

## 1. Evaluate $\theta^1$ using Stochastic Gradient Descent

We are asked to perform one step of Stochastic Gradient Descent (SGD) to find  $\theta^1$ .

### Step 1: Define Model, Loss, and Data

- **Model Hypothesis ( $\hat{y}$ ):**  $\hat{y} = h(x_1, x_2) = \sigma(z)$
- **Linear Input ( $z$ ):**  $z = b + w_1x_1 + w_2x_2$
- **Parameters ( $\theta$ ):**  $\theta = (b, w_1, w_2)$
- **Loss Function ( $L$ ):** For a regression problem (house price), we use the **Squared Error Loss**.

$$L(\theta) = \frac{1}{2}(\hat{y} - y)^2 = \frac{1}{2}(\sigma(z) - y)^2$$

- **Initial Parameters ( $\theta^0$ ):**  $\theta^0 = (b^0, w_1^0, w_2^0) = (4, 5, 6)$
- **Data Point ( $x, y$ ):**  $(x_1, x_2, y) = (1, 2, 3)$

### Step 2: Define the SGD Update Rule

The SGD update rule for the new parameters  $\theta^1 = (b^1, w_1^1, w_2^1)$  is:

$$\theta^1 = \theta^0 - \alpha \nabla L(\theta^0)$$

where  $\alpha$  is the learning rate (which is not given, so we keep it as a symbol). We need to find the gradient vector  $\nabla L = \left[ \frac{\partial L}{\partial b}, \frac{\partial L}{\partial w_1}, \frac{\partial L}{\partial w_2} \right]$ .

### Step 3: Calculate the Gradients (Chain Rule)

We find the partial derivative of  $L$  with respect to each parameter.

$$\frac{\partial L}{\partial \theta_j} = \frac{\partial L}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z} \cdot \frac{\partial z}{\partial \theta_j}$$

Let's find the common components first:

- $\frac{\partial L}{\partial \hat{y}} = \frac{\partial}{\partial \hat{y}} \left[ \frac{1}{2}(\hat{y} - y)^2 \right] = (\hat{y} - y)$
- $\frac{\partial \hat{y}}{\partial z} = \frac{d\sigma(z)}{dz} = \sigma(z)(1 - \sigma(z)) = \hat{y}(1 - \hat{y})$

Now, we find the specific gradients:

$$\begin{aligned} \frac{\partial L}{\partial b} &= \frac{\partial L}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z} \cdot \frac{\partial z}{\partial b} = (\hat{y} - y) \cdot \hat{y}(1 - \hat{y}) \cdot 1 \\ \frac{\partial L}{\partial w_1} &= \frac{\partial L}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z} \cdot \frac{\partial z}{\partial w_1} = (\hat{y} - y) \cdot \hat{y}(1 - \hat{y}) \cdot x_1 \\ \frac{\partial L}{\partial w_2} &= \frac{\partial L}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z} \cdot \frac{\partial z}{\partial w_2} = (\hat{y} - y) \cdot \hat{y}(1 - \hat{y}) \cdot x_2 \end{aligned}$$

### Step 4: Substitute Numbers to find $\theta^1$

As per the instruction, we just write the expression and substitute the numbers, without simplifying.

First, we express the prediction  $\hat{y}^0$  made with the initial parameters  $\theta^0$  and data  $x$ :

$$z^0 = b^0 + w_1^0x_1 + w_2^0x_2 = 4 + 5 \cdot 1 + 6 \cdot 2$$

$$\hat{y}^0 = \sigma(z^0) = \sigma(4 + 5 \cdot 1 + 6 \cdot 2)$$

Now we write the update equation for each parameter, substituting  $\theta^0$ ,  $y = 3$ ,  $x_1 = 1$ , and  $x_2 = 2$ .

**For  $b^1$ :**

$$b^1 = b^0 - \alpha \cdot \left. \frac{\partial L}{\partial b} \right|_{\theta^0, x, y}$$

$$b^1 = 4 - \alpha \cdot [(\sigma(4 + 5 \cdot 1 + 6 \cdot 2) - 3) \cdot \sigma(4 + 5 \cdot 1 + 6 \cdot 2) \cdot (1 - \sigma(4 + 5 \cdot 1 + 6 \cdot 2)) \cdot 1]$$

**For  $w_1^1$ :**

$$w_1^1 = w_1^0 - \alpha \cdot \left. \frac{\partial L}{\partial w_1} \right|_{\theta^0, x, y}$$

$$w_1^1 = 5 - \alpha \cdot [(\sigma(4 + 5 \cdot 1 + 6 \cdot 2) - 3) \cdot \sigma(4 + 5 \cdot 1 + 6 \cdot 2) \cdot (1 - \sigma(4 + 5 \cdot 1 + 6 \cdot 2)) \cdot 1]$$

**For  $w_2^1$ :**

$$w_2^1 = w_2^0 - \alpha \cdot \left. \frac{\partial L}{\partial w_2} \right|_{\theta^0, x, y}$$

$$w_2^1 = 6 - \alpha \cdot [(\sigma(4 + 5 \cdot 1 + 6 \cdot 2) - 3) \cdot \sigma(4 + 5 \cdot 1 + 6 \cdot 2) \cdot (1 - \sigma(4 + 5 \cdot 1 + 6 \cdot 2)) \cdot 2]$$

**Consolidated Result for  $\theta^1$ :** To write the final expression for  $\theta^1$  more concisely, let's define a common term  $G$  (the gradient factor):

$$G = (\sigma(4 + 5 \cdot 1 + 6 \cdot 2) - 3) \cdot \sigma(4 + 5 \cdot 1 + 6 \cdot 2) \cdot (1 - \sigma(4 + 5 \cdot 1 + 6 \cdot 2))$$

The updated parameter vector  $\theta^1 = (b^1, w_1^1, w_2^1)$  can then be written as:

$$\theta^1 = (4 - \alpha G, \quad 5 - \alpha G, \quad 6 - 2\alpha G)$$

Or, using the original vector notation:

$$\theta^1 = (4, 5, 6) - \alpha G \cdot (1, 1, 2)$$