EE 542 Lecture 14: Message Passing Interface

Internet and Cloud Computing

Young Cho
Department of Electrical Engineering
University of Southern California

based on the MPI course developed by Rolf Rabenseifner at the High-Performance Computing-Center Stuttgart (HLRS), University of Stuttgart

Parallel Processing

- Parallel Hardware Accelerators
 - GPU (CUDA, OpenCL, TensorFlow, OpenAcc)
 - Tensor Processing Unit (TensorFlow)
 - FPGA (TensorFlow?!, OpenAcc?!, custom)
- Multicore Processors
 - GPP (OpenMP)
 - GPP+HW accelerators (OpenAcc)
- Multicomputers
 - NOW/Clusters (*MPI)
 - Cloud (Hadoop, Spark, MPI?!)

MPI (Message Passing Interface)?

- Messages
 - More than just the data
 - Generalized framework for parallel programming
 - Data types and other defined parameters
- Active Messages (On top of existing MPI)
 - Carry the actual code or calls to code also along with MPI contents
 - Can be of higher scalability
- Standardized message passing library spec. (IEEE)
 - for parallel computers, clusters and heterogeneous networks
 - o not a specific product, compiler specification etc.
 - many implementations, MPICH, LAM, OpenMPI, AM, and ...
- Real Parallel Programming
 - Portable with C/C++ (and Fortran, obsolete)
 - Support many common parallel functions
 - Difficult to develop and notoriously difficult to debug

History of MPI

- MPI-1 Forum
 - First message-passing interface standard.
 - Sixty people from forty different organizations.
 - Users and vendors represented, from US and Europe.
 - Two-year process of proposals, meetings and review.
 - Message-Passing Interface document produced.
 - MPI I.0 June, 1994.
 - MPI I.I June 12, 1995.
- MPI-2 Forum July 18, 1997

Goals and Scope of MPI

Goals

- To provide a parallel programing interface.
- To provide source-code portability.
- To allow efficient implementations.

Result

- A great deal of functionality for parallel programming
- Support for heterogeneous parallel architectures
- MPI-2: additional functions and backward compatible

Information about MPI

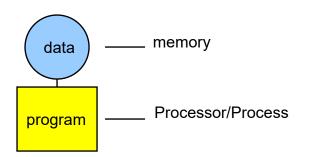
- MPI:A Message-Passing Interface Standard (1.1, June 12, 1995)
- MPI-2: Extensions to the Message-Passing Interface (July 18,1997)
- MPI:The Complete Reference, Marc Snir and William Gropp et al, The MIT Press, 1998 (2-volume set)
- Using MPI: Portable Parallel Programming With the Message-Passing Interface and Using MPI-2: Advanced Features of the Message-Passing Interface. William Gropp, Ewing Lusk and Rajeev Thakur, MIT Press, 1999 – also available in a single volume ISBN 026257134X.
- Parallel Programming with MPI, Peter S. Pacheco, Morgen Kaufmann Publishers, 1997 - very good introduction.
- **Parallel Programming with MPI**, Neil MacDonald, Elspeth Minty, Joel Malard, Tim Harding, Simon Brown, Mario Antonioletti. Training handbook from EPCC.

Example of Compilation

- Compilation in C
 - mpicc -o prog prog.c
- Compilation in C++:
 - mpiCC -o prpg prog.c
 - mpicxx -o prog prog.cpp
- Executing program with num processes
 - mprun –n num ./pra
 - mpiexec -n num ./prg

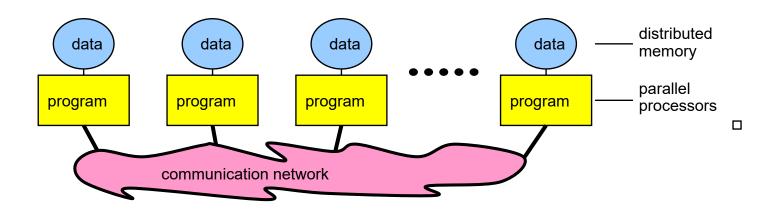
The Message-Passing Programming Paradigm

Sequential Programming Paradigm



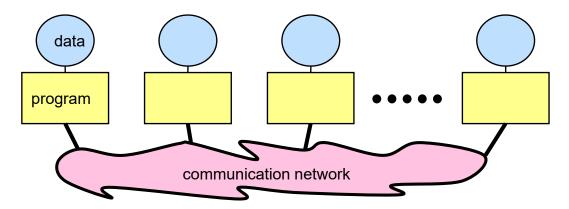
A processor may run many processes

Message Passing Programming Paradigm



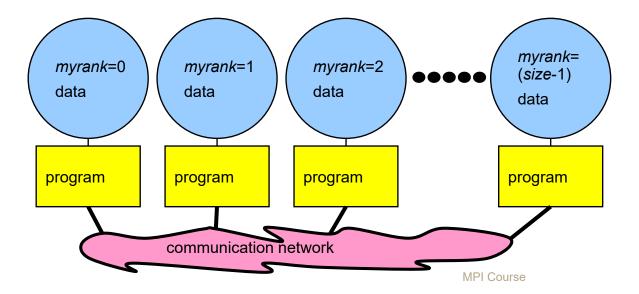
The Message-Passing Programming Paradigm

- A process is a program performing a task on a processor
- Each processor/process in a message passing program runs a instance/copy of a program:
 - written in a conventional sequential language, e.g., C or C++
 - typically a single program operating of multiple dataset
 - the variables of each sub-program have
 - the same name
 - but different locations (distributed memory) and different data!
 - i.e., all variables are local to a process
 - communicate via special send & receive routines (message passing)



Data and Work Distribution

- To communicate together mpi-processes need identifiers: rank = identifying number
- all distribution decisions are based on the rank
 - i.e., which process works on which data



MPI Programming Execution

- Same (sub-)program may run on each processor
 - Single Program, Multiple Data
 - Easier to develop and run
- MPI allows also MPMD
 - Multiple Program, Multiple Data
 - Easier to emulate MPMD with SPMD
 - Decision tree based on rank

Emulation of MPMD

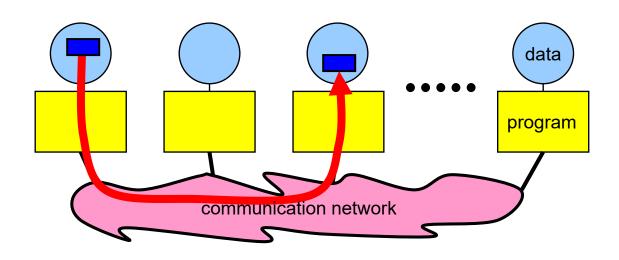
```
    main(int argc, char **argv){
        if (myrank < .... /* process should run the ocean model */){
            ocean( /* arguments */ );
        }else{
            weather( /* arguments */ );
        }
    }</li>
```

PROGRAM
 IF (myrank < ...) THEN !! process should run the ocean model CALL ocean (some arguments)</p>
 ELSE
 CALL weather (some arguments)
 ENDIF
 END

Message passing

- Messages are packets of moving between sub-programs
- Necessary information for the message passing system:
 - sending process
 - source location
 - source data type
 - source data size

- receiving process (i.e., the ranks)
- destination location
- destination data type
- destination buffer size





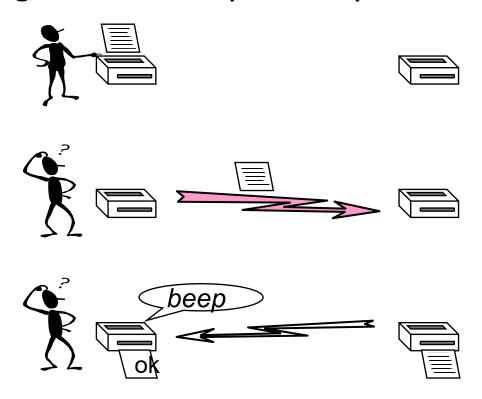
- Program must be linked with an MPI library
- Program must be started with the MPI startup
- A sub-program needs to be connected to a message passing system

Point-to-Point Communication

- Simplest form of message passing.
- One process sends a message to another.
- Different types of point-to-point communication:
 - synchronous send
 - buffered = asynchronous send

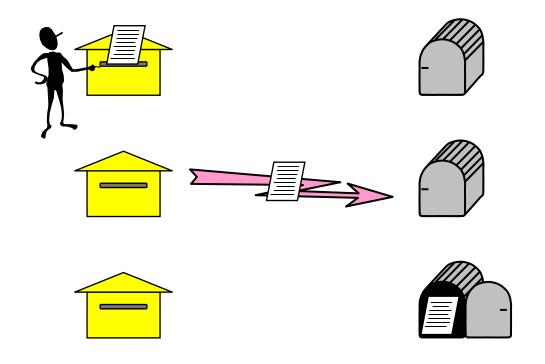
Synchronous Sends

- The sender gets an information that the message is received.
- Analogue to the beep or okay-sheet of a fax.



Buffered = Asynchronous Sends

Only know when the message has left.



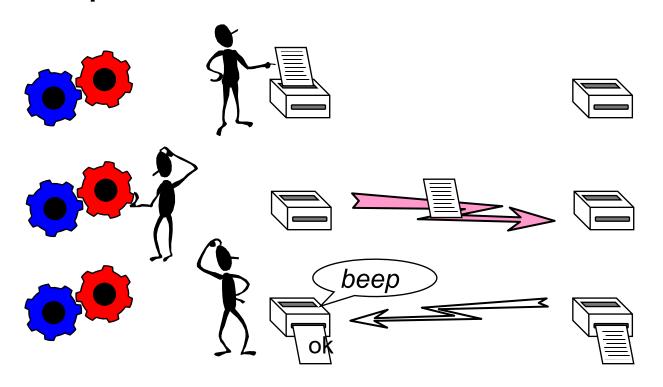


Blocking Operations

- Some sends/receives may block until another process acts:
 - synchronous send operation blocks until receive is issued;
 - receive operation blocks until message is sent.
- Blocking subroutine returns only when the operation has completed.

Non-Blocking Operations

 Non-blocking operations return immediately and allow the sub-program to perform other work.



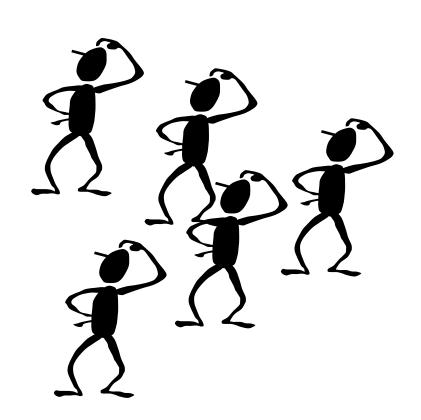
Collective Communications

- Collective communication routines are higher level routines.
- Several processes are involved at a time.
- May allow optimized internal implementations, e.g., tree based algorithms

Broadcast

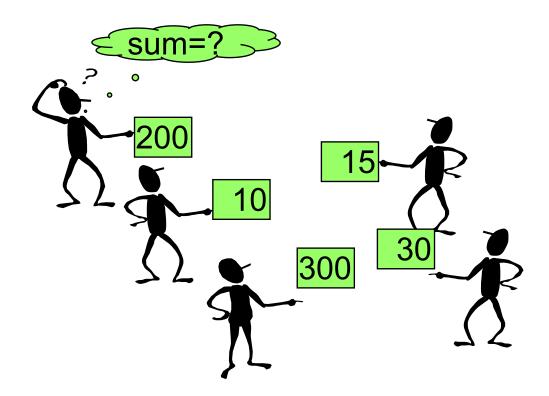
A one-to-many communication.





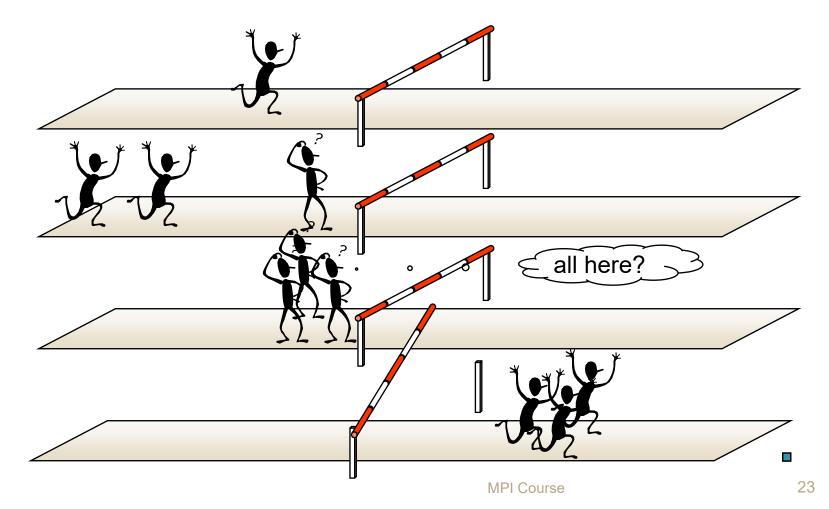
Reduction Operations

 Combine data from several processes to produce a single result.



Barriers

• Synchronize processes.



MPI Function Format

- Include file for C
 - #include <mpi.h>
- Interface in C might look like
 - error = MPI_Xxxxxx(parameter, ...);
 - MPI_..... namespace is reserved for MPI constants and routines
 - i.e. application routines and variable names must NOT begin with MPI_.
- Example arguments in C
 - Definition standard

```
MPI_Comm_rank( ...., int *rank)
MPI_Recv(..., MPI_Status *status)
```

Usage

```
main...
{ int myrank;
   MPI_Status rcv_status;
   MPI_Comm_rank(..., &myrank);
   MPI_Recv(..., &rcv_status); }
```

MPI Programming and Running

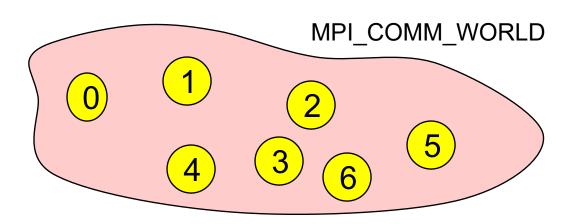
C: int MPI_Init(int *argc, char ***argv)

```
#include <mpi.h>
int main(int argc, char **argv)
{
    MPI_Init(&argc, &argv);
    ....
```

- MPI_Init must be the first MPI routine that is called
- The parallel MPI processes exist at least after MPI_Init
- Start mechanism is implementation dependent
 - Most implementations provide mpirun:
 mpirun –np number_of_processes ./executable
 mprun –n number_of_processes ./executable
 - MPI-2 standard defines mpiexec:
 mpiexec –n number_of_processes ./executable



- All processes of an MPI program are members of the default communicator MPI_COMM_WORLD.
- MPI_COMM_WORLD is a predefined handle in mpi.h and mpif.h.
- Each process has its own rank in a communicator:
 - starting with 0
 - ending with (size-I)

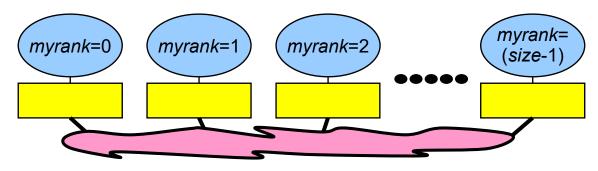


Handles

- Handles identify MPI objects.
- For the programmer, handles are
 - predefined constants in mpi.h or mpif.h
 - example: MPI_COMM_WORLD
 - predefined values exist only after MPI_Init was called
 - values returned by some MPI routines,
 to be stored in variables, that are defined as
 - in C: special MPI typedefs
- Handles refer to internal MPI data structures

Rank and Size

- The rank identifies different processes within a communicator
- The rank is the basis for any work and data distribution.
 - C: int MPI_Comm_rank(MPI_Comm comm, int *rank)
- How many processes are contained within a communicator?
 - C: int MPI_Comm_size(MPI_Comm comm, int *size)



CALL MPI_COMM_RANK(MPI_COMM_WORLD, myrank, ierror)



- C: int MPI_Finalize()
- Must be called last by all processes.
- After MPI_Finalize:
 - Further MPI-calls are forbidden
 - Especially re-initialization with MPI_Init is forbidden

Hello World

- Example hello world by each MPI process.
 - You can compile and run it on a single processor.
 - You can run it on several processors in parallel.
 - Every process knows its rank and the size of MPI_COMM_WORLD,
 - Only process ranked 0 in MPI_COMM_WORLD prints "hello world".

```
I am 2 of 4
Hello world
I am 0 of 4
I am 3 of 4
I am 1 of 4
```

• The sequence of the output non-deterministic?

MPI Data Types

MPI Datatype	C datatype	
MPI_CHAR	signed char	
MPI_SHORT	signed short int	
MPI_INT	signed int	
MPI_LONG	signed long int	
MPI_UNSIGNED_CHAR	unsigned char	
MPI_UNSIGNED_SHORT	unsigned short int	
MPI_UNSIGNED	unsigned int	
MPI_UNSIGNED_LONG	unsigned long int	
MPI_FLOAT	float	
MPI_DOUBLE	double	
MPI_LONG_DOUBLE	long double	
MPI_BYTE		
MPI_PACKED		

MPI Datatype	Fortran datatype	
MPI_INTEGER	INTEGER	
MPI_REAL	REAL	
MPI_DOUBLE_PRECISION	DOUBLE PRECISION	
MPI_COMPLEX	COMPLEX	
MPI_ LOGICAL	LOGICAL	
MPI_CHARACTER	CHARACTER(1)	
MPI_BYTE		
MPI_PACKED		

2345	654	96574	-12	7676
			<u> </u>	

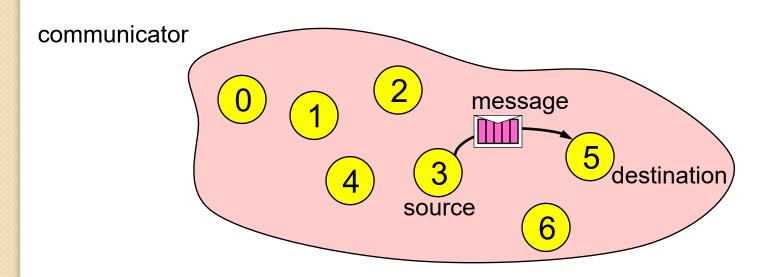
count=5 INTEGER arr(5) datatype=MPI_INTEGER

MPI Derived Data Types

```
static const int blocklen[] = {1, 1, 1, 1};
static const MPI_Aint disp[] = {
    offsetof(struct B, a) + offsetof(struct A, f),
    offsetof(struct B, a) + offsetof(struct A, p),
    offsetof(struct B, pp),
    offsetof(struct B, vp)
};
static MPI_Datatype type[] = {MPI_INT, MPI_SHORT, MPI_INT,
    MPI_INT};
MPI_Datatype newtype;
MPI_Type_create_struct(sizeof(type) / sizeof(*type), blocklen,
    disp, type, &newtype);
MPI_Type commit(&newtype);
```

Point-to-Point Communication

- Communication between two processes.
- Source process sends message to destination process.
- Communication takes place within a communicator, e.g., MPI_COMM_WORLD.
- Processes are identified by their ranks in the communicator.



Sending a Message

- C: int MPI_Send(void *buf, int count, MPI_Datatype datatype, int dest, int tag, MPI_Comm comm)
- <u>buf</u> is the starting point of the message with <u>count</u> elements, each described with <u>datatype</u>.
- <u>dest</u> is the rank of the destination process within the communicator <u>comm</u>.
- tag is an additional nonnegative integer piggyback information, additionally transferred with the message.
- The tag can be used by the program to distinguish different types of messages.

Receiving a Message

- C: int MPI_Recv(void *buf, int count, MPI_Datatype datatype, int source, int tag, MPI_Comm comm, MPI_Status *status)
- buf/count/datatype describe the receive buffer.
- Receiving the message sent by process with rank source in comm.
- Envelope information is returned in <u>status</u>.
- Output arguments are printed blue-cursive.
- Only messages with matching tag are received.

Point-to-Point Communications

- Sender must specify a valid destination rank.
- Receiver must specify a valid source rank.
- The communicator must be the same.
- Tags must match.
- Message datatypes must match.
- Receiver's buffer must be large enough.

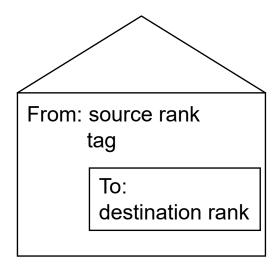
Wildcards

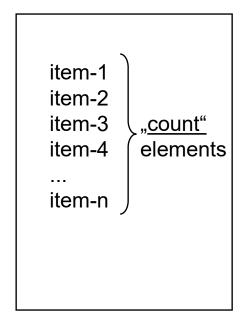
- Receiver can wildcard.
- To receive from any source <u>source</u>= MPI_ANY_SOURCE
- To receive from any tag tag = MPI_ANY_TAG
- Actual source and tag are returned in the receiver's <u>status</u> parameter.

Communication Envelope

 Envelope information is returned from MPI_RECV in status.

 C: status.MPI_SOURCE status.MPI_TAG <u>count</u> via MPI_Get_count()





Communication Modes

- Send communication modes:
 - ∘ synchronous send → MPI SSEND
- - buffered [asynchronous] send MPI **B**SEND
 - standard send

→ MPI SEND

Ready send

- → MPI RSEND
- Receiving all modes → MPI RECV

Communication Modes — Definitions

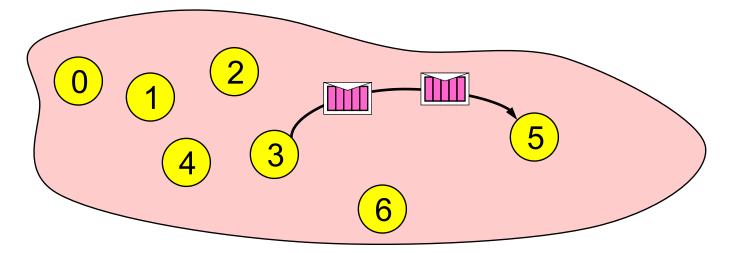
Sender modes	Definition	Notes
Synchronous send MPI_SSEND	Only completes when the receive has started	
Buffered send MPI_BSEND	Always completes (unless an error occurs), irrespective of receiver	needs application-defined buffer to be declared with MPI_BUFFER_ATTACH
Synchronous MPI_SEND	Standard send. Either uses an internal buffer or buffered	
Ready send MPI_RSEND	May be started only if the matching receive is already posted!	highly dangerous!
Receive MPI_RECV	Completes when a the message (data) has arrived	

Rules for the communication modes

- Standard send (MPI_SEND)
 - minimal transfer time
 - may block due to synchronous mode
 - —> risks with synchronous send
- Synchronous send (MPI_SSEND)
 - risk of deadlock
 - risk of serialization
 - risk of waiting —> idle time
 - high latency / best bandwidth
- Buffered send (MPI_BSEND)
 - low latency / bad bandwidth
- Ready send (MPI_RSEND)
 - use **never**, except you have a 200% guarantee that Recv is already called in the current version and all future versions of your code

Message Order Preservation

- Rule for messages on the same connection,
 i.e., same communicator, source, and destination rank:
- Messages do not overtake each other.
- This is true even for non-synchronous sends.



If both receives match both messages, then the order is preserved.

Ping pong

```
rank=0

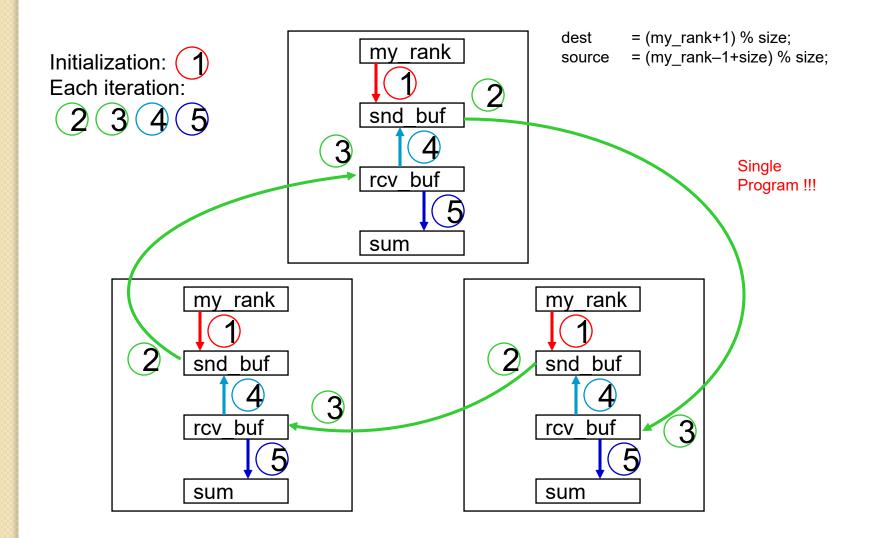
Send (dest=1)

(tag=17)

Recv (source=0)

Send (dest=0)

Recv (source=1)
```



Collective Communication

- Communications involving a group of processes.
- Must be called by all processes in a communicator.
- Examples:
 - Barrier synchronization.
 - Broadcast, scatter, gather.
 - Global sum, global maximum, etc.



- Optimised Communication routines involving a group of processes
- Collective action over a communicator, i.e. all processes must call the collective routine.
- Synchronization may or may not occur.
- All collective operations are blocking.
- No tags.
- Receive buffers must have exactly the same size as send buffers.

Barrier Synchronization

C: int MPI_Barrier(MPI_Comm comm)

• Fortran: *IERROR*)

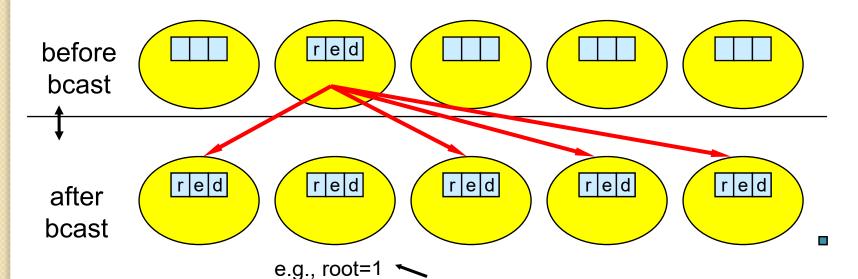
MPI BARRIER(COMM,

INTEGER COMM, IERROR

- MPI_Barrier is normally never needed:
 - all synchronization is done automatically by the data communication:
 - a process cannot continue before it has the data that it needs.
 - if used for debugging:
 - please guarantee, that it is removed in production.

Broadcast

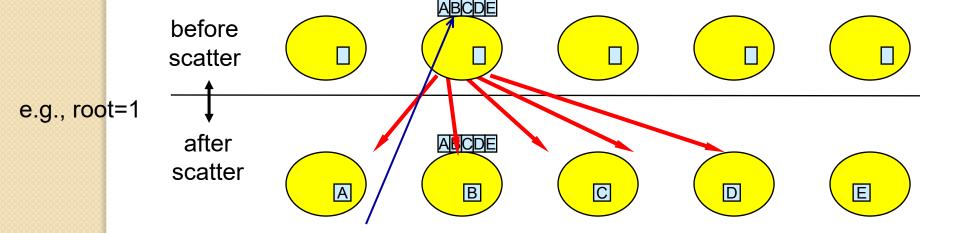
C: int MPI_Bcast(void *buf, int count, MPI_Datatype datatype, int root, MPI_Comm comm)



- rank of the sending process (i.e., root process)
 - must be given identically by all processes

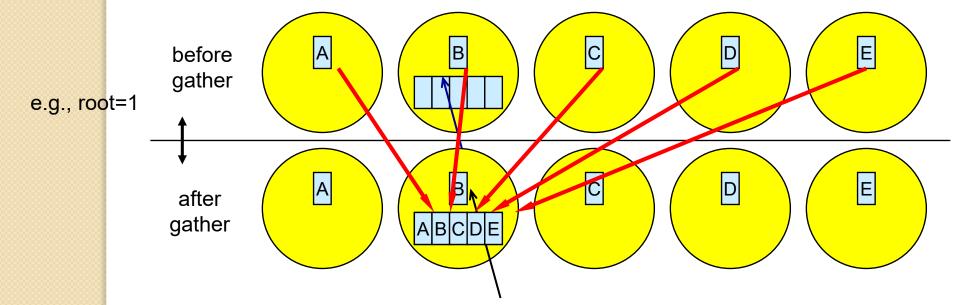
Scatter

C: int MPI_Scatter(void *sendbuf, int sendcount, MPI_Datatype sendtype, void *recvbuf, int recvcount, MPI_Datatype recvtype, int root, MPI_Comm comm)



Gather

C: int MPI_Gather(void *sendbuf, int sendcount, MPI_Datatype sendtype, void *recvbuf, int recvcount, MPI_Datatype recvtype, int root, MPI_Comm comm)



Global Reduction Operations

- To perform a global reduce operation across all members of a group.
- d₀ o d₁ o d₂ o d₃ o ... o d_{s-2} o d_{s-1}
 - d_i = data in process rank i
 - · single variable, or
 - vector
 - o = associative operation
 - Example:
 - global sum or product
 - global maximum or minimum
 - global user-defined operation
- floating point rounding may depend on usage of associative law:
 - \circ [(d₀ o d₁) o (d₂ o d₃)] o [... o (d_{s-2} o d_{s-1})]
 - $\circ ((((((d_0 \circ d_1) \circ d_2) \circ d_3) \circ \dots) \circ d_{s-2}) \circ d_{s-1})$

Example of Global Reduction

- Global integer sum.
- Sum of all inbuf values should be returned in resultbuf.
- C: root=0;
 MPI_Reduce(&inbuf, &resultbuf, I, MPI_INT,
 MPI_SUM,root, MPI_COMM_WORLD);
- Fortran: root=0

 MPI_REDUCE(inbuf, resultbuf, I, MPI_INTEGER,

 MPI_SUM, root, MPI_COMM_WORLD, IERROR)
- The result is only placed in resultbuf at the root process.

Predefined Reduction Operation Handles

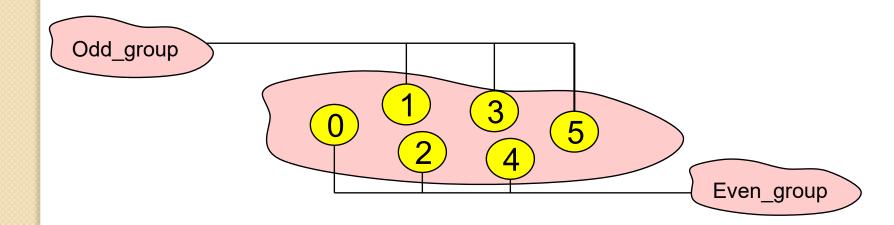
Predefined operation handle	Function	
MPI_MAX	Maximum	
MPI_MIN	Minimum	
MPI_SUM	Sum	
MPI_PROD	Product	
MPI_LAND	Logical AND	
MPI_BAND	Bitwise AND	
MPI_LOR	Logical OR	
MPI_BOR	Bitwise OR	
MPI_LXOR	Logical exclusive OR	
MPI_BXOR	Bitwise exclusive OR	
MPI_MAXLOC	Maximum and location of the maximum	
MPI_MINLOC	Minimum and location of the minimum	

User-Defined Reduction Operations

- Operator handles
 - predefined see table above
 - user-defined
- User-defined operation ■:
 - associative
 - user-defined function must perform the operation vector_A vector_B
 - syntax of the user-defined function → MPI-I standard
- Registering a user-defined reduction function:
 - C: MPI_Op_create(MPI_User_function *func, int commute, MPI Op *op)
- COMMUTE tells the MPI library whether FUNC is commutative.

Working with groups

- Select processes ranks to create groups
- Associate to these groups new communicators
- Use these new communicators as usual
- MPI_Comm_group(comm, group) returns in group the group associated to the communicator comm



Virtual Topologies

- Convenient process naming.
- Simplifies writing of code.
- Can allow MPI to optimize communications.