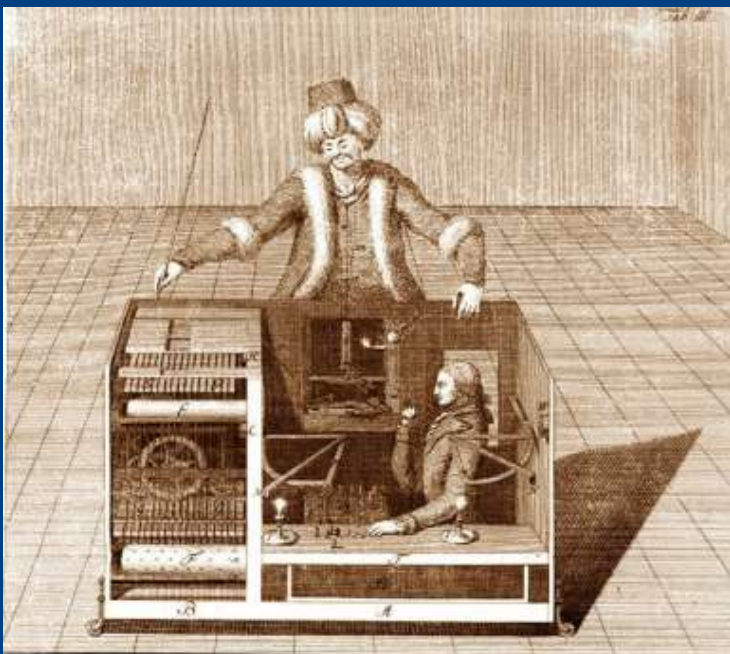


Make your own neural network



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The content of the book

- **some powerful and efficient math.**
- **enough Python.**
- **improve the neural network and have fun.**



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How they work



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Take inspiration from all the small things around you.



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Algorithm → give an impression of a human

Human:



Computer:

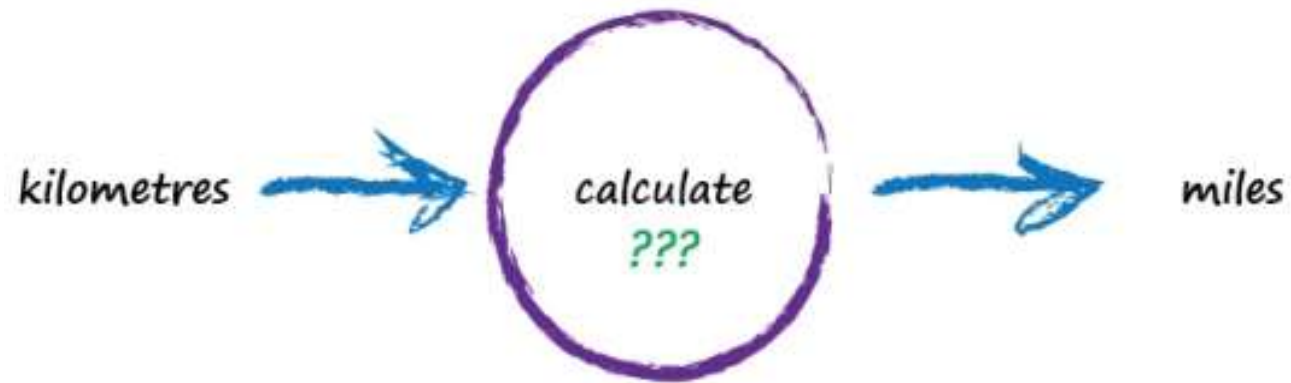
A Simple Predicting Machine





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Ramp up complexity just a tiny notch

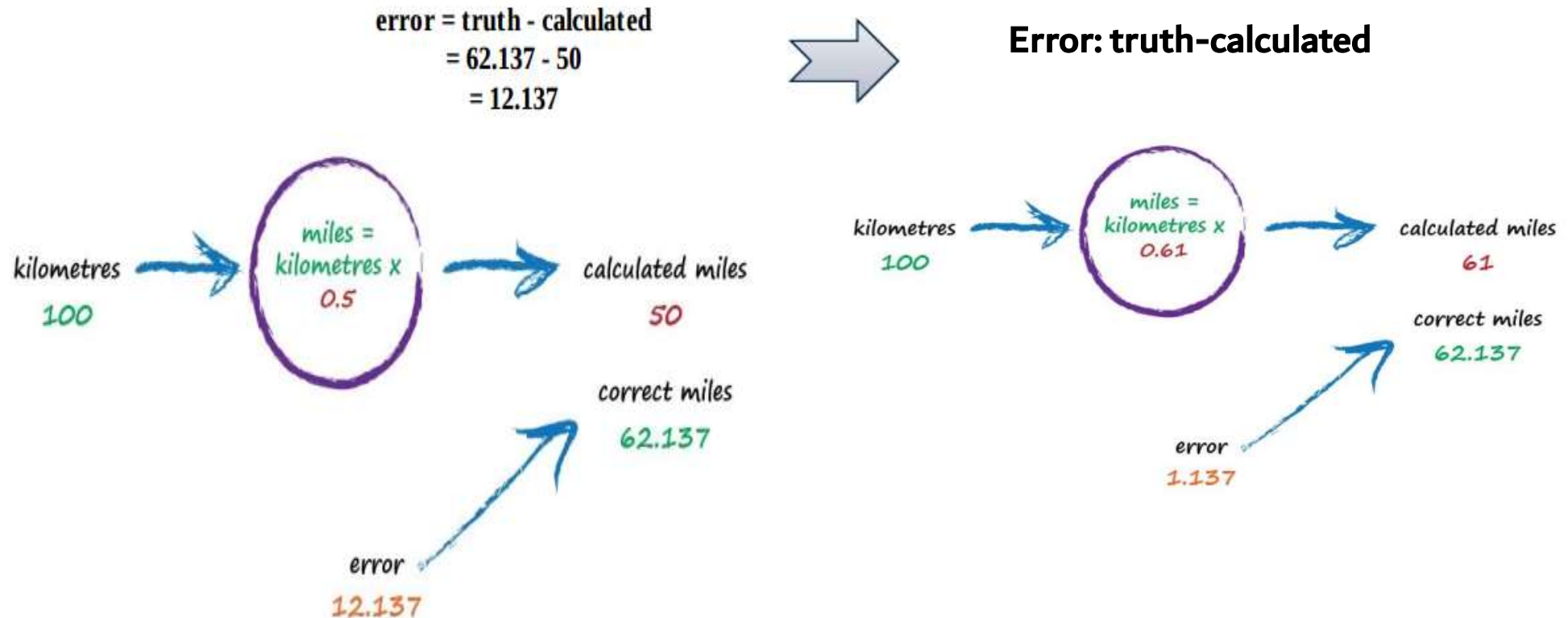


Linear model: input doubles, output doubles.

Try and test it



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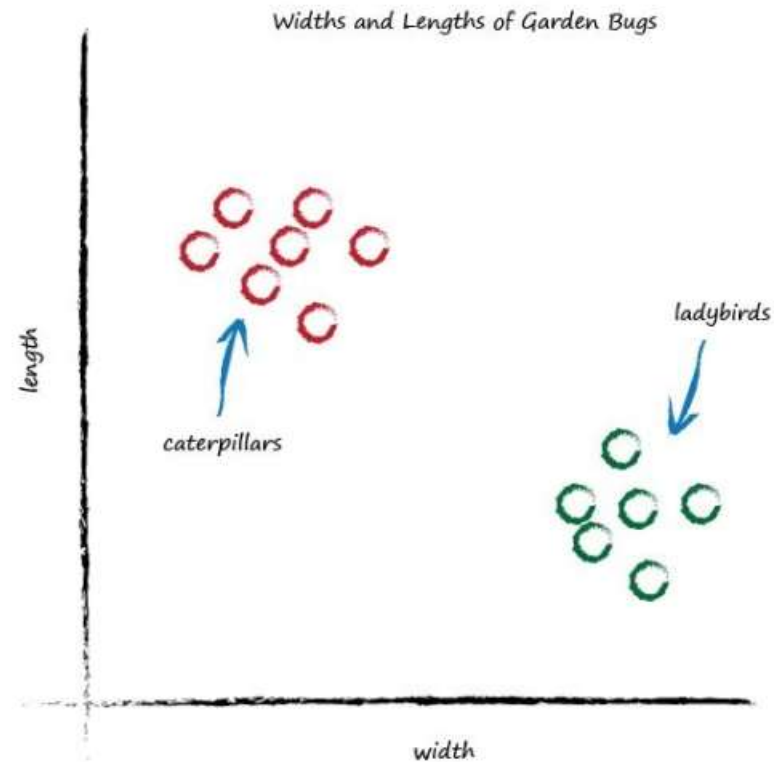


A good way of refining these models is to adjust the parameters based on **how wrong the model is compared to known true examples.**



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Classifying is Not Very Different from Predicting



Use the straight line to **separate** different classes.



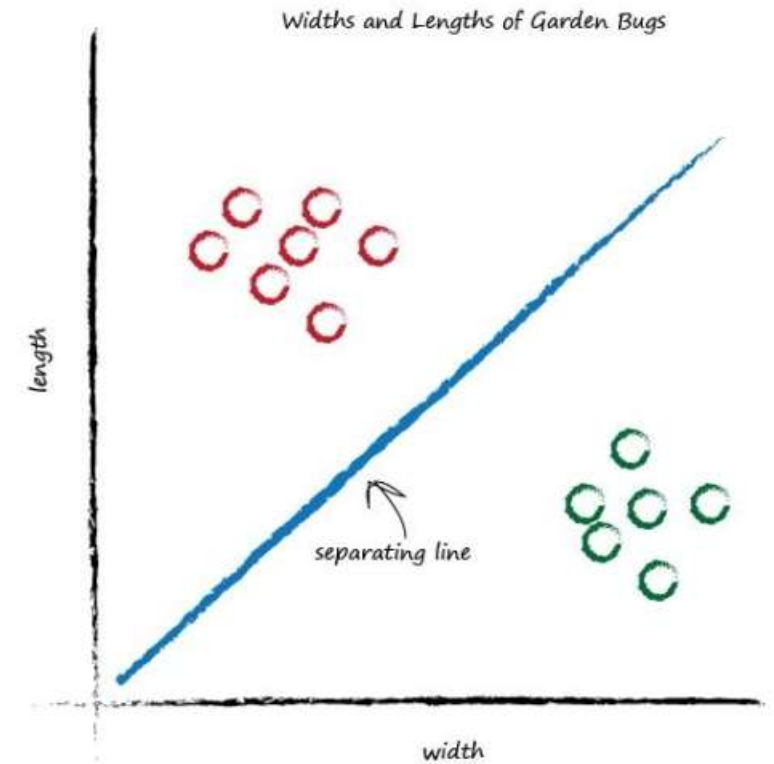
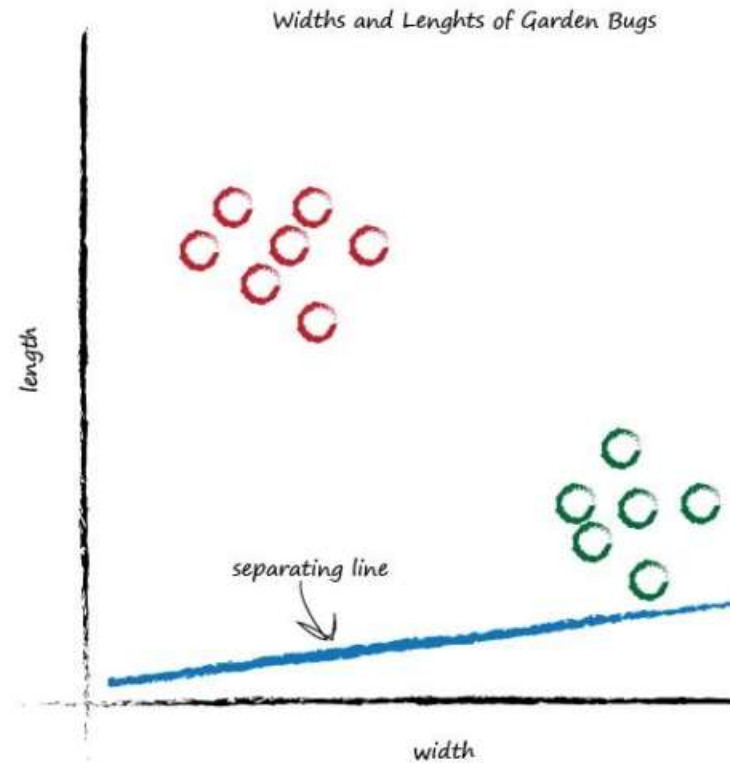
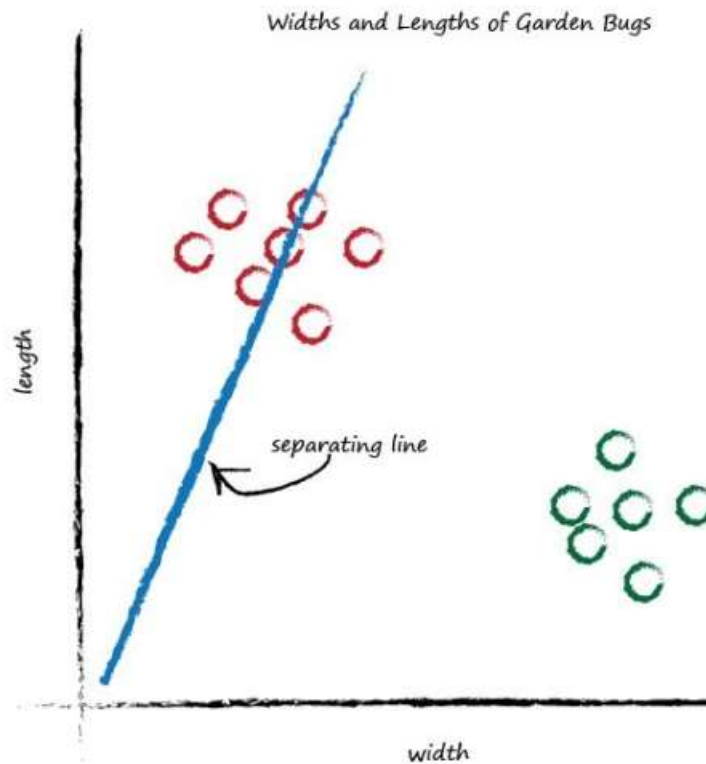
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Solve it

$$E = t - y = Ax + (\Delta A)x - Ax$$

$$E = (\Delta A)x$$

$$\Delta A = E / x$$



Ignore some of the previous value which was arrived at through potentially many previous training iterations.



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Moderate the updates

instead of jumping enthusiastically to each new A , we take a fraction of the change of A .
This way we move in the **direction** that the training example suggests, but do so slightly cautiously



Learning rate

$$\Delta A = L (E / x)$$

no single training example totally dominates the learning

dampen the impact of those errors or noise and smooth them out

To Find causal links or correlations between some observations and others.

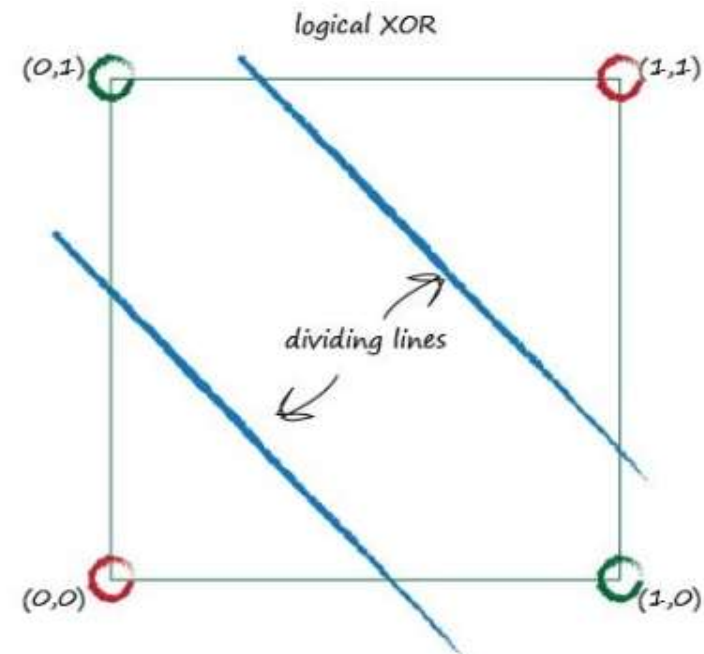


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One classifier may be not enough

Example

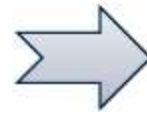
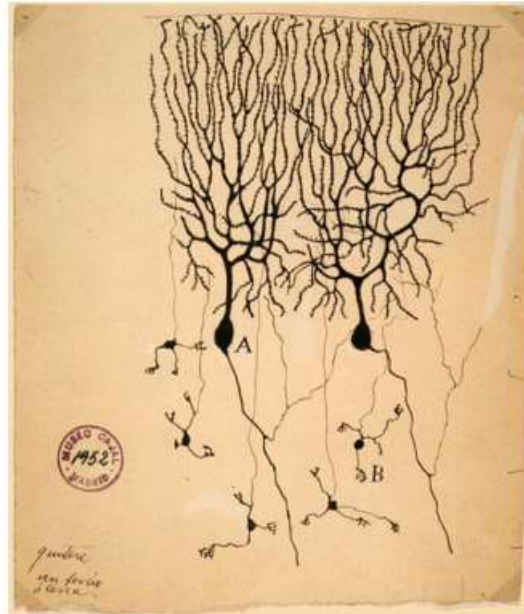
Input A	Input B	Logical XOR
0	0	0
0	1	1
1	0	1
1	1	0



many linear lines can start to separate off even unusually shaped regions for classification.



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process signals **in parallel**

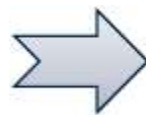
fuzziness

incredibly resilient to damage and imperfect signals
suppress the input until it has grown so large that it triggers
an output

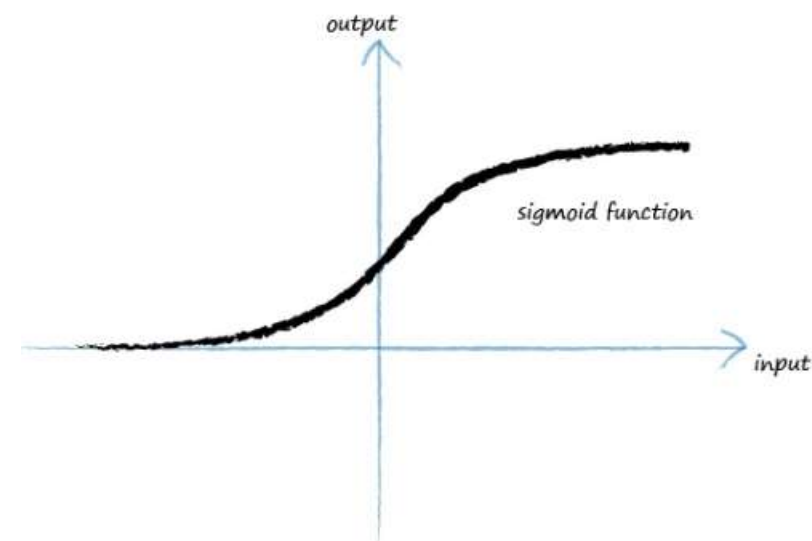
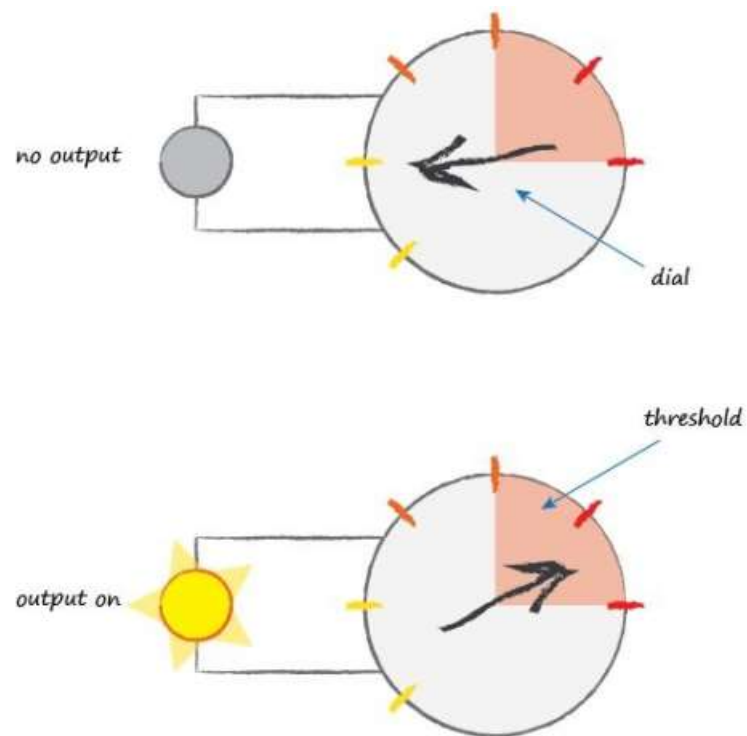


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threshold



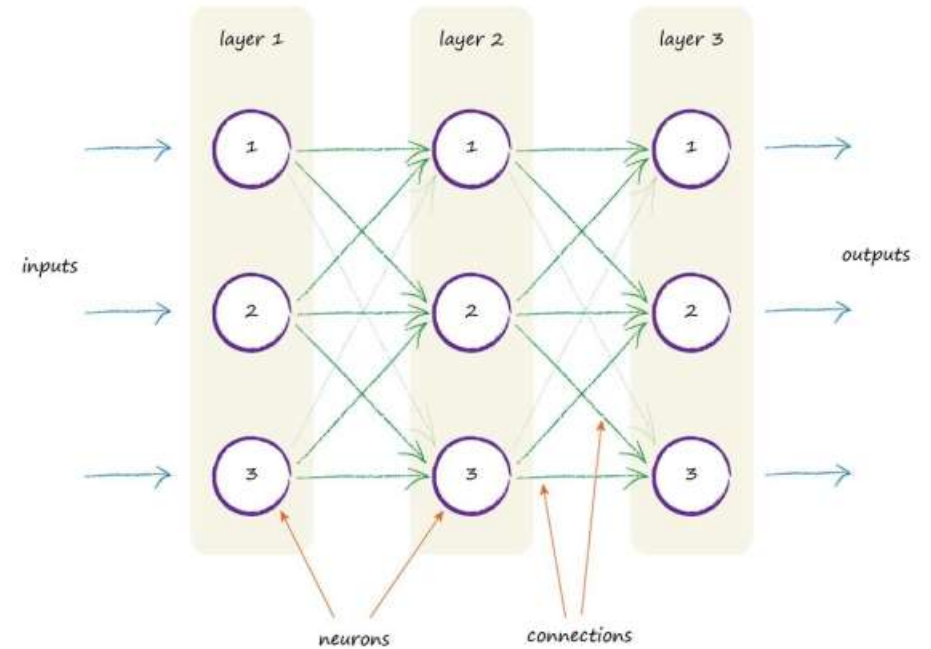
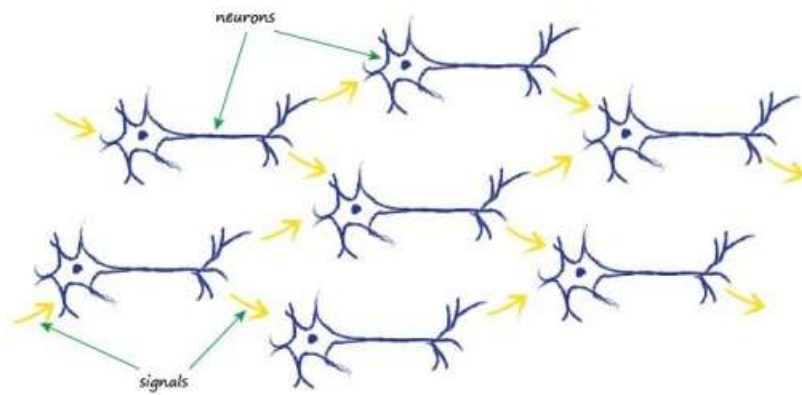
activation function



$$y = \frac{1}{1 + e^{-x}}$$



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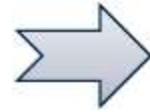


connected neurons

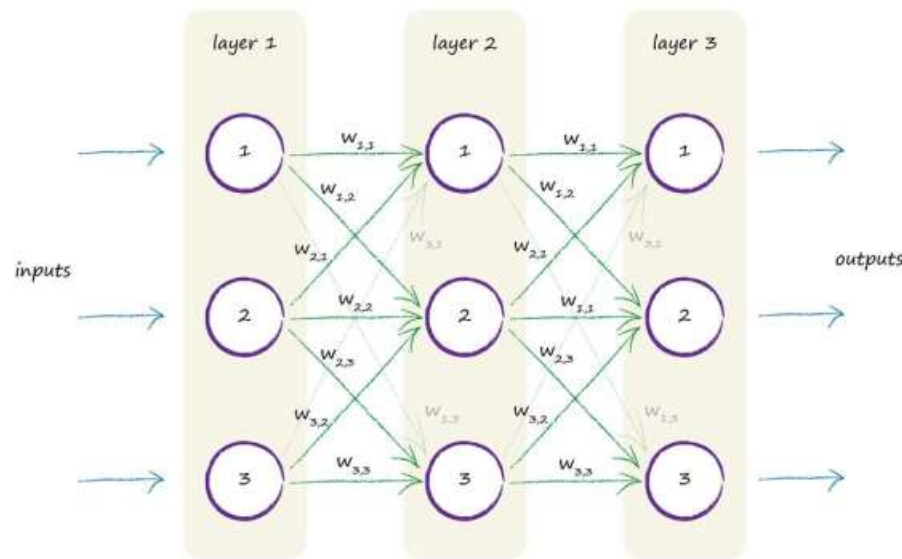


artificial neural networks

weight



To adjust the slope



A low weight will de-emphasise a signal, and a high weight will amplify it.

Pay attention: The first layer: not do anything other than represent the input signals. not apply an activation function.

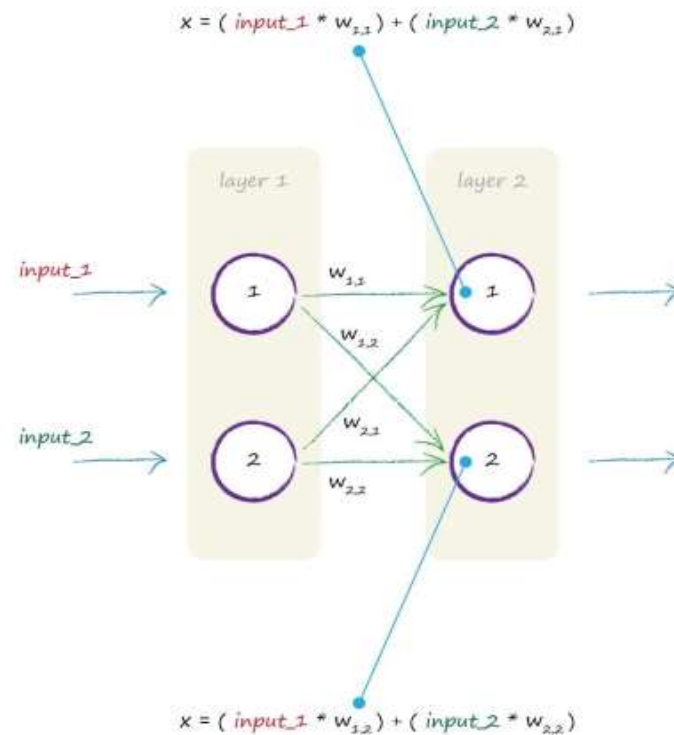


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Why full connectivity??

- easier to encode as computer instructions
- some weights become zero or close to zero, the link is effectively broken.

Matrix Multiplication is useful

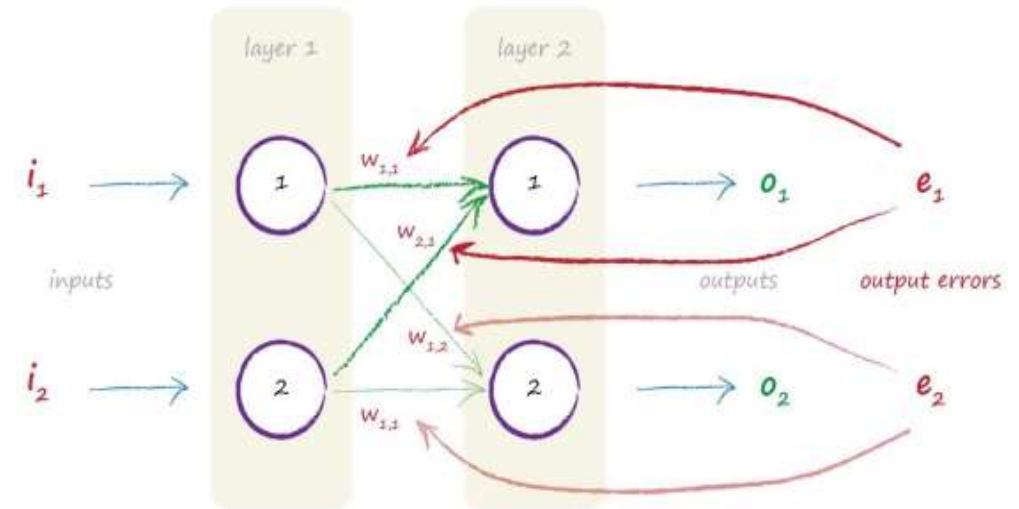
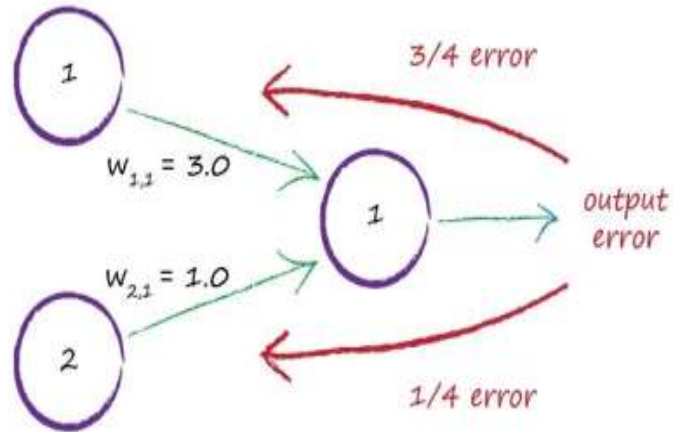


$$\begin{pmatrix} w_{1,1} & w_{1,2} \\ w_{2,1} & w_{2,2} \end{pmatrix} \begin{pmatrix} input_1 \\ input_2 \end{pmatrix} = \begin{pmatrix} (input_1 * w_{1,1}) + (input_2 * w_{2,1}) \\ (input_1 * w_{1,2}) + (input_2 * w_{2,2}) \end{pmatrix}$$

$$X = W \cdot I$$

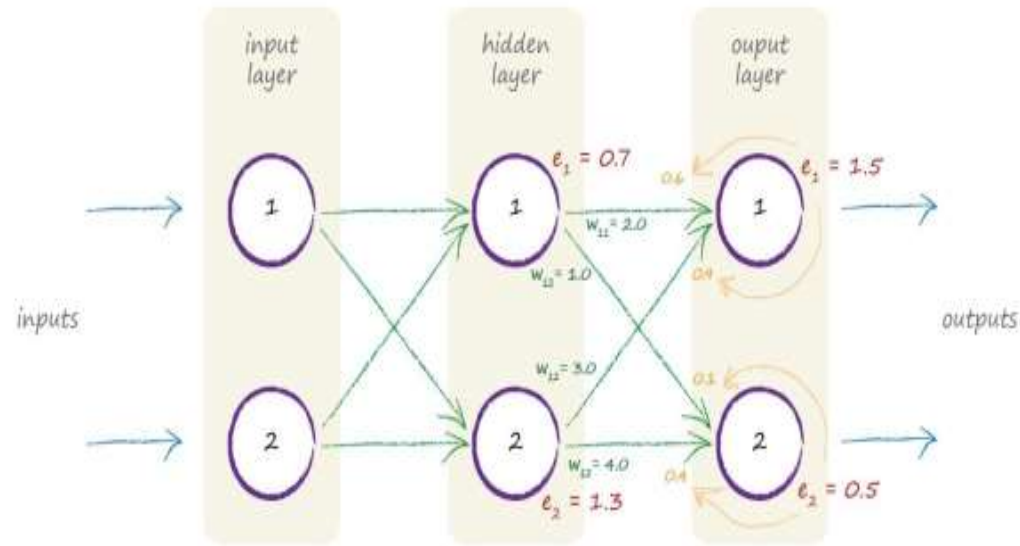
$$O = \text{sigmoid}(X)$$

use that error to refine the neural network

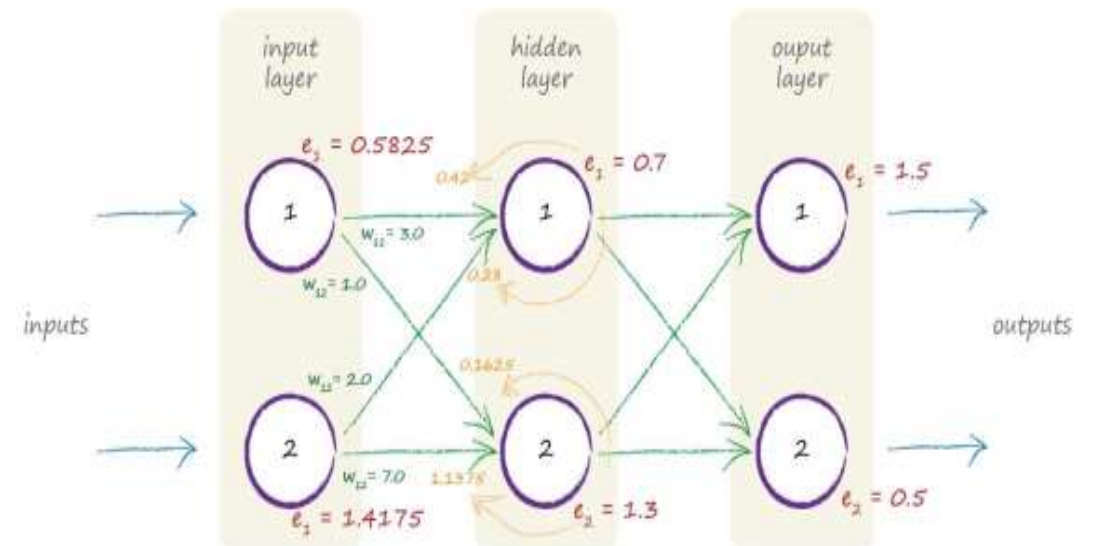


backpropagation

Backpropagating Errors To More Layers



1



2



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Backpropagating Errors with Matrix Multiplication

$$\text{error}_{\text{hidden}} = \begin{pmatrix} (e_1 * w_{11}) + (e_2 * w_{12}) \\ (e_1 * w_{21}) + (e_2 * w_{22}) \end{pmatrix}$$


$$\text{error}_{\text{hidden}} = w^{\text{T}}_{\text{hidden_output}} \cdot \text{error}_{\text{output}}$$

$$\text{error}_{\text{hidden}} = \begin{pmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \end{pmatrix} \cdot \begin{pmatrix} e_1 \\ e_2 \end{pmatrix}$$



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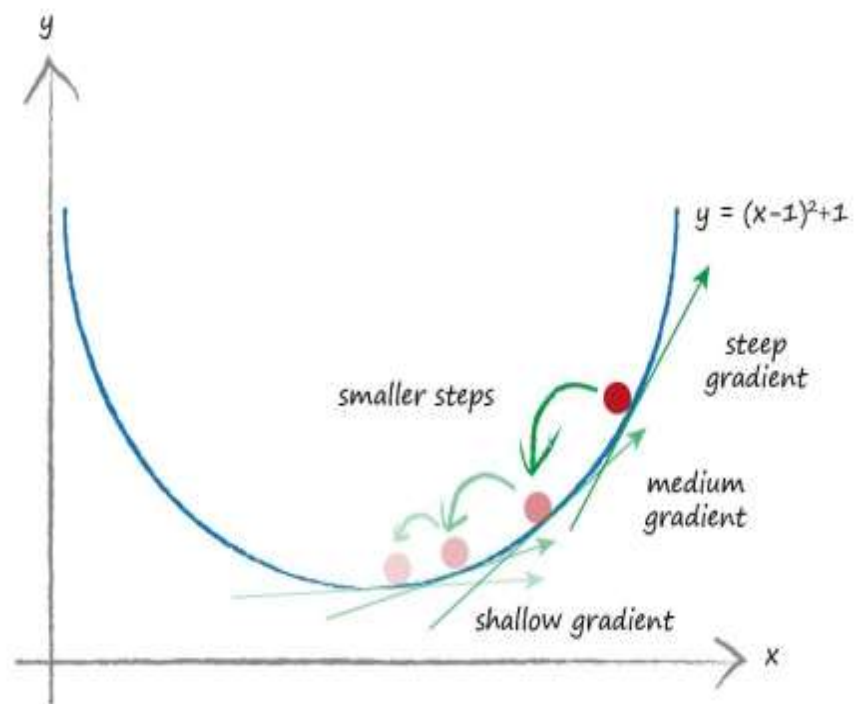
It's too hard, right?

$$o_k = \frac{1}{1 + e^{-\sum_{j=1}^3 (w_{j,k} \cdot \frac{1}{1 + e^{-\sum_{i=1}^3 (w_{i,j} \cdot x_i)})}}$$
A cartoon illustration of a man in a blue suit running to the right with a look of urgency or panic, clutching his chest.

~~brute force~~ ➡ gradient descent



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Cost function

Network Output	Target Output	Error (target - actual)	Error target - actual	Error (target - actual) ²
0.4	0.5	0.1	0.1	0.01
0.8	0.7	-0.1	0.1	0.01
1.0	1.0	0	0	0
Sum		0	0.2	0.02

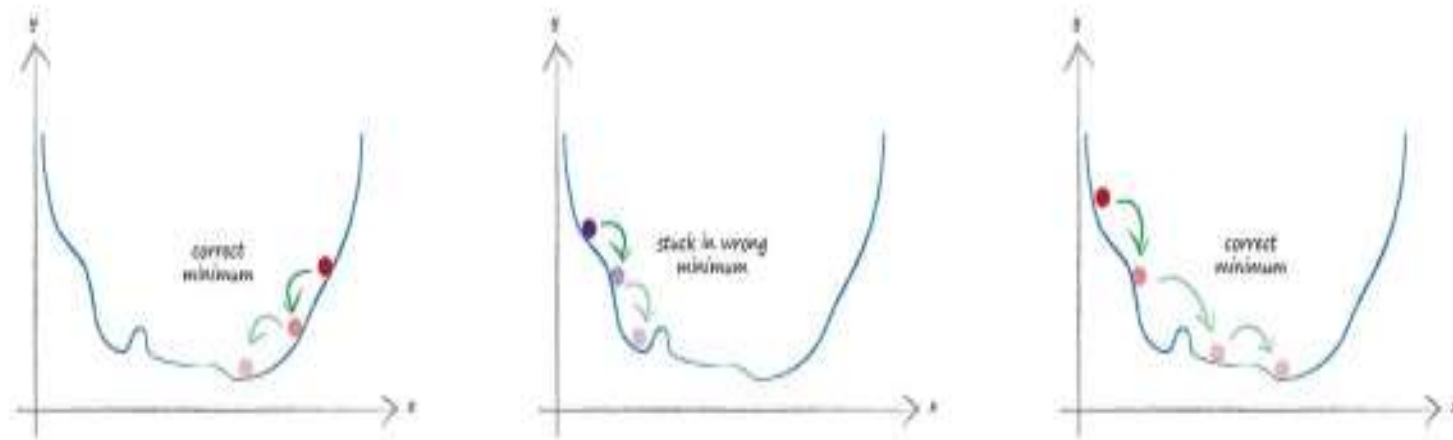
(target - actual): positive and negative errors cancel each other out.

|target - actual|: no continuous near the minimum
Not get smaller closer to the minimum

(target - actual)²: easy enough
smooth and continuous
gets smaller nearer the minimum

How to avoid ending up in the wrong valley?

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starting from different points

choosing **different** starting link weights



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$$\frac{\partial E}{\partial w_{jk}} = \frac{\partial}{\partial w_{jk}} \sum_n (t_n - o_n)^2$$

$$\frac{\partial E}{\partial w_{jk}} = -2(t_k - o_k) \cdot \frac{\partial o_k}{\partial w_{jk}}$$

$$\frac{\partial E}{\partial w_{jk}} = \frac{\partial}{\partial w_{jk}} (t_k - o_k)^2$$

$$\frac{\partial E}{\partial w_{jk}} = -2(t_k - o_k) \cdot \frac{\partial}{\partial w_{jk}} \text{sigmoid}(\sum_j w_{jk} \cdot o_j)$$

$$\frac{\partial E}{\partial w_{jk}} = \frac{\partial E}{\partial o_k} \cdot \frac{\partial o_k}{\partial w_{jk}}$$

$$\frac{\partial}{\partial x} \text{sigmoid}(x) = \text{sigmoid}(x) (1 - \text{sigmoid}(x))$$



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$$\begin{aligned}\frac{\partial E}{\partial w_{jk}} &= -2(t_k - o_k) \cdot \text{sigmoid}(\sum_j w_{jk} \cdot o_j) (1 - \text{sigmoid}(\sum_j w_{jk} \cdot o_j)) \cdot \frac{\partial}{\partial w_{jk}} (\sum_j w_{jk} \cdot o_j) \\ &= -2(t_k - o_k) \cdot \text{sigmoid}(\sum_j w_{jk} \cdot o_j) (1 - \text{sigmoid}(\sum_j w_{jk} \cdot o_j)) \cdot o_j\end{aligned}$$

$$\frac{\partial E}{\partial w_{jk}} = -(t_k - o_k) \cdot \text{sigmoid}(\sum_j w_{jk} \cdot o_j) (1 - \text{sigmoid}(\sum_j w_{jk} \cdot o_j)) \cdot o_j$$



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$$\text{new } w_{jk} = \text{old } w_{jk} - \alpha \cdot \frac{\partial E}{\partial w_{jk}}$$

$$\Delta w_{jk} = \alpha * E_k * \text{sigmoid}(O_k) * (1 - \text{sigmoid}(O_k)) \cdot O_j^T$$



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thanks