

# Fundamentals of Fluid Power – Pneumatics

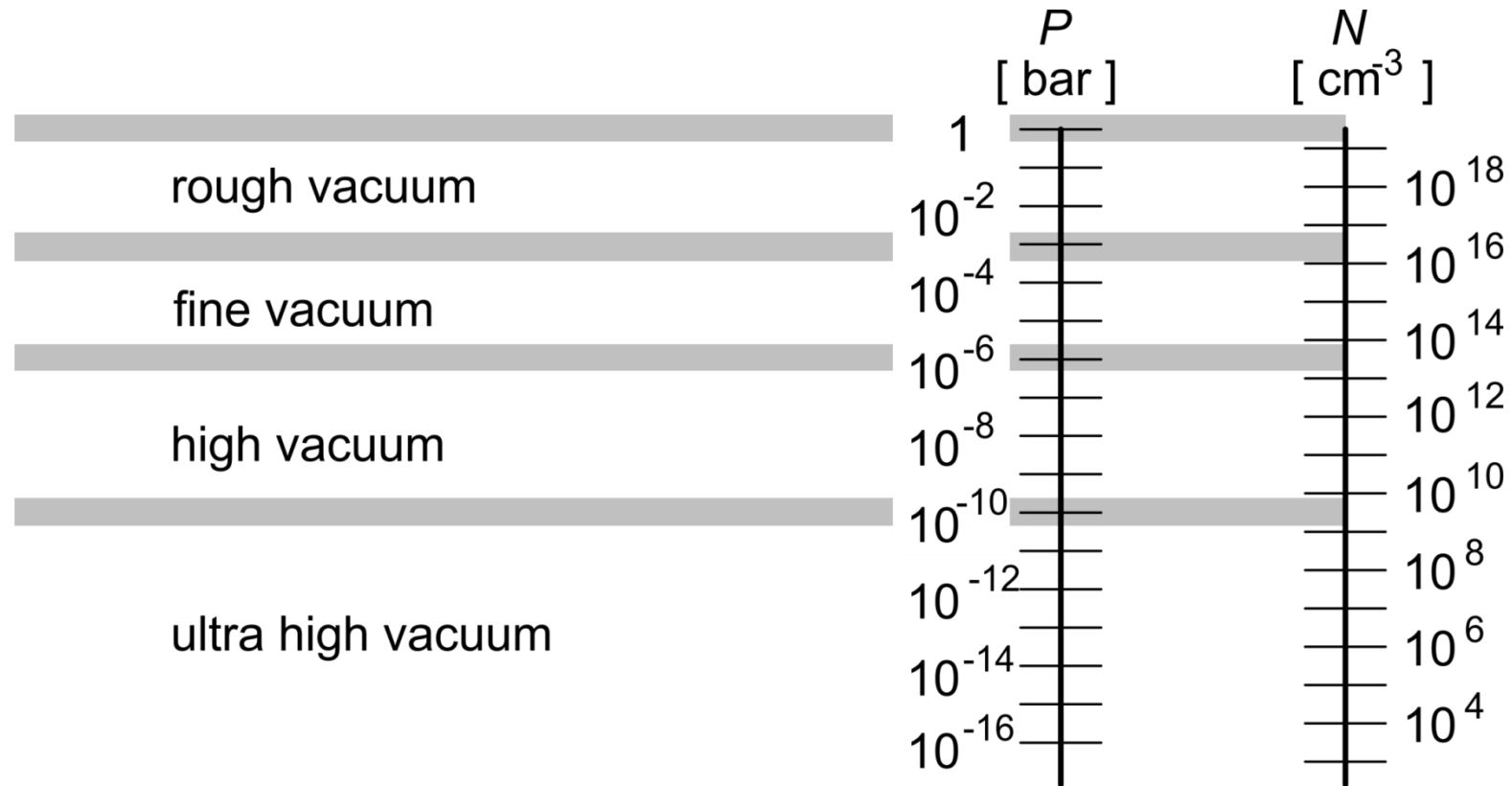
## Fourth Lecture - Applications

# Outline

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- 1 Vacuum Technology
- 2 Systems and Circuits
- 3 Exergy
- 4 Measures for Efficiency Optimization
- 5 Selected Applications

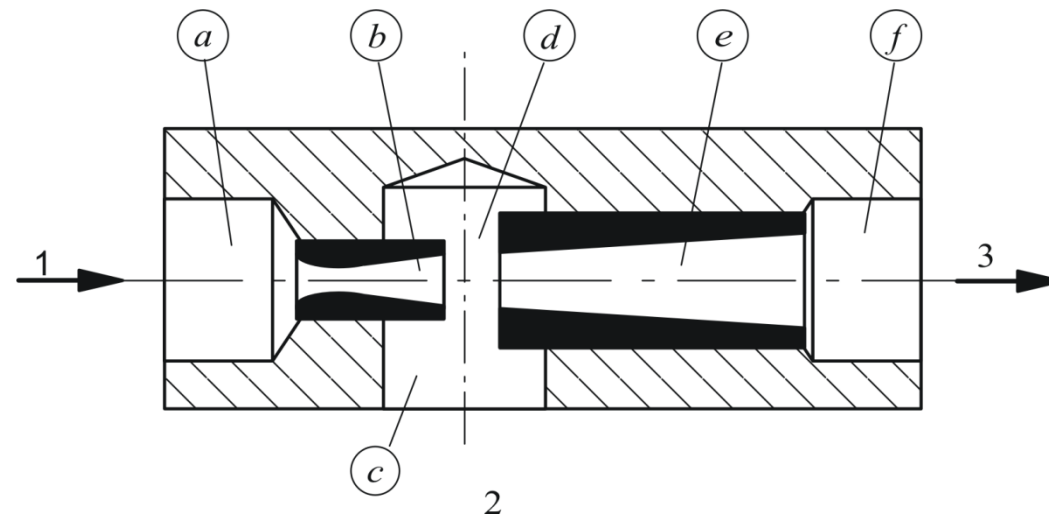
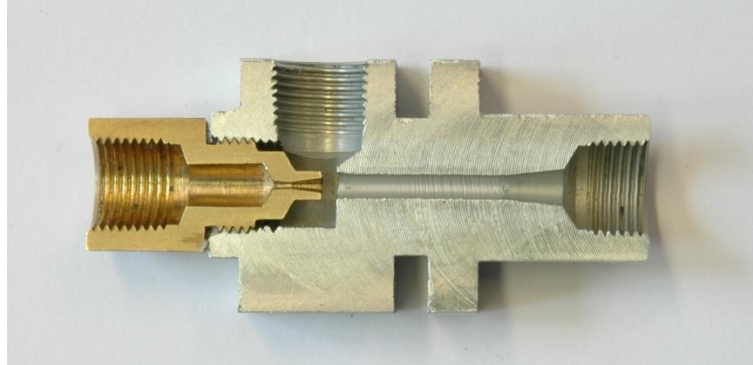
# Vacuum Classification According to DIN 28400



$P$  : absolute pressure

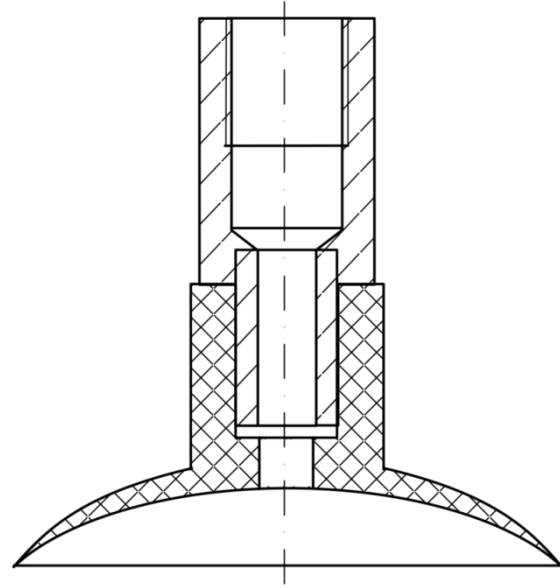
$N$  : number of particles per space unit for air at 20° C

# Ejector

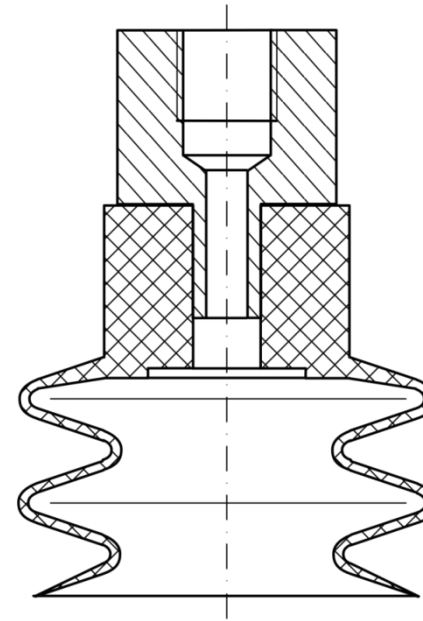




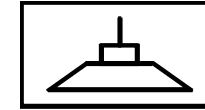
# Different Types of Suction Grippers



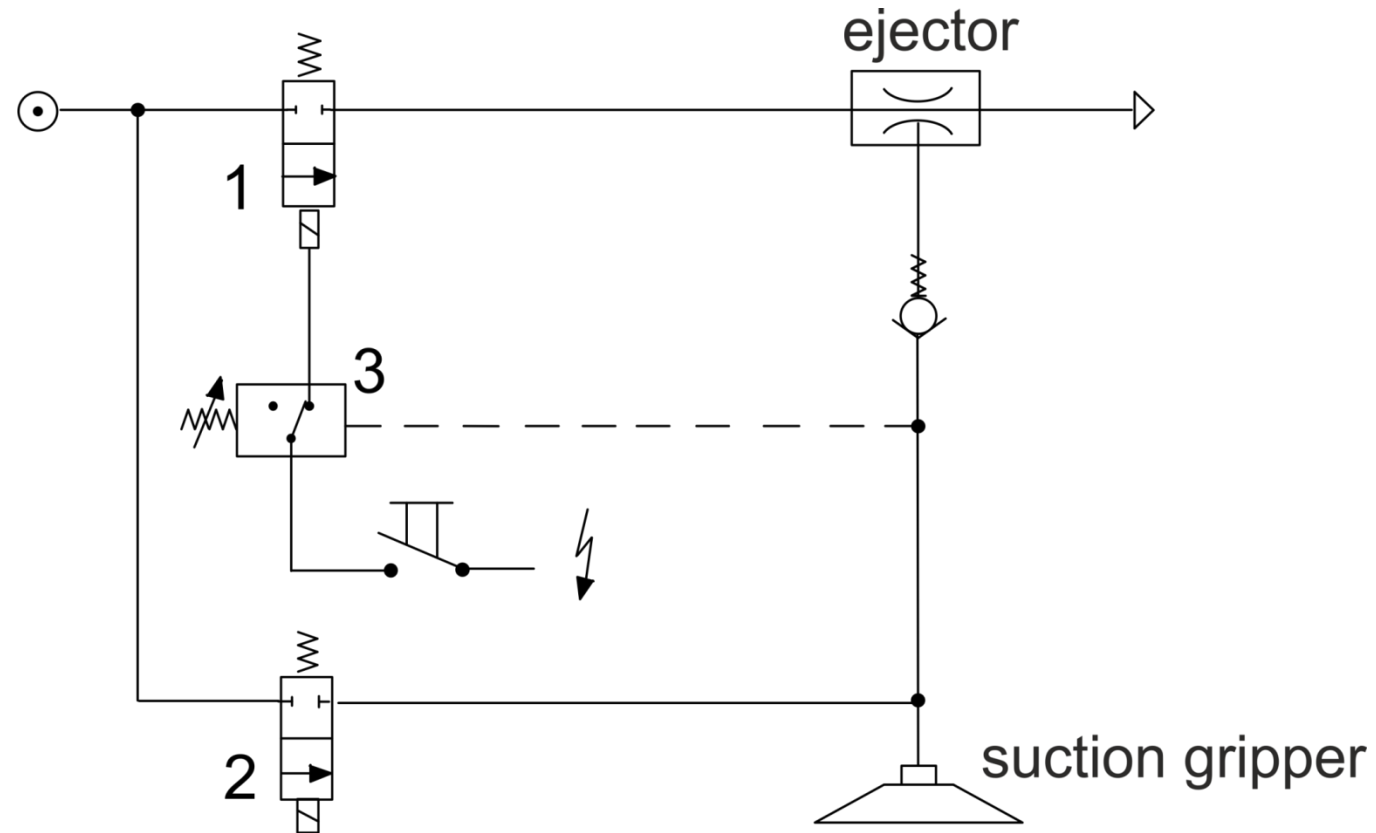
flat suction gripper



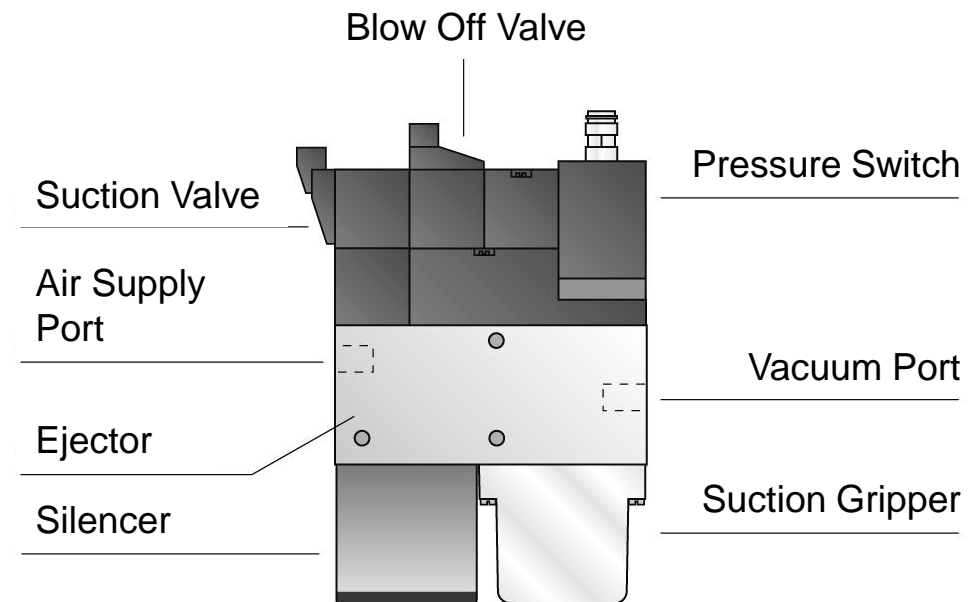
telescopic suction gripper



# Suction Gripper with Ejector



# Integrated Ejector



Source: Schmalz

# Outline

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1 Vacuum Technology

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3 Exergy

4 Measures for Efficiency Optimization

5 Selected Applications



# Open and Closed Loop Control

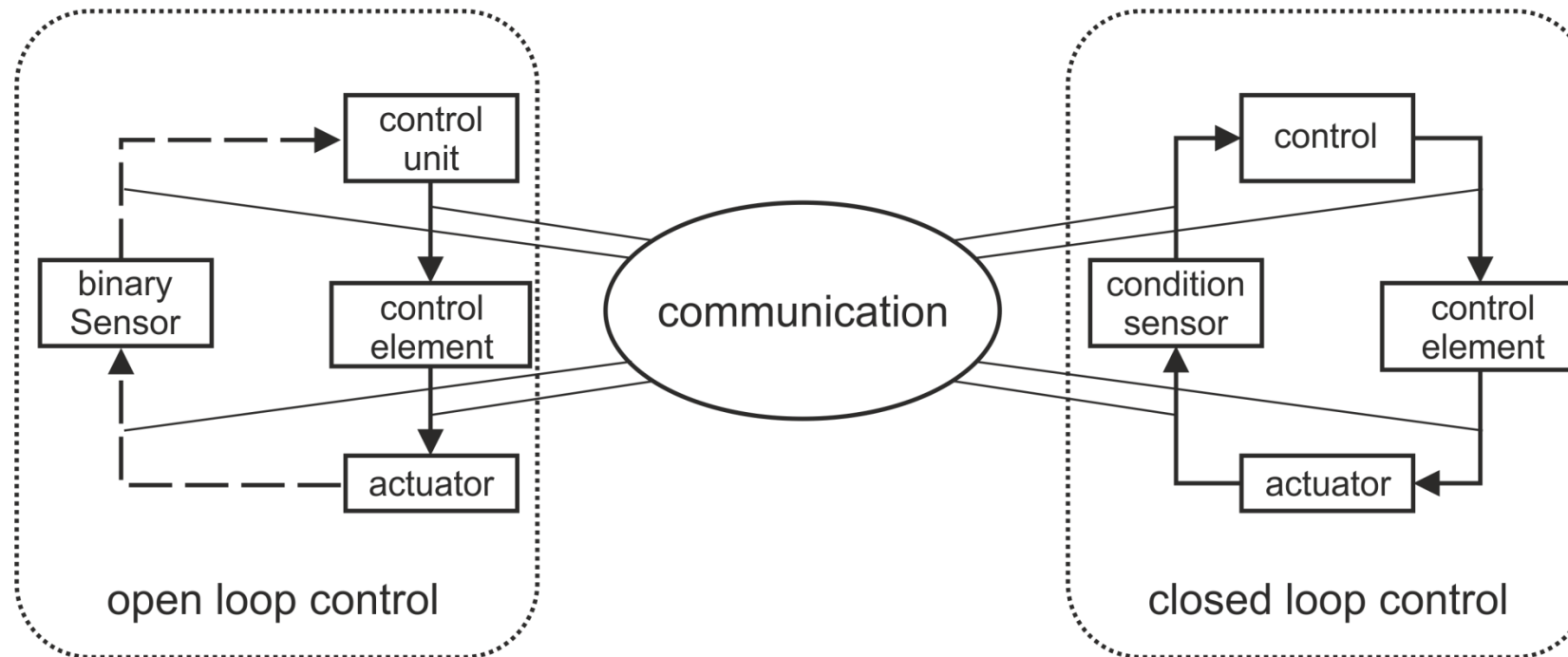
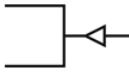
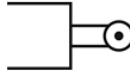
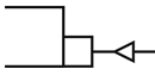
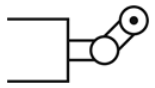
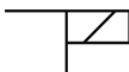
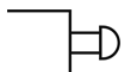

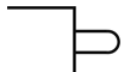



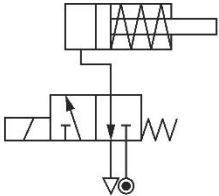
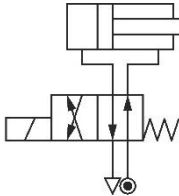
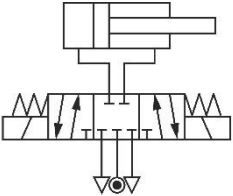
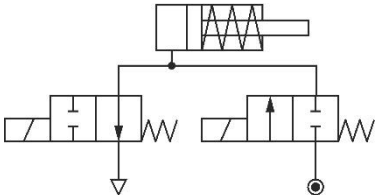
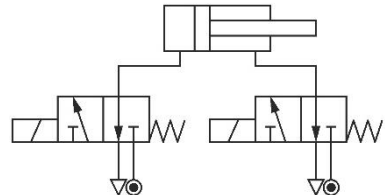
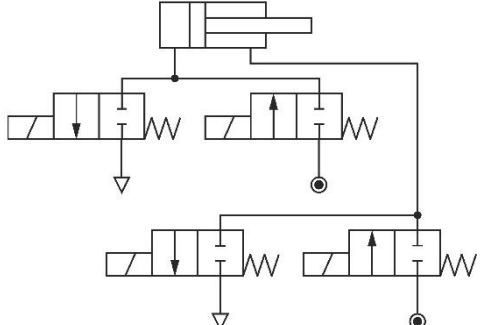
Fig. 4-1

## Selected Actuations of Pneumatic Valves According to DIN-ISO 1219-1

symbol	description	symbol	description
	pressurised, directly operated		roller plunger
	pressurised, small acting area		roller lever for actuation in one moving direction
	magnet coil with single winding		manual actuation
	spring force		plunger actuation
			manual actuation with detent

Tab. 4.1-2

# Example Circuits for Controlling a Cylinder

Single Acting Cylinder	Double Acting Cylinder	
 <p data-bbox="445 514 930 685">Controlled by an electromagnetically actuated spring returned 3/2-way valve</p>	 <p data-bbox="1070 514 1554 685">Controlled by an electromagnetically actuated spring returned 4/2-way valve</p>	 <p data-bbox="1643 514 2127 685">Controlled by an electromagnetically actuated spring centered 5/3-way valve</p>
 <p data-bbox="445 1042 930 1213">Controlled by two electromagnetically actuated spring returned 2/2-way valves</p>	 <p data-bbox="1070 1042 1554 1213">Controlled by two electromagnetically actuated spring returned 3/2-way valves</p>	 <p data-bbox="1643 1085 2127 1213">Controlled by four electromagnetically actuated spring returned 2/2-way valves</p>

Tab. 4.1-3

# Intentional Sequence Control

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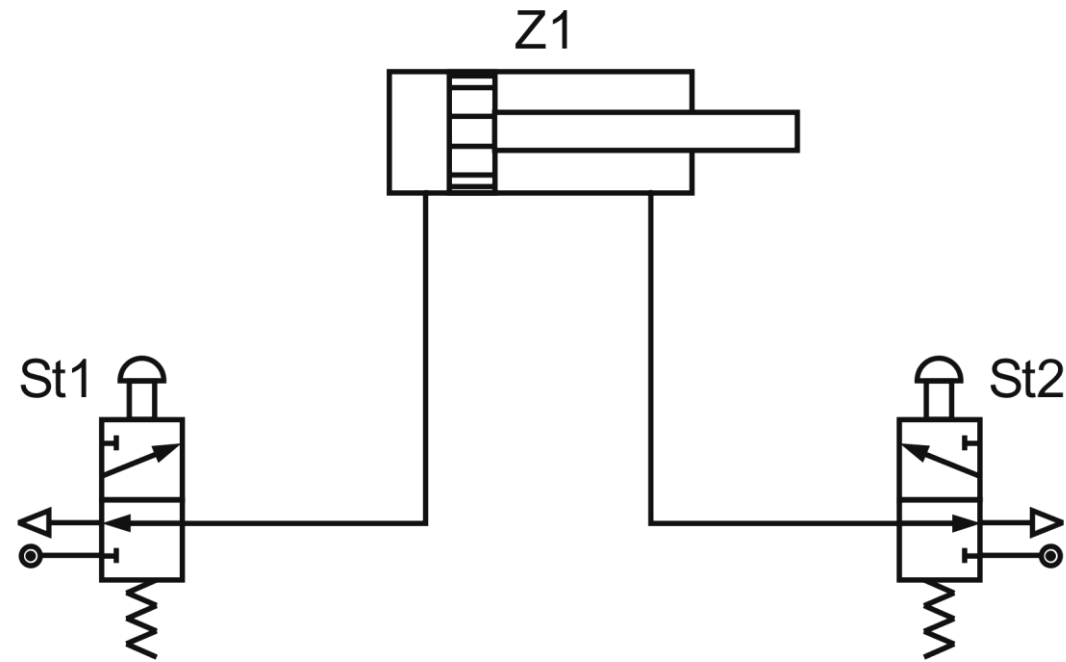


Fig. 4.1-4

# Stroke-Depending Sequence Control

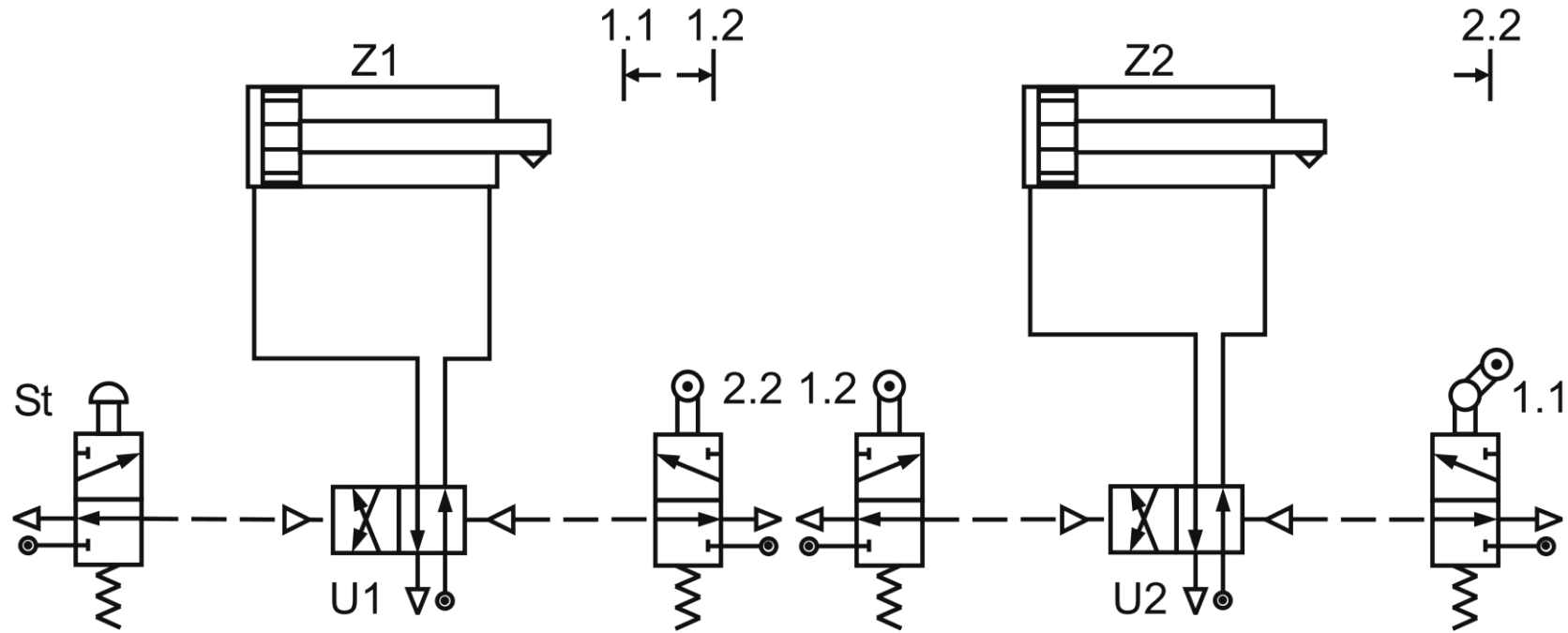


Fig. 4.1-5

# Time-Depending Sequence Control

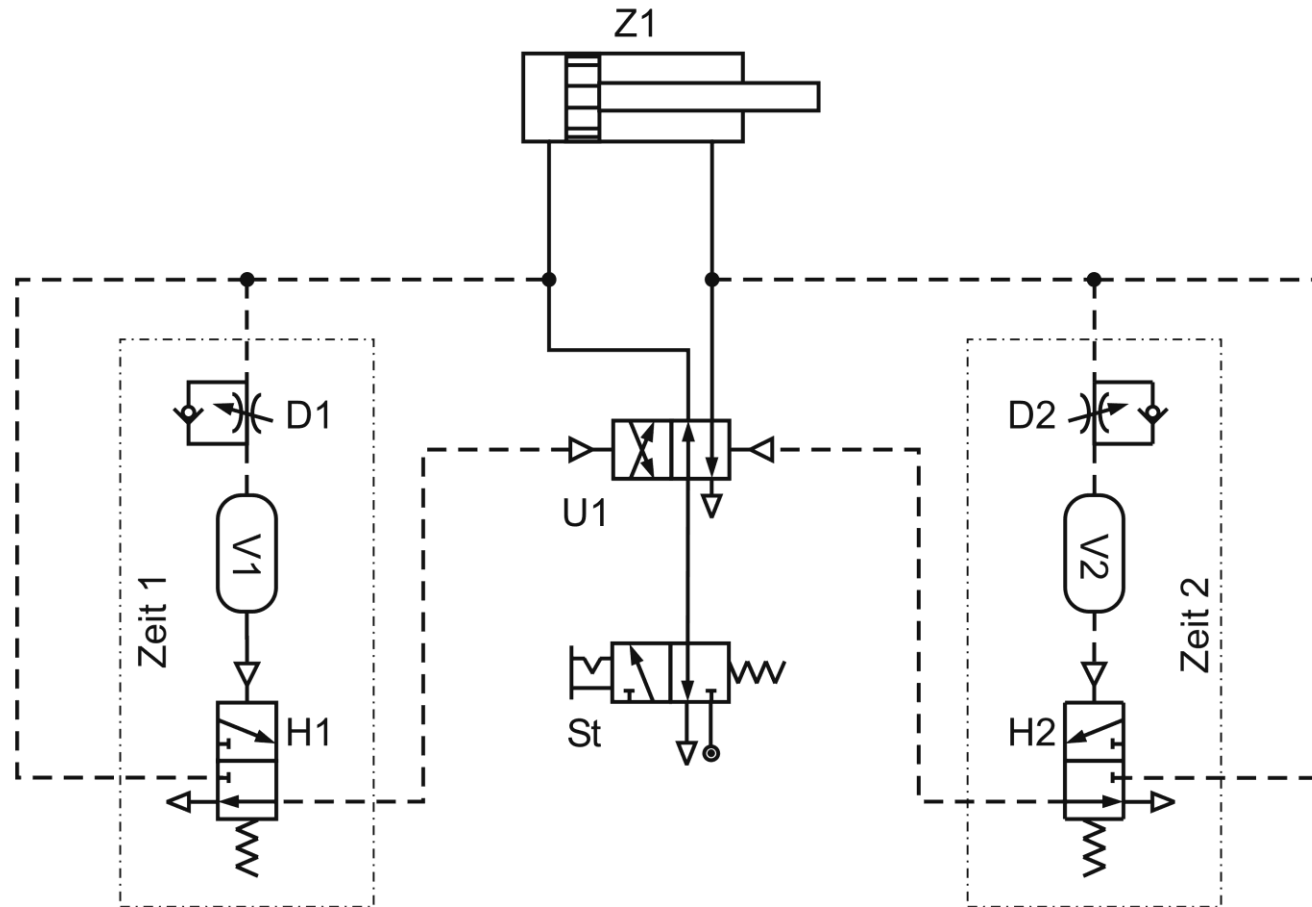


Fig. 4.1-6



# Pressure-Depending Sequence Control

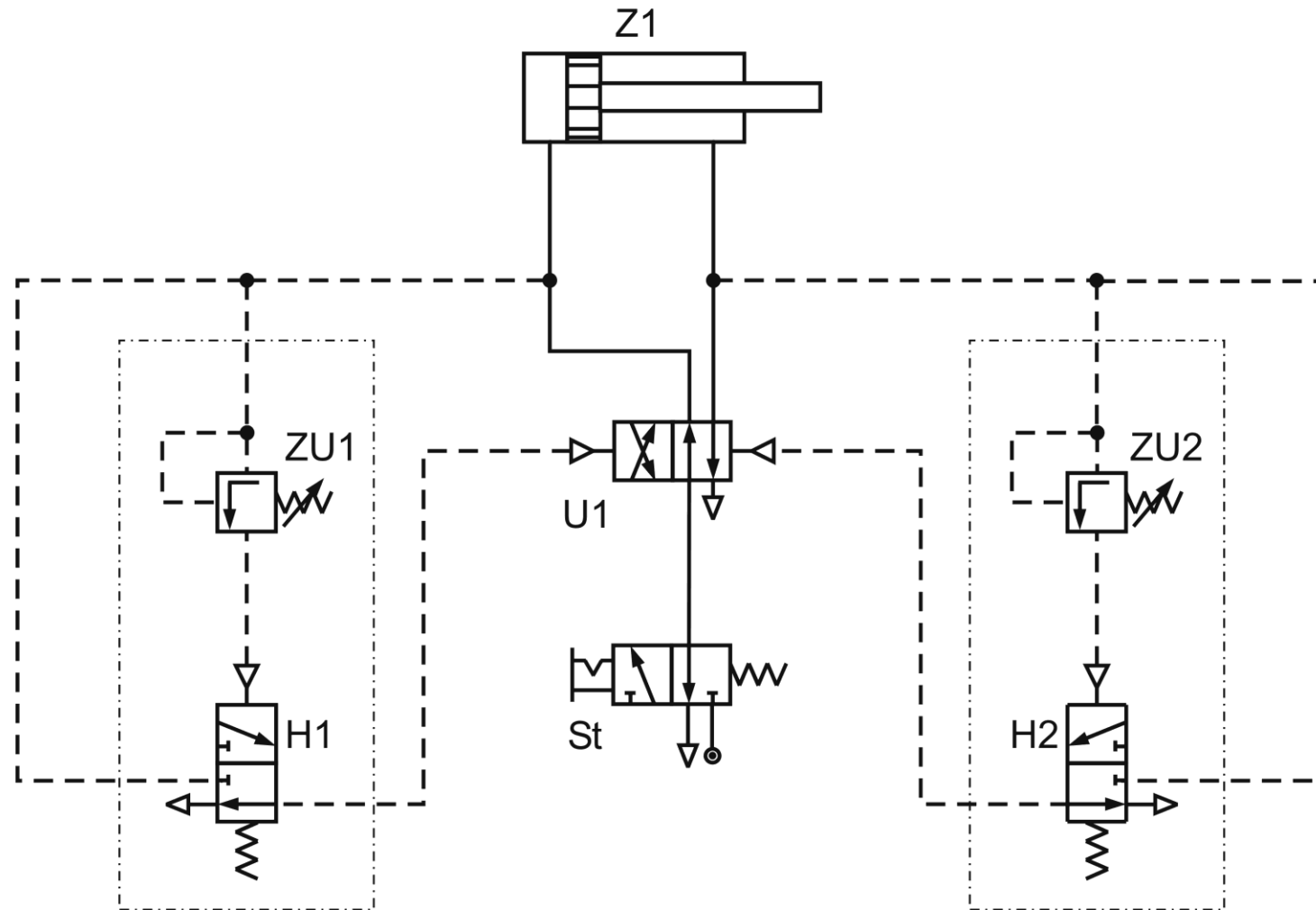


Fig. 4.1-7

# Example for Location Chart (top) and Function Chart (bottom)

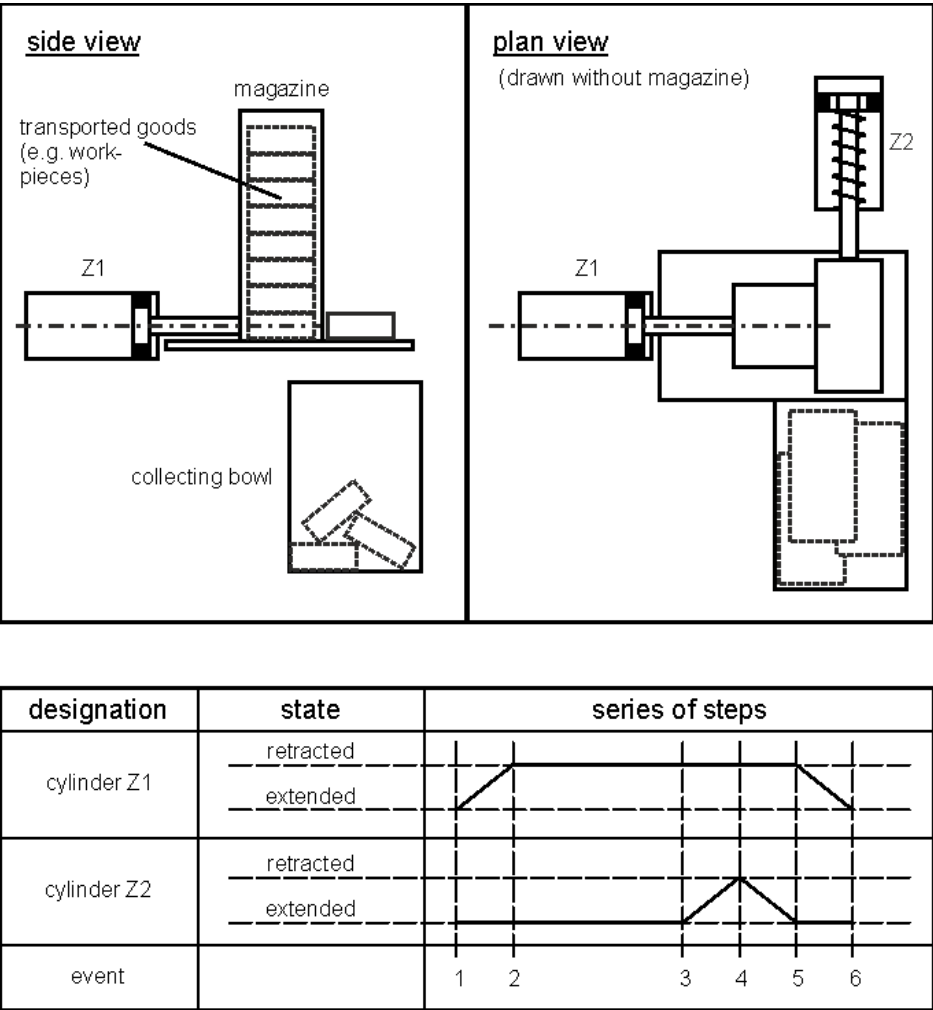
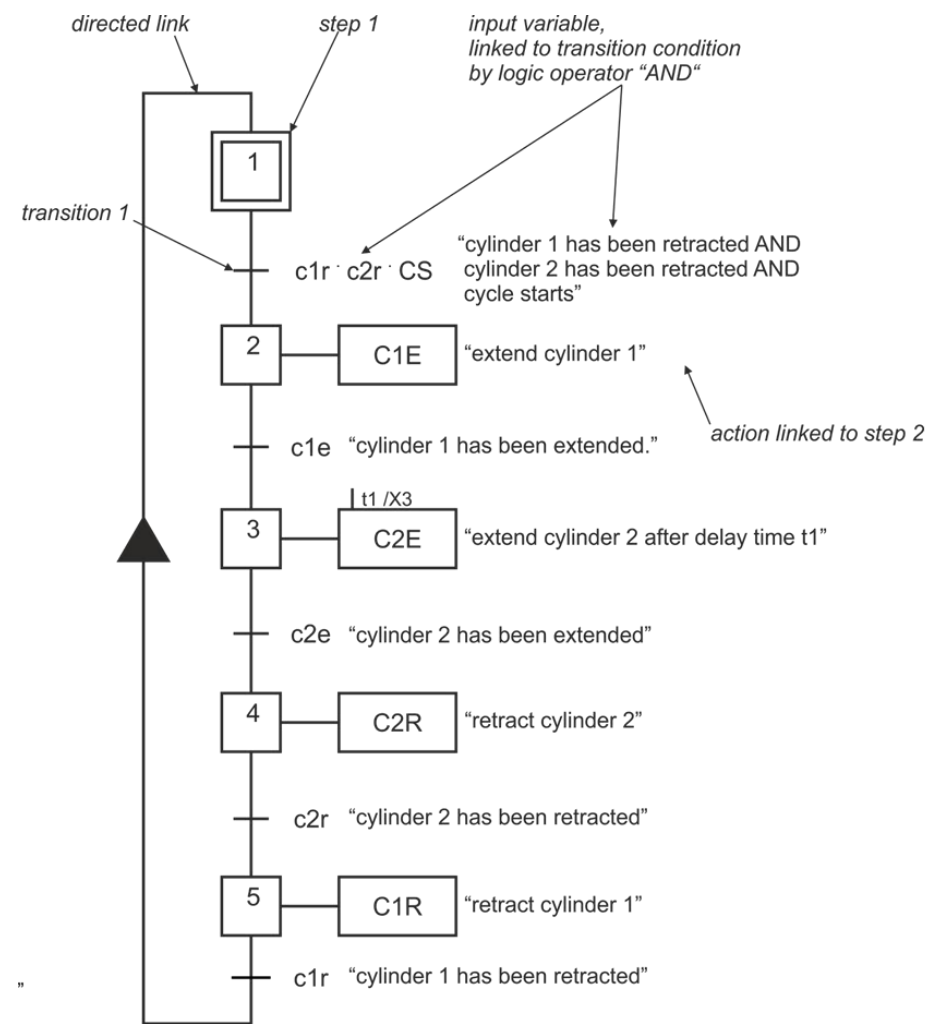


Fig. 4.1-1

# GRAFCET Function Chart



input	
CS	cylinder start
c1e	cylinder 1 is extended
c1r	cylinder 1 is retracted
c2e	cylinder 2 is extended
c2r	cylinder 2 is retracted
output	
C1E	extending cylinder 1
C1R	retracting cylinder 1
C2E	extending cylinder 2
C2R	retracting cylinder 2

Fig. 4.1-2

# Circuit Diagram of a Sequence Control

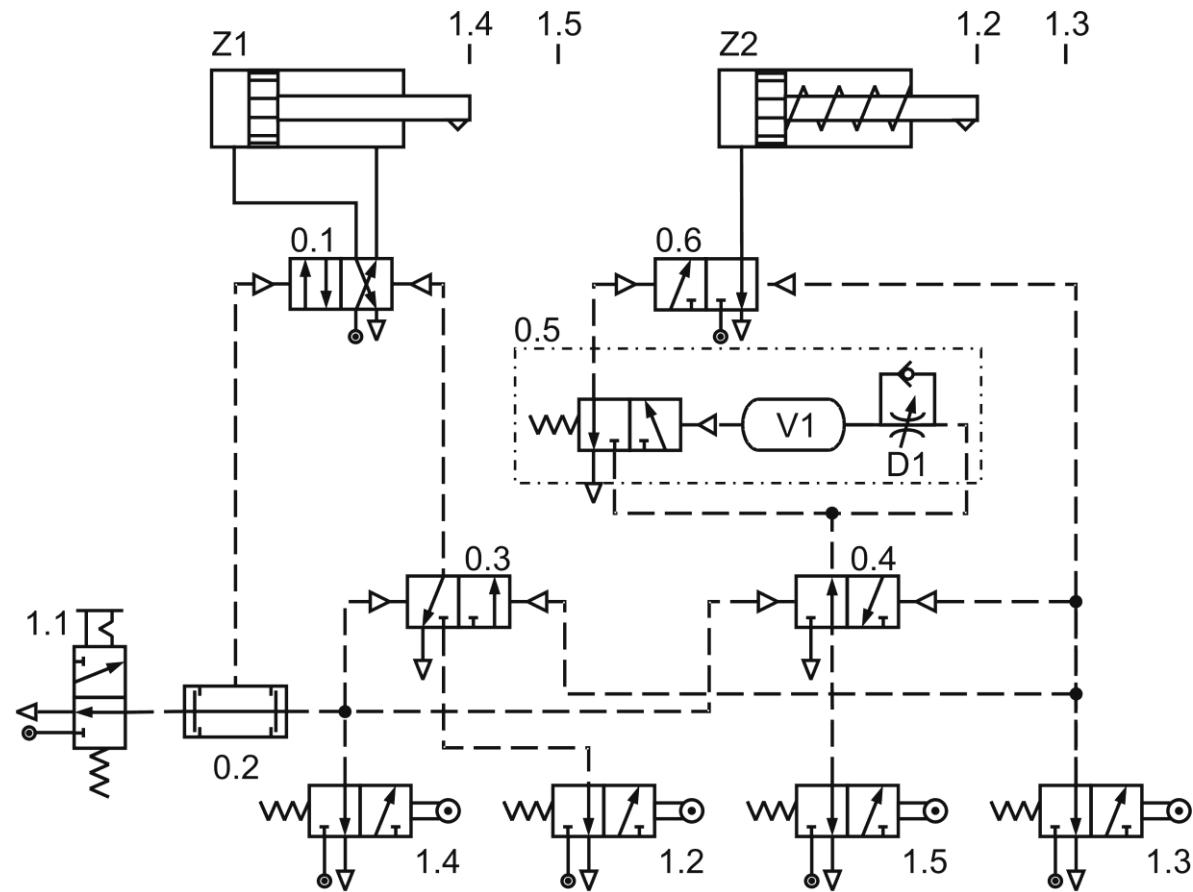
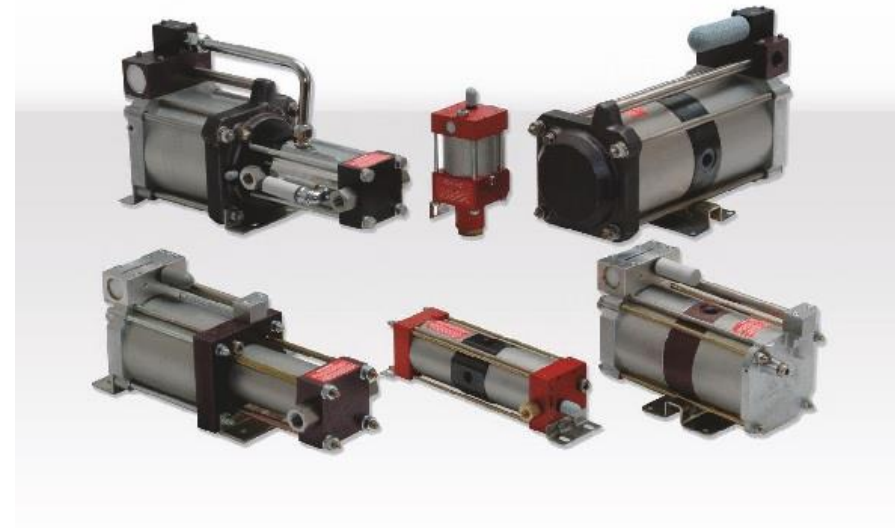
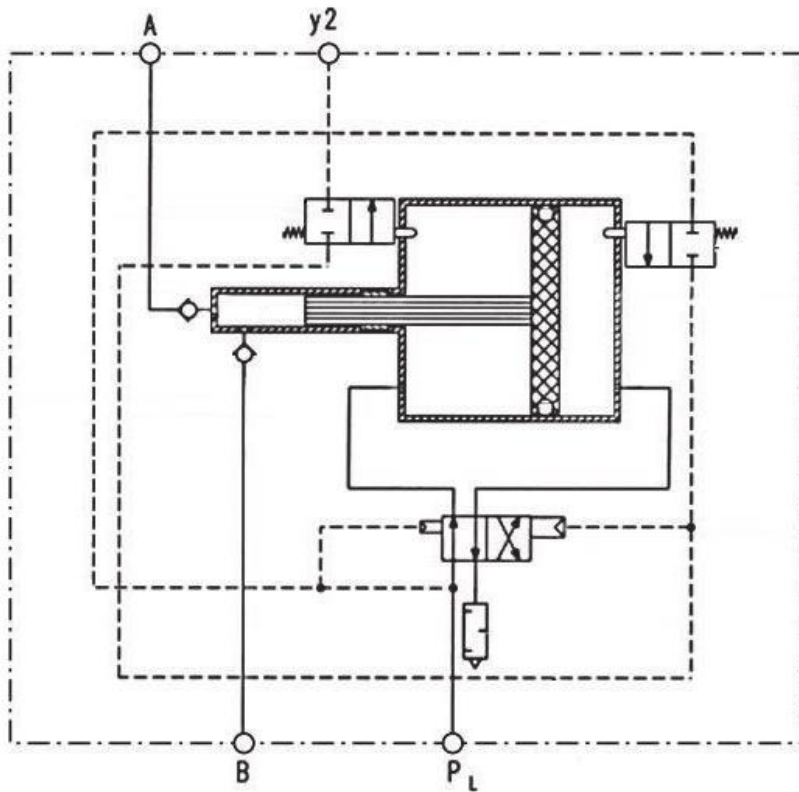


Fig. 4.1-3

# Sequence Control – Example Pressure Booster

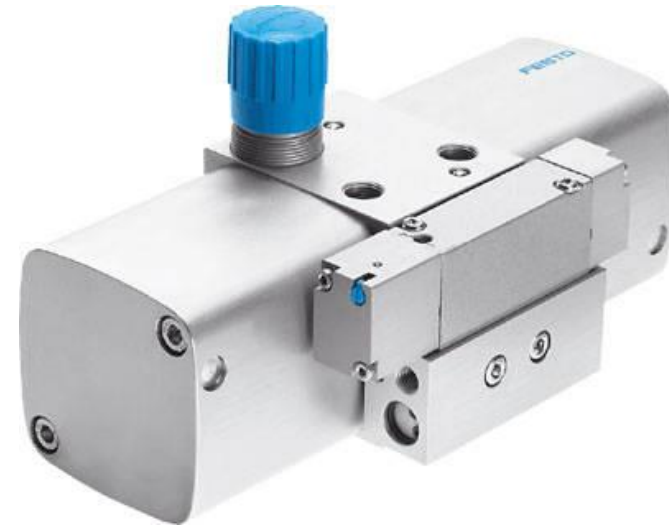
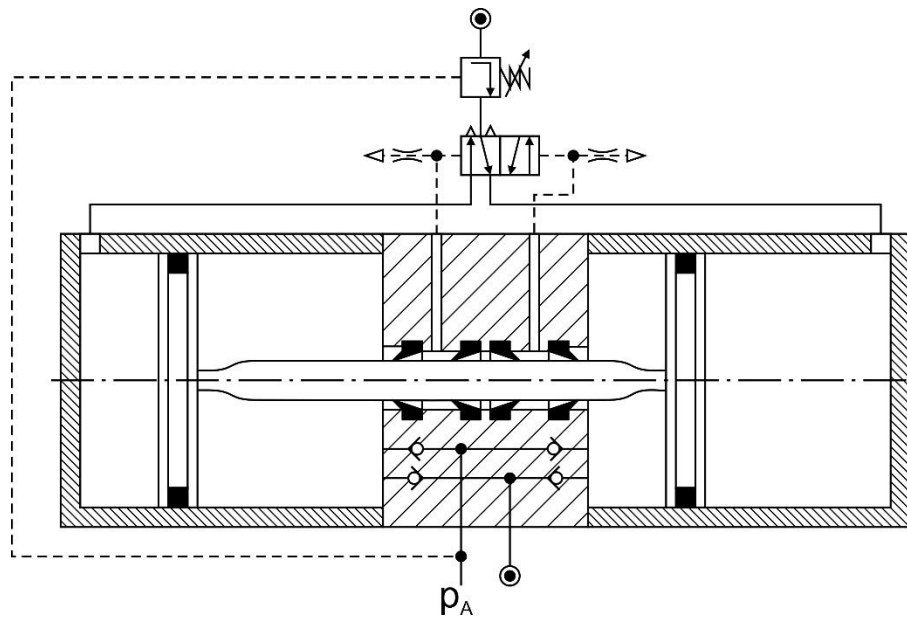
- Component for local pressure increase
  - Double acting self controlled pressure transformer (position controlled)
  - Multiplication of inlet pressure



Source: Maximator

# Sequence Control – Example Pressure Booster

- Component for local pressure increase
  - Double acting self controlled pressure transformer (position controlled)
  - Doubling of inlet Pressure
  - Integrated Control for outlet pressure (automatic start/stop)
  - Pilot „valves“ on piston rod

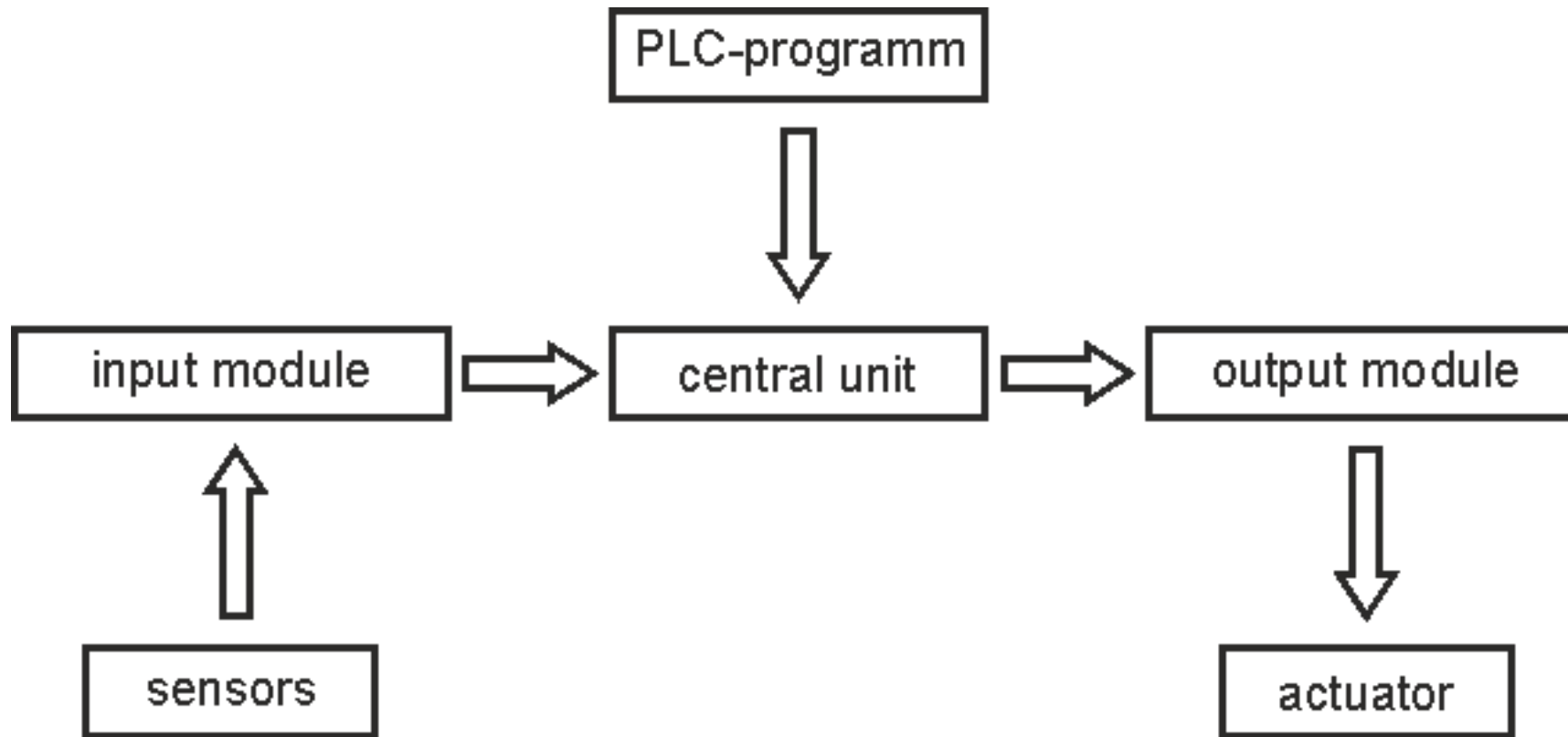


Source: Festo



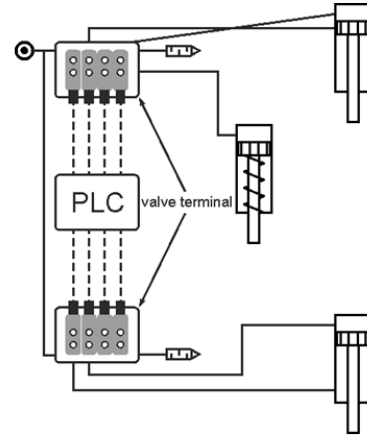
# Programmable Logical Control (PLC) and System Components

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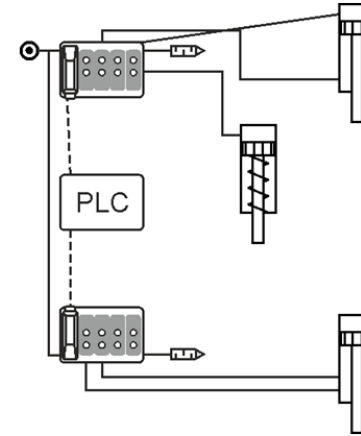


# PLC - Comparison of Different Types of Wirings and Connections

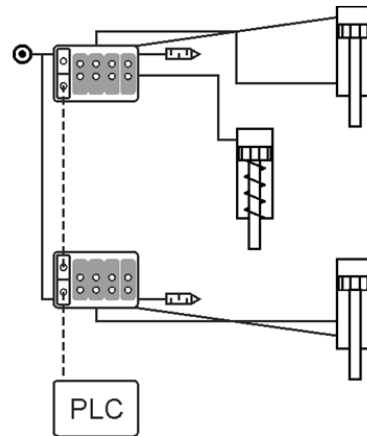
conventional  
wiring  
(parallel wiring)



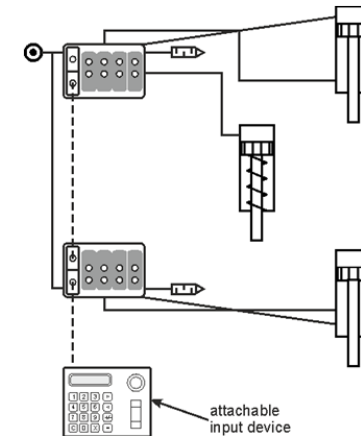
valve terminal with  
„Multipole“  
(parallel interface)



valve terminal with  
fieldbus (serial  
interface)



valve terminal with  
fieldbus connection  
and integrated PLC



# Position Sensor – Reed-Switch

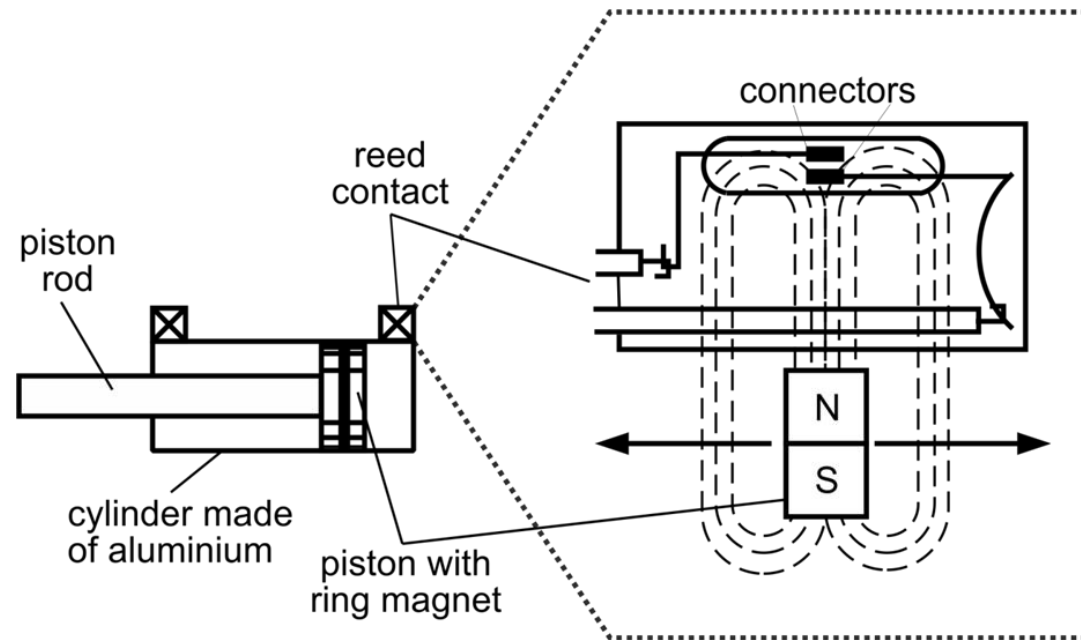


Fig. 4.1-12

Source: Norgren Herion

# Position Sensor - Hall-Switch

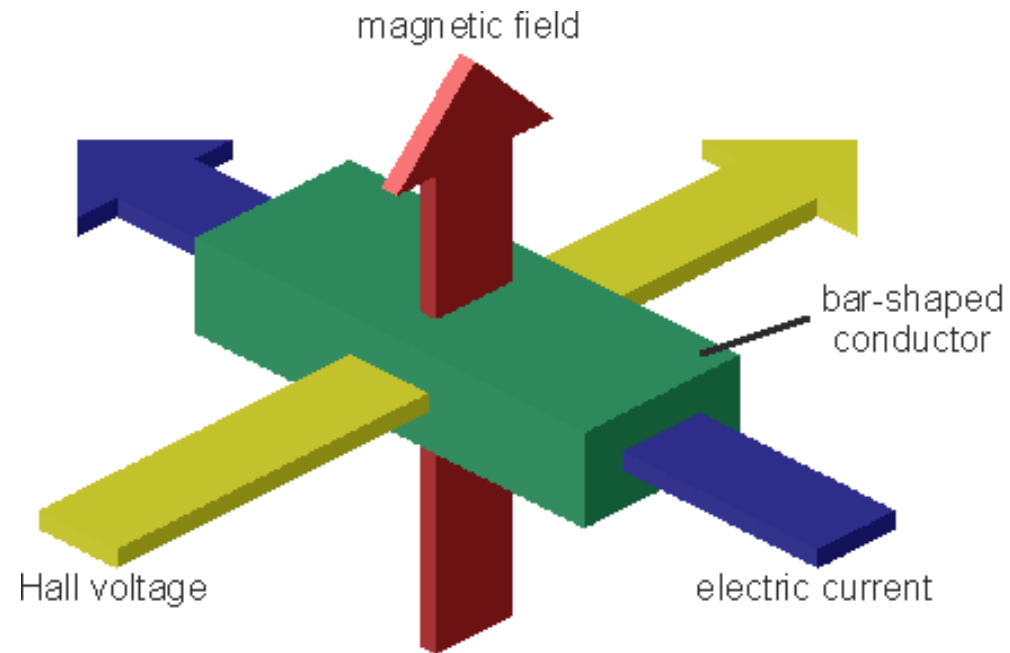


Fig. 4.1-13

Source: FESTO

# Position Sensor – Magneto-Resistive Switch

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- Anisotropic Magneto-Resistive Effect (AMR)
    - Anisotropic electrical Resistance of thin magnetically conducting layers (Direction of anisotropy controlled by magnetic flux direction)
  - Evaluation of a magneto resistive wheatstone bridge
  - Benefits:
    - No moving parts (Endurance)
    - Higher Sensitivity compared to Hall-Switches
- Standard solution for position switches on pneumatic cylinders



Source: FESTO

# Soft-Stop Positioning Drive

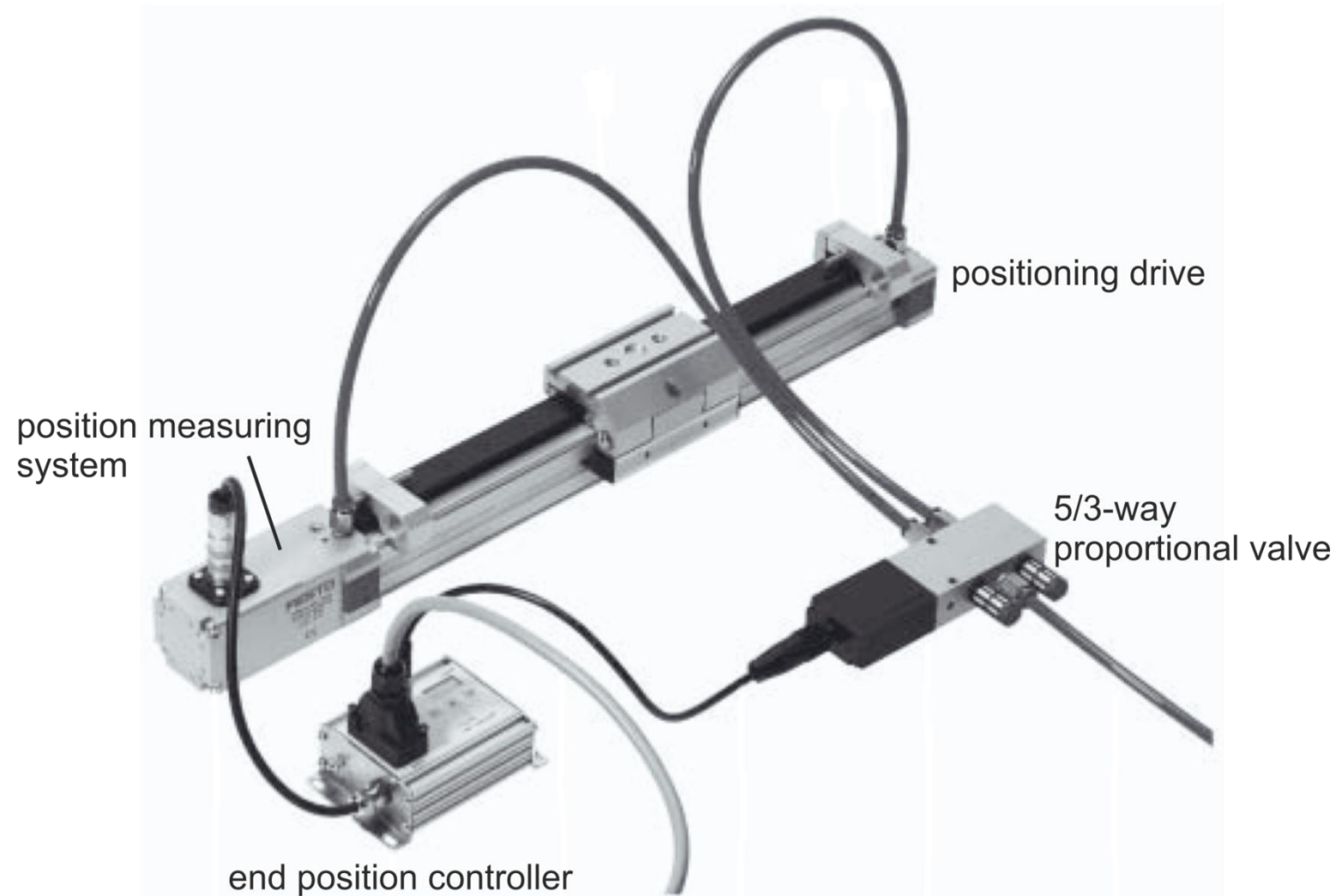


Fig. 4.2-7

Source: FESTO



# Outline

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- 1 Vacuum Technology
- 2 Systems and Circuits
- 3 Exergy**
- 4 Measures for Efficiency Optimization
- 5 Selected Applications

# Limitations of First Law of Thermodynamics

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## Complex Modelling of Heat Flows

- Mostly no reliable data available
- Consideration of simplified changes of state
  - Specification of pressure/volume-Correlation



## Small Significance of Inner Energy

- Energy is only temperature dependent
  - Neglecting the potential of compressed air to provide mechanical energy while cooling down during decompression.

# Definition of Exergy

## Definition – Exergy

The exergy  $e_x$  describes the quality of an energy in form of its maximum working capacity.

$$e_{ex} = e_a + (h_1 - h_U) - T_U \cdot (s_1 - s_U)$$

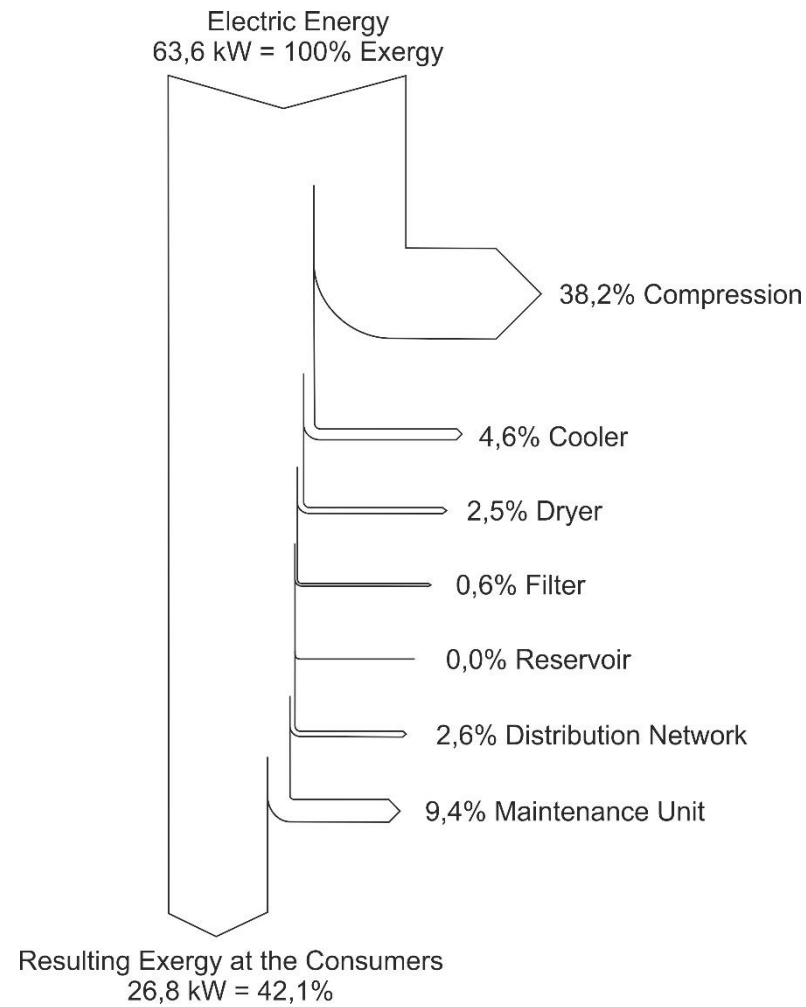
It can exclusively be defined in relation to an (ambient) condition. In contrast to the energy, exergy can be destroyed in real energy conversions.

## Exergy of Ideal Gases

$$e = e_a + c_p(T_1 - T_U) - T_U \cdot \left( R \cdot \ln\left(\frac{p_1}{p_U}\right) - c_p \cdot \ln\left(\frac{T_1}{T_U}\right) \right)$$

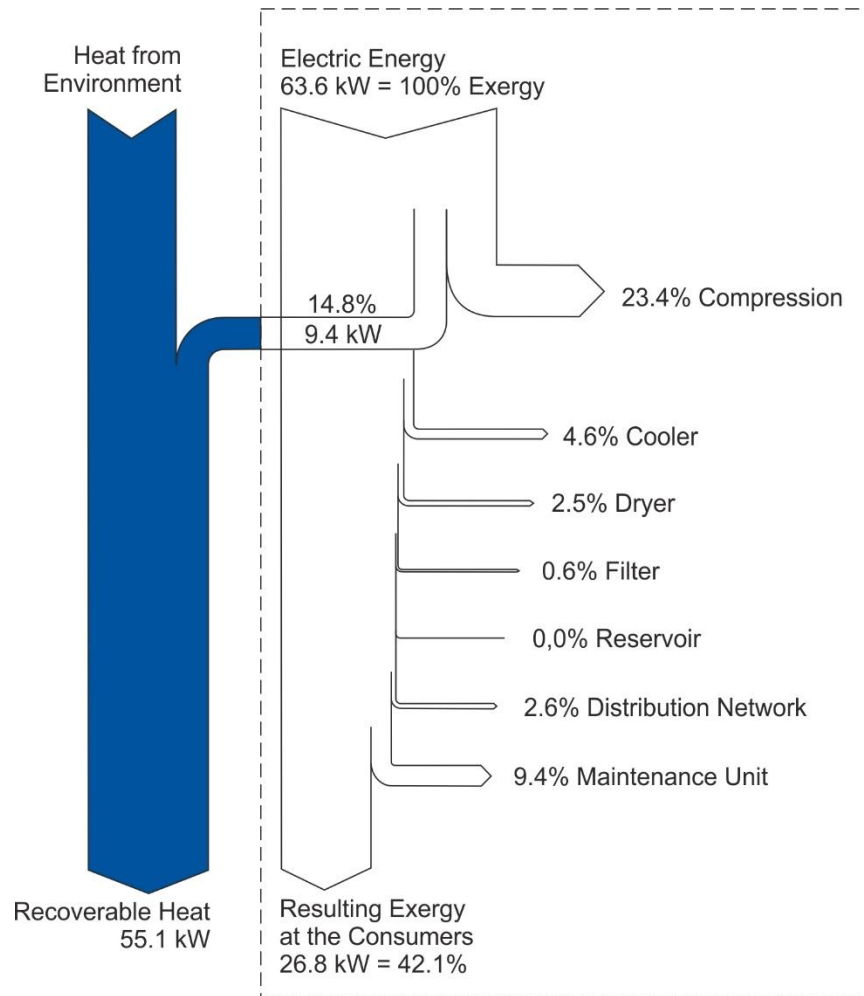
ATTENTION: In case that a heat flow occurs at a temperature unequal to ambient temperature, the heat flow contains exergy.

# Exergy Flow Diagramm



Data Source: Krichel, 2012

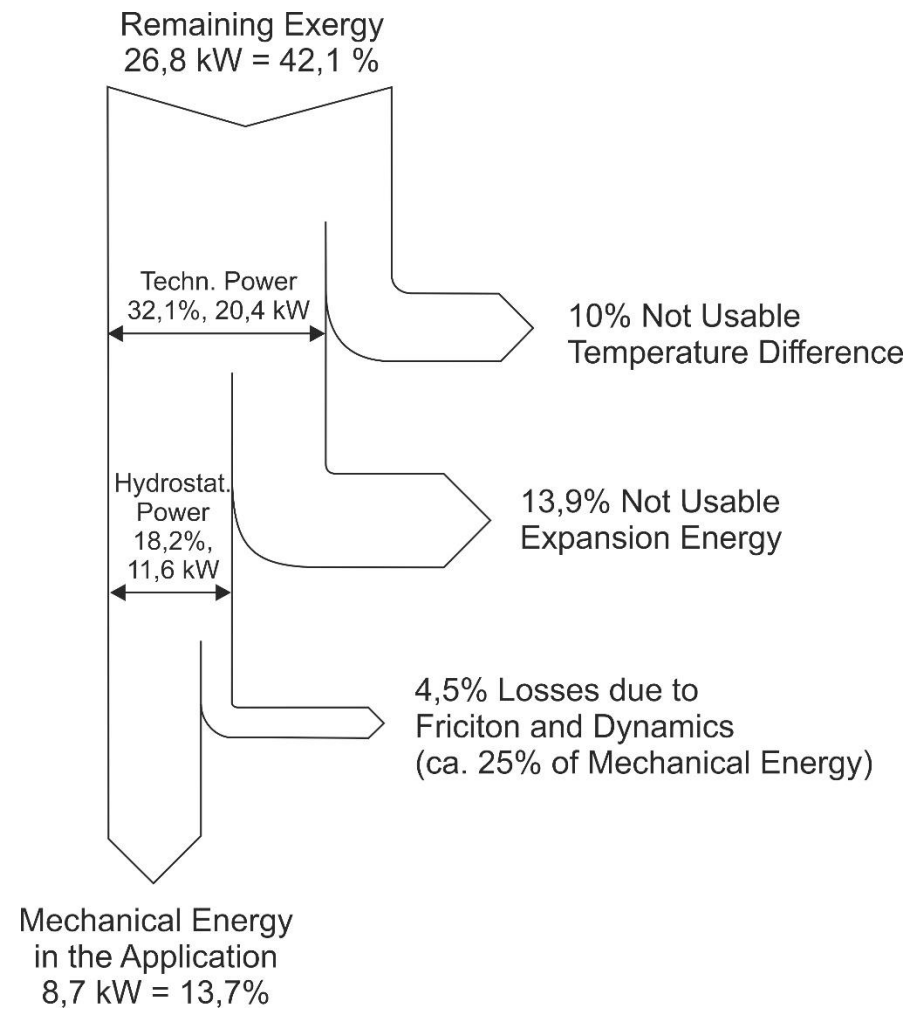
# Heat Recovery



- Large amount of recoverable heat due to heat pump effect
- High benefit of recoverable heat
  - For domestic warm water, heating, etc.
- Exergy of heat is comparatively low
  - Heat recovery at ca. 60 °C
  - Small difference to ambient temperature

Data Source: Krichel, 2012

# Exergy Usage of Cylinder Drives



Data Source: Krichel, 2012



# Outline

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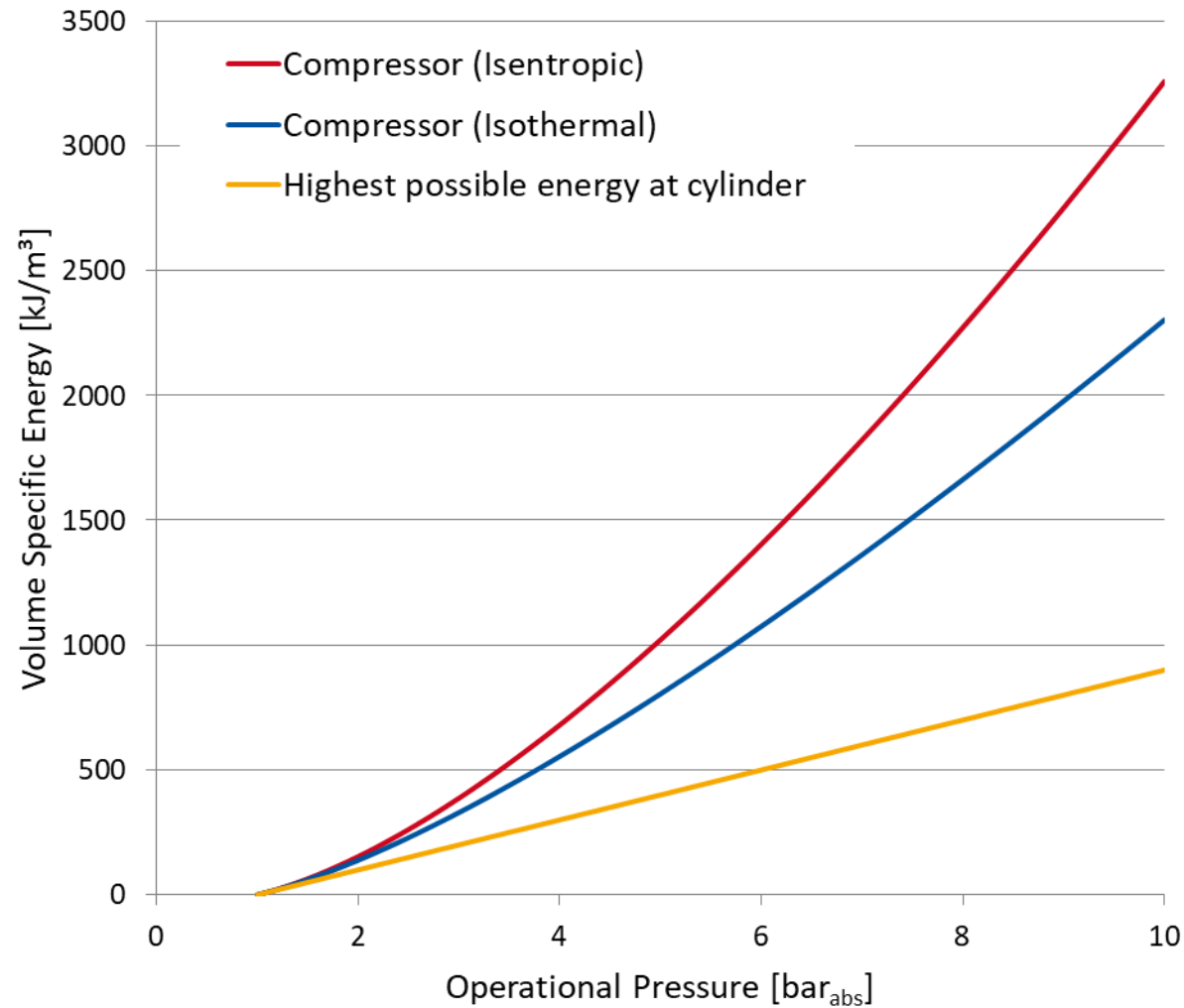
- 1 Vacuum Technology
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# Measures for Efficiency Improvements

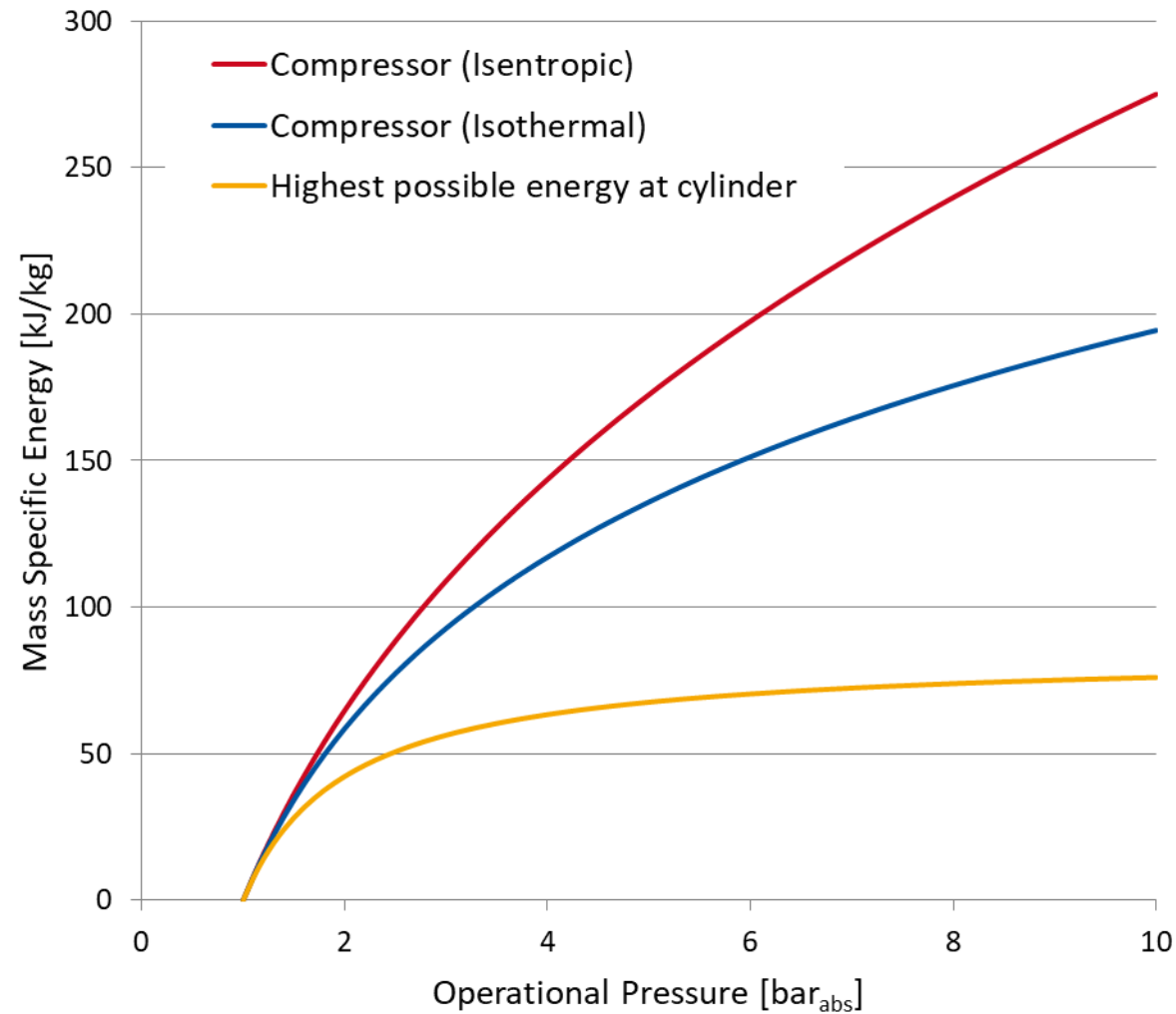
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- Heat recovery at compressors
  - Up to 95% of the input power can be recovered
  - Usually at ca. 60-70 °C → Heating, domestic warm water, process heat?
- Dimensioning
  - Air consumption of cylinders is proportional to cylinder volume (and dead volume!)
  - Reduction of dead volumes in hoses etc.
- Pressure Adjustment
  - Reduction of the pressure of the entire compressed air network

# Specific Energy for Compression and at Hydrostatic Usage (Cylinders)



# Specific Energy for Compression and at Hydrostatic Usage (Cylinders)

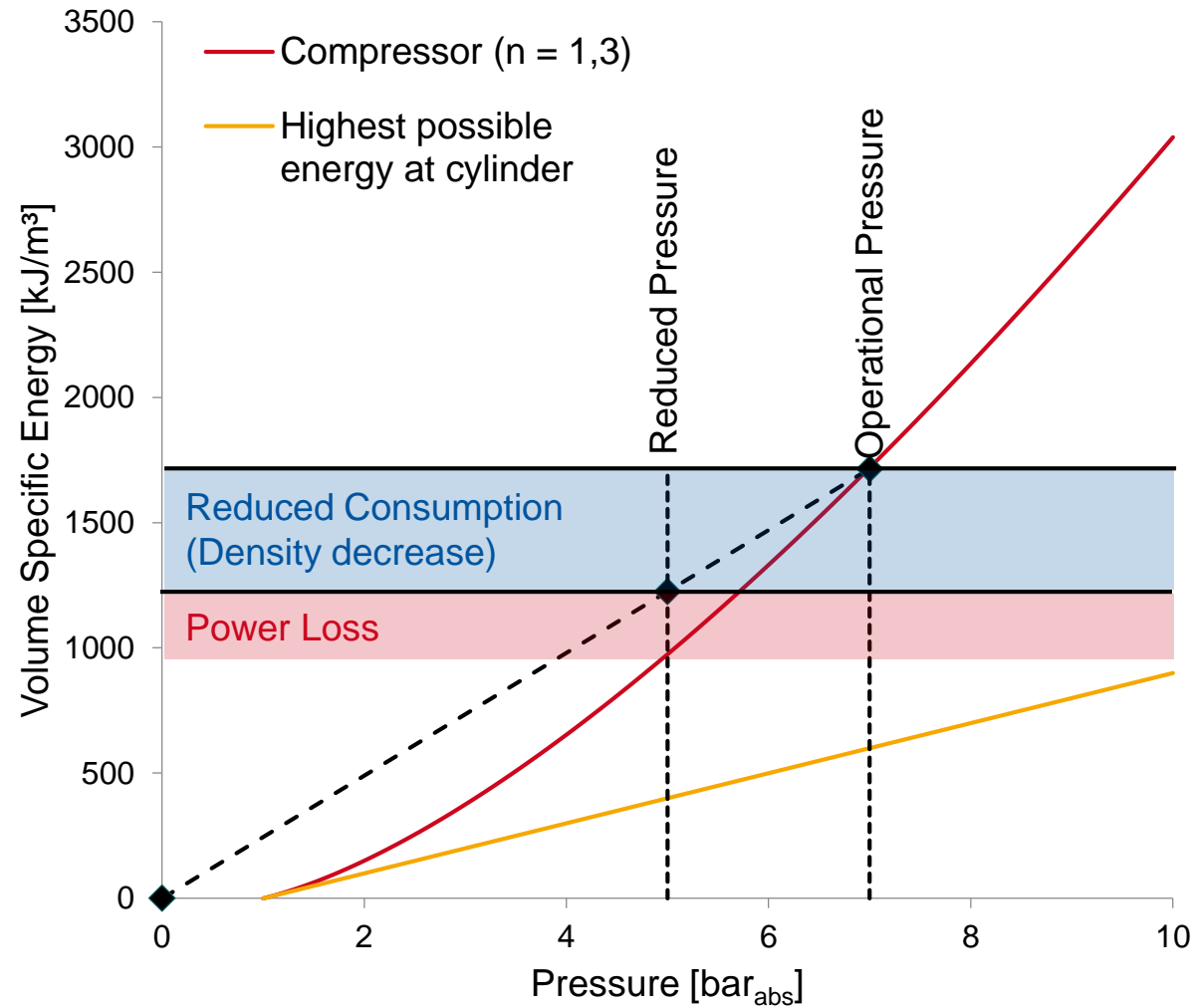


# Measures for Efficiency Improvements

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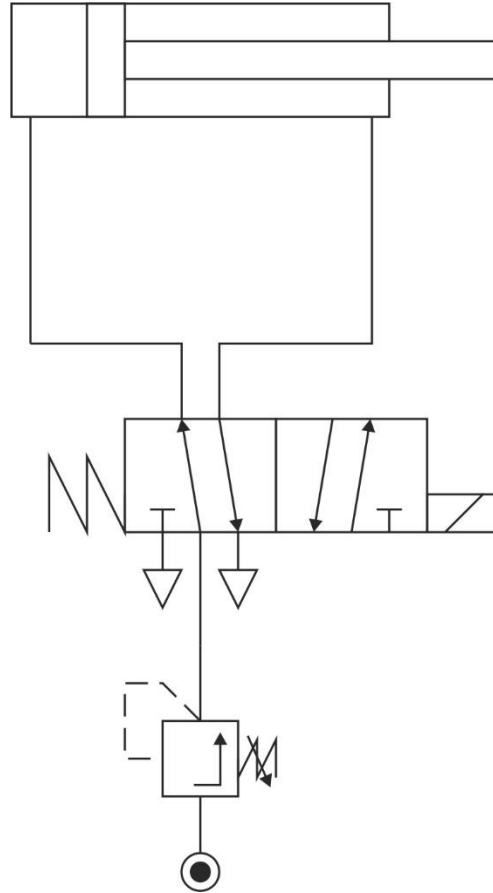
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  - Reduction of dead volumes in hoses etc.
- Pressure Adjustment
  - Reduction of the pressure of the entire compressed air network  
→ partially local pressure amplification required?
  - Pressure reducing valves for local pressure reduction of oversized drives  
(usually economically viable at differential pressures of only 0.5 bar)

# Effect of Local Pressure Reduction at Hydrostatic Usage (Cylinders)



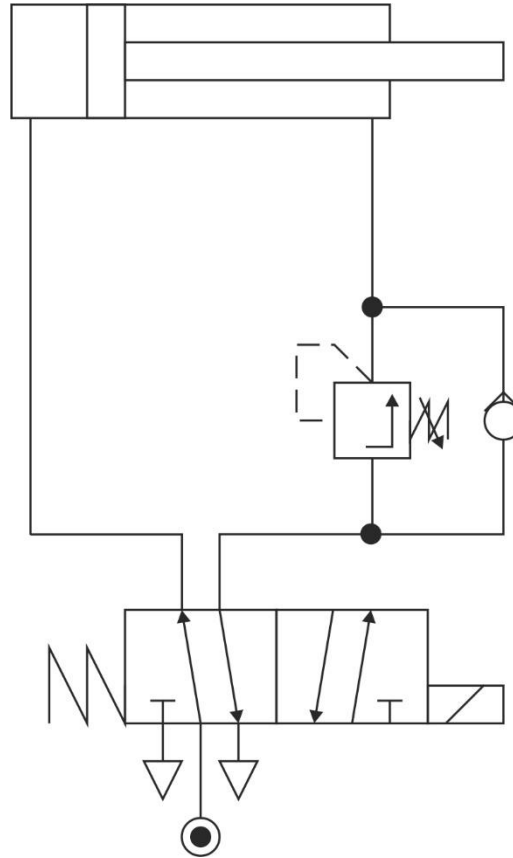
# Circuits for Local Pressure Reduction – Both Directions

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# Circuits for Local Pressure Reduction – Back Stroke

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# Measures for Efficiency Improvements

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- Maintenance
  - Leakage Reduction
    - Ultra sound sensors for leakage localization and mass flow sensors at main lines for leakage detection and trend observation
    - Shut-off valves for unused (parts of) machines
  - Regular filter replacements (especially suction filters of the compressors)

Energy efficiency-Module



Smart Pneumatics Analyser



Sources: Festo, Aventics

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# Parallel Gripper

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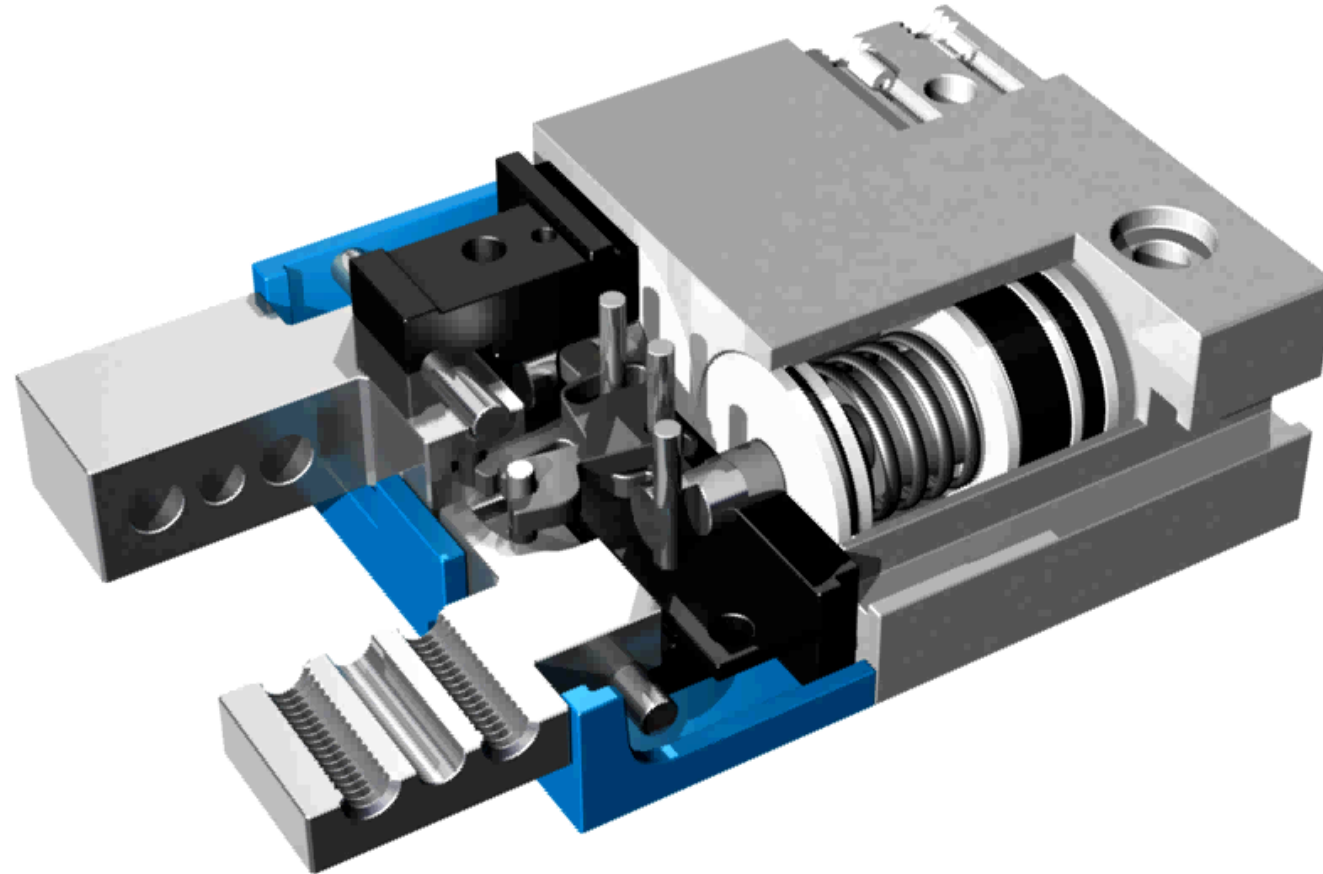


Source: Festo



# Parallel Gripper

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Source: Festo



# Servo-Pneumatic Parallel Gripper

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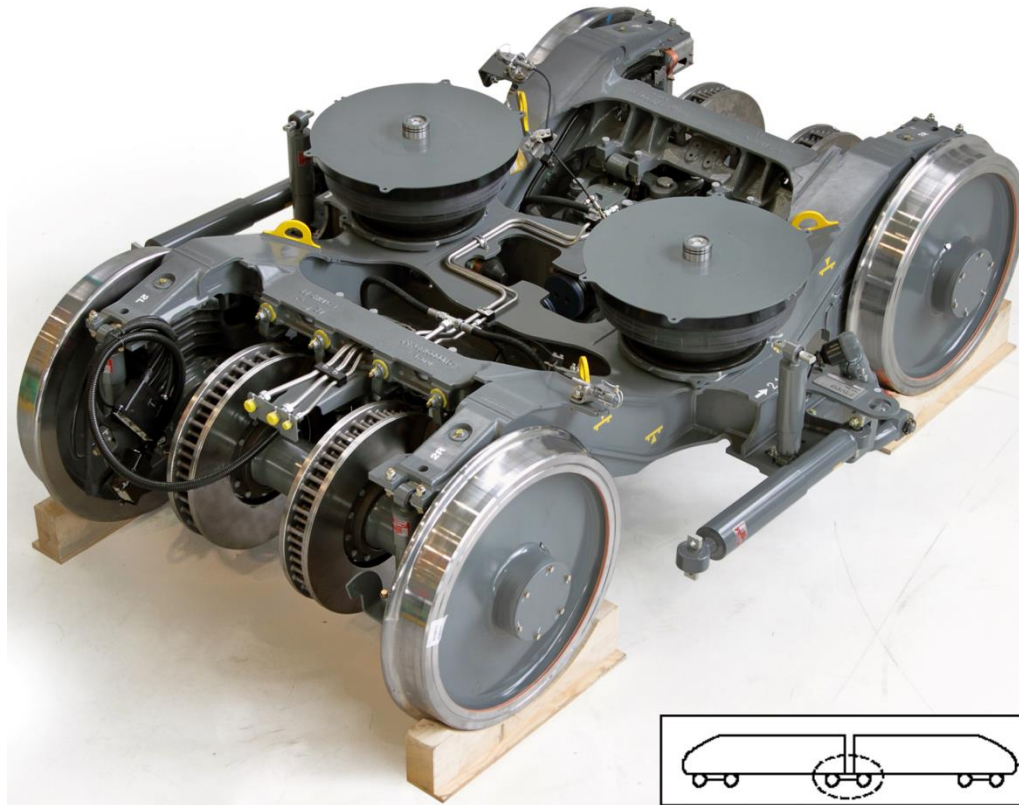
Source: Festo

RWTH AACHEN  
UNIVERSITY



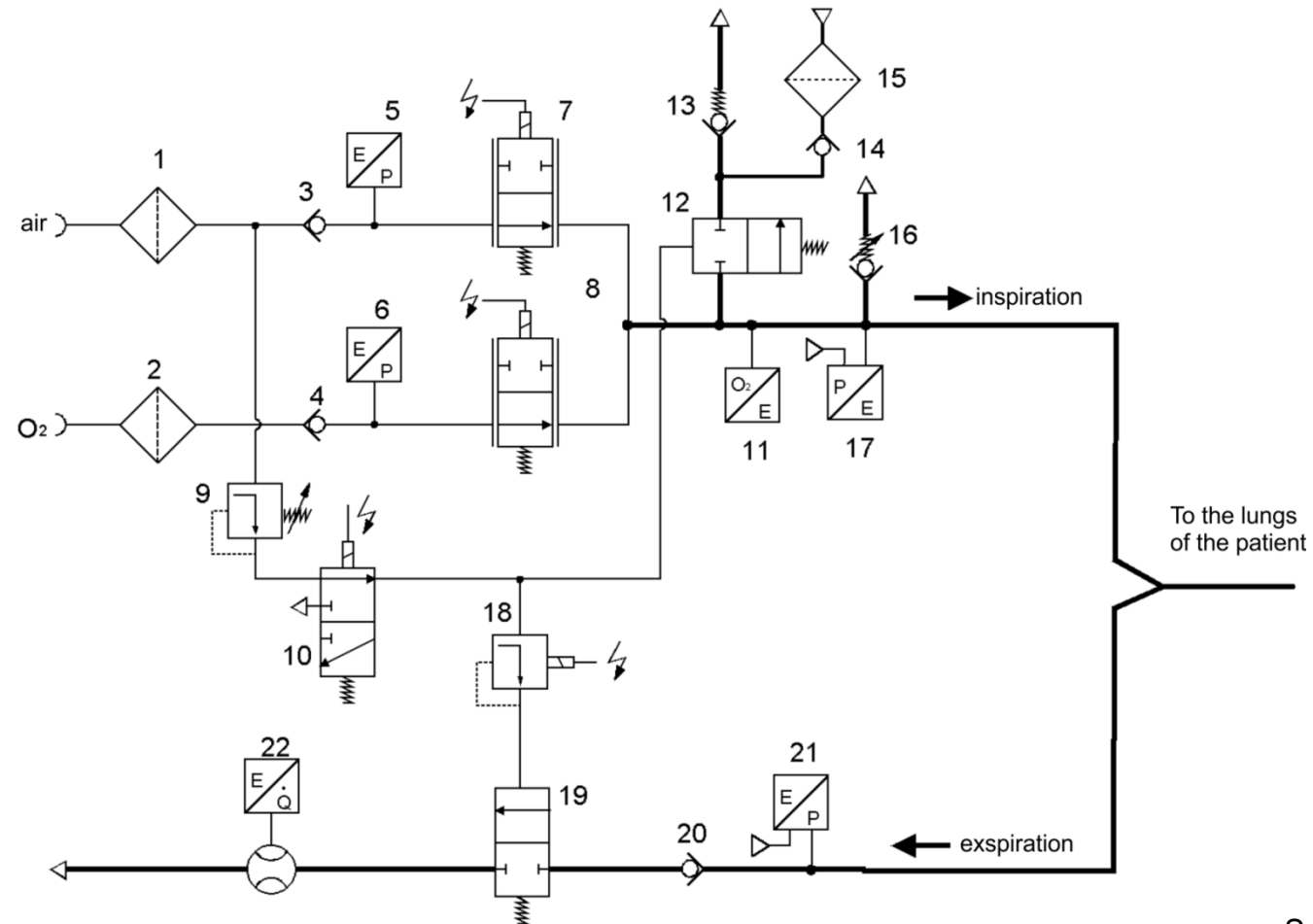
# Jacobs-Bogie of the Local Passenger Train „Desiro City“ with Pneumatic Brakes and Spring Bellows

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Source: Siemens Rail Systems  
©JB2011

## Simplified Pneumatic Diagram of an Artificial Respiration Device

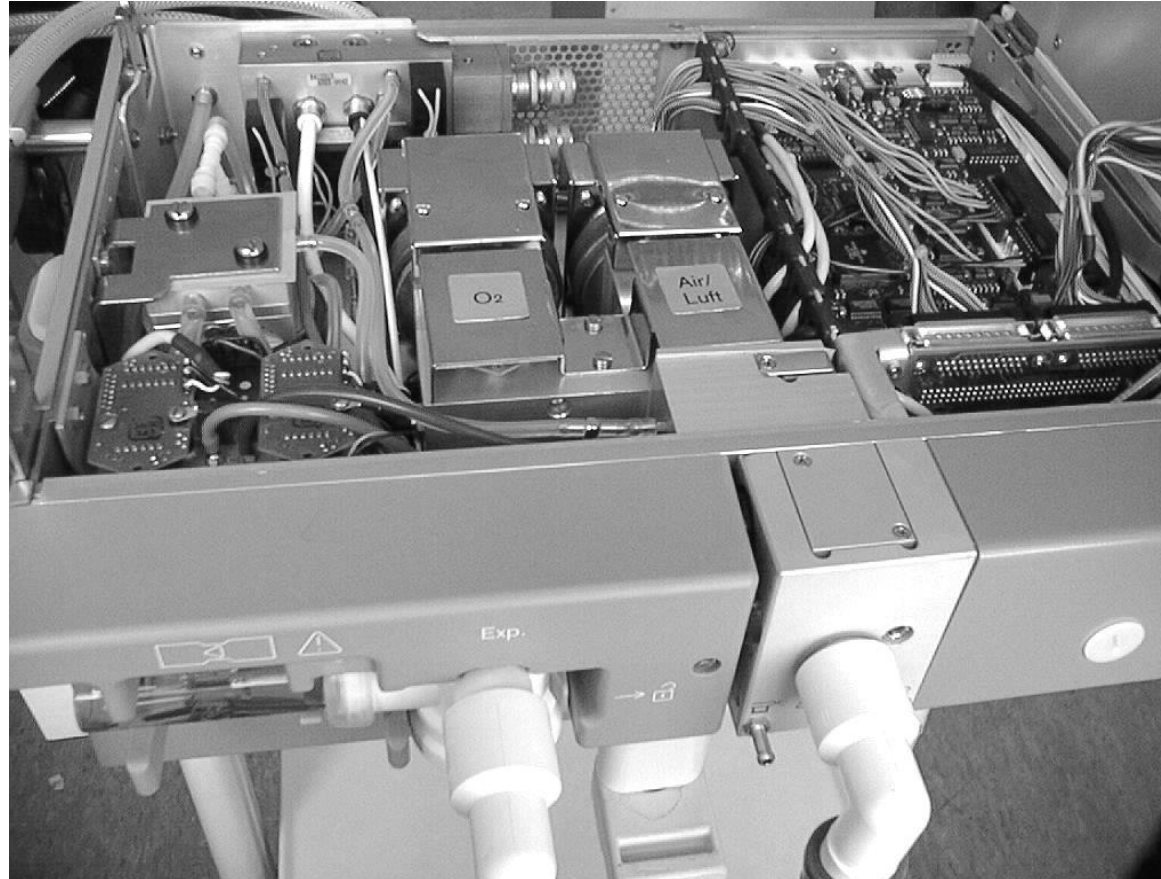


Source: Dräger  
Medizintechnik



## View into the Intensive Ventilation Device „Evita“

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Source: Dräger  
Medizintechnik

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# Thank you for your attention.

Dr.-Ing. Olivier Reinertz  
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