients is *P* . For simplicity, we will assume here that the coreset weights are uniform. Making the idea work for non-uniform weights requires several other technical ingredients.

In that instance for *k* = 1, the cost of a solution (with a single center, *c*) is fully determined by *n*1(*c*), the number of length 1 edges to *c*. Indeed, cost(*c*) = 2(|*P* | − *n*1(*c*)) + *n*1 − *c*) = 2|*P* | − *n*1(*c*). Let us further assume that *n*1(*c*) is equal to its expectation, *δ*|*P* |. For a fixed subset of points Ω, the cost

of the solution for Ω with uniform weights |*P* | verifies the same equation: it is 2|*P* | − *n*1(Ω*, c*) · |*P* | ,

|Ω|

where *n*1(Ω*, c*) the number of length 1 edges from Ω to *c*. Note that E[*n*1(Ω*, c*)] = *δ*|Ω|.

|Ω|

Using anti-concentration inequalities, we show that *n*1(Ω*, c*) *>* (1+200*ε*)E[*n*1(Ω*, c*)] with probability at least exp(−*αε*2|Ω|), for some constant *α*. When this event happens, then Ω does not preserve the cost of solution *c*: indeed,

2|*P* | − *n* (Ω*, c*) · |*P* | *>* 2|*P* | − (1 + 200*ε*)*δ*|Ω| · |*P* |

1

|Ω|

|Ω|

= 2|*P* | − *δ*|*P* | + 200*εδ*|*P* | *>* (1 + 100*ε*)(2|*P* | − *n*1(*c*))*.*

Since the edges are drawn independently, the coreset cost for all possible centers *c* is independent. Hence, there exists one center with *n*1(Ω*, c*) *>* (1 + 200*ε*)*δ*|Ω| with probability at least 1 − (1 − exp(−*αε*2|Ω|))|*C*|. By doing a union-bound over all possible subsets Ω, one can show the following: with positive (close to 1) probability, for any |Ω| ≤ *ε*−2 log |*C*| there exists a center with cost(Ω*, c*) *>* (1 + 100*ε*)cost(*c*).

Using standard concentration inequality, one can show that with probability close to 1, for any

|Ω| *> ε*−2 log |*C*|, there exists a center *c* with cost(Ω*, c*) ∈ (1 ± *ε*)cost(*c*). Since the probabilities are taken on the edges randomness, those two result ensure the existence of a graph that verifies properties (1) and (2) desired for the *k* = 1 instance.

Now, the full instance is made of *k* distinct copies *X*1*, ..., Xk* of the *k* = 1 instance, placed at infinite distance from each other. Let *Pi* be the set of clients of *Xi*: the clients for the full instance are *Pi*. Let Ω be a set of at most 1*/*100 *kε*−2 log *n* points: we show that Ω cannot be a coreset. By Markov’s inequality, there are at least 99*/*100*k* copies that contain less than *ε*−2 log *n* points of Ω. We say those copies are *bad*, the others are *good*. Consider now the solution S defined as follows: from each *Xi*, take the center such that cost(Ω ∩ *Pi, c*) *>* (1 + 100*ε*)cost(*Pi, c*) when *Xi* is bad, and the center such that cost(Ω ∩ *Pi, c*) ∈ (1 ± *ε*)cost(*Pi, c*) when *Xi* is good. Observe also that by construction of the instance for *k* = 1, the cost in each copy must lie in [|*P* |*,* 2|*P* |]. For that

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solution, we have:

cost(Ω*,* S) = cost(Ω ∩ *Pi, si*) =

*i* bad

cost(Ω ∩ *Pi, si*) +

*i* good

cost(Ω ∩ *Pi, si*)

*>* (1 + 100*ε*)cost(*Pi, si*) + (1 − *ε*)cost(*Pi, si*)

*i* bad

99*k*

*i* good

*k*

*>* cost(S) + 100 · 100*ε*|*P* | − 100 · *ε*2|*P* | *>* cost(S) + 98*kε*|*P* | *>* (1 + *ε*)cost(S)*.*

Hence, any Ω with |Ω| ≤ 1*/*100 · *kε*−2 log *n* cannot be a coreset for our instance, which concludes the proof.

# Related Work

Reference Size (Number of Points)

### Coreset Bounds in Euclidean Spaces

Lower Bounds

|  |  |
| --- | --- |
| Baker, Braverman, Huang, Jiang,  Krauthgamer, Wu (ICML’19) [[15]](#_bookmark98) | Ω(*k* · *ε*−1*/*2) |
| Huang, Vishnoi (STOC’20) [[55]](#_bookmark138) | Ω(*k* · min(*d,* 2*z/*20)) |
| **This paper** | Ω(*k* · *ε*−2*/z*4) |

Upper Bounds

|  |  |
| --- | --- |
| Har-Peled, Mazumdar (STOC’04) [[50]](#_bookmark133) | *O*(*k* · *ε*−*d* · log *n*) |
| Har-Peled, Kushal (DCG’07) [[49]](#_bookmark132) | *O*(*k*3 · *ε*−(*d*+1)) |
| Chen (Sicomp’09) [[23]](#_bookmark106) | *O*(*k*2 · *d* · *ε*−2 · log *n*) |
| Langberg, Schulman (SODA’10) [[65]](#_bookmark148) | *O*(*k*3 · *d*2 · *ε*−2) |
| Feldman, Langberg (STOC’11) [[41]](#_bookmark124) | *O*(*k* · *d* · *ε*−2*z*) |
| Feldman, Schmidt, Sohler (Sicomp’20) [[43]](#_bookmark125) | *O*(*k*3 · *ε*−4) |
| Sohler, Woodruff (FOCS’18) [[86]](#_bookmark169) | *O*(*k*2 · *ε*−*O*(*z*)) |
| Becchetti, Bury, Cohen-Addad, Grandoni,  Schwiegelshohn (STOC’19) [[8]](#_bookmark91) | *O*(*k* · *ε*−8) |
| Huang, Vishnoi (STOC’20) [[55]](#_bookmark138) | *O*(*k* · *ε*−2−2*z*) |
| Bravermann, Jiang, Krautgamer, Wu (SODA’21) [[17]](#_bookmark100) | *O*(*k*2 · *ε*−4) |
| Cohen-Addad, Saulpic, Schwiegelshohn (STOC’21) [[35]](#_bookmark118) | *O*˜(*k* · *ε*−2−max(2*,z*)) |
| **This paper** | *O*˜(*k* · *ε*−2 · min(*ε*−*z, k*)) |

### General *n*-point metrics, *D* denotes the doubling dimension

Lower Bounds

|  |  |
| --- | --- |
| Braverman, Jiang, Krauthgamer, Wu (ICML’19) [[16]](#_bookmark99) | Ω(*k* · *ε*−1 · log *n*) |
| **This paper** | Ω(*k* · *ε*−2 · log *n*) |
| **This paper** | Ω(*k* · *ε*−2 · *D*) |

Upper Bounds

|  |  |
| --- | --- |
| Chen (Sicomp’09) [[23]](#_bookmark106) | *O*(*k*2 · *ε*−2 · log2 *n*) |
| Feldman, Langberg (STOC’11) [[41]](#_bookmark124) | *O*(*k* · *ε*−2*z* · log *n*) |
| Huang, Jiang, Li, Wu (FOCS’18) [[51]](#_bookmark134) | *O*(*k*3 · *ε*−2 · *D*) |
| Cohen-Addad, Saulpic, Schwiegelshohn (STOC’21) [[35]](#_bookmark118) | *O*˜(*k* · *ε*− max(2*,z*) · *D*) |
| Cohen-Addad, Saulpic, Schwiegelshohn (STOC’21) [[35]](#_bookmark118) | *O*˜(*k* · *ε*− max(2*,z*) · log *n*) |

Table 1: Comparison of coreset sizes for (*k, z*)-Clustering in Euclidean spaces. [[15]](#_bookmark98) only applies to *k*-median, [[49,](#_bookmark132) [50]](#_bookmark133) only applies to *k*-means and *k*-median, [and[8,](#_bookmark91) [43]](#_bookmark125) only applies to *k*-means.

[[86]](#_bookmark169) runs in exponential time, which has been addressed by Feng, Kacham, and Woodruff [[44].](#_bookmark127) Aside from [[49,](#_bookmark132) [50],](#_bookmark133) the algorithms are randomized and succeed with constant probability. Any dependency on 2*O*(*z* log *z*), as well as polylog factors have been omitted in the upper bounds.

For the most part, related work on coresets for *k* clustering in Euclidean spaces are given in Ta- ble [1.](#_bookmark5) A closely related line of research focusses on dimension reduction for *k*-clustering objectives, particularly *k*-means. Starting with [[37],](#_bookmark120) a series of results [[8,](#_bookmark91) [10,](#_bookmark93) [11,](#_bookmark94) [12,](#_bookmark95) [25,](#_bookmark108) [36,](#_bookmark119) [43,](#_bookmark125) [44,](#_bookmark127) [64,](#_bookmark147) [73,](#_bookmark156) [86]](#_bookmark169) explored the possibility of using dimension reduction methods for *k*-clustering, with a particular focus on principal component analysis (PCA) and random projections. The problem of dimension reduction, at least with respect to these techniques has been mostly resolved by now: Cohen, Elder, Musco, Musco, and Persu [[25]](#_bookmark108) proved tight bounds of *k/ε* for PCA and Makarychev, Makarychev and Razenshteyn [[73]](#_bookmark156) gave a bound of *O*(*ε*−2 log *k/ε*) for random projections, which nearly matches the lower bound by Larsen and Nelson [[66].](#_bookmark149) The arguably most important technique for combining dimension reduction with coresets is the recent work on terminal embeddings, see [[24,](#_bookmark107) [38,](#_bookmark121) [72].](#_bookmark155) No- tably, Narayanan and Nelson [[82]](#_bookmark165) gave an optimal bound of *O*(*ε*−2 log *n*). We will discuss specifics on terminal embeddings in Section [6.4.](#_bookmark44)

While Euclidean spaces are doubtlessly the most intensively studied metric, a number of further metrics have also been considered, including finite metrics [[23,](#_bookmark106) [35,](#_bookmark118) [41],](#_bookmark124) doubling metrics [[35,](#_bookmark118) [51],](#_bookmark134) and graph metrics [[6,](#_bookmark89) [18,](#_bookmark101) [35].](#_bookmark118) Coresets also feature prominently in streaming literature, see [[13,](#_bookmark96) [14,](#_bookmark97) [20,](#_bookmark103) [45,](#_bookmark128) [46]](#_bookmark129) for results with a special focus on various streaming models. Other related work considers generalizations of *k*-median and *k*-means by either adding capacity constraints [[7,](#_bookmark90) [29,](#_bookmark112) [52,](#_bookmark135) [85],](#_bookmark167) generalizing the notion of centers to subspaces [[19,](#_bookmark102) [41,](#_bookmark124) [42],](#_bookmark126) time series [[54]](#_bookmark137) or sets [[61]](#_bookmark144) or considering more general objective functions [[5,](#_bookmark88) [15].](#_bookmark98) Coresets have also been studied for many other problems: we cite non-comprehensively decision trees [[60],](#_bookmark143) kernel methods [[59,](#_bookmark142) [62,](#_bookmark145) [83],](#_bookmark166) determinant

maximization [[57],](#_bookmark140) diversity maximization [[58],](#_bookmark141) shape fitting problems [[2,](#_bookmark84) [22],](#_bookmark105) linear regression [[9,](#_bookmark92)

[53,](#_bookmark136) [88]](#_bookmark171), logistic regression [[56,](#_bookmark139) [81],](#_bookmark163) Gaussian mixtures [[70],](#_bookmark153) dependency networks [[79],](#_bookmark162) or low-rank approximation [[71].](#_bookmark154) The interested reader is referred to [[3,](#_bookmark86) [40,](#_bookmark123) [80]](#_bookmark164) and similar surveys for more pointers to coreset literature.

In terms of approximation guarantee, the best known approximation ratio for general metrics is

2.67 due to Byrka et al. [[21],](#_bookmark104) improving over the result of 2.71 of Li and Svensson [[69]](#_bookmark152) while computing a better than 1 + 2*/e*-approximation has been shown to be NP-hard by Guha and Khuller [[48].](#_bookmark131) In Euclidean spaces of arbitrary dimension, the best known approximation is 2.408 and 5.957 for *k*-median and *k*-means, respectively, due to a recent result of Cohen-Addad et al. [[1]](#_bookmark85) who improved over the work of Grandoni et al. [[47]](#_bookmark130) and Ahmadian et al. [[4].](#_bookmark87) The best known hardness of approximation is 1.73 and 1.27 for *k*-means and *k*-median assuming the Johnson- Coverage Hypothesis or 1.17 and 1.07 respectively assuming P = NP [[32]](#_bookmark115) (see also [[31,](#_bookmark113) [33,](#_bookmark117) [68]).](#_bookmark150) For graphs excluding a fixed-minor, the problem is NP-Hard [[75]](#_bookmark158) and a PTAS is known [[28,](#_bookmark111) [30].](#_bookmark114) For doubling metrics, the problem is NP-Hard (even in the plane [[77])](#_bookmark160) and a linear-time approximation scheme when the dimension is considered constant is known [[27,](#_bookmark110) [26,](#_bookmark109) [63].](#_bookmark146)

## 2.1 Roadmap

The proof of the Euclidean lower bound for *k*-Means is given in Section [4.](#_bookmark6) The proof for general powers is given in Appendix [A.](#_bookmark173) The lower bounds for finite metrics and doubling metrics are given in Section [5.](#_bookmark13) The proof of the upper bound is given in Section [6.](#_bookmark26)

# Preliminaries

**General Preliminaries** Given two points *p* and *c* in some metric space with distance function dist, the (*k, z*)-clustering cost of *p* to *c* is cost(*p, c*) = dist*z*(*p, c*)*.* The *p* norm of a *d* dimensional

*p*

vector *x* is defined as *x* *p* := *p* *d* |*x*| . If the value of *p* is unspecified, it is meant to be the

*i*

*i*=1

Euclidean norm *p* = 2. Given a set of point *P* with weights *w* : *P* → R+ on a metric space *I* and a solution S, we define cost*I*(*P,* S) := *p*∈*P w*(*p*)cost(*p,* S).

**Definition 1.** *Let* (*X, dist*) *be a metric space, let P* ⊂ *X be a set of* clients *and let* Ω *be a set of points with weights w* : Ω → R+ *and a constant* ∆*.* Ω *is an* (*ε, k, z*)*-coreset using offset* ∆ *if for any set* S ⊂ *X,* |S| = *k,*

*cost*(*p,* S) − ∆ + *w*(*p*)*cost*(*p,* S) ≤ *ε* *cost*(*p,* S)

*p*∈*P*

*p*∈Ω

*p*∈*P*

Ω *is a* (*ε, k, z*)*-coreset using offset* ∆ *with additive error E if for any set* S ⊂ *X,* |S| = *k,*

*cost*(*p,* S) − ∆ + *w*(*p*)*cost*(*p,* S) ≤ *ε* *cost*(*p,* S) + *E.*

*p*∈*P*

*p*∈Ω

*p*∈*P*

The offset ∆ is often 0 for most coreset constructions, with a few exceptions [[25,](#_bookmark108) [43,](#_bookmark125) [86].](#_bookmark169) In our algorithm, ∆ = 0. The lower bounds hold for any choice of ∆.

# Lower Bounds in Euclidean Spaces for *k*-Means

We first prove the bound for *k*-means, i.e. for *z* = 2. The generalization to arbitrary powers is made in appendix: the proof idea is exactly alike, but a few new technicalities arise.

## *k*-Means

As mentioned in the proof outline in Section [1.2,](#_bookmark3) we proceed in three steps. First we show tha√t any

clustering of *e*1*, . . . , ed* using *k* cluster centers of unit norm must have cost at least 2*d* − *O*( *dk*).

Next, we show that for any co reset Ω of *t* points and weights *w* : Ω → R+, there is a clustering

*w*(*p*) *p* = *O*( *t/k*√*dk*) = *O*(√*td*). Finally we show that Ω must satisfy *w*(*p*) *p* = Ω(*d*) when *d* = Θ(*k* · *ε*−2). Combining all of these implies √*td* = Ω(*d*) ⇒ *t* = Ω(*d*) = Ω(*k* · *ε*−2).

For technical reasons, we consider the point set *e*1*, . . . , ed* as residing in R2*d* and not R*d*. The reason for this, is that we need to be able to find a vector that is orthogonal to all *ei* and all points in a coreset Ω (see proof of Lemma [4).](#_bookmark10) If the size of the coreset is *t < d*, then such a vector exists in R2*d*.

2 2*p*∈Ω *p*∈Ω

that has cost at most 2*d* − Ω(

*k/t* ·

*p*∈Ω *w*(*p*) *p* 2). Combined with step one, this shows that

**Step One.** We start by showing that any clustering of *e*1*, . . . , ed* using *k* centers of unit norm must have large cost:

**Lemma 1.** *For any d, consider the point set* *P* = {*e*1*, . . . , ed*} *in* R2*d. For* √*any set of k centers*

2

min

*c*1*, . . . , ck* ∈ R2*d with unit norm, it holds that*

*d i*=1

*k j*=1

*ei* − *cj* 2 ≥ 2*d* − 2

*dk.*

*Proof.* We see that

*k* 2

*d*

−

*k* 2 2

*i*=1

min *ei cj* 2 =

*j*=1

*i*=1

min *ei* 2 + *cj* 2 − 2 *ei, cj*

*d*

*d*

*j*=1

= 2*d* − 2

*k*

*e , c*

*i*=1 *k*

max *i j j*=1

= 2*d* − 2

*ei, cj* *.*

Now, for each *cj*, define argmax*h* *ei, ch* . Then:

*j*=1 *i*:*j*=argmax*h* *ei,ch*

*c*ˆ*j* to equal *cj*, except that we set the *i*’th coordinate to 0 if *j* =

*k d k*

2*d* − 2 *ei, cj* = 2*d* − 2 *ei, c*ˆ*j*

*j*=1 *i*:*j*=argmax*h* *ei,ch*

*i*=1 *j*=1

*d k*

= 2*d* − 2 *ei,* *c*ˆ*j*

*i*=1

*k*

*j*=1

By Cauchy-Schwartz, we have *k*

*j*=1

have norm at most 1, we have

√

*k j*=1

*c*ˆ*j* 1 ≤ *k*

*c*ˆ*j* 2 ≤

≥ 2*d* − 2 *c*ˆ*j* 1*.*

*j*=1

*c*ˆ*j* 2 · √*d*. Since the *c*ˆ*j*’s are orthogonal and

√ *j*=1

min

*k*. Thus we conclude

*d i*=1

*k j*=1

*ei* − *cj* 2

≥

2

2*d* − 2 *dk*.

**Step Two.** Next, we show that for any cor eset Ω of *t* points and weights *w* : Ω → R+, there

is a clustering that has cost at most 2*d* − Ω(

*k/t* ·

*p*∈Ω *w*(*p*) *p* 2). To prove this, we start by

considering the case of using a single cluster center to clusterweighted points:

**Lemma 2.** *Let r*1*, . . . , r* ∈ R2*d and let w*1*, . . . , w* ∈ R+*. There exists a unit vector v such that*

*w* | *r , v* | ≥ *t*

√

*i*=1

*i*

*i*

*i*=1

*wi* *ri* 2 *.*

*Proof.* Consider the random vector *u* =

*i*=1

*wiσiri* where the *σi* are i.i.d. uniform Rademachers

(−1 and +1 with probability 1*/*2). We see that

*i*=1

*wi*| *ri, u* | =

*i*=1

*wi*

*j*=1

*wjσj* *ri, rj*

=

*i*=1

*wi*

*j*=1

*wjσiσj* *ri, rj*

≥ *wi* *wjσiσj* *ri, rj*

*i*=1 *j*=1

= *u* 2*.*

2

We may then define the unit vector *v* = *u/* *u* 2 (with *v* = 0 when *u* = 0) and conclude that

*wi*| *ri, v* | ≥ *u* 2*.*

*i*=1

Since E[ *u* 2] = *w*2 *ri* 2 we conclude that there must exist a unit vector *v* with

2 *i*=1 *i* 2

*wi*| *ri, v* | ≥

*w*2 *ri* 2*.*

*i*=1

*i* 2

*i*=1

By Cauchy-Schwartz, we have:

|1 · *wi* *ri* 2| ≤

*i*=1

*w*2 *ri* 2 ·

*i*

2

*i*=1

*i*=1

*w*2 *ri* 2 · √

which finally implies

1 =

*i*=1

*i*

2

*wi*| *ri, v* | ≥

*wi* *ri* 2

*i*=1√

*.*

*i*=1

We can now extend this to using *k* centers of unit norm to cluster *t* weighted points:

**Lemma 3.** *Let r*1*, . . . , rt* ∈ R2*d and let w*1*, . . .* *, wt* ∈ R+*. For any positive e* *ven int* *eger k, there*

*exists a set of k unit vectors v*1*, . . . , vk such that*

*j*=1

*j*=1

*t i*=1

−2*wi* max*k*

*ri, vj* ≤ −

2*k/t*·

*t i*=1

*wi* *ri* 2

*and moreover, for all i we have* max*k*

*ri, vj* ≥ 0*.*

*Proof.* Partition *r*1*, . . . , rt* arbitrarily into *k/*2 disjoint groups *G*1*, . . . , Gk/*2 of at most 2*t/k* vectors

*ri*∈*Gj wi* *ri* 2 . Let *v*

√

each. For each group *Gj*, apply Lemma [2](#_bookmark8) to find a unit vector *uj* with *ri*∈*Gj wi*| *ri, uj* | ≥

2*t/k*

2*j*−1

= *uj*

and *v*2*j*

= −*uj*. Since we always add both *uj*

and −*uj*, it holds for

all *ri* that max*k*  *ri, vj* = max*k*

*j*=1

*j*=1

| *ri, vj* |. We therefore conclude (notice the ≤ rather than ≥

due to the negation):

− *k*

*t*

*t*

*r , v* = −

*k*

| *r , v* |

*i*=1

2*wi* max *i j j*=1

*i*=1 *k/*2

2*wi* max *i j*

*j*=1

≤ −2*wi*| *ri, uj* |

*j*=1 *ri*∈*Gj*

*k/*2

*ri*∈*Gj*

2*t/k*

≤ −2

*wi* *ri* 2

√2 *t*

*j*=1

*wi* *ri* 2

= *i*=1

*.*

−

*t/k*

With this established, we now combine this with step one to show that for any coreset Ω with *t* points, we must have *p* Ω *w*(*p*) *p* 2 = *O*( *t/k dk*) = *O*( *td*). This is established in two smaller steps:

√ √∈

**Lemma 4.** *For any d, consider the point set P* = {*e*1*, . . . , ed*} *in* R2*d. Let r*1*, . . . , rt* ∈ R2*d and let w*1*, . . . , wt* ∈ R+ *be an ε-coreset for P, using offset* ∆ *and with t < d. Then we must have*

∆ +

2

*t*

*i*=1

*wi*( *ri* 2 + 1) ∈ (1 ± *ε*)2*d.*

*Proof.* Since *t* + *d <* 2*d* there exists a unit vector *v* that is orthogonal to all *ri* and all *ej*. Consider placing all *k* centers at *v*. Then the cost of clustering *P* with these centers is 2*d*. It therefore must

hold that ∆ +  *t wi*( *ri* 2 + *v* 2 − 2 *ri, v* ) = ∆ + *t wi*( *ri* 2 + 1) ∈ (1 ± *ε*)2*d*.

*i*=1

2

2

*i*=1

2

**Lemma 5.** *For any d and any k >* 1*, let P* = {*e*1*, . . . , ed*} *in* R2*d. Let r*1*, . . . , rt* ∈ R2*d and let*

*w*1*, . . . , wt* ∈ R+ *be an ε-coreset for P with t < d, using offset* ∆*. Then*

√

*t*

*i*=1

*wi* *ri* 2 ≤

4*εd* + 2 *dk*

2*k/t .*

*Proof.* By Lemma [3,](#_bookmark9) we can find *k* unit vectors *v*1*, . . . , vk* such that *t*

*i*=1

*j*=1

min

−2*wi* max*k*

*ri, vj* ≤

− 2*k/t* · *t*

*i*=1

*wi* *ri* 2. By Lemma [1,](#_bookmark7) it holds that

*p*∈*P*

*k j*=1

*p* − *vj* 2 ≥ 2*d* − 2√*dk*. Since

points *r*1*, . . . , rt* with respective weights *w*1*, . . . , wt* and offset ∆ form an *ε*-coreset for *P* , we must

2

have

(1 − *ε*)(2*d* − 2√*dk*) ≤ ∆ + *k*

*t*

*r* − *v*

*i*=1 *t*

min *wi i j* 2

*j*=1

2

= ∆ + *w* ( *r* 2 + *v* 2 −

*k*

*r , v* )

*i i* 2

*i*=1

*t*

*j* 2 2 max *i j j*=1

*t*

= ∆ + *w* ( *r* 2 + 1) − 2

*k*

*r , v*

*i i* 2

*i*=1

*t*

*i*=1

*wi* max *i j j*=1

*t*

≤ ∆ + *wi*( *ri* 2 + 1) − 2*k/t* · *wi* *ri* 2*.*

2

By Lemma [4,](#_bookmark10) this is at most

*i*=1

*i*=1

We have therefore shown that

*t*

≤ (1 + *ε*)2*d* − 2*k/t* · *wi* *ri* 2*.*

*i*=1

*t*

√

(1 − *ε*)(2*d* − 2 *dk*) ≤ (1 + *ε*)2*d* − 2*k/t* · *wi* *ri* 2 ⇒

*i*=1

*t*

√

2*k/t* · *wi* *ri* 2 ≤ (1 + *ε*)2*d* − (1 − *ε*)(2*d* − 2 *dk*) ⇒

*i*=1 *t*

√

2*k/t* · *wi* *ri* 2 ≤ 4*εd* + (1 − *ε*)2 *dk* ⇒

*i*=1

√

*t*

*i*=1

*wi* *ri* 2 ≤

4*εd* + 2 *dk*

2*k/t .*

**Step Three.** Finally we show that any coreset Ω must satisfy *p*∈Ω *w*(*p*) *p* 2 = Ω(*d*) when

*d* = Θ(*k* · *ε*−2):

**Lemma 6.** *For any* 0 *< ε <* 1*/*2 *and any positive even integer k, let d* = *k/*(36*ε*2) *and let*

*P* = {*e*1*, . . . , ed*} *in* R2*d. Let r*1*, . . . , rt* ∈ R2*d and let w*1*, . . . , wt* ∈ R+ *be an ε-coreset for P with*

*t < d, using offset* ∆*. Then* *t wi* *ri* 2 ≥ *d/*6*.*

*i*=1

*Proof.* Consider the Hadamard basis *h*1*, . . . , hq* on *q* = 1*/*(36*ε*2) coordinates, i.e. the set of rows in the normalized Hadamard matrix. This is a set of *q* orthogonal unit vectors with all coordinates in

{−1*/*√*q,* 1*/*√*q*}. All *hi* except *h*1 have equally many coordinates that are −1*/*√*q* and 1*/*√*q* and

√

*h*1 have all coordinates 1*/ q*. Now partition the first *d* coordinates into *k* groups *G*1*, . . . , Gk* of *q*

coordinates each. For any *hi*, consider the *k* centers *vi , . . . , vi*

obtained as follows: For each group

1 *k*

*Gj* of *q* coordinates, copy *hi* into those coordinates to obtain the vector *vi*. We must have that

*j*

*d* min*k*  *eh* − *vi* 2 = *d* min*k*  *eh* 2 + *vi* 2 − 2 *eh, vi* . Since *k >* 1, there is always a *j*

*h*=1

*j*=1

*j*

2

*h*=1

*j*=1

2

*j*

2

*j*

such that *eh, vi* = 0. Moreover, for *i* = 1, we have max*k*  *eh, vi* = 1*/*√*q* and for *i* = 1, it holds

*j*

*j*=1

*j*

that precisely half of all *eh* have max*k*  *eh, vi* = 1*/*√*q*. Thus we have *d*

√

√*j*=1

*j*

*h*=1

*j*=1

*j*

2

min*k*

*eh* − *vi* 2 ≤

(*d/*2)2 + (*d/*2)(2 − 2*/ q*) = 2*d* − *d/ q*. Thus:

*t*

(1 + *ε*)(2*d* − *d/*√*q*) ≥ ∆ + *wh*

2

*j*

*h*=1

( *rh*

2 + 1 −

*k*

2 max

*j*=1

*rh*

*, vi* )

By Lemma [4,](#_bookmark10) this is at least

We have thus shown

*j*

*t*

≥ (1 − *ε*)2*d* − 2

*h*=1

*k*

*wh* max

*j*=1

*rh*

*, vi* *.*

*t*

√

(1 + *ε*)(2*d* − *d/ q*) ≥ (1 − *ε*)2*d* − 2

*h*=1

*k*

*wh* max

*j*=1

*rh*

*, vi* ⇒

*t*

√

4*εd* − (1 + *ε*)*d/ q* ≥ −2

*h*=1

*k*

*j*

*wh* max

*j*=1

*rh*

*, vi* ⇒

*k i* √

*j*

*t*

*h*=1 *t*

*wh* max *rh, vj* (1 + *ε*)*d/*(2

*j*=1

≥

*q*) − 2*εd* ⇒

*k i* √

≥

*wh* max *rh, vj d/*(2

*j*=1

*q*) − 2*εd.*

*h*=1

Now consider any *rh* with weight *wh*. Collect the vectors *ui* such that *ui* = *vi*∗ with *j*∗ =

*h*

*h*

*j*

argmax*j* *rh, vi* . By construction, all these *q* vectors are orthogonal (either disjoint support or

*j*

distinct vectors from the Hadamard basis). By Cauchy-Schwartz, we then have *whrh,* *q ui* ≤

*q i* √

*wh* *rh* 2

*i*=1 *uh* 2 = *wh* *rh* 2

*q*. We then see that

*q*

*i*=1 *h*

*dq/*(2√*q*) − 2*εdq* ≤

*j*

*t*

*i*=1 *h*=1

*k*

*wh* max

*j*=1

*rh*

*, vi*

*t q*

= *wh* *rh, ui*

*h*

*h*=1 *i*=1

*t q*

= *whrh,* *ui*

*h*

*h*=1 *t*

*i*=1

≤ *wh* *rh* 2√*q.*

*h*=1

We have thus shown *t*

*h*=1

*wh* *rh* 2 ≥ *d/*2 − 2*εd*√*q* = *d/*2 − 2*εd/*(6*ε*) = *d/*2 − *d/*3 = *d/*6.

### Combining it All.

**Theorem 5.** *For any* 0 *< ε <* 1*/*2 *and any positive even integer k, let d* = *k/*(36*ε*2) *and let P* = {*e*1*, . . . , ed*} *in* R2*d. Let r*1*, . . . , rt* ∈ R2*d and let w*1*, . . . , wt* ∈ R+ *be an ε-coreset for P, using offset* ∆*. Then t* ≥ *ε*−2*k/*180*.*

*Proof.* If *t* ≥ *d*, then we are done. Otherwise, we combine Lemma [5](#_bookmark11) and Lemma [6,](#_bookmark12) to get:

*t*

This finally implies:

*d/*6 ≤

≤

=

=

*wi* *ri* 2

*i*=1

√

4*εd* + 2 *dk*

2*k/t* 4*εd* + 6*εd*

2*k/t* 10*εd*

2*k/t.*

*t* ≥ *ε*−2*k/*180*.*

# Lower Bounds For Discrete Metrics

We show in this section Theorem [1,](#_bookmark0) that we recall here for convenience:

**Theorem 1.** *For any* 0 *< ε <* 1*/*2*, k and n* ≥ *ε*−5 *such that* log *k* = *O*(log *n*)*, the* *re exists* *a finite*

*n point metric such that any* (*ε, k, z*) *coreset using offset* ∆ *consists of at least* Ω

*ε*2

*points.*

*k* log *n*

To prove the theorem, we create a *subinstance* that implies a lower bound for the case *k* = 1. The general lower bound for arbitrary *k* then naturally combines several copies of the subinstance. The key technical part of our proof is the use of some Azuma-Hoeffding type concentration inequality, but where the concentration probability is *lower bounded*. The results we use are developed in Section [5.1.](#_bookmark14) We present the subinstance in Section [5.2,](#_bookmark19) and the general lower bound in Section [5.3.](#_bookmark21)

## Technical lemmas

Our proof relies on Lemma [8,](#_bookmark16) which we prove using the following result from [[39].](#_bookmark122)

**Lemma 7** (Equation 2.11 in [[39])](#_bookmark122)**.** *Let ξ*1*, ..., ξm be independent centered random variables, and ε*˜ *such that*

∀*i, k* ≥ 3 |E[*ξk*]| ≤ 1 *k*!*ε*˜*k*−2E[*ξ*2]*.*

*Let σ*2 = E[*ξ*2]*, and Sm* = *m*

*i* 2 *i*

*ξi.*

*i i*=1

*Then, for all* 0 ≤ *x* ≤ 0*.*1 *σ ,*

*ε*˜

Pr[*S* ≥ *xσ*] ≥ 1 − Φ *x*(1 − *cx*  *ε*˜ · 1 − *c*(1 + *x*) *ε*˜ *,*

*m*

*σ*

*σ*

*where c is an absolute positive constant and* Φ *is the standard normal distribution function.*

**Lemma 8.** *Let X , ..., X be independent Bernouilli random variables with expectation p* 1*/*4*,*

≤1 *m*

*ε >* 0 *and w*1*, ..., wm be some positive weights, such that* max *wi* ≤ *γ* · *wi , for some γ. Let*

*εm*

*µ* = *p* · *wi. Then, there exists a constant β such that*

Pr *wiXi* − *µ > εµ* ≥ exp(− *ε*2*mp*)

*β*

*γ*2

*Proof.* Define *ξi* = *wiXi* − *pwi*. We show that the variables *ξi* verify the conditions of Lemma [7.](#_bookmark15) They are independent and centered, and:

E[*ξ*2] = *p*(*wi* − *pwi*)2 + (1 − *p*)(*pwi*)2)

*i*

= *w*2 *p* − 2*p*2 + *p*3 + *p*2 − 2*p*3 + *p*4

*i*

2 2 3 4

*w*2*p*

= *wi* (*p* − *p*

≥

−

using *p* ≤ 1*/*4. The *k*-th moment verifies:

*p* + *p* ) *i ,*

2

E[*ξk*] = *wk* · *p* · (1 − *p*)*k* + (1 − *p*) · (−*p*)*k* ≤ *wkp,*

*i*

*i*

*i*

hence *ξi* verifies the condition of Lemma [7](#_bookmark15) with *ε*˜ = max*i wi*. We want to apply that lemma to *x*

of the order *εµ* : therefore, we need to bound that quantity. Note that

*σ*

2 *p* 2

*p* ( *wi*)2

*σ* ≥ 2

*σ*

*wi* ≥ 2 ·

*ε*√*mp*

*,* (1)

*m*

and so by the assumptions of the lemma

*ε*˜ ≥

*γ*√2 . Furthermore,

*µ p* *wi*

*σ* ≤ *p*

2*m*

≤

2*mp* (2)

*wi*

Now, let *x* := *ε*√

· *µ* . Thus, *x* verifies *x* ≤ *ε* √

· √2*pm* ≤ 0*.*1 *σ*

and so applying Lemma [7](#_bookmark15) we

obtain:

10*γc* 2 *σ*

10*γc* 2

*cε*˜

Pr *wiXi*

− *µ > εµ* ≥ 1 − Φ *x*(1 −

*ε*˜

*cx* )

*σ*

· 1 − *c*(1 + *x*) *ε*˜

≥ (1 − Φ (0*.*9*x*)) · 0*.*9

*σ*

= 0*.*9 · Pr[N (0*,* 1) ≥ 0*.*9*x*]

≥ 0*.*9 · 1 1 − 1 − *e*−(0*.*9*x*)2

2

*β*

≥ exp(− *γ*2 *ε*

*β*

2 *µ*2

*σ*2 )

2

≥ exp(− *γ*2 *ε mp*)*,*

where *β* is some absolute constant, and where the last line uses Eq. [(2).](#_bookmark17)

Figure 2: Illustration of an instance *Uδ*. Dashed edges have length 21*/z*, black ones have length 1.

## A subinstance for the case *k* = 1

We now turn to proving a lower bound for the case where *k* = 1. This is going to be our building block in the next subsection where we generalize the result to arbitrary *k*. Let *δ* = 1*/*4 be a parameter.

**Definition 2.** *A subinstance Uδ is defined as follows. Let C be a set of n* candidate centers *and P a set of of nU* clients*. The metric on the ground set P* ∪ *C is defined according to the following probability distribution.*

*For each pair* (*p, c*) ∈ *P* × *C,*

*dist*(*p, c*) = 1 *with probability δ*

21*/z otherwise*

*Distances between any pair of points p, p* ∈ *P or c, c* ∈ *C is set to* 21*/z. Fig.* [*2*](#_bookmark18) *illustrates the definition.*

(3)

Since any complete graph with edge length only 1 or≤ 2 defines a metric space, it immediately follows that (*P* ∪ *C,* dist) is a metric space.

The important properties of the subinstance are summarized in the following lemma. We say that a set of weights is *ε-rounded* if all weights are multiples of *ε*.

**Lemma 9.** *There exists a constant η and an instance Uδ* = (*P, C, dist*) *with* |*P* | = *nU* = *ε*−2 log |*C*|*, δ* ≤ 1*/*4 *and* |*C*| ≥ *ε*−5*, the following holds. For any subset* Ω ⊆ *P with ε/*2*-rounded weights wx being such that wx* ∈ (1 ± 1*/*2)*nU , we have:*

* + 1. *If* |Ω| *< ε*−2*η* log |*C*|*, there exists a center c*˜ ∈ *C such that*

*x*∈Ω:*d* *ist*(*x,c*˜)=1

*and* |*x* ∈ *P* : *dist*(*x, c*˜) = 1| ≥ *δnU*

*wx >* (1 + 200*ε*)*δnU*

* + 1. *If* |Ω| ≥ *ε*−2*η* log |*C*|*, there exists a center c*∗ ∈ *C such that*

*x*∈Ω:*di* *st*(*x,c*∗)=1

*and* |*x* ∈ *P* : *dist*(*x, c*∗) = 1| ≥ *δnU .*

*wx* ≥ (1 − *ε*)*δnU*

*Proof.* We use the probabilistic method: we will show that, when *Uδ* is generated according to the process defined above, the two properties of the lemma hold with some positive probability. This is enough to ensure the existence of an instance *Uδ* verifying them.

We start by proving the first item. Fix some arbitrary subset of clients Ω of size at most *ε*−2*η* log |*C*|, with weight *wx,* ∀*x* ∈ Ω and a candidate center *c* ∈ *C*. Let *w*1(*c,* Ω) := *x*∈Ω:dist(*x,c*)=1 *wx* denote the (weighted) number of edges of length 1 from Ω to *c*. The expected value of *w*1(*c,* Ω) over the random choice of edges is *δ* · *nU* . We aim at applying Lemma [8](#_bookmark16) on the variable *w*1(*c,* Ω). This cannot be done directly, as we have no control on max *wx*. Hence, we partition the points of Ω into five groups:

* Ω1 := {*x* ∈ Ω : *wx < ε*}
* Ω2 := {*x* ∈ Ω : *wx* ∈ [*ε,* 1)}
* Ω3 := {*x* ∈ Ω : *wx* ∈ [1*, ε*−1)}
* Ω4 := {*x* ∈ Ω : *wx* ∈ [*ε*−1*,* 10 log(1*/δ*) · *ε*−2)}
* Ω5 := {*x* ∈ Ω : *wx* ≥ 20 log(1*/δ*) · *ε*−2}

We will show that, ∀*i* ∈ {2*, ...,* 5}, *w*1(*c,* Ω*i*) exceeds its expectation by a factor (1 + 205*ε*) with large probability, and that *w*1(*c,* Ω1) is negligible.

First, note that since *x*∈Ω *wx* ≤ (1 + 1*/*2)*nU* = 3 *ε*−2 log |*C*|, it must be that

2

|Ω | ≤ log |*C*| *.*

5

10 log(1*/δ*)

Hence, *c* is connected with length 1 to all points of Ω5 with probability *δ*|Ω5| ≥ exp (− log |*C*|*/*10) =

|*C*|−1*/*10.

Now, on each group Ω2*,* Ω3*,* Ω4, the maximum weight cannot be more than 20 log(1*/δ*) · *ε*−1 times the average.

For *i* ∈ {2*,* 3*,* 4}, *w*1(*c,* Ω*i*) is the sum of *m* = |Ω*i*| ≤ *ε*−2*η* log |*C*| random variables *Xx*, for *x* ∈ Ω*i*, with *Xx* = 0 with probability (1 − *δ*) and *Xx* = *wx* with probability *δ* = 1*/*4. Hence, Lemma [8](#_bookmark16) gives that:

Pr [*w* (*c,* Ω ) ≥ (1 + 205*ε*) · E[*w* (*c,* Ω )]] *>* exp(− *β ε*2*δ*|Ω |)

1 *i* 1 *i* log(1*/δ*)2 *i*

≥ exp(− log |*C*|*/*10)*,*

for some absolute constant *β* given by Lemma [8](#_bookmark16) and *η* ≤ log(1*/δ*)2 .

10*βδ*

Finally, to deal with Ω1, we note that E[*w*1(*c,* Ω1)] ≤ *εδnU* . Hence, 5

*i*=2

E[*w*1(*c,* Ω*i*)] ≥ E[*w*1(*c,* Ω)]−

*εδnU* , and

5 5

*w*1(*c,* Ω*i*) ≥ (1 + 205*ε*) E[*w*1(*c,* Ω*i*)] ⇒ *w*1(*c,* Ω) ≥ (1 + 200*ε*)*δnU .*

*i*=2

*i*=2

Since all groups are disjoint, the variables *w*1(*c,* Ω*i*) are independents and we can combine the previous equations to get:

Pr 



*x*∈Ω:dist(*x,c*˜)=1

*wx* ≥ (1 + 200*ε*) · *δnU*  *>* |*C*|−3*/*10*.*

Since the length of the edges are chosen independently, the probability that there exists no center

*c*˜ with *x*∈Ω:dist(*x,c*˜)=1 *wx* ≥ (1 + 200*ε*) · *δnU* is at most

1 − |*C*|−3*/*10 |*C*| = exp |*C*| log(1 − |*C*|−3*/*10)

7*/*10

≤ exp(−|*C*| )*.*

And hence with probability at least 1 − exp(−|*C*|7*/*10) there is a center *c*˜ with *x*∈Ω:dist(*x,c*˜)=1 *wx* ≥

(1 + 200*ε*) · *δnU* .

To conclude the proof of the first bullet, it remains to do a union-bound over all possible weighted subset Ω. Such an Ω consists of at most *nU* different points, with *ε/*2-rounded weights in [0*,* (1 + 1*/*2)*nU* ]. Hence, there are at most 4 *nU* many different weights.

*ε*

Therefore, there are 4*nU* *nU* many possible weighted subset Ω with *ε/*2-rounded weights, i.e.,

*ε*

exp *ε*−2 log |*C*| · log 2*ε*−3 log |*C*| *.*

We can conclude that there exists a center *c*˜ ∈ *C* with *x* Ω:dist(*x,c*˜)=1 *wx* ≥ (1 + 200*ε*) · *δnU* with probability at least

∈

1 − exp *ε*−2 log |*C*| · log 2*ε*−3 log |*C*| · exp(−|*C*|7*/*10) ≥ 99

100

by our choice of |*C*|. Furthermore, Pr[|*x* ∈ *P* : dist(*x, c*˜) = 1| ≥ *δnU* ] ≥ 1*/*2, because |*x* ∈ *P* : dist(*x, c*˜) = 1| follows a binomial law with mean *δnU* . This concludes the proof of the first bullet.

We now turn to the second bullet of the claim, for which the proof is a more standard application of Azuma inequality. Fix some coreset Ω of size at least *ε*−2*η* log |*C*|, and a center *c*. We have,

Pr [*w*1(*c,* Ω) ∈*/* (1 ± *ε*) · *δnU* ] ≤ exp(−2*ε*2*δ*

2 *n*2

*w*2 )

*U*

*i*

2

where the second inequality uses *n*2

*U*

≤ exp(−2*/*4 · *δ*

≤ exp(−1*/*2 · *δ*

2

≥ 1*/*4 ( *wi*)2 ≥ 1*/*4 · *w*2.

*i*

*ε*2) *ε*2)*,*

Since those events are independent for different centers *c*, the probability that there exists no center

*c* ∈ *C* with *w*1(*c,* Ω) ∈ (1 ± *ε*) · *δnU* is at most exp(−1*/*2 · *δ*2*ε*2|*C*|).

Hence, a union-bound over the 4*nU* *nU* many possible weighted subset Ω ensures that the following

*ε*

holds with probability at most 1 −

*U* *nU*

· exp(−1*/*2 · *δ*2

*ε*2|*C*|) ≥ 99*/*100: For any Ω there exists

*ε*

4*n*

a center *c* with *w*1(*c,* Ω) ∈ (1 ± *ε*) · *δ*|Ω| as desired.

## Combining the subinstances

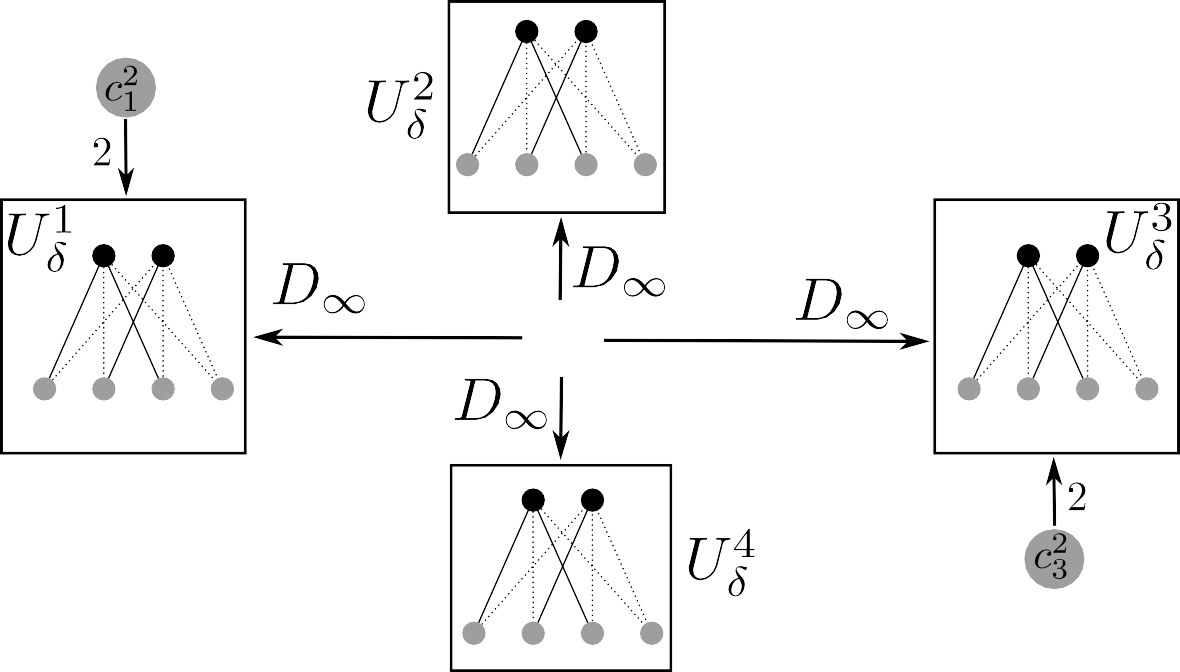


Figure 3: Illustration of a full instance, in the case *z* = 1. The subinstance are inside squares, and there is an edge from a node to a square when the node is linked to every point of the subinstance, with the distance written on the edge. *D*∞ is set to be 4*i* · *nU* ·*k* . The node *c*4·∞ is not represented.

*ε*

We now conclude the proof of the lower bound for the (*ε, k, z*) coreset using offset ∆. We consider *k*

copies of the subinstance given by Lemma [9,](#_bookmark20) *U* 1*, . . . , Uk*, where the set of clients in each subinstance

*δ δ*

has size *nU* = 10*ε*−2 log *n*, and the set of candidate centers has size |*C*| such that |*C*| ≥ *ε*−5 and log (|*C*| · *k*) = *O*(log |*C*|). In total, there are *k*|*C*| many candidate centers, and *knU* many different clients. The subinstances are numbered from 1 to *k*, and connected together in a star-graph metric

centered at an arbitrary point *c*∞, where all points are at distance *nU* ·*k* of *c*∞. There is some

*ε*

additional candidate centers: *c*4·∞, at distance 4 · *nU* ·*k* of every client, and for subinstance *i* there is a center *c*2, at distance 21*/z* from every client of the subinstance. Fig. [3](#_bookmark22) illustrates that construction.

*ε*

*i*

We can now turn to the proof of the theorem. For this, we start with three claims: The first one shows that the total weight of the coreset must be very close to the number of point in the instance. The second shows that the offset ∆ must be negligible, and the third that the coreset weight in each subinstance is close to *nU* , the number of point in a subinstance.

**Claim 6.** *If* Ω *is an ε-coreset with offset* ∆ *for the instance, then the total weight verifies w*(Ω) ∈

(1 ± 2*ε*)*knU .*

*Proof.* Consider the solution consisting only of one center placed at *c*∞. Let *D*∞ = *nU* ·*k* . This

*ε*

solution has cost cost(*c*∞) = *knU* · *Dz* , and cost(Ω*, c*∞) = *w*(Ω) · *Dz* . Hence,

∞ ∞

∆ + *w*(Ω) · *Dz* ∈ (1 ± *ε*)*knU* · *D*∞*.*

∞

*z*

Similarly, considering the solution that places only one center at *c*4·∞ gives

∆ + *w*(Ω)4*zDz*

∞

∈ (1 ± *ε*)*knU* · 4 *D*∞*.*

Substracting those two equations yields:

*z z*

(4*z* − 1)*w*(Ω) · *Dz*

∞

∈ ((4 − 1) ± (4 + 1)*ε*)*knU* · *D*∞*,*

*z z z*

and so *w*(Ω) ∈ (1 ± 2*ε*)*knU* .

**Claim 7.** *If* Ω *is an ε-coreset with offset* ∆ *for the instance, then* |∆| ≤ 3*εk* · *nU .*

*Proof.* Consider the solution S2 = {*c*2*,* ∀*i*}. We have cost(S2) = 2*knU* and cost(Ω*,* S2) = 2*w*(Ω) ∈

*i*

(1 ± 2*ε*)cost(S2), using Claim [6.](#_bookmark23) Since |∆ + cost(Ω*,* S2) − cost(S2)| ≤ *ε*cost(S2), it must be that

|∆| ≤ 3*ε*cost(S2) = 3*εknU* .

**Claim 8.** *If* Ω *is an ε-coreset with offset* ∆ *for the instance, then in every subinstance, the sum of the coreset weights is in* (1 ± 1*/*2)*nU .*

*Proof.* Assume towards contradiction that, in some subinstance, say subinstance *i*, the coreset mass is not in (1 ± 1*/*2)*nU* , and consider a solution S that places one center in each subinstance but subinstance *i*. Suppose w.l.o.g. that the subinstance is overweighted: the coreset places a total weight larger than 3*/*2 · *nU* in it. The cost of the solution is a most

cost(S) ≤ 2(*k* − 1)*nU*

+ *nU*

· *knU*

*ε*−1 *z*

for subinstances that contain a center

≤ (1 + *ε*) *k* · *n*2 *ε*−1 *z ,*

*U*

for the overweig h ted subi nstance

while the cost in the coreset verifies

∆ + cost(Ω*,* S) *>* −3*εknU*

+ 3*/*2 · *nU*

· *knU*

*ε*−1 *z*

(using Claim [7](#_bookmark24) and keeping only the cost of the overweighted subinstance)

*>* (1 + *ε*) · (1 + *ε*) *k* · *n*2 *ε*−1 *z*

*U*

*>* (1 + *ε*)cost(S)*,*

hence contradicting the fact that Ω is an *ε*-coreset with offset ∆.

The proof of the case where some subinstance is underweighted is done exactly alike.

We can now turn to the proof of the theorem.

*Proof of Theorem* [*1.*](#_bookmark0)Assume toward contradiction that there exists an *ε*-coreset with offset ∆ of

size smaller than *η*

10

· *kε*−2 log |*C*|, where *η* is the constant of Lemma [9.](#_bookmark20)

First, this implies the existence of an 2*ε*-coreset with *ε*-rounded weights, simply by rounding each weight to the closest multiple of *ε*.

Using Claim [8,](#_bookmark25) we can apply Lemma [9](#_bookmark20) on each subinstance. The total coreset size is *η* ·*kε*−2 log |*C*|: that means that there are at least *k/*10 subinstances for which the coreset contains no more than *ηε*−2 log |*C*| many different points. We refer to these subinstances as the *bad* subinstances. Using Lemma [9,](#_bookmark20) we construct a solution by taking the center given by bullet 1 for the bad subinstances, i.e.: center *c*ˆ as per the notation of Lemma [9,](#_bookmark20) and bullet 2 for the others, i.e.: center *c*∗ as per the notation of Lemma [9.](#_bookmark20) The cost of that solution is *n*1 + 2(*knU* − *n*1) = 2*knU* − *n*1, where *n*1 the number of edges of length 1 from the clients to S. Similarly, the cost of S for the coreset is 2 · *w*(Ω) − *w*1(S*,* Ω), where *w*(Ω) is the total coreset weight and *w*1(S*,* Ω) the weighted number of length 1 edges from Ω to S. By construction of S, *w*1(S*,* Ω) verifies

S

10

*w*1(S*,* Ω) ≥ *k/*10 · (1 + 200*ε*)*δnU* + 9*k/*10 · (1 − *ε*)*δnU >* (1 + 19*ε*)*δ* · *knU*

Furthermore, using properties of Lemma [9,](#_bookmark20) *n*1 ≤ *δknU* . Hence, the cost of S in the coreset satisfies

∆ + 2 · *w*(Ω) − *w*1(S*,* Ω) *<* 3*εknU* + 2 · (1 + 2*ε*)*knU* − (1 + 19*ε*)*δ* · *knU*

≤ (2*knU* − *n*1) + *εknU* · (7 − 38*δ*) *<* (1 − *ε*)(2*k*|*P* | − *n*1)*,*

where the last inequality uses *δ* = 1*/*4, so that (38*δ* − 7)*knU* ≥ 2*knU* . Therefore the cost of the coreset for S is smaller than a (1−*ε*) factor times the cost of *P* for S, a contradiction that concludes the proof.

A simple corollary of that proof is a lower bound for metric with bounded doubling dimension. Since any *n* points metric has doubling dimension *O*(log *n*), the metric constructed has doubling dimension *D* = *O*(log *n*) = *O*(log |*C*|), which implies Corollary [2.](#_bookmark1)

# Algorithm

Throughout this section, we use the following notation. We use *P* 0 to denote the distinct number of points in *P* . For a solution S, we define the |*P* | dimensional cost vector *v*S induced by S as

*vp*S = cost(*p,* S)*.*

Hence, *v*S 1 = cost(*P,* S).

We will also make use the following lemma to have a weaker version of the triangle inequality for *k*-Means and more general powers of distances. See Appendix A from Makarychev, Makarychev, and Razenshteyn [[73]](#_bookmark156) for a proof.

**Lemma 10** (Triangle Inequality for Powers)**.** *Let a, b, c be an arbitrary set of points in a metric space with distance function d and let z be a positive integer. Then for any ε >* 0

1 + *ε* *z*−1

*z*

*d*(*a, b*)*z* ≤ (1 + *ε*)*z*−1*d*(*a, c*)*z* +

*ε*

*d*(*b, c*)*z*

*z*

+

|*d*(*a, b*)

*z*

− *d*(*a, c*) | ≤ *ε* · *d*(*a, c*)

*z* + *ε* *z*−1

*ε*

*d*(*b, c*)*z.*

We also require Bernstein’s inequality:

**Theorem 9** (Bernstein’s Inequality)**.** *Let X*1*, . . . Xδ be non-negative independent random variables.*

*Let S* = *δ Xi. If there exists an almost-sure upper bound M* ≥ *Xi, then*

*i*=1

P [|*S* − E[*S*]| ≥ *t*] ≤ exp − 2  *δ*

*t*2

*.*

*Var*[*X* ] + 2 · *M* · *t*

## Preprocessing and General Outline

We make the following three assumptions:

*i*=1 *i* 3

**Assumption 1** The number of distinct points *P* 0 is in poly(*k/ε*).

**Assumption 2** The dimension *d* of the points is in *O*(*ε*−2 log *P* 0) = *O* *ε*−2 log *k* · poly *z* .

*ε*

**Assumption 3** The point set is unweighted.

Assuming these simplifies the presentation significantly. The first assumption can be justified by computing a (potentially weighted) coreset in preprocessing. Coresets of size *O*˜(*k*2 · *ε*−4 · 2*O*(*z*)) are known to exists for all (*k, z*) clustering objectives [[35],](#_bookmark118) which is sufficient for our purposes.

The second assumption follows from a result on terminal embeddings due to Narayanan and Nel- son [[82].](#_bookmark165) We will discuss this result in more detail in Section [6.4.](#_bookmark44) Suffice to say here is that there exists a coreset-preserving embedding from an arbitrary dimension to the desired target dimension.

The final assumption follows by scaling the weights and rounding them to integers. Each weight is then treated as a multiplicity of a point. Note that this does not increase the distinct number of points. For a proof of the validity of such an operation, we refer to Corollary 2.3 [[35].](#_bookmark118)

We now describe the algorithm. We first compute some constant factor approximation A for the

entire instance.[1](#_bookmark28) Let *Ci* be the *i*th cluster induced by A. The average cost of *Ci* is ∆*C*

*i*

= cost(*Ci,*A) .

|*Ci*|

For all *i, j*, the *ring Ri,j* is the set of points *p* ∈ *Ci* such that 2*j*∆*C* ≤ cost(*p,* A) ≤ 2*j*+1∆*C .* The

*i*

*i*

*inner rings RI*(*Ci*) := ∪*j*≤*z* log(*ε/z*)*Ri,j* (resp. *outer rings RO*(*Ci*) := ∪*j>*2*z* log(*z/ε*)*Ri,j*) of a cluster

*Ci* consists of the points of *Ci* with cost at most (*ε/z*)*z* ∆*C* and resp. at least (*z/ε*)2*z* ∆*C* . The *main*

*i*

*i*

*rings RM* (*Ci*) consists of all the other points of *Ci*. For each *j*, *Rj* is defined to be ∪*k*

*i*=1

*Ri,j*. We

then partition the input point set into the following groups.

* For each *j*, the rings *Ri,j* are gathered into *groups GM* :

*j,b*

*GM* := *p* | ∃*i, p* ∈ *Ri,j* and

*j,b*

*ε* *z* · cost(*Rj,* A) · 2*b* ≤ cost(*R*

4*z*

*k*

*,* A) ≤ *ε* *z* · 2*b*+1 · cost(*Rj,* A) *.*

* For any *j*, let *GM* := ∪*b*≤0*GM* be the union of the cheapest groups, and *GM* :=

*j,min*

*j,b*

*j,max*

*i,j*

4*z*

*k*

∪ 4*z GM* be the union of the most expensive ones. We define *GM* := *GM* ∪

*b*≥*z* log *ε*

*j,b*

*j*

*j,max*

*GM* \ *GM* .

*b*

*j,b*

*j,min*

1A bicriteria approximation that uses *O*(*k*) centers and yields a constant factor approximation would also be possible. See [[74]](#_bookmark157) for state of the art bounds on bicriteria approximations for *k*-median and *k*-means. For higher powers, see Mettu and Plaxton [[78]](#_bookmark161) for a 2*O*(*z*) approximation.

**Algorithm 1** Euclidean Coreset Construction Compute a *O*(2*z*) approximation A to *P* .

Preprocess the instance such that Assumptions 1-3 hold.

Partition the points into groups G =

*Gj,*max ∪

*G*(*j, b*) \ *Gj,*min ∪ *GO*

∪ *GO* \ *GO* .

*j b*

**for all** Groups *G* ∈ G **do**

max

*b b* min

cost(*p,*A)

Sample *δ* ∈ *k* ·log *k* ·*ε*−2 ·2*O*(*z* log(1+*z*))·log3 *ε*−1 ·min(*ε*−*z, k*) points Ω*G* proportionate to

*ε*

and weighted by  cost(*G,*A) .

cost(*G,*A) ,

### end for

**for all** *ci* ∈ A **do**

*δ*·cost(*p,*A)

Weigh *ci* ∈ A by the number of points not in G ∩ *Ci*

### end for

Output Ω = A ∪ *G* Ω*G*.

* The points in the outer rings are also partitioned into *outer groups*:

*GO* = *p* | ∃*i, p* ∈ *Ci* and

*b*

*ε* *z* · cost(*RO*A*,* A) · 2*b* ≤ cost(*R* (*C* )*,* A) ≤ *ε* *z* · 2*b*+1 · cost(*RO*A*,* A) *.*

4*z*

*k*

*O*

*i*

4*z*

*k*

We denote by *PGO* := {*p* ∈ *P* | *p* ∈ *C* ∧ *C* ∩ *GO* = ∅} the set all points in clusters intersecting

*b b*

with *G*.

*b*

*max*

*b*≥*z* log *ε*

*b*

*max*

*b*

*b*

* We let as well *GO*

*min*

*G*

*O*

*min*

.

= ∪*b*≤0*GO* and *GO* = ∪

4*z GO*. We define *GO* := *GO*

∪ *GO* \

The set of all groups is denoted by G := *GM* ∪ *GO*. We sometimes abuse notation and also use G to denote the set of points in the groups *GM* ∪ *GO*, i.e. *P* ∩ G = {*p* ∈ *P* | *p* ∈ *G* ∈ G} and *P* \ G = {*p* ∈ *P* | *p* ∈ *G* ∈*/* G}. We summarize the group partitioning scheme with the following two facts.

**Fact 1.** *There exist at most O*(*z*2 log2 *z/ε*) *groups in* G*.*

**Fact 2.** *All groups are pairwise disjoint. Moreover, every cluster C induced by* A *intersects with at most one group G* ∈ *GO.*

The final algorithm now consists of sensitivity sampling for all groups *G* ∈ G. Specifically, we pick a point *p* ∈ *G* with probability  cost(*p,*A) . We repeat this *δ* times, where *δ* is the size of the desired

cost(*G,*A)

coreset. For each picked point *p*, we set the weight equal to *wp* := cost(*G,*A) . For every cluster *Ci*,

*δ*·cost(*p,*A)

we weigh the center *ci* with the number of points in *Ci* ∩ *j*

*Gj,*min ∪ *GO*

. The entire coreset

construction then consists of steps required to satisfy the three initial assumptions followed by the sampling procedure, see Algorithm [1.](#_bookmark29)

min

For every group *G* ∈ G, we will prove that the sampling yields an (*ε, E*) coreset with *E* = *ε* ·

cost(*G,* A).

Given a solution S, the basic estimator for the error is

*p*∈Ω

*D*Ω(*G*) := *wp* · cost(*p,* S) − cost(*G,* S) *.*

S

If for all solutions S we have a coreset of group *G* ∈ G, we can compose the coresets of each group such that we have a coreset for *P* . Specifically, we will prove Theorem [4](#_bookmark2) by proving the following three lemmas.

The first lemma states that we can use the centers of A as proxies for all points not in G. The second and third lemmas informally give the bounds such that sensitivity sampling for every group *G* ∈ *GM* and respectively *G* ∈ *GO* yield corsets.

**Lemma 11.** *Let P be a set of points and let* S *be an arbitrary solution. Then*

*Ci*

*cost*(*P* \ G*,* S) − |G ∩ *Ci*| · *cost*(*ci,* S) ≤ *ε* · (*cost*(*P,* S) + *cost*(*P,* A)) *.*

**Lemma 12.** *Let P be a set of points and let G* ⊂ *GM be a group. Then there exist absolute constants*

*γ*1 *>* 0 *such that the sampling procedure of Algorithm* [*1*](#_bookmark29) *with δ* ≥ *k* · log *k* · *ε*−2 · 2*γ*1·*z* log(1+*z*) · log3 *ε*−1 ·

*ε*

min(*ε*−*z, k*) *yields*

E *sup* 1 · *D*Ω(*G*) ≤ *ε.*

S *cost*(*G,* S) + *cost*(*G,* A) S

**Lemma 13.** *Let P be a set of points and let G* ⊂ G*O be a group. Then there exist absolute constants*

*γ*2 *>* 0 *such that the sampling procedure of Algorithm* [*1*](#_bookmark29) *with δ* ≥ *k* · log *k* · *ε*−2 · 2*γ*2·*z* log(1+*z*) · log3 *ε*−1

*ε*

*yields*

E *sup* 1 · *D*Ω(*G*) ≤ *ε.*

S *cost*(*PG,* S) + *cost*(*PG,* A) S

First, we show that this lemma implies our main theorem.

*Proof of Theorem* [*4.*](#_bookmark2)For every group *G* ∈ G, let Ω*G* be the set of points returned by the sampling

routine and let ΩG be the union of the output of all sampling routines. We consider

E sup 1 *D*ΩG (*P* ∩ G)

S cost(*P,* S) + cost(*P,* A) S

= E sup  1 *w* · cost(*p,* S) − cost(*G,* S) 

*G*∈G *p*∈Ω*G*

S

cost(*P,* S) + cost(*P,* A)

*p*

≤ E sup 1 *D*Ω*G* (*G*)

≤ E sup 

S

cost(*P,* S) + cost(*P,* A) *G*∈G

S

S

*G*∈*GM*

cost(*P,* S) + cost(*P,* A)

S

cost(*G,* S) + cost(*G,* A)

S

cost(*G,* S) + cost(*G,* A) · E sup 1

· *D*Ω*G* (*G*)

+

*G*∈*GO*

Ω*G*

cost(*PG,* S) + cost(*PG,* A) cost(*P,* S) + cost(*P,* A)

E sup

S

·

1

cost(*PG,* S) + cost(*PG,* A)

· *D*S (*G*)



(*Lemma* [12)](#_bookmark32) ≤ E sup 

S

*G*∈*GM*

cost(*P,* S) + cost(*P,* A)

cost(*G,* S) + cost(*G,* A) · *ε*

(*Lemma* [13)](#_bookmark33) +

*G* ∈*GO*

cost(*PG,* ) + cost(*PG,* ) cost(*P,* S) + cost(*P,* A) · *ε*

E sup [*ε* + *ε*] = 2*ε*

S A

≤



S

Due to Markov’s inequality, we have with probability at least 3*/*4 that *D*Ω(*P* ∩ G) ≤ 8 · *ε* ·

S

(cost(*P,* S) + cost(*P,* A)) for all S. Combining this with Lemma [11,](#_bookmark31) we then have for all S

S S

*D*Ω(*P* ) ≤ *D*ΩG (*P* ∩ G) + cost(*P* \ G*,* S) − |G ∩ *Ci*| · cost(*ci,* S)

*Ci*

≤ 9 · *ε* · (cost(*P,* S) + cost(*P,* A)) *.*

Rescaling *ε* by a factor 9 · 1 + cost(*P,*A) ∈ 2*O*(*z*) yields the desired accuracy. What is left is to prove the space bound. The maximum number of samples in any group required by Lemma [12](#_bookmark32) and Lemma [13](#_bookmark33) is in *O*(*k* · log *k* · *ε*−2 · log3 *ε*−1 · 2*O*(*z* log *z*) · min(*ε*−*z, k*)). Due to Fact [1,](#_bookmark30) the overall coreset therefore has size *O*(*k* · log *k* · *ε*−2 · log5 *ε*−1 · 2*O*(*z* log *z*)).

*ε*

*ε*

OPT

The remainder of this section will now focus on the proofs of Lemma [12](#_bookmark32) and Lemma [13.](#_bookmark33) Our main analysis tool will be a chaining argument. To do this, we require two things: (i) a reduction to a Gaussian process and (ii) controlling the variance of said Gaussian process. The proof of Lemma [11](#_bookmark31) is standard in this line of research and included in the appendix for completeness sake.

## Setting up a Gaussian process

The chaining arguments we use for proving Lemma [12](#_bookmark32) and Lemma [13,](#_bookmark33) while similar, are distinct enough that each lemma requires it’s own notation and approach. We will focus on Lemma [12,](#_bookmark32) as

it arguably the more interesting and important step. The differences for Lemma [13](#_bookmark33) are discussed at the end of this section.

Unless mentioned otherwise, we let the group *G* be in *GM* . For proving Lemma [12,](#_bookmark32) we need to have a handle on *w* cost(*p,* ), to show that *D*Ω(*G*) is concentrated around zero. We will not try

S

S*pp*∈*G*∩Ω

to work directly with the basic cost estimator *p*∈*P* ∩Ω *vp*S · *wp*, since it has a too large variance. We

denote the cost vector *vG,*S = *vp*S if *p* ∈ *G .* We will split the cost vector *vG,*S into two vectors

*p*

0 else

for which we have separate estimators, for which we will be able show strong concentration.

To define those estimators, let us first characterize the clusters of the initial solution A as follow.

* + - We say that a clu ster *Ci* ∩ *G* induced by A is *huge* if there exists a point *p* ∈ *Ci* ∩ *G* such

*z*

4*z*

*ε*

that cost(*p,* S) ≥

by *HG,*S.

· cost(*p,* A). The set of huge clusters induced by S in *G* are denoted

Instead of estimating *vG,*S 1 directly, we now split *vG,*S in two vectors for which we carry out the estimation separately. We, define the |*P* |-dimensional vector *uG,*S with entries

*uG,*S := cost(*p,* S) if *p* ∈ *C* ∩ *G* and *C* ∈ *HG,*S *.* (4)

*p*

0 otherwise

Clearly *vG,*S = *vG,*S − *uG,*S + *uG,*S, but even more importantly

*vG,*S 1 = *vG,*S − *uG,*S 1 + *u**G,*S 1 (5) as none of the entries of the considered vectors are negative.

For a group *G* ∈ *GO*, we also characterize the clusters by a type.

* + - We say that a cluster *Ci* ∩ *G* induced by A is *far* if there exists a point *p* ∈ *Ci* ∩ *G* such that cost(*p,* S) ≥ 4*z* · cost(*p,* A). The set of far clusters induced by S in *G* are denoted by *FG,*S.

Again, we split the cost vector *vG,*S into two parts. Here we define

*uG,*S := cost(*p,* S) if *p* ∈ *C* ∩ *G* and *C* ∈ *FG,*S *.* (6)

*p*

0 otherwise

As above, Equation [5](#_bookmark34) holds for this definition of *uG,*S.

We will estimate *vG,*S − *uG,*S 1 in both cases by means of controlling a Gaussian process. Esti- mating *uG,*S 1 is done via more straightforward methods.

To show that *w* · *vG,*S − *uG,*S is concentrated around its expectation *vG,*S − *uG,*S , we

*p*∈Ω

*p*

*p*

*p*

1

introduce a notion of nets for cost vectors defined as follows.

**Definition 3.** *Let I be a metric space, P a set of points and two positive integers k and z, and let α >* 0 *be a precision parameter. Given some solution* A*, suppose that G is a group of P. Let* C ⊂ *Ik be a (potentially infinite) set of candidate k-clusterings. We say that a set of cost vectors* N ⊂ R|*P* | *is an* (*α, k, z*)*-clustering net if for every* S ∈ C *there exists a vector v* ∈ N *such that the following condition holds.*

*For all p* ∈ *C* ∩ *G such that C* ∩ *G is not huge and not far,*

|*cost*(*p,* S) − *vp*| ≤ *α* · (*cost*(*p,* S) + *cost*(*p,* A))*.*

*For all p* ∈ *C* ∩ *G such that C* ∩ *G is either huge or far,*

*vp* = 0*.*

The existence of small clustering nets is given by Lemma [21](#_bookmark47) and [22](#_bookmark51) in Section [6.4](#_bookmark44) further below. Before we prove these lemmas, we first describe how this allows us to use a Gaussian process.

Consider a sequence of |*P* | dimensional vectors *v*S*,*1*, v*S*,*2*, . . .* such that *v*S*,h* is the vector approxi- mating the cost vector *vG,*S − *uG,*S of S from a (2−*h, k, z*) clustering net N*h*. Let us now consider our estimator of *vG,*S − *uG,*S 1 defined as follows.

*Y* := ∞ *w*

*G,p,*S

*h*=1

· *v*S*,h*+1 − *v*S*,h* + *w*

· *v*S*,*1

*YG,*S := *YG,p*

*p*

*p*

*p*

*p*

*p*

*p*∈Ω

The following fact shows that this sum telescopes, and that the expectation of *YG,*S remains *vG,*S −

*uG,*S 1.

**Fact 3.** EΩ [*YG,*S] = *vG,*S − *uG,*S 1*.*

*Proof.* For a fixed point *p*, it holds that lim

*vh* = *vG,*S − *uG,*S. Hence, the infinite sum is well

defined and we have:

*h*→∞ *p p p*

*w* *v*S*,h*+1 − *v*S*,h* + *w* · *v*S*,*1

*h*=1

∞

*p*

*p*

*p*

*p*

*p*

= *wpvG,*S − *uG,*S since the sum telescopes

Hence, summing over all points *p* ∈ Ω and taking the expecation concludes the lemma. Using this fact, we can estimate *vG,*S − *uG,*S 1 by *YG,*S.

*p*

To prove Lemma [12,](#_bookmark32) we in particular wish to show for *G* ∈ *GM*

E sup

1

· (*Y*

− E[*Y*

]) ≤ *ε.*

Ω S cost(*G,* S) + cost(*G,* A) *G,*S

*G,*S

Analogously, for Lemma [13,](#_bookmark33) we wish to show for *G* ∈ *GO*

E sup

1

· (*Y*

− E[*Y*

]) ≤ *ε.*

Ω S cost(*PG,* S) + cost(*PG,* A)

*G,*S

*G,*S

Unfortunately, it is difficult to apply the chaining framework with weighted Boolean variables. This is usually addressed using the following symmetrization argument. We pick *δ* independent standard normal Gaussian random variables *ξ*1*, . . . , ξδ* ∼ N (0*,* 1) and analyse the following random variables for the respective cases *G* ∈ *GM* and *G* ∈ *GO*

∞ *ξp* · *wp* · *vp*S*,h*+1 − *vp*S*,h* + *ξp* · *wp* · *v*S*,*1(*p*)

*XG,*S :=

*p*∈Ω *h*=1 *,*

cost(*G,* S) + cost(*G,* A)

∞ *ξp* · *wp* · *vp*S*,h*+1 − *vp*S*,h* + *ξp* · *wp* · *vp*S*,*1

*XG,*S :=

*p*∈Ω *h*=1 *.*

cost(*PG,* S) + cost(*PG,* A)

The following lemma is due to Rudra and Wootters [[84],](#_bookmark168) see also the book by Ledoux and Tala- grand [[67]](#_bookmark151) for more general statements.

**Lemma 14** (Appendix B.3 of [[84])](#_bookmark168)**.** *Let T* = 1 *or T* =

*cost*(*G,*S)+*cost*(*G,*A)

*cost*(*P*

1

*G,*S)+*cost*(*P*

*G,*A)

*. Then*

EΩ*sup*  *δ T* · (*YG,p,*S − E[*YG,p,*S]) ≤ √2*π* · EΩE*ξsup*|*XG,*S|*.*

S

*p*∈Ω

S

With these, we now prove the following lemmas.

**Lemma 15.** *Let G* ∈ *GM . Suppose δ* = *γ*3 · *k* · log *k* · *ε*−2 *for some absolute constant γ*5*. Then*

*ε*

EΩ sup

*p*∈Ω *wp*

· *uG,*S − *uG,*S

1

≤ *ε.*

S *cost*(*G,* A) + *cost*(*G,* S)

*p*

**Lemma 16.** *Let G* ∈ *GM . Suppose δ* = 2*γ*4·*z* log(1+*z*) · *k* · log *k* · *ε*−2 · log3 *ε*−1 · min(*ε*−*z, k*) *for absolute*

*ε*

*constants γ*6 *and γ*7*. Then*

EΩ E*ξ* sup |*XG,*S| ≤ *ε.*

**Lemma 17.** *Let G* ∈ *GO. Suppose δ* = *γ*5 · *k* · log *k* · *ε*−2 *for some absolute constant γ*9*. Then*

S

*ε*

EΩ sup

*p*∈Ω *wp*

*G*

· *uG,*S − *uG,*S

*G*

*p*

1

≤ *ε.*

S *cost*(*P ,* A) + *cost*(*P ,* S)

**Lemma 18.** *Let G* ∈ *GO. Suppose δ* = 2*γ*6·*z* log(1+*z*) · *k* · log *k* · *ε*−2 · log3 *ε*−1 *for absolute constants*

*ε*

*γ*8 *and γ*9*. Then*

EΩ E*ξ* sup |*XG,*S| ≤ *ε.*

The proofs of Lemma [15](#_bookmark36) and Lemma [17](#_bookmark38) are in Section Section [6.6,](#_bookmark67) the proofs of Lemma [16](#_bookmark37) and Lemma [18](#_bookmark39) is split into proving the existence of sufficiently small nets (Section [6.4)](#_bookmark44) and analysing the variance of the Gaussian process. For now, we show why these lemmas imply Lemma [12](#_bookmark32) and Lemma [13.](#_bookmark33)

S

*Proof of Lemma* [*12.*](#_bookmark32)As mentioned in Equation [5,](#_bookmark34) we have cost(*G,* S) = *vG,*S 1 = *vG,*S −*uG,*S 1 +

*uG,*S 1. Due to Lemma [14,](#_bookmark35) we have

· |

EΩ sup

S

1 *Y*

cost(*G,* S) + cost(*G,* A)

*G,*S

− E[*Y*

*G,*S

]| ≤ √2*π* · EΩ E*ξ*

sup *X*

|

S

*G,*S|*.*

Plugging in the bound from Lemma [16,](#_bookmark37) we therefore have

Then

EΩ sup

S

1 *Y*

cost(*G,* S) + cost(*G,* A)

· |

*G,*S

− E[*Y*

*G,*S

]| ≤ √2*πε.*

E sup 1 *D*Ω(*G*)]

Ω

S cost(*G,* S) + cost(*G,* A) S

 *vG,*S − *uG,*S



1

1

*p*∈Ω

*p*

*p*

*p*

*p*

*p*

= EΩsup

S



+ *uG,*S −

*w* · *vG,*S − *uG,*S + *w*

· *uG,*S 

cost(*G,* S) + cost(*G,* A)

*w* · *uG,*S − *uG,*S

≤ E

Ω

sup

*p*∈Ω

*p*

*p*

1

S cost(*G,* S) + cost(*G,* A)

*w* · (*vG,*S − *uG,*S) − *vG,*S − *uG,*S

+E

sup

*p*∈Ω

*p*

*p*

*p*

1

Ω

S cost(*G,* S) + cost(*G,* A)

*wp* · *uG,*S − *uG,*S 1

*δ*

− E[*Y* ]

EΩsup

≤

S

√

*p*∈Ω *p*

cost(*G,* S) + cost(*G,* A)

+ EΩsup

S

*p*∈Ω

*YG,p,*S *G,p,*S

cost(*G,* S) + cost(*G,* A)

(*Lemma* [15)](#_bookmark36) ≤ *ε* + 2*πε.*

Rescaling *ε* yields the claim.

The proof of Lemma [13](#_bookmark33) is completely analogous. For completeness sake, we repeat the steps.

*Proof of Lemma* [*13.*](#_bookmark33)As mentioned in Equation [5,](#_bookmark34) we have cost(*G,* S) = *vG,*S 1 = *vG,*S −*qG,*S 1 +

*uG,*S 1. Due to Lemma [14,](#_bookmark35) we have EΩ sup

*G*

1

*,*S)+cost(*P*

*G*

*,*A)

· |*YG,*S − E[*YG,*S]|

≤ √2*π* ·

EΩ E*ξ* sup|*XG,*S|. Plugging in the bound from Lemma [18,](#_bookmark39) we therefore have

S

cost(*P*

EΩ sup

S

S

cost(*P*

1

*G,*S)+cost(*P*

*G,*A)

· |*YG,*S − E[*YG,*S]| ≤ √2*πε*. Then

EΩ sup

S

1

cost(*PG,* S) + cost(*PG,* A)

*D*Ω(*G*)]

 *vG,*S − *uG,*S



1

1

*p*∈Ω

*p*

*p*

*p*

*p*

*p*

= EΩsup

S



+ *uG,*S −

*w* · *vG,*S − *uG,*S + *w*

· *uG,*S 

S

cost(*PG,* S) + cost(*PG,* A)

*w* · *uG,*S − *uG,*S

≤ E

Ω

sup

*p*∈Ω

*G*

*p*

*p*

*G*

1

S cost(*P ,* S) + cost(*P ,* A)

*w* · (*vG,*S − *uG,*S) − *vG,*S − *uG,*S

+E

sup

*p*∈Ω

*p*

*p*

*p*

1

Ω

S cost(*PG,* S) + cost(*PG,* A)

*Lemma* [17](#_bookmark38) ≤ *ε* + √2*πε.* Rescaling *ε* yields the claim.

## A Structural Lemma

We will use the property for *GM* that we have a good estimator for the size of every cluster of A. We will frequently use this property in subsequent sections. By definition of groups, we have for every point *p* of any cluster *C* with a non-empty intersection with *G* ∈ *GM*

cost(*G,* A) ≤ 2*k* · cost(*C* ∩ *G,* A) ≤ 4*k* · |*C* ∩ *G*| · cost(*p,* A)*.* (7) We first show that, given we sampled enough points, |*C* ∩ *G*| is well approximated for every cluster

*C*. This lemma will also be used later for bounding the supremum of *XG,*S in the proof of Lemma [16.](#_bookmark37)

We define event E*G* to be for all clusters *C*,

± · | ∩ |

*wp*

*p*∈*C*∩*G*∩Ω

=

*p*∈*C*∩*G*∩Ω

cost(*G,* A) = (1 *ε*) *C G . δ* · cost(*p,* A)

**Lemma 19.** *Let G* ∈ *GM . We have that with probability at least* 1 − *k* · exp − *ε*2 *δ* *, event* E

9·*k*

*G*

*happens.*

The proof is similar to the one used in Lemma 4.4 from [[35].](#_bookmark118) The main difference is, due to using a slightly different sampling distribution, Hoeffding’s inequality is insufficient and we have to rely on Bernstein’s inequality.

*Proof of Lemma* [*19.*](#_bookmark41)First, observe that E[ *p C G* Ω *wp*] = |*C* ∩ *G*|. We will bound both the variance as well as *M* in order to apply Bernstein’s inequality. Let Ω be the set of sampled points and let *pj* be the *j*th point in the sample with respect to some arbitrary but fixed ordering. Consider

∈ ∩ ∩

the random variable *w*

*pj,C*

= *wp* if *pj* = *p* ∈ *C* ∩ *G* . Then

0 else

Var[*w*

*pj,C*

] ≤ E[*w*2

] =

*p*∈*C*∩*G*

2

*p*

*w* · P[*p* ∈ Ω] =

*p*∈*C*∩*G*

≤

cost(*G,* A)

*δ*2 · cost(*p,* A)

(*Eq.* [7)](#_bookmark40) ≤

*pj,C*

*p*∈ *C*∩*G*

2*k*cost(*C,* A) *δ*2cost(*p,* A)

*p*∈ *C*∩*G*

4*k* · |*C* ∩ *G*| *δ*2

4*k C G* 2

*δ*2 (8)

≤

· | ∩ |

For the maximum upper bound, we have again due to Equation [7](#_bookmark40)

*w* = cost(*P,* A) ≤ 4*k* · |*C* ∩ *G*|

(9)

*pj,C*

*δ* · cost(*pj,* A) *δ*

Thus, combining Equation [8](#_bookmark42) and [9](#_bookmark43) with Bernstein’s inequality, we have

P 

*wp* − |*C* ∩ *G*| *> ε* · |*C* ∩ *G*|

≤ exp

*ε*2 *C G* 2

− 2*δ* · 4*k*·|*C*∩*G*|2 + 2 4*k*·|*C*∩*G*| · *ε* · |*C* ∩ *G*|

· | ∩ |

*p*∈*Ci*∩Ω

≤ exp

*δ*2 3 *δ*

*ε*2

− 9 · *k* · *δ .*

The lemma now follows by taking a union bound over all clusters in A.

## Existence of Small Clustering Nets

For a set of points *P* , a set of points N*ε* is an *ε-net* of *P* if for every point *x* ∈ *P* there exists some point *y* ∈ N*ε* with *x* − *y* ≤ *ε*. The existence of small nets in Euclidean spaces is given by the following statement.

**Lemma 20** (Lemma 5.2 of [[89])](#_bookmark172)**.** *For the unit d-dimensional Euclidean ball centered around the origin, there exists an ε-net of cardinality* (1 + 2*/ε*)*d.*

We further will crucially rely on terminal embeddings defined as follows. A terminal embedding of a set *P* ∈ R*d* is a mapping *f* : R*d* → R*m* such that

∀*x* ∈ *P,* ∀*y* ∈ R *,* (1 − *ε*) · *x* − *y* 2 ≤ *f* (*x*) − *f* (*y*) 2 ≤ (1 + *ε*) · *x* − *y* 2*.*

*d*

The statement is closely related to the classic Johnson-Lindenstrauss lemma. The crucial general- ization is that the pairwise distances between any point of R*d* and any point of *P* , rather than just the pairwise distances of points in *P* , are preserved.

**Theorem 10** (Theorem 1.1 of [[82])](#_bookmark165)**.** *For any point set P in* R*d, there exists a terminal embedding*

*f* : R*d* → R*m with m* ∈ *O*(*ε*2 log *P* 0)*.*

The target dimension here is optimal for a wide range of parameters (see Larsen and Nelson for a matching lower bound [[66]).](#_bookmark149) Using both of these statements, we now show the existence of small clustering nets.

**Lemma 21.** *Let k, z be two positive integers, G be a group and* A *be a solution to* (*k, z*)*-clustering. Define* C *to be the set of possible candidate centers. For all α* ≤ 1*/*2*, there exists an* (*α, k, z*)*- clustering net* N *of* C *with*

|N| ≤ exp *γ* · *z*2 · *k* · log *P* */α*2 · log 1 ) *,*

0

7

*where γ*7 *is an absolute constant.*

*α* · *ε*

*Proof.* Let *f* be a terminal embedding of *P* into *O*( *z* 2 log *P* 0) dimensions given by Theorem [10.](#_bookmark46)

*α*

Given a solution S, we then have for any *p* ∈ *P*

cost(*p, f* (S)) =

*z*

min *f* (*p*) *f* (*s*) =

−

*s*∈S

*z*

(1 ± *α/O*(*z*)) · min *p* − *s*

*s*∈S

= (1 ± *α*) · cost(*p,* S)

Let *B* be an arbitrary subset of the clusters induced by A. Here *B* is meant to contain the clusters that are not in *HG,*S for a given candidate solution S, but the exact interpretation of *B* is not important for the proof. We will show that for every *B*, there exists an (*α, k, z*) clustering net N*B* of size

|N*B*| ∈ exp *O* *z*2*/α*2*k* · log *P* 0 · log *.* (10)

*z*

*α* · *ε*

Since th ere are at most 2*k* subsets *B*, t h e overal l si ze of the clustering net is t h e n *B* |N*B*| ≤

*O*

= exp

*O*

*.*

2*k* · exp

*z*2 · *k* · log *P* 0*/α*2 · log

*z α*·*ε*

*z*2 · *k* · log *P* 0*/α*2 · log

*z α*·*ε*

We now justify Equation [10.](#_bookmark48) We take an *α* · dist(*p,* A)-net of the Euclidean ball centered around

*p* ∈ *C* ∈ *B* with radius 8 · 4*z* · dist(*p,* A). *z* h a net has size at most

Suc

*ε*

exp *O* *z*2 log *P* */α*2 · log *z*

due to Lemma [20.](#_bookmark45)

0

*α* · *ε*

We now take the union of all *α* ·dist(*p,* A)-nets of all points *p* ∈ *C* ∈ *B*. This yields a total number of

*P* · exp *K* log *P* · *α*−2 *z* log 1 nets points. We set N to be set of all subsets of size *k* of the

union of nets. Clearly, |N*B*| = exp

0 *z* 0

*B*

*Kz* · *k* · log *P* 0*/α*

· log *α*·*ε*

as desired in Equation [10.](#_bookmark48) What

· *α*· *ε*

2 1

is left to show is that N*B* is an (*O*(*α*)*, k, z*) clustering net. The lemma then follows by rescaling *α*. Let S ∈ C be a set of *k* centers. Consider the set *N* of *k* net points defined as follows : *N* :=

∪*s*∈S{*ns* : *ns* is the closest net point to *f* (*s*)}. Define the cost vector *vN* such that

*vN* (*p*) =

cost(*f* (*p*)*, N* ) if *p* ∈ *C* ∈*/ HG,*S . Let *p* be a point from a cluster *C*

0 else

∈*/*

*H*

*G,*S

. By

definition of *HG,*S, this implies

cost(*p,* S) ≤

4*z* *z*

*ε*

cost(*p,* A)*.* (11)

We need to show that |cost(*p,* S) − *vN*S (*p*)| ≤ *α* · (cost(*p,* S) + cost(*p,* A)).

Let *s* be the center closest to *p* in S, and *c* be *p*’s closest center in A. The terminal embedding ensures

Then,

*f* (*p*) − *f* (*s*) 2 ≤ (1 + *α/O*(*z*)) *p* − *s* 2 ≤ (1 + *α/O*(*z*)) · *f* (*p*) − *f* (*s*) 2*.*

*f* (*c*) − *f* (*s*) 2 ≤ *f* (*c*) − *f* (*p*) 2 + *f* (*p*) − *f* (*s*) 2

2

≤ (1 + *α/z*) · *c* − *p* 2 + (1 + *α/z*) · *p* − *s* 2

≤ (1 + *α/O*(*z*)) 1 + 4*z* · *p* − *c*

*ε* 2

≤ 4 · 4*z* *p* − *c*

*ε*

2

where third inequality holds due to Equation [11.](#_bookmark49) Hence, *f* (*s*) is in the ball of radius 8 4*z* dist(*p, c*)

*ε*

centered around *p* which implies

|dist(*f* (*p*)*, f* (S)) − dist(*f* (*p*)*, n* )| ≤ 2*α* · dist(*f* (*p*)*, f* (A))*.*

*s*

*z*

We therefore have

|cost(*f* (*p*)*, f* (S)) − cost(*f* (*p*)*, ns*)|

= |dist(*f* (*p*)*, f* (S)) − dist(*f* (*p*)*, ns*)| · dist(*f* (*p*)*, f* (S))*z*−1 ·

*z*−1 dist(*f* (*p*)*, ns*) *i*

*i*=0

*z*

dist(*f* (*p*)*, f* (S))

≤ 2*α*

*z*

· dist(*f* (*p*)*, f* (A)) · dist(*f* (*p*)*, f* (S))*z*−1 · *z* ·

1 + 2*α* ·

dist(*f* (*p*)*, f* (A)) *z*−1

dist(*f* (*p*)*, f* (S))

≤ 2*α*

*z*

· dist(*f* (*p*)*, f* (A)) · *z* ·

dist(*f* (*p*)*, f* (S)) +

2*α*

*z*−1

dist(*f* (*p*)*, f* (A))

≤ 2*α* · dist(*f* (*p*)*, f* (A)) · *z* · 1 + 2*α* · max (dist(*f* (*p*)*, f* (S))*,* dist(*f* (*p*)*, f* (A)))*z*−1

*z*

*z*

*z*

≤ 4*α* · (cost(*f* (*p*)*, f* (A) + cost(*f* (*p*)*, f* (S)) *.* (12) This implies that

|cost(*p,* S) − *vN* (*p*)| ≤ |cost(*f* (*p*)*, f* (S)) − cost(*f* (*p*)*, ns*)| + *O*(*α*) · cost(*p,* S)

(*Eq.* [12)](#_bookmark50) ≤ 4*α* · (cost(*f* (*p*)*, f* (A) + cost(*f* (*p*)*, f* (S)) + *O*(*α*) · cost(*p,* S)

= *O*(*α*) · (cost(*p,* S) + cost(*p,* A))*.*

Thus, up to a rescaling of *α* by constant factors, we have the desired accuracy and thereby proving Equation [10.](#_bookmark48)

**Lemma 22.** *Let k, z be two positive integers, G be a group and* A *be a solution to* (*k, z*)*-clustering. Suppose the points of G lie in d dimensional Euclidean space. Define* C *to be the set of possible candidate centers. For all α* ≤ 1*/*2*, there exists an* (*α, k, z*)*-clustering net* N *of* C *with*

|N| ≤ exp (*γ*8 · *k* · *d* · *z* log(4*z/*(*α* · *ε*))) *,*

*where γ*8 *is an absolute constant.*

*Proof.* The construction is essentially identical to that of Lemma [21.](#_bookmark47) The main difference is that we now take nets of the *d*-dimensional Euclidean ball centered around every point *p*. These nets has size at most

due to Lemma [20.](#_bookmark45)

exp (*O* (*d* · *z* log(4*z/*(*α* · *ε*)))) = exp (*γ*11 · *d* · *z* log(4*z/*(*α* · *ε*)))

The remaining arguments from Lemma [21](#_bookmark47) are not affected by this change.

Recall that we assumed that *d* ∈ *O*(*ε*−2 log *P* 0), which is a consequence of Theorem [10.](#_bookmark46) We will describe the chaining procedure in more detail in Section [6.5.](#_bookmark52) For those familiar with chaining: this assumption on *d*, combined with the bound of Lemma [22](#_bookmark51) will ensure that the chain converges after only a small number of steps.

## Proofs of Lemma [16](#_bookmark37) and Lemma [18](#_bookmark39)

We focus on the proof of Lemma [16.](#_bookmark37) The proof of Lemma [18](#_bookmark39) follows along the same lines, but is far simpler. For completeness, we repeat the arguments at the end of the section.

*Proof of Lemma* [*16.*](#_bookmark37)In the following, let *G* ∈ *GM* . We recall the random variable

*p*

*p*

*p*

*p*

*p*

*p*

*p*

1

*X* :=

*G,*S

∞ *ξ* · *w*

*p*∈Ω

*h*=1

· *v*S*,h*+1 − *v*S*,h* + *ξ* · *w*

· *v*S*,*1*.*

Define

cost(*G,* A) + cost(*G,* S)

*XG,*S*,*0 *X*

*G,*S*,h*

:= 1 *ξ*

cost(*G,* A) + cost(*G,* S) *p*∈Ω

*p*

:= 1 *ξ*

cost(*G,* A) + cost(*G,* S)

*p*

*p*∈Ω

* *wp*
* *w*

*p*

* *vp*S*,*1

· *v*S*,h*+1 − *v*S*,h* *.*

*p*

*p*

We have EΩE*ξ* sup |*XG,*S| ≤ *h*∞=0 EΩE*ξ* sup |*XG,*S*,h*|*.* The number of vectors *v*S*,h* are bounded via Lemma [21](#_bookmark47) and [2](#_bookmark51)S[2.](#_bookmark51) The primary remainingS challenge is to control the variance of *X**G,*S*,h*.

**Lemma 23.** *Let G* ∈ *GM . Fix a solution* S *and let β*1*, β*2 *>* 0 *be absolute constants. Then XG,*S*,h*

*is Gaussian distributed with mean* 0*. The variance of XG,*S*,h is always at most*

 · *v*S*,h*+1 − *v*S*,h* 2

*p*

*p*

*p*

 *cost*(*G,* A) + *cost*(*G,* S) 

∈ *δ*−1 · 2*β*1*z* log(1+*z*)2−2*h* · *ε*−2*z.*

*w*

*p*∈Ω

*Furthermore, conditioned on event* E*G, the variance of XG,*S*,h is at most*

 · *v*S*,h*+1 − *v*S*,h* 2

*p*

*p*

*p*

 *cost*(*G,* A) + *cost*(*G,* S) 

∈ *δ*−1 · 2*β*2*z* log(1+*z*)2−2*h* · min(*ε*−*z, k*)*.*

mean 0 and variance

*w*

*p*∈Ω

*Proof.* We recall the standard fact that if *ξp* ∼ N (0*,* 1), then *p ap* · *ξp* is Gaussian distributed with

*p*

*a*2.

For any *p* ∈ *C* ∈*/ HG,*S, we have cost(*p,* S) ≤ 4*z z* cost(*p,* A). A terminal embedding with target dimension *O*(*z*222*h* log *P* 0) preserves the cost up to a factor (1 ± 2−*h*), i.e. we have (1 − 2−*h*) ·

*p*

*ε*

cost(*p,* S) ≤ *vp*S*,h* ≤ (1 + 2−*h*)cost(*p,* S). Therefore

 · *v*S*,h*+1 − *v*S*,h* 2

*p*

*p*

*p*

*w*

*p*∈Ω cost(*G,* A) + cost(*G,* S) 

 *w* · *v*S*,h*+1 − cost(*p,* S) + cost(*p,* S) − *v*S*,h* 2

=

*p*∈Ω



*p*

*p*

cost(*G,* A) + cost(*G,* S)

*p*



*wp*

· 2−*h*−1 · cost(*p,* S) 2

≤

*p*∈Ω

cost(*G,* A) + cost(*G,* S)

≤ *p* ∈Ω

2−2*h*+2 

cost(*G,*A) cost(*p,* )

*δ*cost(*p,*A)

· S

2



cost(*G,* A) + cost(*G,* S)

To prove the first bound, we now merely recall since *p* ∈ *C* ∈*/ HG,*S, we have cost(*p,*S) ≤ 4*z* *z* .

*.* (13)

cost(*p,*A)



For the second bound, we first consider an arbitrary cluster *C* and let *q* = argmin

*p*∈*C*

*ε*

cost(*p,* S).

Then we have for any solution S

*z* 2*z* · cost(*C* ∩ *G,* S) + 4*z* · cost(*C* ∩ *G,* A)

cost(*p,* S) ≤ (dist(*q,* S) + dist(*p, q*)) ≤

*.* (14)

|*C*|

We first focus on the case *εz < k*. Continuing from Equation [13](#_bookmark54) and combining with Equation [14,](#_bookmark55) we have

*p* ∈Ω

2−2*h*+2 

cost(*G,*A) cost(*p,* )

*δ*cost(*p,*A)

· S



2



cost(*G,* A) + cost(*G,* S)

cost(*G,* A) 2−

·

≤

*δ* · (cost(*G,* A) + cost(*G,* S))2

2*h*+2

cost(*G,* A) cost(*p,* )

*p*∈Ω *δ*cost(*p,* A)

·

4*z* *z*

*ε*

cost(*G,* A) · 2−2*h*+2 · 4*z* *z*  2*z* · cost(*C* ∩ *G,* S) + 4*z* · cost(*C* ∩ *G,* A)

· S ·

*ε*

cost(*G,* A)

≤ *δ* · (cost(*G,* A) + cost(*G,* S))2 ·

A · ·

*C*

cost(*G,* ) 2−2*h*+2 4*z z*

*ε*

*z*

≤ *δ* · (cost(*G,* A) + cost(*G,* S))2 · 2

*C*

cost(*G,* A) · 2−2*h*+2 · 4*z* *z*

*ε*

*z*

|*C*|

* cost(*C* ∩ *G,* S) + 4

*z*

* cost(*C* ∩ *G,* A)

*p*∈*C*∩Ω

*δ*cost(*p,* A)

≤ *δ* (cost(*G,* ) + cost(*G,* ))2 · 8

−2 · · 8

· A S

2*h*+2 4*z z z*

*ε*

≤

*δ*

* (cost(*G,* A) + cost(*G,* S))

where the third inequality uses event E*G*.

We now obtain a bound depending on *k*. Recall for any point *p* ∈ *C* ∩ *G*, we have

cost(*G,* A) ≤ 2*k* · cost(*C* ∩ *G,* A) ≤ 4*k* · cost(*p,* A) · |*C*| (15)

by definition of the groups. Then

*p* ∈Ω

2−2*h*+2 

cost(*G,*A) cost(*p,* )

· S



2

*δ*cost(*p,*A)



cost(*G,* A) + cost(*G,* S)

1 2−2*h*+2

*C*

≤ · ·

*δ* · (cost(*G,* A) + cost(*G,* S))2

*p*∈ *C*∩Ω

4 · cost(*G,* A) · |*C*| · *k* cost2(*p,* )

*δ* · cost(*p,* A)

· S

2−2*h*+4 *k*

·

≤ *δ* · (cost(*G,* A) + cost(*G,* S))2 ·

|*C*| ·

*C*

2*z* · cost(*C* ∩ *G,* S) + 4*z* · cost(*C* ∩ *G,* A) 2

|*C*|

· cost(*G,* A)

2−2*h*+4 *k*

·

≤ *δ* · (cost(*G,* A) + cost(*G,* S))2 ·

(2*z*

*C*

*p*∈*C*∩Ω *δ*cost(*p,* A)

* cost(*C* ∩ *G,* S) + 4

*z*

* cost(*C* ∩ *G,* A))

2

2−2*h*+4 *k*

·

≤ *δ* · (cost(*G,* A) + cost(*G,* S))2 ·

2−2*h*+4 · *k* · 64*z*

2*z*

*C*

* cost(*C* ∩ *G,* S) + 4

2

*z*

2

* cost(*C* ∩ *G,* A)

≤ *δ* · (cost(*G,* A) + cost(*G,* S))2 · (cost(*G,* A) + cost(*G,* S))

2−2*h*+4 · *k* · 64*z*

≤

*δ*

where the first inequality uses Equation [15,](#_bookmark56) the second inequality uses Equation [14](#_bookmark55) and the third inequality uses Equation [13.](#_bookmark54)

We now combine the bound on the variance with union bounds for *XG,*S*,h*. Let *δ* be as given in the statement of Lemma [16.](#_bookmark37)

We will use the following lemma for bounding the expected maximum of independent Gaussians.

**Lemma 24** (Lemma 2.3 of Massart [[76])](#_bookmark159)**.** *Let gi* ∼ N (0*, σ*2)*, i* ∈ [*n*] *be Gaussian random variables*

*i*

*and suppose σi* ≤ *σ for all i. Then*

E[max *gi* ] 2*σ* √2 ln *n.*

*i*∈[*n*]

| | ≤ ·

We use the following fact:

### Fact 4.

EΩ*,ξ*[sup *XG,*S*,h*] = PΩ[E*G*] · E*ξ*[sup *XG,*S*,h* | E*G*] + PΩ[E*G*] · E*ξ*[sup *XG,*S*,h* | E*G*]*.*

S S S

EΩ*,ξ*[sup *X*S] = PΩ[E*G*] · EΩ*,ξ*[sup *XG,*S*,h* | E*G*] + PΩ[E*G*] · EΩ*,ξ*[sup *XG,*S*,h* | E*G*]*.*

S S S

*Proof.* Since E*G* is independent of *ξ*, the law of total expectation gives

EΩ*,ξ*[sup *XG,*S*,h*] = PΩ*,ξ*[E*G*] · EΩ*,ξ*[sup *XG,*S*,h* | E*G*] + PΩ*,ξ*[E *G*] · EΩ*,ξ*[sup *XG,*S*,h* | E *G*]

S S S

= PΩ[E*G*] · EΩ*,ξ*[sup *XG,*S*,h* | E*G*] + PΩ[E *G*] · EΩ*,ξ*[sup *XG,*S*,h* | E *G*]

S S

We will bound the expectation, first assuming the (more likely case) that event E*G* holds, then assuming the (more unlikely case) that event E*G* does not hold.

Condition on E*G*. We simply upper bound P[E*G*] with 1. Assume that the points lie in dimension *α* · log *P* 0 · *ε*−2 and let *t* ∈ *O*(log(*α* · *ε*−2)). We will show that the contribution of the *XG,*S*,h* with *h* ≤ *t* to the expectation is at most *ε/* log(1*/ε*), and then bound the expectation for all remaining *h* ≥ *t*.

First, we recall that, conditioned on event E*G* and due to Lemma [23](#_bookmark53) and by our choice of *δ*, we have

**Var**[*Xh,*S | E*G*] ≤ *β*3 · *δ*−1 · 2*β*4*z* log *z* 2−2*h* · min(*ε*−*z, k*)*.*

for absolute constants *β*3 and *β*4.

For the number of distinct *XG,*S*,h*, we have an upper bound of |N*h*−1| · |N*h*| ≤ |N*h*|2, where |N*h*| is the size of an (2−*h, k, z*)-clustering net. Due to Lemma [21,](#_bookmark47) this is at most exp(2 · *γ*7 · *z*2 · *k* · log *P* 0 · 22*h* · log 1 ), which by the upper bound on *h* is at most exp(2 · *γ*7 · *z*2 · *k* · log *P* 0 · 22*h* · log *α*3 ).

·

2−*h ε ε*−

Therefore, using Lemma [24](#_bookmark57)

E[sup |*XG,*S*,h*| | E*G*]

S

≤ 2 **Var**[*XG,*S*,h* | E*G*] 2 ln(|N*h*−1| · |N*h*|)

≤ 2 *δ*−1 · 2*β*1*z* log *z* 2−2*h* · min(*ε*−*z, k*) · 2 · *γ*7

· *z*2 · *k* · log *P* 0

22*h* log log *α*

*ε*−3

· ·

= 2 ·

2 · *γ*7 · *z*2 · *k* · log *P* 0 · 22*h* · log *α* · 2*β*1*z* log *z* 2−2*h* · min(*ε*−*z, k*)

1*/*2

−3*ε*

2*γ*4·*z* log(1+*z*) · *k* · log *k* · *ε*−2 · log3 *ε*−1 · min(*ε*−*z, k*))

*ε*

*ε*

≤ *β* · log 1*/ε,* (16)

where the final inequality holds for a sufficiently large choice of the constants *γ*4.

We now assume that *h* ≥ *t*. T his time, using Lemma [22,](#_bookmark51) we have a net of size at most |N*h*| ≤

exp

*γ*8 · *k* · *d* · *z* log(4*z/*(2−*hε*)) . Furthermore, using the assumption that the points lie in dimen-

sion log *P* 0 · *ε*−2 ∈ *O*(log *k/ε*) · *ε*−2, we have

E[sup |*XG,*S*,h*| | E*G*]

S

≤ 2 **Var**[*XG,*S*,h* | E*G*] 2 ln(|N*h*−1| · |N*h*|)

(17)

2 · *γ*8 · *k* · *d* · *z* log(4*z/*(2−*hε*)) · *β*3 · 2*β*4*z* log *z* 2−2*h* · min(*ε*−*z, k*)

1*/*2

≤ 2 ·

*ε*

≤ 2 ·

2 · *γ*8

2*γ*4·*z* log(1+*z*) · *k* · log *k* · *ε*−2 · log3 *ε*−1 · min(*ε*−*z, k*))

· *k* · *α* · *P* *ε*−2 · *z* log(4*z/*(2−*hε*)) · 2*β*2*z* log(1+*z*)2−2*h* · min(*ε*−*z, k*) 1*/*2

0

2*γ*4·*z* log(1+*z*) · *k* · log *k* · *ε*−2 · log3 *ε*−1 · min(*ε*−*z, k*))

*ε*

≤ *β* ·

log *h* 1*/*2

22*h* log2 1*/ε*

*,* (18)

where again the final inequality holds for a sufficiently large choice of the constant *γ*4 and with the assumption *P* 0 = poly(*k/ε*).

Summing up Equations [16](#_bookmark58) and [18](#_bookmark59) for all *h*, we then obtain

∞

E[sup |*X*S| | E*G*] ≤ E[sup |*Xh,*S| | E*G*]

S *h*=0 S

*t*−1 ∞

= E[sup |*Xh,*S| | E*G*] + E[sup |*Xh,*S| | E*G*]

∞

S

S

*h*=0

*h*=*t*

(Eq. [16](#_bookmark58) [18)](#_bookmark59) ≤

*t*−1

*h*=0

*ε*

*β* · log 1*/ε* +

*β* ·

*h*=*t*

log *h*

22*h* log2 1*/ε*

1*/*2

*t*=log(*α/ε*2)

≤ *β* · *ε* + *β* · *ε*

∞

*h*=0

log(*h* + *t*)

*β* · 22*h* log2 1*/ε*

1*/*2

∈ *O*(*ε*)*.* (19)

Now, we move onto the case E*G*. Due to Lemma [19,](#_bookmark41) we have

P[E*G*] ≤ *k* · *z*2

log2(*z/ε*) exp(−*O*(1) ·

*ε*2 2*z*

*k δ*) ≤ *ε*

*,* (20)

where the second upper bound follows from our choice of sufficiently large constants in the definition of *δ*[2](#_bookmark63)

Using the worse variance bound from Lemma [23](#_bookmark53) for the variance in equations [16](#_bookmark58) and [18,](#_bookmark59) we then have for *h* ≤ *t*

E[sup *X*

|

S

*h,*S

| | E*G*

] *β*  *ε ε*−*z.* (21)

log 1*/ε*

≤ ·

2The bound is not close to tight and can be any power of *ε*. The stated bound happens to be sufficient here.

and for *h > t*

E[sup |*Xh,*S| | E*G*] ≤ *β* ·

S

log *h* 1*/*2

22*h* log2 1*/ε*

· *ε*−

*z.* (22)

Using an analogous calculation to those in the derivation of Equation [19](#_bookmark60) using Equations [21](#_bookmark62) and [22,](#_bookmark64) we now obtain

E[sup |*X ,*S| | E*G*] ∈ *O*(*ε*−*z*)*.* (23)

S

Combining Equations [19,](#_bookmark60) [20,](#_bookmark61) and [23,](#_bookmark65) we finally have

PΩ[E*G*] · E*ξ*[sup *X ,*S | E*G*] + PΩ[E*G*] · E*ξ*[sup *X ,*S | E*G*] ∈ *O*(*ε* + *ε*2*z* · *ε*−*z*) = *O*(*ε*)*.*

S S

We now repeat these calculations for Lemma [18.](#_bookmark39) The main difference is the variance bound, which improves over what we were able to prove for Lemma [16.](#_bookmark37) The remaining arguments differ only in the calculations and are omitted.

*Proof of Lemma* [*18.*](#_bookmark39)Let *G* ∈ *GO*. As for Lemma [18,](#_bookmark39) we bound the random variable

*p*

*p*

*p*

*p*

*p*

*p*

*p*

1

*X* :=

*G,*S

∞ *ξ* · *w*

*p*∈Ω

*h*=1

· *v*S*,h*+1 − *v*S*,h* + *ξ* · *w*

· *v*S*,*1*.*

by bounding

cost(*G,* A) + cost(*G,* S)

*XG,*S*,*0 *X*

*G,*S*,h*

:= 1 *ξ*

cost(*G,* A) + cost(*G,* S) *p*∈Ω

*p*

:= 1 *ξ*

cost(*G,* A) + cost(*G,* S)

*p*

*p*∈Ω

* *wp*
* *w*

*p*

* *vp*S*,*1

· *v*S*,h*+1 − *v*S*,h* *.*

*p*

*p*

**Lemma 25.** *Let G* ∈ *GO and let β*3 *>* 0 *be a constant. Fix a solution* S*. Then XG,*S*,h is Gaussian distributed with mean* 0*. The variance of XG,*S*,h is always at most*

 · *v*S*,h*+1 − *v*S*,h* 2

*w*

*z* −2*h*+2

*δ*

*p p p*





*cost*(*G,* A) + *cost*(*G,* S)

*p*∈Ω

∈ 16 · 2 *.*

*Proof.* As in the proof of Lemma [23,](#_bookmark53) we use that if *ξp* ∼ N (0*,* 1), then *p ap* · *ξp* is Gaussian

*p*

distributed with mean 0 and variance

*p*

*a*2.

For any *p* ∈ *C* ∈*/ HG,*S, we have cost(*p,* S) ≤ 4*z z* cost(*p*A). A terminal embedding with target dimension *O*(*z*222*h* log *P* 0) preserves the cost up to a factor (1 ± 2−*h*), i.e. we have (1 − 2−*h*) ·

*ε*

cost(*p,* S) ≤ *vp*S*,h* ≤ (1 + 2−*h*)cost(*p,* S). Therefore

 · *v*S*,h*+1 − *v*S*,h* 2

*p*

*p*

*p*

*w*

*p*∈Ω cost(*G,* A) + cost(*G,* S) 

 *w* · *v*S*,h*+1 − cost(*p,* S) + cost(*p,* S) − *v*S*,h* 2

=

*p*∈Ω



*p*

*p*

cost(*G,* A) + cost(*G,* S)

*p*



*wp*

· 2−*h*−1 · cost(*p,* S) 2

≤

*p*∈Ω

cost(*G,* A) + cost(*G,* S)

≤ *p* ∈Ω

2−2*h*+2 

cost(*G,*A) cost(*p,* )

*δ*cost(*p,*A)

· S

2



cost(*G,* A) + cost(*G,* S)

*.* (24)

By definition, none of the points with non-zero coordinates in the cost vector *v* are far, i.e. cost(*p,* S) ≤ 4*z* · cost(*p,* A).



Therefore, Equation [24](#_bookmark66) becomes

*.*

*δ*

*z* −2*h*+2 1

16

· 2

*δ*2 =

16*z* · 2−2*h*+2

*p*∈Ω

The remaining calculations are completely analogous to that of Lemma [16,](#_bookmark37) albeit with a significantly better (and simpler) bound on the variance.

## Estimating *uG,*S 1 (Proofs of Lemma [15](#_bookmark36) and Lemma [17)](#_bookmark38)

**Lemma 26.** *Let G* ∈ *GM be a group. Condition on event* E*G. Suppose ε <* 1*/*4*. Then, for any solution* S*, and point p* ∈ *C with C* ∈ *HG,*S*, we have:*

|*cost*(*C* ∩ *G,* S) − |*C* ∩ *G*| · *cost*(*p,* S)| ≤ 10 · *ε* · *cost*(*C,* S)*.*

*Proof.* Let *p, p* ∈ *C* ∈ *H*S. First, we require an upper bound on cost(*p, p*). We have due to Lemma [10](#_bookmark27) and since cost(*p,* A) ≤ 2 · cost(*p**,* A)

cost(*p, p*) ≤ 2*z*−1 cost(*p,* A) + cost(*p**,* A) ≤ 2*z*+1cost(*p**,* A)*.*

Let *p* ∈ *C* be a point such that cost(*p,* S) *>* 4*z* *z* cost(*p**,* A). We now give upper and lower bounds

*ε*

for cost(*p,* S) in terms of cost(*p**,* S), again using Lemma [10.](#_bookmark27) For the upper bound:

cost(*p,* S) ≤ (1 + *ε*) · cost(*p**,* S) +

*z* + *ε* *z*−1

*ε*

*z* + *ε* *z*−1

cost(*p, p*)

*z*+1

≤ (1 + *ε*) · cost(*p ,* S) +

*ε*

*z* + *ε* *z*−1

2

*z*+1

* cost(*p ,* A)

*ε* *z*

·

For the lower bound:

≤ (1 + *ε*) · cost(*p ,* S) + *ε*

≤ (1 + 2*ε*) · cost(*p**,* S)

2 4*z* cost(*p ,* S)

cost(*p**,* S) ≤ (1 + *ε*) · cost(*p,* S) +

≤ (1 + *ε*) · cost(*p,* S) +

≤ (1 + *ε*) · cost(*p,* S) +

*z* + *ε* *z*−1

*ε*

*z* + *ε* *z*−1

*ε*

*z* + *ε* *z*−1

*ε*

cost(*p, p*)

2*z*+1 · cost(*p**,* A)

*ε* *z*

2*z*+1 ·

cost(*p**,* S)

4*z*

≤ (1 + *ε*) · cost(*p,* S) + *ε* · cost(*p**,* S)

⇒ cost(*p,* S) ≥ 1 − *ε* · cost(*p**,* S) ≥ (1 − 2*ε*) · cost(*p**,* S)

1 + *ε*

Thus we have cost(*Ci,* S) = *p*∈*Ci* cost(*p,* S) = (1 ± 2*ε*) · |*Ci*| · cost(*p**,* S). Conditioned on event E,

*p*∈*Ci*∩Ω *wp* = (1 ± *ε*) · |*Ci*|, hence

we now have

*p*∈ *Ci*∩Ω

*wp* · cost(*p,* S) ≤

*p*∈*Ci*∩Ω

*wp* · (1 + 2*ε*) · cost(*p**,* S) = (1 + *ε*) · (1 + 2*ε*) · |*Ci*| · cost(*p**,* S)

≤ cost(*C ,* S) · (1 + *ε*) · (1 + 2*ε*)

*i*

and analogously for the lower bound

1 − 2*ε*

*p*∈ *Ci*∩Ω

*wp* · cost(*p,* S) ≥

*p*∈*Ci*∩Ω

*wp* · (1 − 2*ε*) · cost(*p**,* S) = (1 − *ε*) · (1 − 2*ε*) · |*Ci*| · cost(*p**,* S)

≥ cost(*C ,* S) · (1 − *ε*) · (1 − 2*ε*) *.*

*i*

1 + 2*ε*

The final bound follows by observing for *ε <* 1*/*4, we have (1+*ε*)·(1+2*ε*) ≤ 1 + 10*ε* and (1−*ε*)·(1−2*ε*) ≥

1 − 10*ε*.

1−2*ε*

1+2*ε*

*Proof of Lemma* [*15.*](#_bookmark36)We have

E sup *p*∈Ω *wp* · *u*S(*p*) − *u*S 1

Ω

S cost(*G,* A) + cost(*G,* S)

*p*∈Ω *wp* · *uG,*S(*p*) − *uG,*S 1

≤

EΩ sup

S

cost(*G,* A) + cost(*G,* S)

| E*G*

· PΩ[E*G*] (25)

*p*∈Ω *wp* · *uG,*S(*p*) − *uG,*S 1

+EΩ sup

S

| E*G*

· PΩ[E*G*] (26)

cost(*G,* A) + cost(*G,* S)

We first consider the term [25.](#_bookmark69) A trivial upper bound for PΩ[E*G*] is 1. Using Lemma [26](#_bookmark68) we have

S*w* · *u* =*p*

*C*∈ *HG,*S

*G,*

*p*

*C*∈*HG,*S

*wp* · cost(*p,* S) = (1 ± 10*ε*)

*C*∈*HG,*S

cost(*p,* S)*.*

The remaining entries of *uG,*S are 0. Since *uG,*S 1 ≤ cost(*G,* S), we therefore have

*p*∈Ω *wp* · *uG,*S(*p*) − *uG,*S 1

EΩ sup

S

| E*G*

· PΩ[E*G*] ≤ 10*ε.* (27)

cost(*G,* A) + cost(*G,* S)

We now focus on term [26.](#_bookmark69) We distinguish between two cases. If *p* Ω *wp* · *u*S(*p*) ≤ *u*S 1 then we have

∈

*p*∈Ω *wp* · *u*S(*p*) − *u*S 1 ≤ *u*S 1

≤ 1 (28)

cost(*G,* A) + cost(*G,* S) cost(*P,* A) + cost(*P,* S)

If *p*∈Ω *wp* · *u*S(*p*) ≥ *u*S 1 then we have

*wp*

*p*∈Ω

*δ* · cost(*G,* A)

*p*

* *uG,*S

=

*p*∈Ω

cost(*G,* A)

*δ* · cost(*p,* A)

*p*

*p*

* *uG,*S

(*Eq.* [7)](#_bookmark40) ≤

*p*∈Ω∩*C*∩*G*

*δ*

*p*

*C*

4*k*|*C* ∩ *G*| · cost(*G,* A) · *uG,*S

≤ 4*k* ·

*p*∈Ω∩*C*∩*G*

*C*

|*C* ∩ *G*| · *uG,*S

Therefore in this case

≤ 4*k* · *u*S 1*,*

*w* · *uG,*S − *uG,*S

· *u*S

*p*∈Ω *p p*

1 4*k* 1

≤

≤ 4*k* (29)

cost(*G,* A) + cost(*G,* S) cost(*G,* A) + cost(*G,* S)

Due to Lemma [19,](#_bookmark41) P [E ] ≤ *k*·exp − *ε*2 *δ* . Hence, if we set *δ* ≥ 9*ε*−2*k* log 4*k*2 , we have P[E

Ω

*G*

9·*k*

*ε*

*G*

4*k*

] ≤ *ε* .

This implies together with Equations [28](#_bookmark70) and [29](#_bookmark72)

*p*∈Ω *wp* · *qG,*S(*p*) − *qG,*S 1 *ε*

EΩ sup

S

| E*G*

· PΩ[E*G*] ≤ 4*k* · 4*k* ≤ *ε.* (30)

cost(*G,* A) + cost(*G,* S)

The claim now follows by combining Equations [27](#_bookmark71) and [30](#_bookmark73) and rescaling *ε*.

We now turn our attention to Lemma [17.](#_bookmark38) Henceforth, we let *G* ∈ *GO*. We first require an analogue of event E*G*. We define event E*far,G* that for all clusters *C* with

cost(*G,* A) cost(*p,* A) = (1 ± *ε*) · cost(*C* ∩ *G,* A)*.*

*p*∈*C*∩*G*∩Ω *δ* · cost(*p,* A)

Furthermore, by definition of the groups, we have

cost(*G,* A) ≤ 2*k* · cost(*C* ∩ *G,* A)*.* (31)

We start by bounding the probability that E*far,G* fails to occur.

**Lemma 27.** *Event* E

*far,G*

*happens with probability at least* 1 *k* exp( *ε*2

5·*k*

−

· *δ*)*.*

*Proof.* Again, we aim to use Bernstein’s Inequality. Let *pj* be the *j*th point in the sample Ω with respect to arbitrary but fixed ordering. Consider the random variable

*wpj,C*

= *wp* · cost(*p,* A) if *pj* = *p* ∈ *C* ∩ *G* . Then:

0 else

*pj,C* ] =

*E*[*w*

2

*p*∈ *C*∩*G*

cost(*G,* A)

*δ* · cost(*p,* A)

2

* cost(*p,* A)

* P[*p* ∈ Ω]

= cost(*G,* A)

·

*δ*2

cost(*p,* A)

*p*∈*C*∩*G*

= cost(*G,* A) cost(*C G,* )

∩ A

*δ*2

(*Eq.* [31)](#_bookmark74) ≤ 2*k* · cost2(*C* ∩ *G,* A)

*δ*2

Furthermore, we have by the same argument the following upper bound for the maximum value any of the *wpj,C* :

cost(*G,* A) 2*k*

*M* := max · cost(*p,* A) ≤ · cost(*C* ∩ *G,* A)*.*

*p*∈*C*∩*G δ* · cost(*p,* A) *δ*

Combining both bounds with Bernstein’s inequality now yields

P[|cost(*C* ∩ *G* ∩ Ω*,* A) − cost(*C* ∩ *G,* A)| ≤ *ε* · cost(*C* ∩ *G,* A)]

≤ exp − 2 *δ*

*ε*2 · cost2(*C* ∩ *G,* A)

*V ar*[*X* ] + 1 *M* · *ε* · cost(*C* ∩ *G,* A)

*i*=1

*i*

3

≤ exp

*ε*2

− 5 · *k* · *δ*

Reformulating, we now have

*p*∈*C*∩*G*∩Ω *δ* · cost(*p,* A)

cost(*G,* A) cost(*p,* A) = (1 ± *ε*) · cost(*C* ∩ *G,* A)*.*

Taking a union bound over all clusters yields the claim.

**Lemma 28.** *Condition on event* E*far,G. Suppose C* ∈ *FG,*S*. Then*

*cost*(*C* ∩ *G,* S) +

*p*∈*C*∩*G*∩Ω

*wp* · *cost*(*p,* S) ≤ *ε* · *cost*(*C,* S)*.*

*Proof.* First, we fix a cluster *C* ∈ A, and show that points of *C* ∩ *Gfar,*S are very cheap compared to cost(*C,* S), assuming that *C* ∈ *FG,*S. Let *c* be the center serving *p* ∈ *Gfar,*S ∩ *C* in A. Let *Cclose* be

the points of *C* with cost at most 2*z* *z* · cost(*C,c*) . Consider an arbitrary point in *p* ∈ *C* . Due to

S · S ≥ S − ≥

*ε*

|*C*|

*close*

4dist(*p, c*) −dist(*p, c*) ≥ dist(*p, c*). Therefore cost(*c,* S) ≥ 4*z* 2*z* · cost(*C,c*) . Using this and Lemma [10](#_bookmark27)

the triangle inequality and cost(*p,* ) *>* 4*z* cost(*p, c*), we have dist(*c,* ) dist(*p,* ) dist(*p, c*)

we now have for any *p*

∈ *Cclose*

*ε*

2*z* + *ε* *z*−1

cost(*c,* S) ≤ (1 + *ε*) · cost(*p ,* S) +

*ε*

|*C*|

≤ (1 + *ε*) · cost(*p**,* S) +

2*z* + *ε* *z*−1

*ε*

2*z* *z*

*ε*

cost(*C, c*)

|*C*|

4*z* 2*z*−1 cost(*C,c*)

·

· cost(*p , c*)

·

·

(1 + *ε*) cost(*p**,* ) + *ε* |*C*| cost(*p, c*)

≤ · S ·

cost(*p, c*)

≤ (1 + *ε*) · cost(*p**,* S) + *ε* · cost(*p, c*) since *p* ∈ *G* ∈ *GO*

≤ (1 + *ε*) · cost(*p**,* S) + *ε* · cost(*c,* S)

⇒ cost(*p**,* S) ≥ 1 − *ε* · cost(*c,* S) (32)

1 + *ε*

We now bound cost(*C,* ) in terms of cost(*C, c*). We have due to Markov’s inequality *C G*

S | ∩ | ≤

*ε* 2*z* and |*Cclose*| ≥ (1 − *ε*) · |*C*| and therefore

4*z*

cost(*C,* S) ≥ cost(*C*

1 + *ε*

*close*

*,* S) =

*p* ∈*Cclose*

≥ | −*C* | · ·

·

cost(*p**,* S) ≥ |*C*

*close*

| · 1 − *ε* · *cost*(*c,* S) (33)

1 *ε*

*close* 1 + *ε*

which yields for any *C* ∈ *Gfar,*S.

4*z* 2*z*

*ε*

cost(*C, c*)

|*C*| ≥

4*z* 2*z*−1

*ε*

· cost(*C, c*) (34)

cost(*C* ∩ *G,* S) =

*C*

*p*∈ *C*∩*G*

cost(*p,* S)

(*Lemma* [10)](#_bookmark27) ≤

*p*∈ *C*∩*G*

(1 + *ε*) · cost(*c,* S) +

2*z* + *ε* *z*−1

*ε*

* cost(*p, c*)

≤ |*C* ∩ *G*| · (1 + *ε*) · cost(*c,* S) +

2*z* + *ε* *z*−1

* cost(*C* ∩ *G, c*)

(Markov) ≤ (1 + *ε*) ·

*ε* 2*z*

*ε*

2*z*

* |*C*| · cost(*c,* S) +

2*z* + *ε* *z*−1

· cost(*C* ∩ *G, c*) (35)

(Markov) ≤

1 + *ε*

1 − *ε* ·

*ε* 2*z*

*ε*

2*z*

* |*Cclose*| · cost(*c,* S) +

2*z* + *ε* *z*−1

*ε*

* cost(*C* ∩ *G, c*)

(*Eq.* [33)](#_bookmark77) ≤

(*Eq.* [34)](#_bookmark77) ≤

(1 + *ε*)2

(1 − *ε*)2 ·

(1 + *ε*)2

(1 − *ε*)2 ·

*ε* 2*z*

2*z*

*ε* 2*z*

2*z*

* cost(*C,* S) +

· cost(*C,* S) +

2*z* + *ε* *z*−1

*ε*

2*z* + *ε* *z*−1

*ε*

* cost(*C* ∩ *G, c*)

*ε* 2*z*−1

·

· cost(*C,* S) (36)

4*z*

≤ *ε* · cost(*C,* S) (37)

What is left to show is that the weighted cost of the points in *Gfar,*S ∩ Ω can be bounded similarly.

For that, we use event E*far,G* to show that all clusters *C* induced by A

≈ |*G* ∩ *C*|. We have for*far,*S

cost(*G,*A0)

*p*∈*Gfar,*S ∩*C*∩Ω cost(*p,*A0)

*p*∈*C* ∩*G*∩Ω

cost(*G,* A)

*δ* · cost(*p,* A)

2*z* 2*z*

*ε*

cost(*C,* A)

|*C*|

*p*∈*C* ∩*G*∩Ω

cost(*G,* A) cost(*p,* )

*δ* · cost(*p,* A)

A

⇒ cost(*Gj,* A)

·

≤

·

≤ (1 + *ε*) · cost(*C* ∩ *G,* A)

≤ (1 + *ε*) · *ε* 2*z* · |*C*|cost(*C* ∩ *G,* A)

*p*∈*C*∩*G*∩Ω *δ* · cost(*p,* A)

2*z*

cost(*C,* A)

≤ (1 + *ε*) · *ε* 2*z* · |*C*| (38)

2*z*

Therefore, we have

cost(*G*

*far,*S

∩ Ω ∩ *C,* S) =

*p*∈*Gfar,*S ∩*C*

cost(*G,* A) cost(*p,* )

*δ* · cost(*p,* A)

· S

(*Lemma* [10)](#_bookmark27) ≤

*p*∈*Gfa* *r,*S ∩Ω∩*C*

cost(*G,* A)

*δ* · cost(*p,* A)

(1 + *ε*) · cost(*c,* S) +

2*z* + *ε* *z*−1

*ε*

* cost(*p, c*)

≤ (1 + *ε*) · cost(*c,* S) ·

·

cost(*G,* A)

(E*far,G*) +

2*z* + *ε* *z*−1

*p*∈*Gfar,*S ∩Ω∩*C δ* · cost(*p,* A)

· (1 + *ε*) · cost(*C* ∩ *G,* A)

(*Eq.* [38)](#_bookmark80) ≤ (1 + *ε*)2 · cost(*c,* S) ·

*ε*

*ε* 2*z*

≤ (1 + *ε*)

2

·

· |*C*| · cost(*c,* S) +

2*z*

*ε* 2*z*

2*z*

· |*C*| +

2*z* + *ε* *z*−1

*ε*

2*z* + *ε* *z*−1

*ε*

· (1 + *ε*) · cost(*C* ∩ *G,* A)

· cost(*C, c*) (39)

≤ *ε* · cost(*C,* S)

where the steps following Equation [39](#_bookmark81) are identical to those used to derive Equation [37](#_bookmark79) from Equation [35.](#_bookmark78) Summing up Equations [37](#_bookmark79) and [39](#_bookmark81) and rescaling *ε* by a factor 2 yields the claim.

*Proof of Lemma* [*17.*](#_bookmark38)Similar to the proof of Lemma [15,](#_bookmark36) we bound the expectation when condition- ing on E*far,G* and when E*far,G* fails to hold:

*w* · *uG,*S − *uG,*S

EΩ sup

*G G*

S

*p*∈Ω *p p* 1

cost(*P ,* A) + cost(*P ,* S)

= EΩ

sup

*p*∈Ω *wp*

*G*

* *uG,*S − *uG,*S

*G*

1 E

*far,G*

*p*

* + P [E

*far,G*

] (40)

S cost(*P ,* A) + cost(*P ,* S)

*w* · *uG,*S − *uG,*S

+E

Ω

sup

*p*∈Ω

*p*

*p*

1

E

*far,G*

· P

E

*far,G*

(41)

S cost(*P ,* A) + cost(*P ,* S)

*G*

*G*

For term [40,](#_bookmark82) Lemma [28](#_bookmark76) states that

*wp* · *uG,*S + *uG,*S 1 =

*p*

*wp* · *uG,*S +

*p*

cost(*p,* S)

*p*∈Ω

*C*∈*FG,*S *p*∈Ω∩*G*

*p*∈*C*∩*G*

≤ *C*∈ *FG,*S

*ε* · cost(*C* ∩ *G,* S) = *ε* · cost(*PG,* S)*.* (42)

S *wp*·*uG,*S − *uG,*S 1

*G,*

We now consider term [41.](#_bookmark82) If *uG,S* 1

*>*

*p*∈Ω

*w*

· *up*

, we can bound

*p*∈Ω *p*

cost(*PG,*A)+cost(*PG,*S)

by

*p*

1. Otherwise, let *rC* = max

cost(*p,*S)

*>* 4*z* and let *p* = argmaxcost(*p,*S) . We have dist(*c,* S) ≥

*p*∈*C*∩*G* cost(*p,*A

*p*∈*C*∩*G*

cost(*p,*A

dist(*p**,* S) − dist(*p**, c*) ≥ (*r*1*/z* − 1) · dist(*p**, c*), which implies cost(*c,*S) · 2*z* ≥ *r*

. Therefore

*C*

*w uG,*S =

*p*

*p*

*p*∈Ω

*C*

cost(*p* *,c*) *C*

cost(*G,* A) · cost(*p,* S)

*δ* · cost(*p,* A)

*p*∈Ω∩*C*

(*Eq.* [31)](#_bookmark74) ≤ 4*k* ·

*C*

≤ 4*k* ·

*C*

max cost(*C G,* ) *rC*

*p*∈*C*∩*G*

∩ A ·

max cost(*C* ∩ *G,* A) · 2*z* · cost(*c,* S)

*p*∈*C*∩*G*

cost(*p* *,* A)

≤ 2*z*+2*k* · max cost(*C,* A) · cost(*c,* S)

*C*

*p*∈*C*∩*G* cost(*p* *,* A)

(*Markov*) ≤ 2*z*+2*k* · *ε* 2*z* |*C*| · cost(*c,* S)

*C*

4*z*

(*Lemma* [10)](#_bookmark27) ≤ 22*z*+2*k* · (cost(*C,* A) + cost(*C,* S))

*C*

≤ 2 *k* · (cost(*P ,* A) + cost(*P ,* S))

2*z*+2 *G G*

*wp*·*uG,*S − *uG,*S 1

With this, we may bound the ratio

·

*p*∈Ω *p*

cost(*PG,*A)+cost(*PG,*S)

by 22+2*k*. The probability of E

*far,G*

is at

most *k* · exp

2

− 5·*k* ·

*ε*

*δ* due to Lemma [27.](#_bookmark75) Therefore setting *δ >* 5*k* log *k*2

22*z*+2·*ε*

yields

EΩ sup

*p*∈Ω *wp*

*G*

* *uG,*S − *uG,*S

*G*

*p*

1 E

*far,G*

* + P E

*far,G*

2*z*+2 *ε*

≤ 2 *k* · 2*z*+2

≤ *ε.*

S cost(*P*

*,* A) + cost(*P*

*,* S)

2 · *k*

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Summing this with Equation [42](#_bookmark83) and rescaling *ε* by a factor of 2 yields the claim.

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# A Lower bound for Arbitrary Powers in Euclidean Spaces

In this section, we generalize the lower bound to arbitrary powers *z* = 2. The proof follows exactly the same steps as for *z* = 2, except that we make use of the following observation to handle *z* = 2:

**Observation 1.** *For any* 0 *< a* ≤ 1 *any b >* 0 *and any x* ∈ [0*, b*] *we have ba*(1 − *x/b*) ≤ (*b* − *x*)*a* ≤

*ba*(1−*xa/b*)*. For any* 1 ≤ *a any b >* 0 *and any x* ∈ [0*, b*] *we have ba*(1−*xa/b*) ≤ (*b*−*x*)*a* ≤ *ba*(1−*x/b*)*.*

*Proof.* For any 0 *< a* ≤ 1 any *b >* 0 and any *x* ∈ [0*, b*], we have (*b* − *x*)*a* = *ba*(1 − *x/b*)*a* = *b* exp (−*a n*=1(*x/b*) */n*). Since *a* ≤ 1, this is at most *b* exp (− *n*=1(*xa/b*) */n*) = *b* (1 − *xa/b*). Also, since 0 ≤ 1 − *x/b* ≤ 1, it holds for any 0 *< a* ≤ 1 that (1 − *x/b*)*a* ≥ 1 − *x/b*.

∞ ∞*a n a n a*

For any 1 ≤ *a* any *b >* 0 and any *x* ∈ [0 *, b*], we have (*b*−*x*)*a* = *ba*(1−*x/b*)*a* = *ba* exp (−*a* ∞*n*=1(*x/b*)*n/n*).

it holds for any 1 ≤ *a* that (1 − *x/b*)*a* ≤ 1 − *x/b*.

Since *a* ≥ 1, this is at least *ba* exp (−

∞*n*=1(*xa/b*)*n/n*) = *ba*(1 − *xa/b*). Also, since 0 ≤ 1 − *x/b* ≤ 1,

The first step of our proof is again to argue that for any coreset using few points, there is a “cheap” clustering using a single center of unit norm:

**Lemma 29.** *Let r*1*, . . . , r* ∈ R2*d and let w*1*, . . . , w* ∈ R+*. There exists a unit vector v such that*

*w* min *r* − *ξv* *z* ≤ *w* ( *r* 2 + 1)*z/*2 − 2 min{1*, z/*2}

√

*i*=1

*i*

*ξ*∈{−1*,*1}

*i*

2

*i*=1

*i*

*i*

2

*i*=1 2

*wi*( *ri* 2+1)*z/*2−1 *ri* 2 *.*

*Proof.* Consider the random vector *u* =

*i*=1

2

*wi*( *ri* 2 + 1)*z/*2−1*σiri* where the *σi* are i.i.d. uniform

Rademachers. We see that

−*w* ( *r*  + 1) | *r , u* | =*i i* *i*

2 *z/*2 1

2

*i*=1

*i*=1

2 *z/*2 1

*wi*( *ri* + 1) −

2

*j*=1

*wi*( *ri* + 1) −

2 *z/*2 1

2

*wj*( *rj* + 1) − *σj* *ri, rj*

=

*i*=1

2 *z/*2 1

2

*j*=1

2 *z/*2 1

2

*wj*( *rj* + 1) − *σiσj* *ri, rj*

≥ *wi*( *ri* 2 + 1)*z/*2−1 *wj*( *rj* 2 + 1)*z/*2−1*σiσj* *ri, rj*

2

*i*=1

= *u* 2*.*

2

2

*j*=1

We may then define the unit vector *v* = *u/* *u* 2 (with *v* = 0 when *u* = 0) and conclude that

*wi*( *ri* 2 + 1)*z/*2−1| *ri, v* | ≥ *u* 2*.*

*i*=1

2

Since E[ *u* 2] = *w*2( *ri* 2 + 1)*z*−2 *ri* 2 we conclude that there must exist a unit vector *v* with

2 *i*=1 *i* 2 2

*wi*( *ri* 2 + 1)*z/*2−1| *ri, v* | ≥ *w*2( *ri* 2 + 1)*z*−2 *ri* 2*.*

*i*=1

*i*=1

2

*i*

2

2

By Cauchy-Schwartz, we have:

√

|1·*wi*( *ri* 2+1)*z/*2−1 *ri* 2| ≤ *w*2( *ri* 2 + 1)*z*−2 *ri* 2· 1 = *w*2( *ri* 2 + 1)*z*−2 *ri* 2·

*i*=1

*i*=1

*i*=1

*i*=1

2

*i*

2

2

*i*

2

2

which finally implies

2

*i*=1

*wi*( *ri* 2 + 1)*z/*2−1| *ri, v* | ≥

*i*=1

*wi*( *ri* 2 + 1)*z/*2−1 *ri* 2

2

√

*.*

For that unit vector *v*, consider *wi* min*ξ*∈{−1*,*1} *ri* − *ξv* *z* :

*i*=1

2

*wi* min *ri* − *ξv*

*z*

= *wi*( *ri* 2 + *v* 2 − 2| *ri, v* |)*z/*2

*i*=1

*ξ*∈{−1*,*1}

2 2 2

*i*=1

= *wi*( *ri* 2 + 1 − 2| *ri, v* |)*z/*2*.*

2

By Observation [1,](#_bookmark174) this is at most:

2

*z/*2

*i*=1

2 min{1*, z/*2}| *ri, v* |

≤ *wi*( *ri* 2 + 1) 1 −

*r* 2 + 1

*i*=1 *i* 2

≤ *wi*( *ri* 2 + 1)*z/*2 − *wi*2 min{1*, z/*2}| *ri, v* |( *ri* 2 + 1)*z/*2−1

2

*i*=1

*i*=1

*wi*( *ri* 2 + 1)*z/*2 − 2 min{1*, z/*2}

≤

2

*i*=1

2

*wi*( *ri* 2 + 1)*z/*2−1 *ri* 2

2

*i*=1

√

*.*

We now extend this to create a cheap clustering using *k* centers of unit norm:

**Lemma 30.** *Let r*1*, . . . , rt* ∈ R2*d and let w*1*, . . . , wt* ∈ R+*. There exists a set of k unit vectors*

*v*1*, . . . , vk such that*

− min{1*, z/*2}

*k z*

*t*

*t*

*wi* min *ri* − *vj* 2 ≤

*wi*( *ri* 2 + 1)

*i*=1

*j*=1

*i*=1

2 *z/*2

*t*

2 *z/*2−1

2*k/t*

*wi*( *ri* 2 + 1)

*ri* 2*.*

*i*=1

*and moreover, for every vj, there is a vi such that vj* = −*vi.*

*Proof.* Partition *r*1*, . . . , rt* arbitrarily into *k/*2 disjoint groups *G*1*, . . . , Gk/*2 of at most 2*t/k* vectors each. For each group *Gj*, apply Lemma [29](#_bookmark175) to find a unit vector *uj* with

*wi*( *ri* 2 + 1)*z/*2−1 *ri* 2

*ξ*∈{− 21*,*1}

2

*.*

*wi* min *ri* − *ξuj* *z* ≤

*wi*( *ri* 2 + 1)

*z/*2

− 2 min{1*, z/*2}

*ri*∈*Gj* 2

2*t/k*

*ri*∈*G*

*j*

*ri*∈*G*

*j*

Let *v*2*j*−1 = *uj* and *v*2*j* = −*uj*. Since we always add both *uj* and −*uj* we conclude:

*t*

*k z*

*j*=1

*k/*2

*z*

*i*=1

*wi* min *ri* − *vj* 2 ≤

*wi* min

*ξ*∈{−1*,*1}

*ri* − *ξuj* 2 ≤

*j*=1 *ri*∈*Gj*

*t t*

*wi*( *ri* 2 + 1)*z/*2 − min{1*, z/*2} 2*k/t* *wi*( *ri* 2 + 1)*z/*2−1 *ri* 2*.*

*i*=1

*i*=1

2

2

We now use the orthogonality of the standard unit vectors *e*1*, . . . , ed* to argue that any clustering of them using unit norm centers must be expensive:

**Lemma 31.** *For any d, consider the point set P* = {*e*1*, . . . , ed*} *in* R2*d. For any set of k centers*

*c*1*, . . . , ck* ∈ R2*d, all with unit norm and satisfying that for every cj there is*√*an index i such that*

*cj* = −*ci, it holds that* *d*

*i*=1

min

2

*k j*=1

*ei* − *cj* *z* ≥ 2*z/*2*d* − 2*z/*2 · max{1*, z/*2} ·

*dk.*

*Proof.* We see that

*k p*  *k* 2 2

*n*

*d*

min *ei* − *cj* 2 =

min

*j*=1

*ei* 2 + *cj* 2 − 2 *ei, cj*

*i*=1

*j*=1

*i*=1

*z/*2

*d*

=

*i*=1

*k*

2 2 max *ei, cj*

*j*=1

*z/*2

*.*

−

Since *c*1*, . . . , ck* satisfy that for every *cj* there is an index *h* with *cj* = −*ch*, it holds that max*k*  *ei, cj* ≥

*j*=1

0 for every *ei*. By Cauchy-Schwartz, we have | *ei, cj* | ≤ 1 hence by Observation [1,](#_bookmark174) the above is at

least:

*d*

2*z/*2*d* − 2*z/*2 · max{1*, z/*2} ·

*i*=1

*k*

*e , c* *.*

max

*j*=1

*i*

*j*

Now, for each *cj*, define *c*ˆ*j* to equal *cj*, except that we set the *i*’th coordinate to 0 if *j* =

argmax*h* *ei, ch* or *i > d*. Then:

*d d k*

2*z/*2*d* − 2*z/*2 · max{1*, z/*2} · *k* *e , c* = 2*z/*2*d* − 2*z/*2 · max{1*, z/*2} · *e , c*ˆ

*i*=1

max *i j j*=1

*i j*

*i*=1 *j*=1

*d k*

= 2*z/*2*d* − 2*z/*2 · max{1*, z/*2} · *ei,* *c*ˆ*j*

*i*=1

*k*

*j*=1

≥ 2*z/*2*d* − 2*z/*2 · max{1*, z/*2} · *c*ˆ*j* 1*.*

*j*=1

By Cauchy-Schwartz, we have *k*

*j*=1

have norm at most 1, we have

√

*k j*=1

*c*ˆ*j* 2 ≤

*c*ˆ*j* 1 ≤ *k*

*c*ˆ*j* 2 · √*d*. Since the *c*ˆ*j*’s are orthogonal and

min

*d i*=1

*k j*=1

*ei* − *cj* *z*

≥

2

2*z/*2*d* − 2*z/*2 · max{1*, z/*2} · *dk*.

√ *j*=1

*k*. Thus we conclude

We also need a handle on the offset of any coreset. This is obtained by considering a clustering using a single center that is orthogonal to all points *e*1*, . . . , ed* and all points of a coreset:

**Lemma 32.** *For any d, consider the point set P* = {*e*1*, . . . , ed*} *in* R2*d. Let r*1*, . . . , rt* ∈ R2*d and let w*1*, . . . , wt* ∈ R+ *be an ε-coreset for P, using offset* ∆ *and with t < d. Then we must have*

∆ +

2

*t*

*i*=1

*wi*( *ri* 2 + 1)*z/*2 ∈ (1 ± *ε*)2*z/*2*d.*

*Proof.* Since *t* + *d <* 2*d* there exists a unit vector *v* that is orthogonal to all *ri* and all *ej*. Consider placing all *k* centers at *v*. Then the cost of clustering *P* with these centers is 2*z/*2*d*. It therefore must

hold that ∆ +  *t wi*( *ri* 2 + *v* 2 − 2 *ri, v* )*z/*2 = ∆ + *t wi*( *ri* 2 + 1)*z/*2 ∈ (1 ± *ε*)2*z/*2*d*.

*i*=1

2

2

*i*=1

2

**Lemma 33.** *For any d and any k >* 1*, let P* = {*e*1*, . . . , ed*} *in* R2*d. Let r*1*, . . . , rt* ∈ R2*d and let*

*w*1*, . . . , wt* ∈ R+ *be an ε-coreset for P with t < d, using offset* ∆*. Then*

*t z/*2

*z/*2√

*i*=1

*wi*( *ri* 2 + 1)

*z/*2−1

*ri* 2 ≤

2*ε*2 *d* + max 1*, z/*2 2 *dk*

√2 · min{1*, z/*2} ·

{ }

*t/k.*

2

*Proof.* By Lemma [30,](#_bookmark176) we can find *k* unit vectors *v*1*, . . . , vk* such that

− min{1*, z/*2}

*k z*

*t*

*t*

*wi* min *ri* − *vj* 2 ≤

*wi*( *ri* 2 + 1)

*i*=1

*j*=1

*i*=1

2 *z/*2

*t*

2 *z/*2−1

2*k/t*

*wi*( *ri* 2 + 1)

*ri* 2*.*

*i*=1

Moreover, those vectors s atisfy that for every *vj*, there is an index *i* such th√at *vj* = −*vi*. By

2

*r*1*, . . . , rt* with respective weights *w*1*, . . . , wt* and offset ∆ form an *ε*-coreset for *P* , it follows from

min

Lemma [31,](#_bookmark177) it holds that

*p*∈*P*

*k j*=1

*p* − *vj* *z* ≥ 2*z/*2*d* − 2*z/*2 · max{1*, z/*2} ·

*dk*. Since points

Observation [1](#_bookmark174) that we must have

(1 − *ε*)2*z/*2(*d* − max{1*, z/*2} · √*dk*) ≤

*t*

∆ + *k*  *r* − *v* ≤

*z*

*i*=1

*t t*

min *wi i j* 2

*j*=1

∆ + *wi*( *ri* 2 + 1)*z/*2 − min{1*, z/*2} 2*k/t* *wi*( *ri* 2 + 1)*z/*2−1 *ri* 2*.*

*i*=1

*i*=1

2

2

By Lemma [32,](#_bookmark178) this is at most:

*t*

(1 + *ε*)2*z/*2*d* − min{1*, z/*2} 2*k/t* *wi*( *ri* 2 + 1)*z/*2−1 *ri* 2*.*

We have therefore shown that

2

*i*=1

*t*

2

(1 − *ε*)2*z/*2(*d* − max{1*, z/*2} · √*dk*) ≤ (1 + *ε*)2*z/*2*d* − min{1*, z/*2} 2*k/t* *wi*( *ri* 2 + 1)*z/*2−1 *ri* 2*.*

Which implies:

*i*=1

min{1*, z/*2} 2*k/t* · *wi*( *ri* 2 + 1)*z/*2−1 *ri* 2 ≤ 2*ε*2*z/*2*d* + max{1*, z/*2}2*z/*2√*dk* ⇒

*t*

2

*i*=1

*t*

{ }

*z/*2

*z/*2√

*i*=1

*wi*( *ri* 2 + 1)

*z/*2−1

*ri* 2 ≤

2*ε*2 *d* + max 1*, z/*2 2 *dk*

√2 · min{1*, z/*2} ·

*t/k.*

2

**Lemma 34.** *For any* 0 *< ε <* 1*/*2 *and any k >* 1*, let d* = *k/*(min{1*,* (*z/*2)2}322*ε*2) *and let P* = {*e*1*, . . . , ed*} *in* R2*d. Let r*1*, . . . , rt* ∈ R2*d and let w*1*, . . . , wt* ∈ R+ *be an ε-coreset for P, using offset* ∆*. Then*

2

*t*

*wh*

*h*=1

( *rh*

2 + 1)*z/*2−1 *rh*

2*z/*2*d*

2 ≥ 11 max{1*, z/*2} min{1*, z/*2} *.*

*Proof.* Consider the Hadamard basis *h*1*, . . . , hq* on *q* = 1*/*(min{1*,* (*z/*2)2}322*ε*2) coordinates, i.e. the set of rows in the normalized Hadamard matrix. This is a set of *q* orthogonal unit vectors with

all coordinates in {−1*/*√*q,* 1*/*√*q*}. All *hi* except *h*1 have equally many coordinates that are −1*/*√*q*

√ √

and 1*/ q* and *h*1 have all coordinates 1*/ q*. Now partition the first *d* coordinates into *k* groups

*G*1*, . . . , Gk* of *q* coordinates each. For any *hi*, consider the *k* centers *vi , . . . , vi*

obtained as follows:

1 *k*

For each group *Gj* of *q* coordinates, copy *hi* into those coordinates to obtain *vi*. We must have that

*j*

*d* min*k*  *eh* − *vi* *p* = *d* min*k* ( *eh* 2 + *vi* 2 − 2 *eh, vi* )*z/*2. Since *k >* 1, there is always a

*h*=1

*j*=1

*j*

2

*h*=1

*j*=1

2

*j*

2

*j*

*j* such that *eh, vi* = 0. Moreover, for *i* = 1, we have max*k*  *eh, vi* = 1*/*√*q* (since all coordinates

√ *j j*=1 *j* √

of *h*1 are 1*/ d*, and for *i* = 1, it holds for precisely half of all *eh* that max*k*  *eh, vi* = 1*/ q*. Thus

we have *d* min*k*  *eh* −*vi* *z* ≤ (*d/*2)2*z/*2 +(*d/*2)(2−1*/*√*q*)*z/*2. By Observation [1,](#_bookmark174) this is at most

*j*=1

*j*

*h*=1

*j*=1

*j*

2

(*d/*2)2*z/*2+(*d/*2)2*z/*2(1−min{1*, z/*2}*/*(2√*q*)) = *d*2*z/*2−(*d* min{1*, z/*2}*/*(4√*q*))2*z/*2 = *d*2*z/*2−8*εd*2*z/*2.

Thus:

2

*t*

(1 + *ε*)(*d*2*z/*2 − 8*εd*2*z/*2) ≥ ∆ + *wh*

*h*=1 *t*

( *rh*

2 + 1 −

*k*

2 max

*j*=1

2

*rh*

*, vi* )*z/*2

By Observation [1,](#_bookmark174) this is at least

*j*

≥ ∆ + *wh*

*h*=1

( *rh*

2 + 1 −

*k*

2 max

*j*

*j*=1

| *rh*

*, vi* |)*z/*2

*t*

∆ + *wh*

*h*=1

( *rh*

*t*

2 *z/*2

+ 1) − 2 max{1*, z/*2}

2

*h*=1

*k*

*wh* max

*j*=1

| *rh*

*, vi* |( *rh*

2 + 1)*z/*2−1

By Lemma [32,](#_bookmark178) this is at least

*j*

2

*t*

(1 − *ε*)2*z/*2*d* − 2 max{1*, z/*2}

*h*=1

*k*

*wh* max

*j*=1

| *rh*

*, vi* |( *rh*

2 + 1)*z/*2−1*.*

We have thus shown

*j*

2

*t*

2 max{1*, p/*2}

*h*=1

*t*

*k*

*wh* max

*j*=1

| *rh*

*, vi* |( *rh*

2 + 1)*p/*2−1 ≥ −2*ε*2*z/*2*d* + (1 + *ε*)8*εd*2*z/*2 ⇒

*z/*2

*j*

2

≥

*.*

*k i* 2

*j*=1

*wh* max | *rh, vj* |( *rh* 2 + 1)

max{1*, z/*2}

*z/*2−1

3*ε*2 *d*

Now consider any *rh* with weight *wh*. Collect the vectors *ui* such that *ui* = *vi*∗ where *j*∗ =

*h*

*h*

*j*

*h*=1

argmax*j* | *rh, vi* |. Let *σi* = sign( *rh, ui* ). By construction, all these *q* vectors are orthogonal

*j*

*h*

*h*

(either disjoint support or distinct vectors from the Hadamard basis). By Cauchy-Schwartz, we then

have *wh*( *rh* 2 + 1)*z/*2−1*rh,* *q σi ui* ≤ *wh*( *rh* 2 + 1)*z/*2−1 *rh* 2 *q σi ui* 2 = *wh*( *rh* 2 +

2

*i*=1

*h*

*h*

2

*i*=1

*h*

*h*

2

1. *z/*2−1 *rh* 2√*q*. We then see that

*z/*2 *q t*

3*ε*2 *dq*

*j*

2

max{1*, z/*2}

≤ *i*=1 *h*=1

*k*

*wh* max

*j*=1

| *rh*

*, vi* |( *rh*

2 + 1)*z/*2−1

*t q*

=

*h*=1 *i*=1

*t*

*j*

*k*

*wh* max

*j*=1

| *rh*

*, vi* |( *rh*

2 + 1)*z/*2−1

*q*

2

= *wh*( *rh* 2 + 1)*z/*2−1*rh,* *σi ui*

2

*h*=1 *t*

*h h*

*i*=1

≤ *wh*( *rh* 2 + 1)*z/*2−1 *rh* 2√*q.*

2

We have thus shown

*t*

2 *z/*2 1

2

*h*=1

*h*=1

3*ε*2*z/*2*d*√*q*

−*w* ( *r*  +1) *r*  ≥2*h h h*

=

max{1*, z/*2}

3 2*z/*2*d*

32 max{1*, z/*2} min{1*, z/*2} ≥

·

2*z/*2*d*

*.*

11 max{1*, z/*2} min{1*, z/*2}

We finally combine it all:

**Theorem 11.** *For any* 0 *< ε <* 1*/*2 *and any k, let d* = *k/*(min{1*,* (*z/*2)2}322*ε*2) *and let P* =

{*e*1*, . . . , ed*} *in* R2*d. Le* *t r*1*, . . . , rt* ∈ R2*d and let w*1*, . . . , wt* ∈ R+ *be an* (*ε, k, z*)*-coreset for P, using*

*offset* ∆*. Then t* = Ω

2

*k*

4

*.*

*ε*

max{1*,z* }

*Proof.* Combining Lemma [33](#_bookmark179) and Lemma [34,](#_bookmark180) we get 2*z/*2*d*

√

11 max{1*,z/*2} min{1*,z/*2}

*h*=1

*h*

*h*

2

≤ *t*

*w* ( *r*

2 +

1)*z/*2−1 *rh* 2

2*ε*2*z/*2*d*+max{1*,z/*2}2*z/*2

2·min{1*,z/*2}

≤ √

*dk* · *t/k*. That is,

*k* · 2 min{1*,* (*z/*2)2} · *d*2 · 2*z*

*t* ≥ (2*ε*2*z/*2*d* + max{1*, z/*2}2*z/*2√*dk*)2112 max{1*,* (*z/*2)2} min{1*,* (*z/*2)2} *.*

We have √*dk* = *d* min{1*,* (*z/*2)}32*ε*. Asymptotically, the whole bound thus becomes:

*t* = Ω *k .*

*ε*2 max{1*, z*4}