Data Structures Sorting

CS284

Objectives

- ► To learn how to implement the following sorting algorithms:
 - selection sort
 - bubble sort
 - insertion sort
 - shell sort
 - merge sort
 - heapsort
 - quicksort
- ➤ To understand the differences in performance of these algorithms, and which to use for small, medium arrays, and large arrays

Heapsort

Quicksort

Comparison of Algorithms

Heapsort

- Heapsort has the same complexity as Mergesort
- ▶ In contrast to Mergesort, Heapsort does not require any additional storage
- As its name implies, heapsort uses a heap to store the array
 - When used as a priority queue, a heap maintains a smallest value at the top
 - Naive heapsort:
 - place an array's data into a heap,
 - then remove each heap item and move it back into the array

Naive Version of a Heapsort Algorithm

▶ This version of the algorithm requires *n* extra storage locations

```
Insert each value from table into a priority queue (heap).
i=0
while (priority queue is not empty) {
   Remove next item from the queue
   Insert it back into the array at position i
   i++
}
```

► Tracing an example

0	1	2	3	4	5	6	7
15	20	30	45	50	60	80	90

Revising the Heapsort Algorithm

- We can do better in terms of space usage
- ► We can build a heap so that each parent node value is not less than its children (maxHeap)
- ► Then,
 - move the top item to the bottom of the heap
 - reheap, ignoring the item moved to the bottom
- If we implement the heap as an array,
 - each element removed will be placed at end of the array, and
 - the heap part of the array decreases by one element

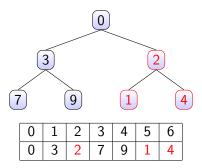
Algorithm for In-Place Heapsort

```
Heapify the input array
while (h is not empty) {
  Remove the first item h by swapping it with the last item in h
  Restore the heap property on h
}
```

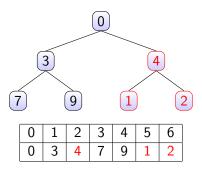
0	1	2	3	4	5	6
0	3	2	7	9	1	4

Example: sorting the array 0, 3, 2, 7, 9, 1, 4

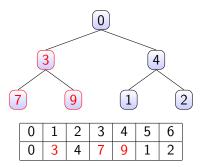
```
for (int i = this.heap.length - 1; i >= 0; i --) {
   find i's parent and sibling;
   swap parent with the larger sibling;
   heapify down the larger sibling;
}
```



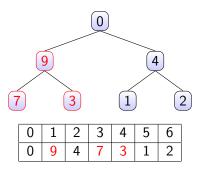
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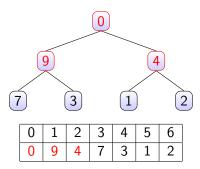
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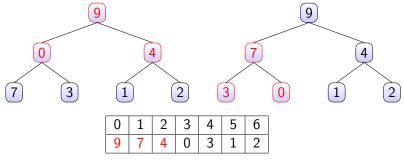
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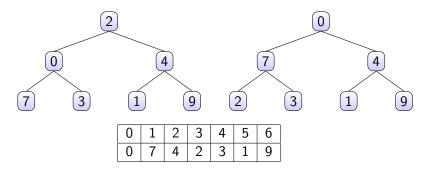
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}
```



Can you prove the correctness of heapifyAll?

Step 2: Poll and place the next largest element

```
for (int i = this.heap.length - 1; i >= 0; i --) {
   int next_element = this.peek();
   this.poll();
   this.heap[i] = next_element;
}
```



```
/** heap sort: (1) heapify the input array
* (2) for i= length...0
* remove the i-th smallest element, and
* append it to the length - i-th position
* @param array
* /
private void heapSort(int[] array) {
  this.set_array(array);
  this.heapifyAll();
  for (int i = this.heap.length - 1; i >= 0; i --) {
      int next_element = this.peek();
      this.poll();
      this.heap[i] = next_element;
  this.size = this.heap.length;
```

```
private void heapifyAll() {
  int[] visited = new int[this.heap.length];
  for (int i = this.heap.length - 1; i >= 0; i --) {
    int parentIdx = this.getParentIndex(i);
    if (parentIdx == i)
        continue;
    if (visited[i] == 1) continue;
    int leftChildIdx = this.getLeftChildIndex(parentIdx);
    int rightChildIdx = this.getRightChildIndex(parentIdx);
```

```
if (this.heap[leftChildIdx] >
this.heap[rightChildIdx]) {
    swap(leftChildIdx, parentIdx);
    heapifyDown(leftChildIdx);
else {
    swap(rightChildIdx, parentIdx);
    heapifyDown(rightChildIdx);
visited[leftChildIdx] = 1;
visited[rightChildIdx] = 1;
```

```
private void heapifyDown(int index) {
while (hasLeftChild(index)) {
  int largerChildIndex = getLeftChildIndex(index);
  if (hasRightChild(index) &&
  rightChild(index) > leftChild(index)) {
    largerChildIndex = getRightChildIndex(index);
  if (heap[index] < heap[largerChildIndex]) {</pre>
    swap(index, largerChildIndex);
  } else {
   break;
  index = largerChildIndex;
```

Heapsort - Analysis

- ▶ Heapify: $O(n \log n)$
- Poll and place: $O(n \log n)$
- ▶ Total time complexity: $O(n \log n)$

Run the demo for heapsort and quicksort

Heapsort

Quicksort

Comparison of Algorithms

Quicksort

- ► Developed in 1962
- Selects a specific value called a pivot and rearranges the array into two parts (called partitioning)
 - ► all the elements in the left subarray are less than or equal to the pivot
 - ▶ all the elements in the right subarray are larger than the pivot
- The pivot is placed between the two subarrays
- ▶ The process is repeated until the array is sorted

Quicksort by Example

- ► We'll look at an example
- We will use a simple partitioning strategy
 - the pivot is chosen to be the first element in the current subarray to be partitioned

0	1	2	3	4	5	6	7	8
44	75	23	43	55	12	64	77	33

Divide-and-Conquer using Pivot

```
public void quick_sort(E[] a) {
   recursive_quicksort(a, 0, a.length - 1);
}

public void recursive_quicksort(E[] a, int first, int last)
   int pivIdx = partition(a, first, last);
   if (first < pivIdx - 1)
      recursive_quicksort(a, first, pivIdx - 1);
   if (pivIdx + 1 < last)
      recursive_quicksort(a, pivIdx + 1, last);
}</pre>
```

Quicksort Partition: Execution trace

int pivIdx = partition(a, first, last); first up down first down

Quicksort Partition: Execution trace

int pivIdx = partition(a, first, last); first down up first pivldx - 1 pivldx + 1 last quickSort(a, first, pivIdx - 1); quickSort(a, pivIdx + 1, last);

Quicksort Partition: Code

```
public int partition(E[] a, int first, int last) {
  E pivot = a[first];
  int up = first;
  int down = last;
  do {
      while ((up < last) && (up<last)</pre>
      && (pivot.compareTo(a[up])>=0)) {
         up++; }
      while (down > first && pivot.compareTo(a[down]) < 0) {</pre>
        down--;
       if (up < down) { // if up is to the left of down.
           swap(a, up, down);
    } while (up < down); // Repeat while up is left of down.
  swap(a, first, down);
  return down;
```

Analysis of Quicksort

- ▶ If the pivot value is a random value selected from the current subarray, then statistically half of the items in the subarray will be less than the pivot and half will be greater
- ► If both subarrays have the same number of elements (best case), there will be log *n* levels of recursion

Analysis of Quicksort

- ▶ At each recursion level, the partitioning process involves moving every element to its correct position (*n* moves)
- ▶ Quicksort is $\mathcal{O}(n \log n)$, just like merge sort
- ▶ The array split may not be the best case, i.e. 50-50
- An exact analysis is difficult (and beyond the scope of this class), but, the running time will be bounded by a constant * n log n

Analysis of Quicksort (cont.)

- A quicksort will give very poor behavior if, each time the array is partitioned, a subarray is empty.
- ▶ In that case, the sort will be $\mathcal{O}(n^2)$
 - Prove this with an example
- Under these circumstances, the overhead of recursive calls and the extra run-time stack storage required by these calls makes this version of quicksort a poor performer relative to the quadratic sorts
- We'll discuss a solution later

Revised Partition Algorithm

- ▶ Quicksort is $\mathcal{O}(n^2)$ when each split yields one empty subarray, which is the case when the array is presorted
- ► A better solution is to pick the pivot value in a way that is less likely to lead to a bad split
 - ▶ Use three references: first, middle, last
 - Select the median of the these items as the pivot

Heapsort

Quicksort

Comparison of Algorithms

Comparison of Sorting

	Number of comparisons				
	Best	Average	Worst		
Selection sort	$\mathcal{O}(n^2)$	$\mathcal{O}(n^2)$	$\mathcal{O}(n^2)$		
Bubble sort	$\mathcal{O}(n)$	$\mathcal{O}(n^2)$	$\mathcal{O}(n^2)$		
Insertion sort	$\mathcal{O}(n)$	$\mathcal{O}(n^2)$	$\mathcal{O}(n^2)$		
Shell sort	$\mathcal{O}(n^{7/6})$	$\mathcal{O}(n^{5/4})$	$\mathcal{O}(n^2)$		
Merge sort	$\mathcal{O}(n \log n)$	$\mathcal{O}(n \log n)$	$\mathcal{O}(n \log n)$		
Heapsort	$\mathcal{O}(n \log n)$	$\mathcal{O}(n \log n)$	$\mathcal{O}(n \log n)$		
Quicksort	$\mathcal{O}(n \log n)$	$\mathcal{O}(n \log n)$	$\mathcal{O}(n^2)$		