





# **Outline of todays lecture**

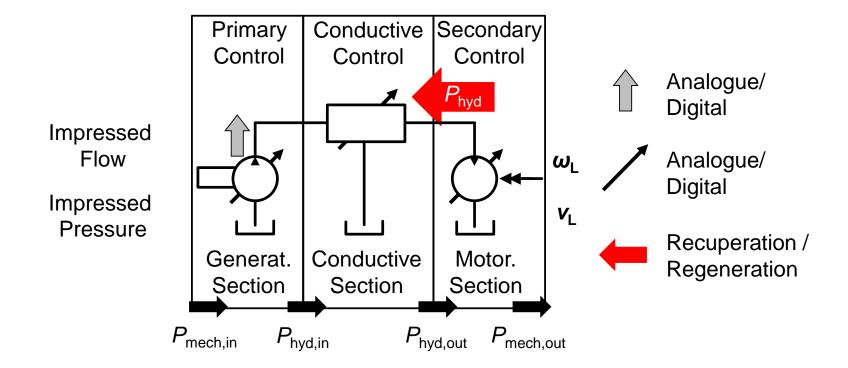
1	Backflip classification	of hydraulic controls
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- 2 Additional classification of hydraulic controls
- 3 Concepts for energy recovery
- 4 Exemplary system
- 5 Practical exercise
- 6 Summary





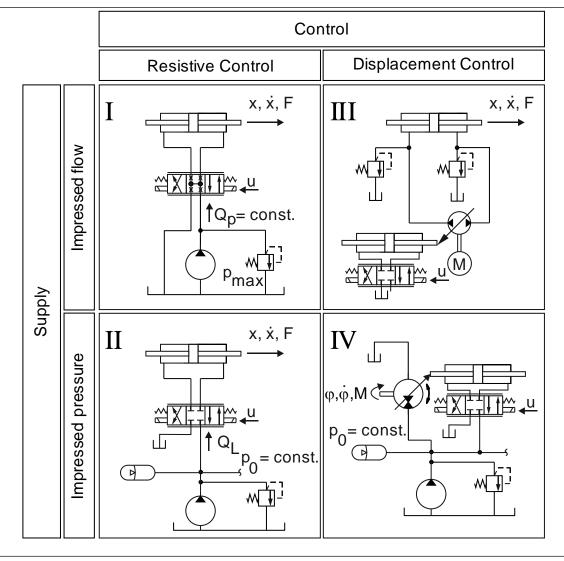
## **Structure of hydraulic systems**







## Classification of common types of hydrauli controls



#### **Resistance Control:**

- Good dynamics
- Good controllability
- Low investment costs
- High energy losses

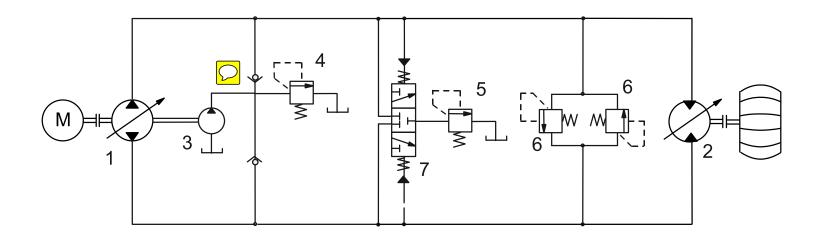
#### **Displacement Control:**

- Worse dynamics
- High investment costs
- Low energy losses





## Hydrostatic transmission in a closed circuit



- 1 Adjustable pump
- 2 Adjustable motor
- 3 Feed pump
- 4 PRV feed circuit

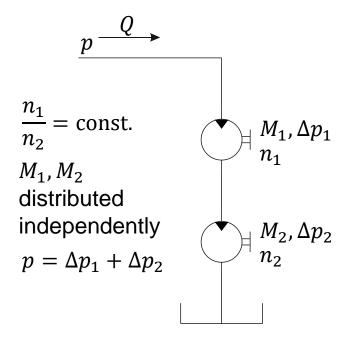
- 5 PRV flushing circuit
- 6 PRVs main circuit
- 7 Flushing valve



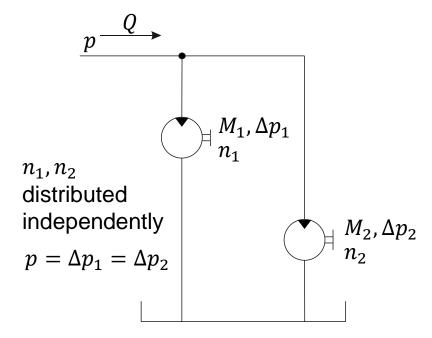


# **Serial and parallel motor connection**

#### Serial connection



#### Parallel connection





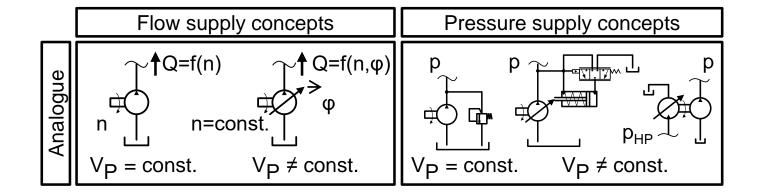
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# **Concepts for supplying hydraulic systems**

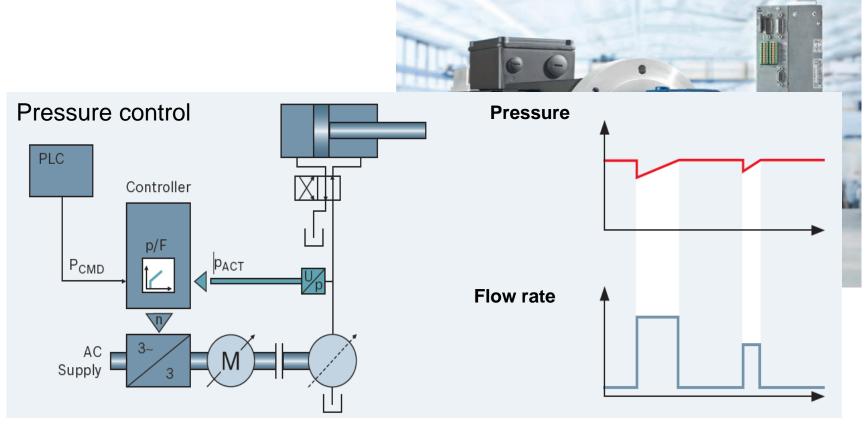






## **Example: Variable speed pump drives**

 Control of operating variables by software not by hydraulic-mechanical control units



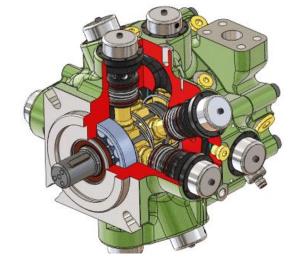
Source: Bosch Rexroth

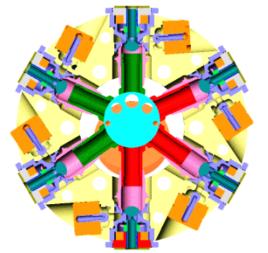


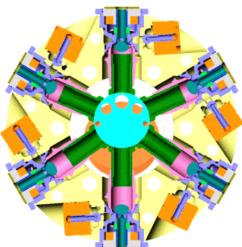


#### **Example: Artemis Digital Pump**

- Internally supported radial piston pump with digitally switchable pistons
- Discrete switchable displacement volumes
- Better efficiency in partial load operation compared to conventional pumps
- Idle mode





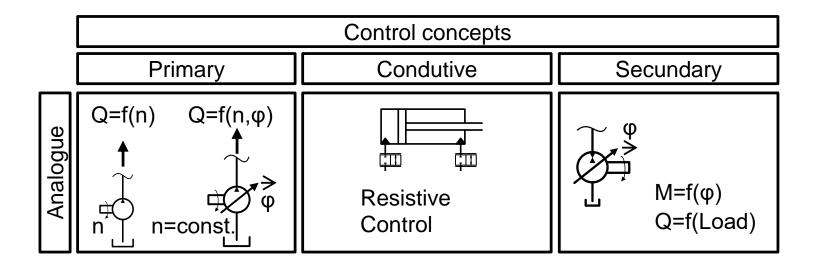


Source: Artemis





## **Concepts for hydraulic system controls**

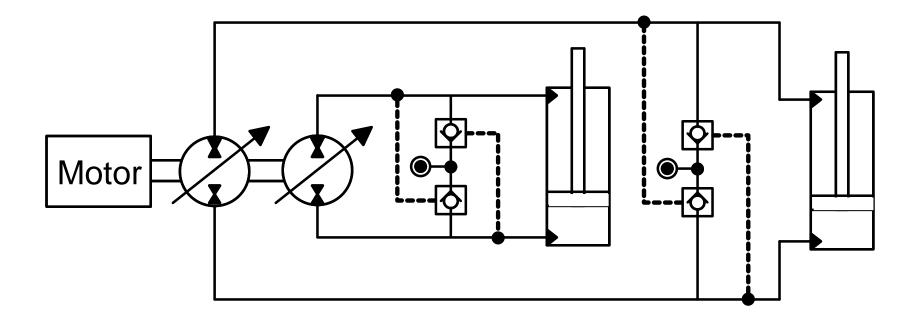






# **Example: Displacement controlled differential cylinder**

Control: Primary, analogue

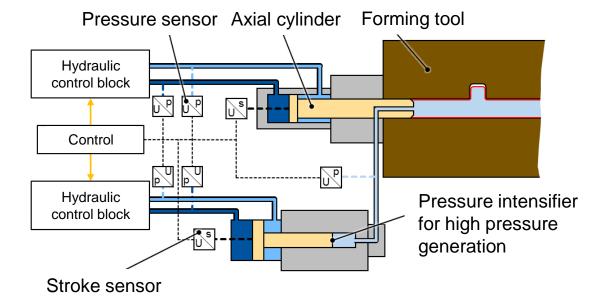






#### **Example: Pressure intensifier in forming processes**

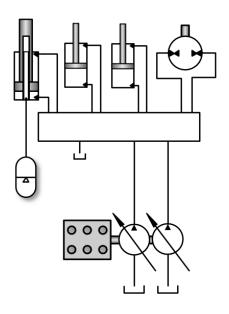
- Control of the pressure during hydroforming
- Use of simple control valves for pressure ranges up to 350 bar to adjust the high pressure up to 2000 bar





## **Example: Multi-chamber cylinder**

- Mantsinen HybriLift
  - Multi-chamber cylinder for the boom drive
  - Two different areas on the piston side of the cylinder allow energy recovery by increasing the pressure during lowering
  - Fuel savings of 35 %











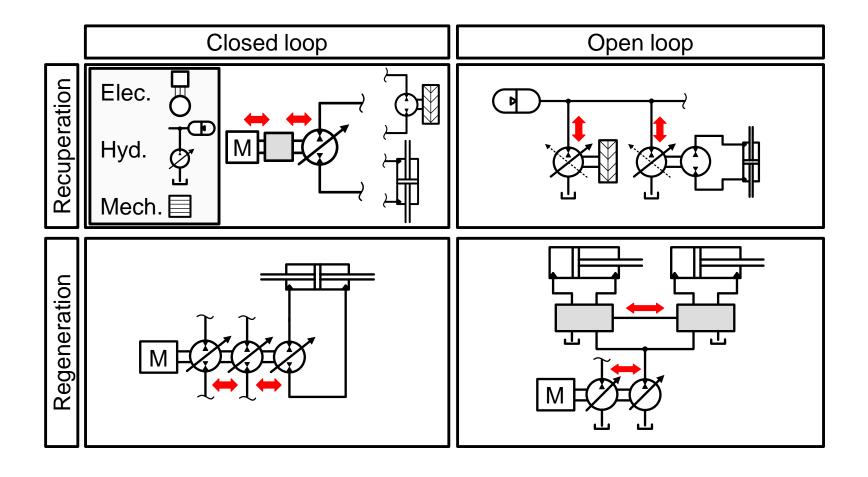
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# **Concepts for energy recovery**

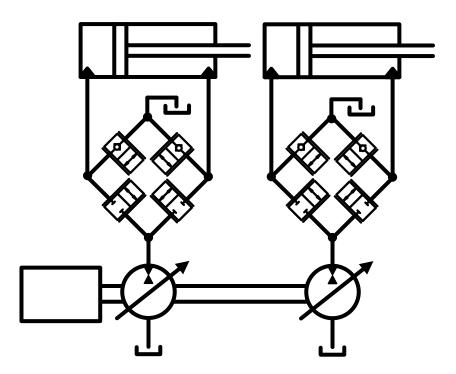






#### **Example: Displacement control in open circuit**

- Displacement control shows poor efficiency in partial load range
- Independent metering enables regeneration circuits (connecting both cylinder chambers)
- Regeneration between the two pumps additionally possible



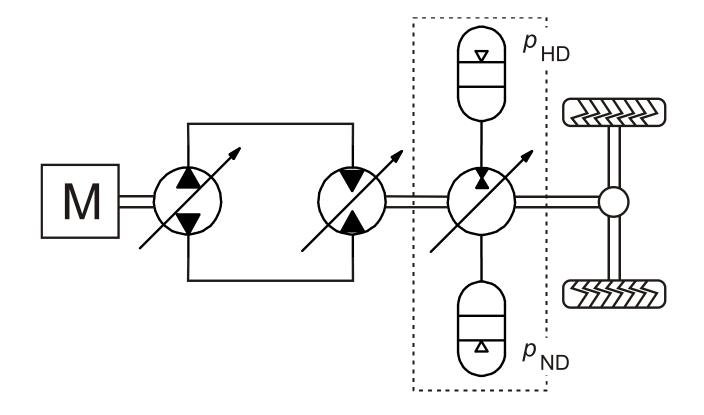
Source: Heybroek





## **Example: Displacement control in closed circuit**

- Hydrostatic drive in a closed circuit
- Braking energy is temporarily stored in the hydraulic accumulator
- Energy is taken from accumulator to accelerate



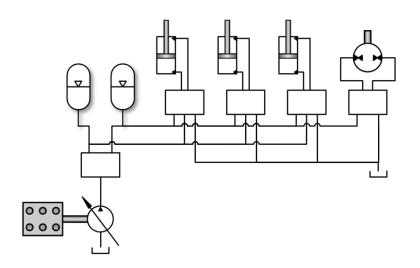


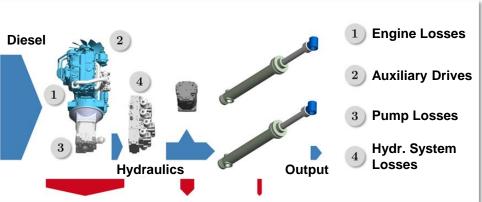


## **Excursus: STEAM project at ifas**

- Focus on relevant loss points in today's machines
- Decoupling of external load and diesel engine load
- Complete development from simulations to prototype









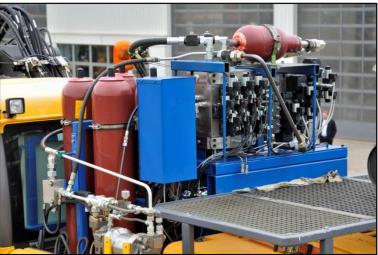


#### **STEAM project: Prototype**

- Parallel installation of standard system and the new hybrid system
- Validation on the basis of a 90° truck loading cycle











# **STEAM** project: Field test



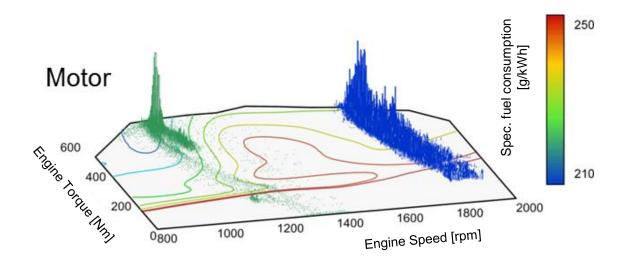


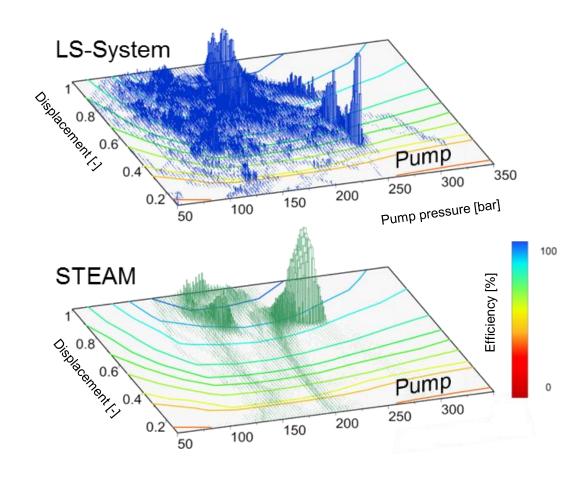




#### **STEAM project: Results**

 Same productivity as standard system with fuel savings of approx. 27%









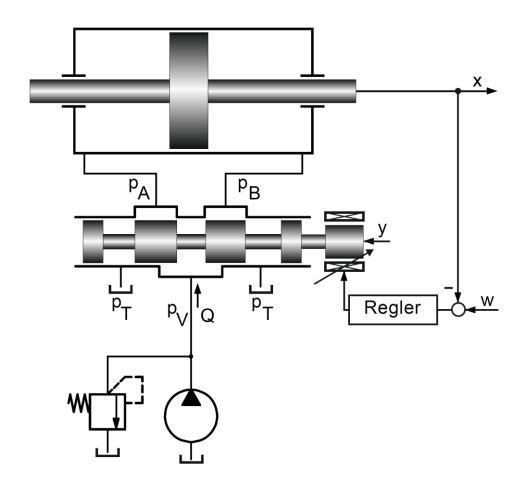
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# Position control of a cylinder

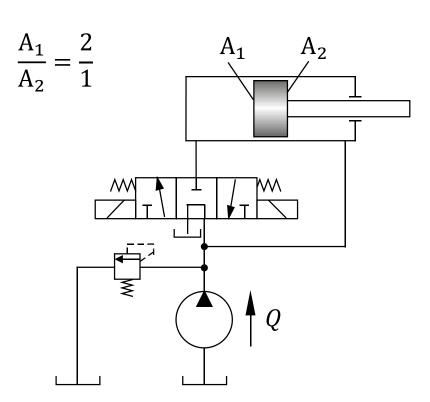






# Velocity control: differential cylinder with equal speeds

- Permanent connection of the rod side to the pump line
- Same speeds at an area ratio of 2:1
- Equal loads in both directions possible







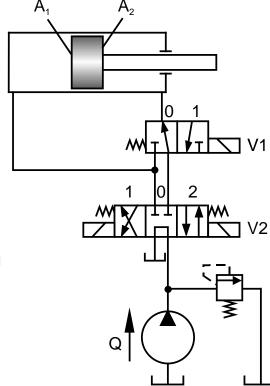
# Fast forward circuit – with differential cylinder

- Control of direction of movement or standstill with valve V2
- Fast forward during extension is effected by switching valve V1
- Velocity during extension

$$v = \frac{Q}{A_1}$$

Fast forward-velocity during extension

$$v = \frac{Q}{A_1 - A_2}$$



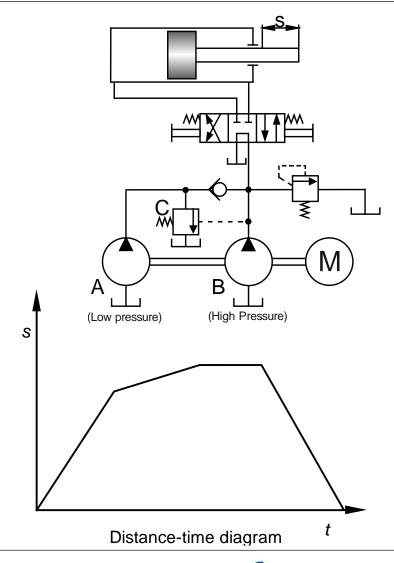
		V 1	
		0	1
	0	Stop	Stop
V2	1	Forward	Fast forward
	2	Backward	Float





#### Fast forward circuit – with low pressure pump

- Parallel connection of a low pressure pump with a high delivery flow, pump A, and a high pressure pump with a low delivery flow, pump B
- In fast forward, pumps A and B both deliver to the cylinder
- When the load increases, valve C is opened and flow of pump A returns into the reservoir

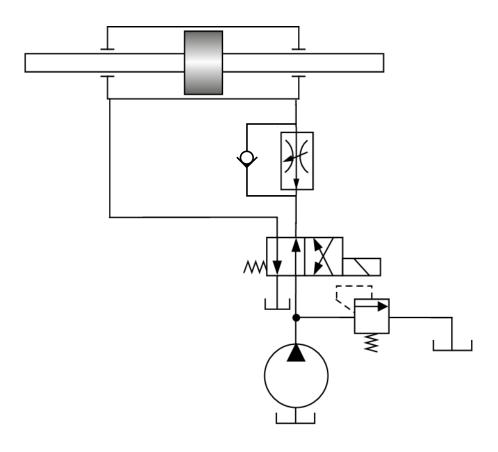






# **Velocity control – with one flow control valve**

 Velocity control of the volume flow from the right cylinder chamber

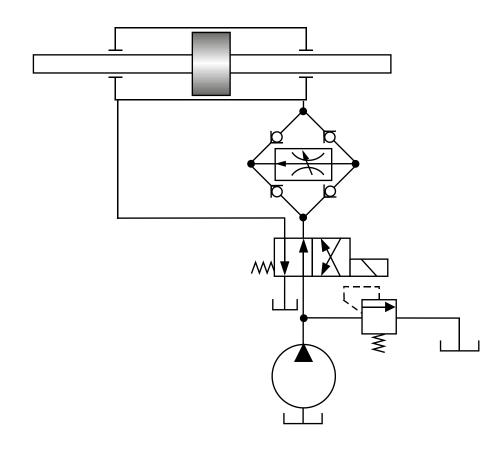






#### **Velocity control – flow control valve in Graetz bridge design**

- Velocity control of the volume flow from and to the right cylinder chamber
- Same extension and retraction speeds
- Usability of this circuit depending on the actual loads (risk of cavitation)

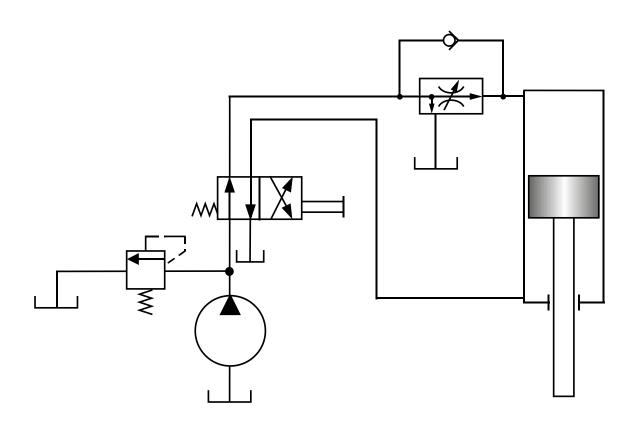






#### **Velocity control** – with upstream flow control

- A flow control upstream can take place only when loads are effective in the pressing direction
- When employing a 3-ways pressure compensator, the pressure rises as highly as the load requires

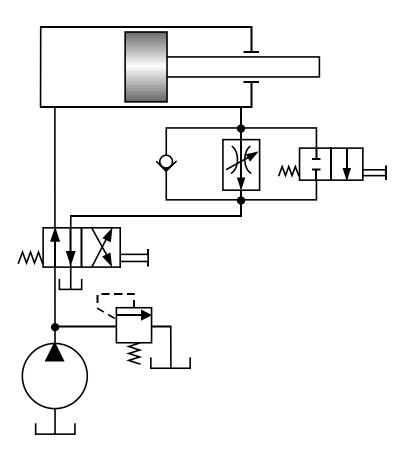






## **Velocity control – with downstream flow control**

- The speed is variable in two steps with the 2/2-directional valve
- Frequent use for drives with active loads, e.g. lifting cylinders for forklift trucks



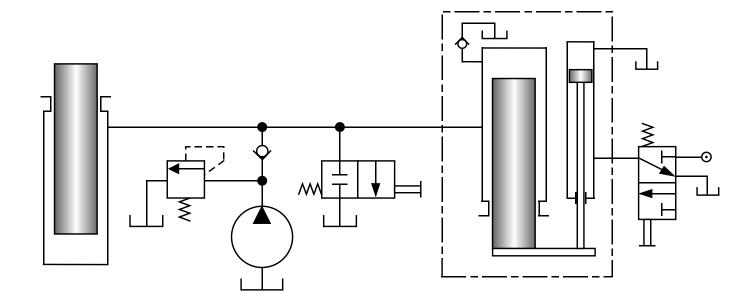




#### Simple press control

 With the downstroke press, the back flow ensues with the piston's own weight

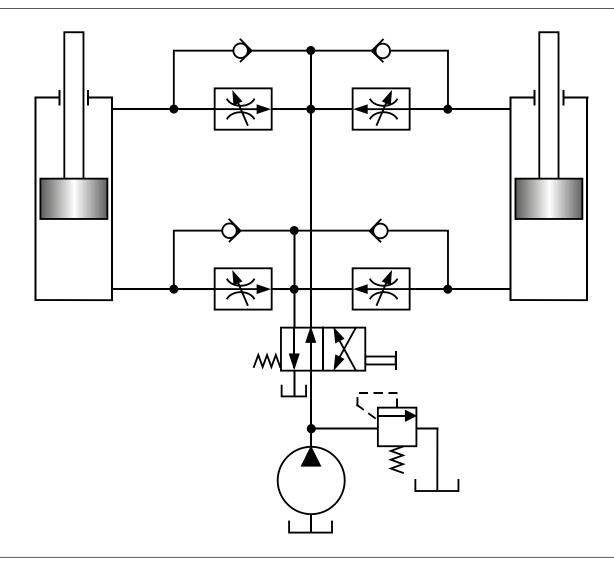
- With the downstroke press, however, the press is closed by its own weight.
- The cylinder is filled from a higher vessel by a suction valve. The return trip is performed by a separate pullback cylinder.







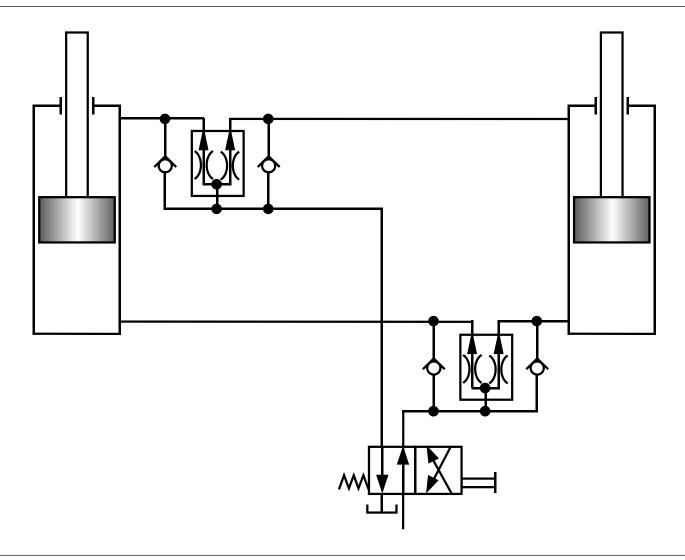
# Synchronous run – with flow control valve in return line







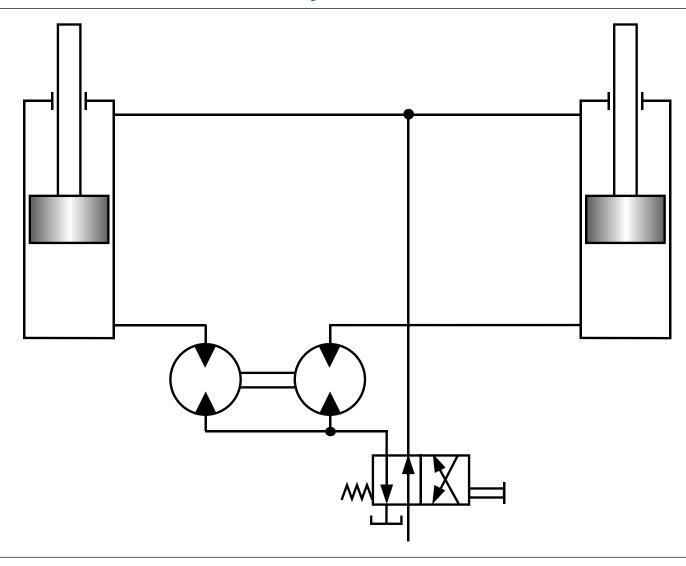
# Synchronous run control – with flow divider in feed line







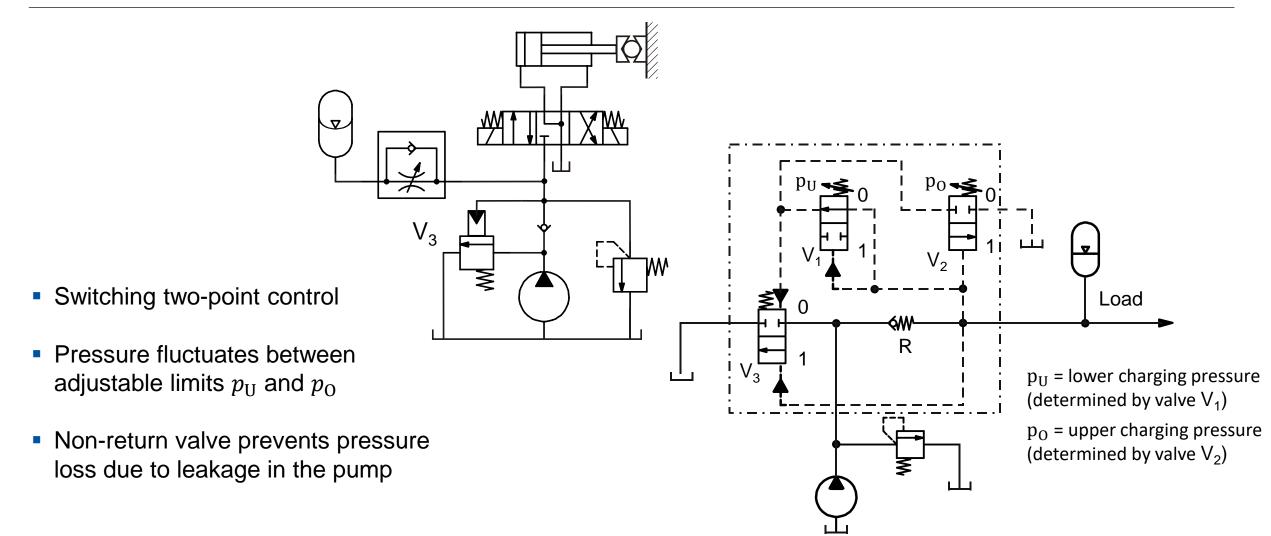
# Synchronous run control – with mechanically connected motors







# **Accumulator Charging Circuit**







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#### Practical excercise: designing a hydraulic system of a boatlift

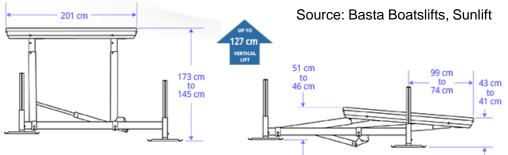
#### Boundaries:

Installation space, weight of the boat, lifting speed

#### What to do:

- calculate the required force of the cylinder
- set max. system pressure, dimensioning cylinder
- calculate required cylinder speed
  - → pump volume flow
- select pump(utility frequency of electric motor)
- estimate losses in the system
  - → pump pressure level
- select electric motor(max. pressure, max. volume flow)
- select valves (directional valve, PRV, etc.)
- dimension the tank
- cooler ?, filter
- design circuit diagram & create parts list









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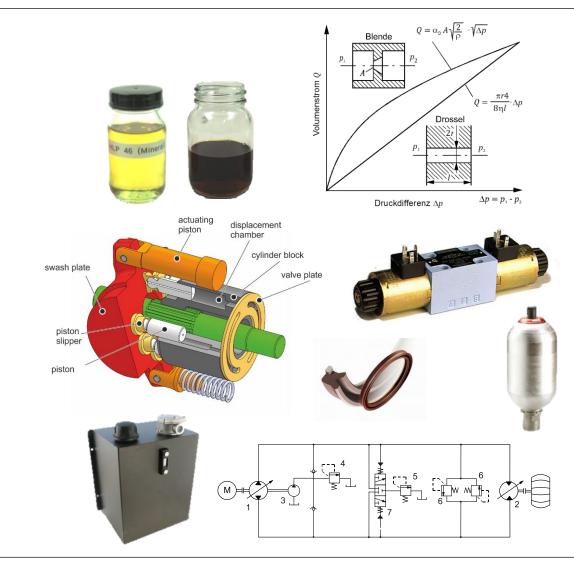
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### **Summary**

- Lecture 1: Fundamentals
- Lecture 2: Hydraulics networks
- Lecture 3: Fluids
- Lecture 4/5: Pumps & motors
- Lecture 6/7: Valves
- Lecture 8: Seals, components
- Lecture 9/10: Hydraulic circuits







Thank you for your attention.



