Hardware Design and Lab: Lab3

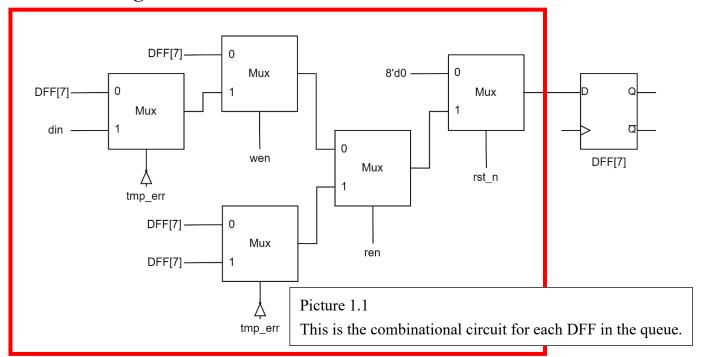
111060013 EECS 26' 劉祐廷

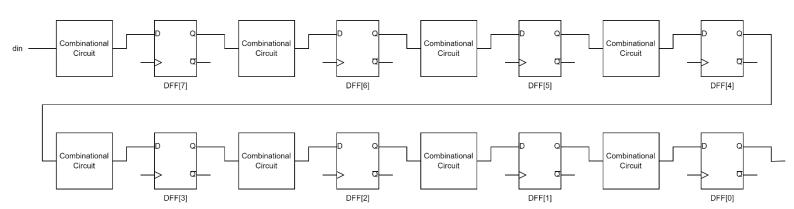
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1. Advanced Question: First-In First Out (FIFO) Queue

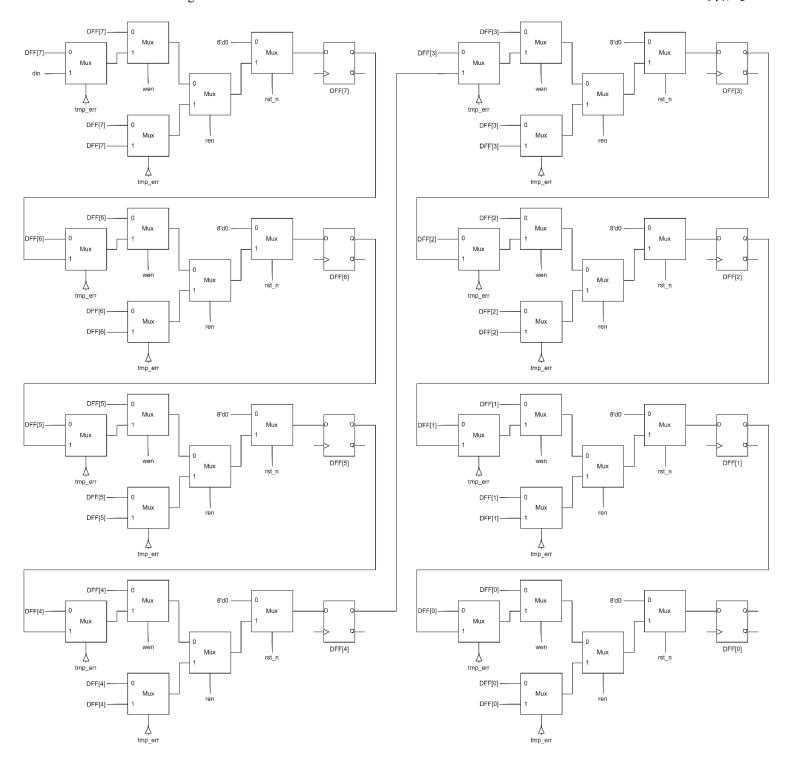
A. Block Diagram



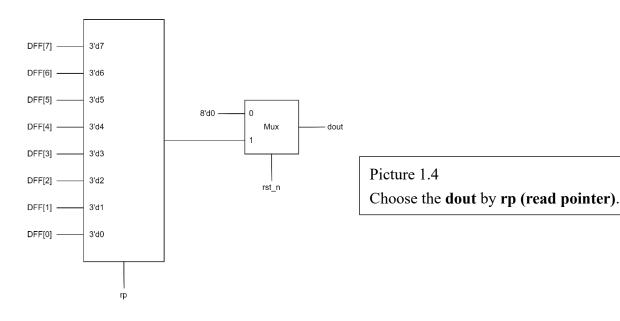


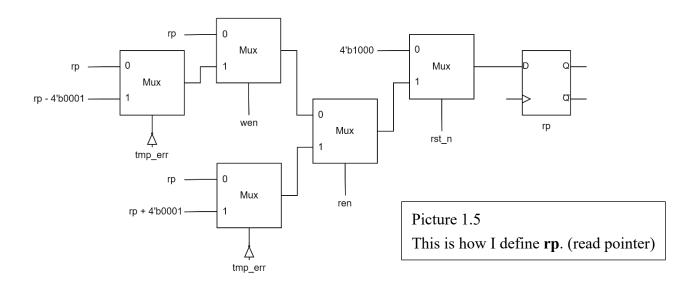
Picture 1.2

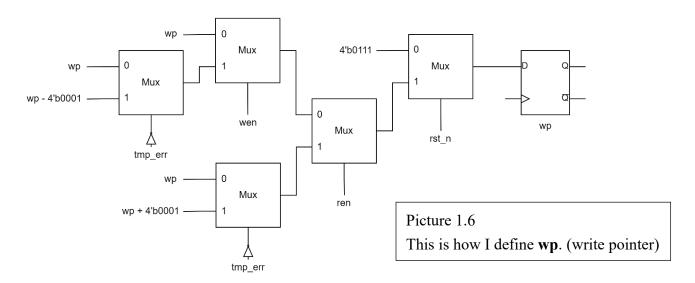
This is the architecture of the 8-bits FIFO Queue.

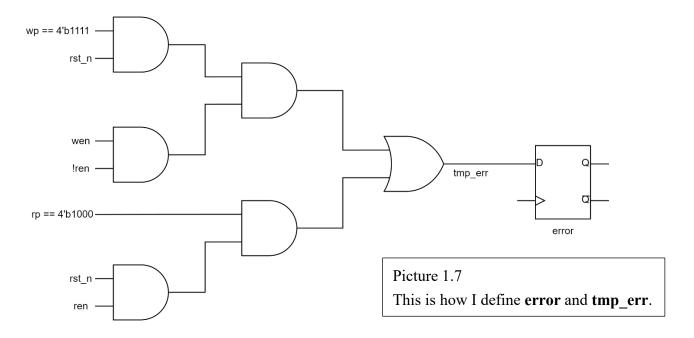


Picture 1.3
This is the block diagram of the 8-bits FIFO Queue.

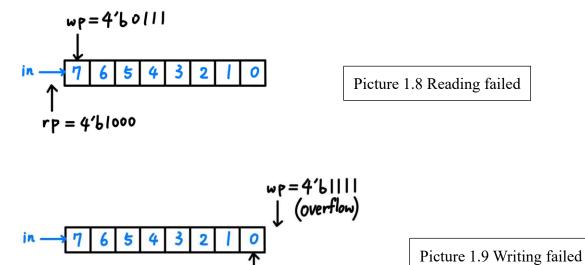






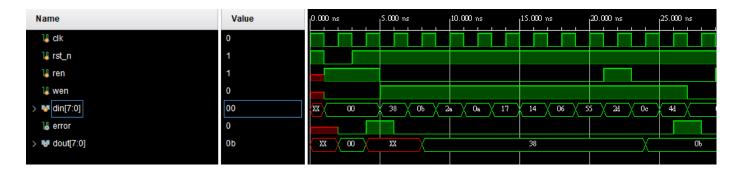


In the beginning, I reset **rp** (read pointer) and **wp** (write pointer) to **4'b0111** and **4'b1111** respectively. If writing data into queue is successful, both of **rp** and **wp** will -1 as moving the pointers to the next DFF. If reading data out of queue is successful, both of **rp** and **wp** will +1 as moving the pointers to the previous DFF. The data in the queue will only be passed to the next DFF while writing is successful. Otherwise, they will be kept in the same DFF. The error cases are that rp == 4'b1000 and ren == 1'b1, which means reading failed, or wp == 4'b1111 (overflow when writing), ren == 1'b0 and wen == 1'b1, which means writing failed. In these cases, **error** will be pulled up for a clock cycle.



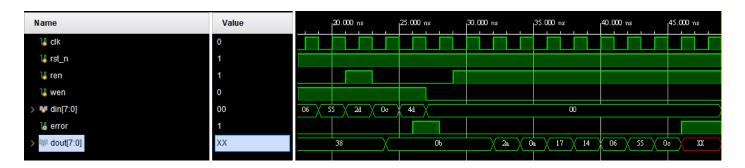
rp = 4'60000

C. Testbench



Picture 1.10 Wave form 1

I test my design with the input in the lecture slide to see if there is something wrong or not. As the wave form showed in Picture 1.10m it looks like everything is correct. However, it only tests the condition of writing failed. Therefore, I let it read out all the data in the queue to check the condition of reading failed.

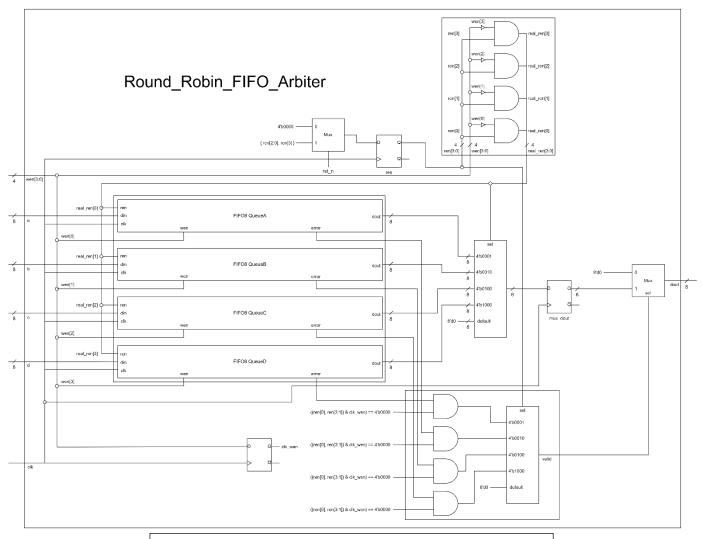


Picture 1.11 Wave form 2

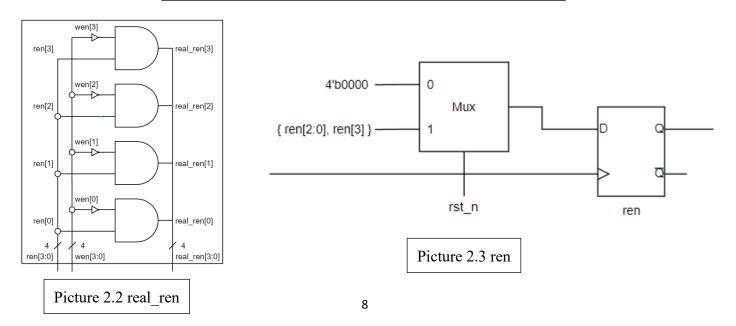
As the result showed in Picture 1.11, we can see that the condition of reading fail is also correct.

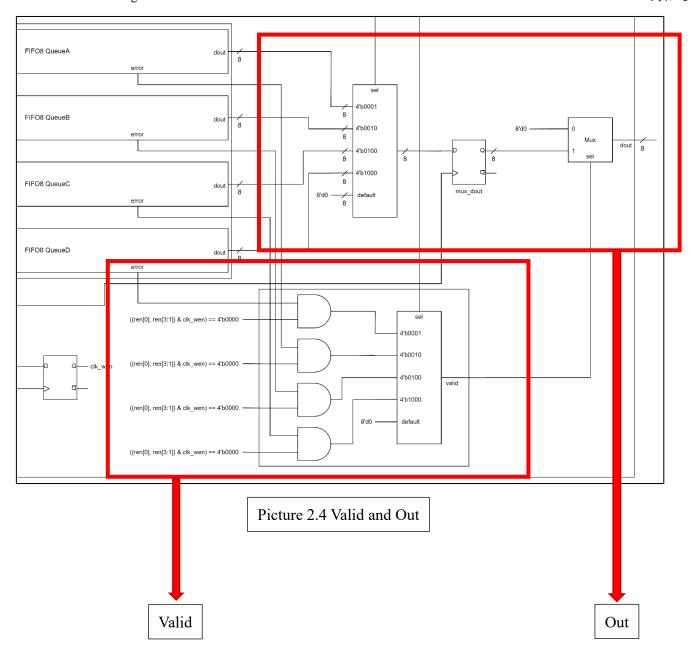
2. Advanced Question: Round-Robin FIFO Arbiter

A. Block Diagram



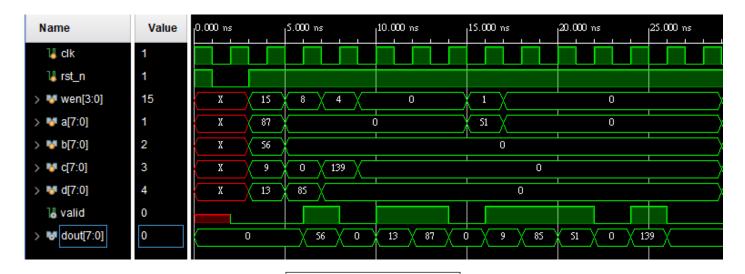
Picture 2.1 The whole design of Round-Robin FIFO Arbiter





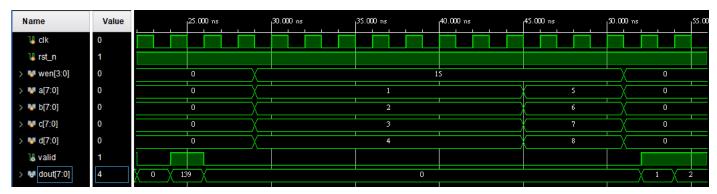
FIFO8 here is totally the same as the FIFO8 in the advanced question, First-In First Out (FIFO) Queue. For valid, error in FIFO8 is synchronized, so valid isn't needed to be contained in a DFF. However, because valid is not contained in a DFF, which means that it will change if wen changes, so I use a DFF to keep wen for a clock cycle which called clk_wen to help me define valid correctly. For dout, I use a 4-bit counter called ren to decide which queue should be access. Different from the advanced question, First-In First Out (FIFO) Queue, if both ren and wen is 1'b1, it will write instead of read. Therefore, I define an extra reg called real ren to fix this problem.

C. Testbench

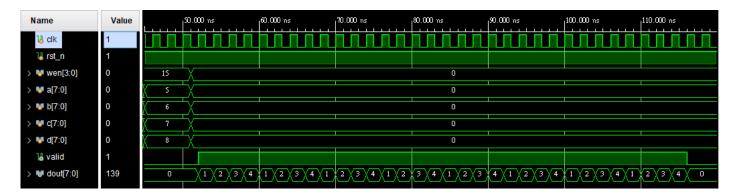


Picture 2.5 wave form 1

First, I use the input data from lecture slide to test if there is something wrong or not. As the result showed in Picture 2.5, we can see that everything works correctly. However, here we can't test the situation of writing failed. Therefore, after clear the queues, I let it write 8 times of same numbers and 1 times of different numbers. After that, I pop every queue for 9 times to check if everything is correct.



Picture 2.6 wave form 2

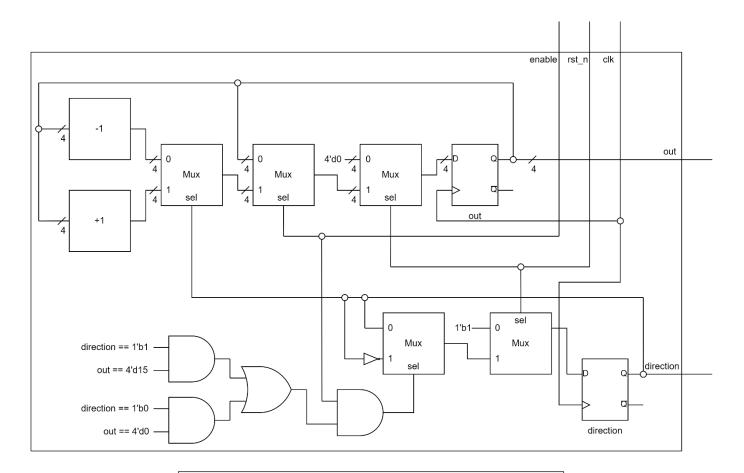


Picture 2.7 wave form 3

From Picture 2.6 and Picture 2.7, we can see that when the condition of reading failed or writing failed happened, my design can work correctly.

3. Advanced Question: 4-bit Ping-Pong Counter

A. Block Diagram



Picture 3.1 The whole design of 4-bit Ping-Pong Counter

B. Explanation

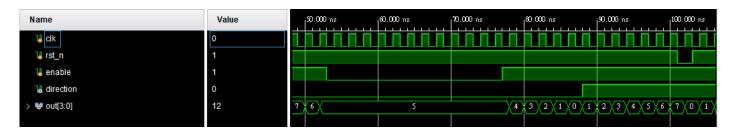
I use two DFF to contain **out** and **direction** respectively. If **direction** == 1'b1 and **out** == 4'd15, which means the counter hits the upper bound, and **direction** == 1'b0 and **out** == 4'd0, which means the counter hits the lower bound, **direction** should be inverted.

C. Testbench



Picture 3.2 wave form 1

For the beginning of the testbench, I test the counter without changing **enable** and **rst_n**. As the result showed in Picture 3.2, we can see that everything works properly.

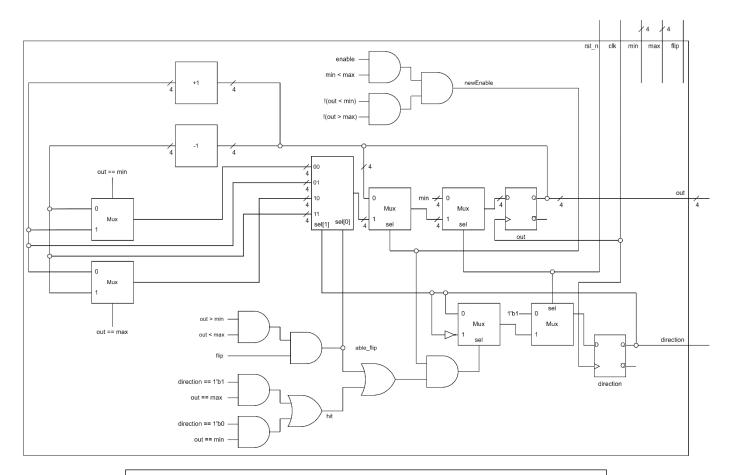


Picture 3.3 wave form 2

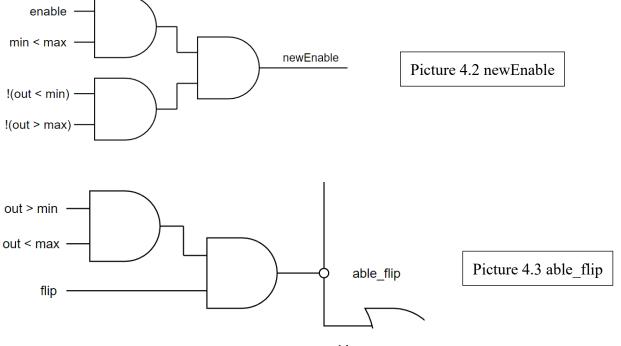
And then I test **enable** and **rst_n** to check if they work or not. From the result in Picture 3.3. It seems that everything is correct.

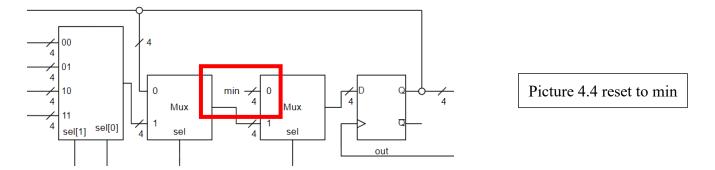
4. Advanced Question: 4-bit Parameterized Ping-Pong Counter

A. Block Diagram



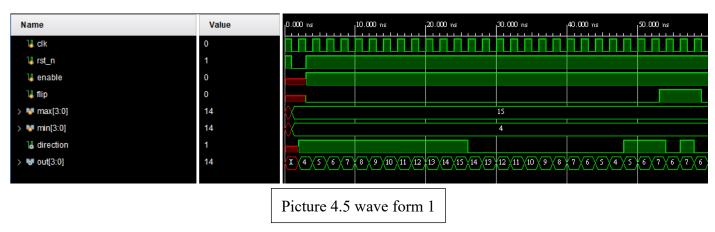
Picture 4.1 The whole design of 4-bit Parameterized Ping-Pong Counter



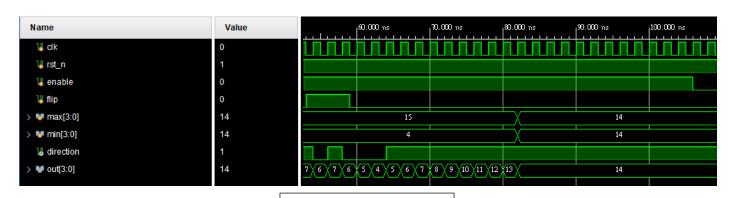


This module extends from the advanced question, 4-bit Ping-Pong Counter. Most of its architecture and methods are the same. There are three different things between them. First, in this problem, enable is not the only factor of triggering counter. Thus, I define a reg called newEnable like Picture 4.2. Second, there is an extra signal called flip in this problem. When flip == 1'b1 and min < out < max, it will trigger the counter to change it direction of counting. I define a reg called able_flip to store this factor as Picture 4.2 shows. Third, according to the problem, while rst_n == 1'b0, I should set out to min. So I change the reset case of out as it shows in Picture 4.4.

C. Testbench



First of all, I test the counter counting from min to max back and forth. And then test if **flip** works properly. As Picture 4.5 shows, these two functions work properly.



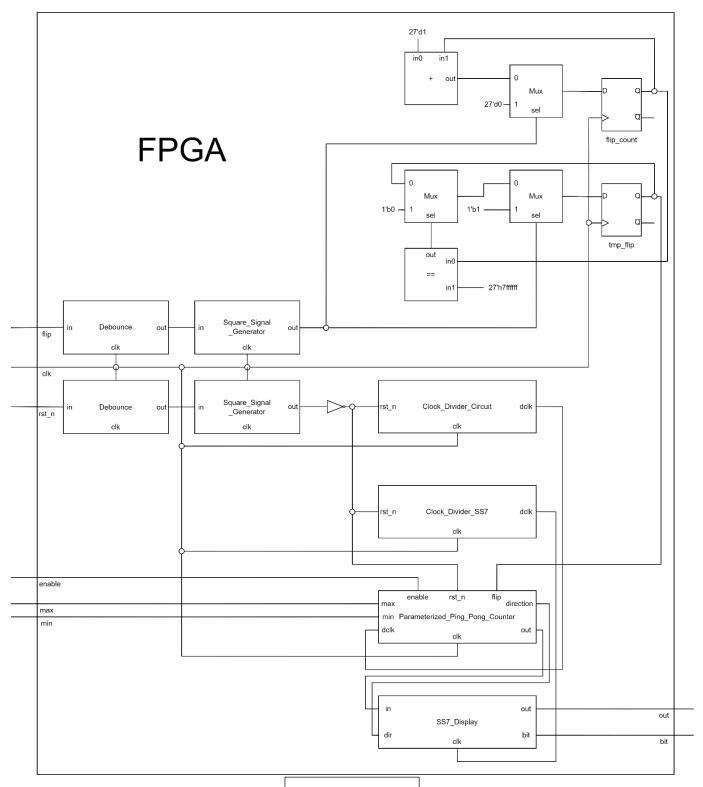
Picture 4.6 wave form 2

After that, I try to change **min** and **max** to check if **newEnable** works correctly or not. As Picture 4.6 shows, we can see that it is correct.

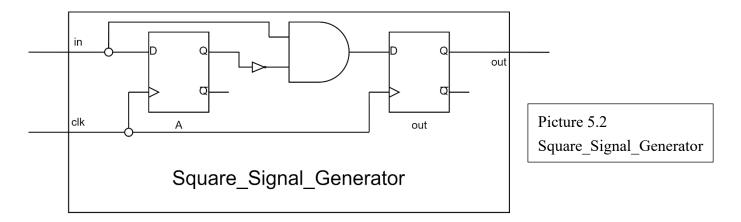
5. Advanced Question: 4-bit Parameterized Ping-Pong Counter

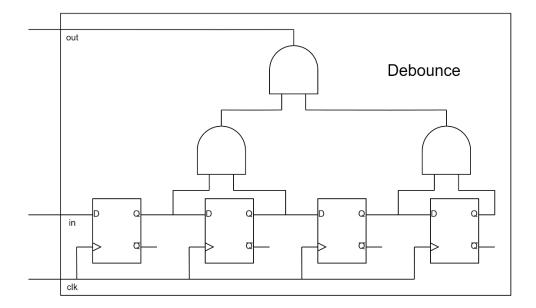
FPGA

A. Block Diagram

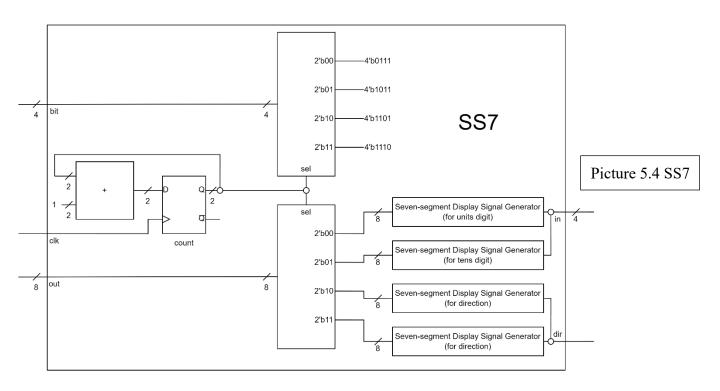


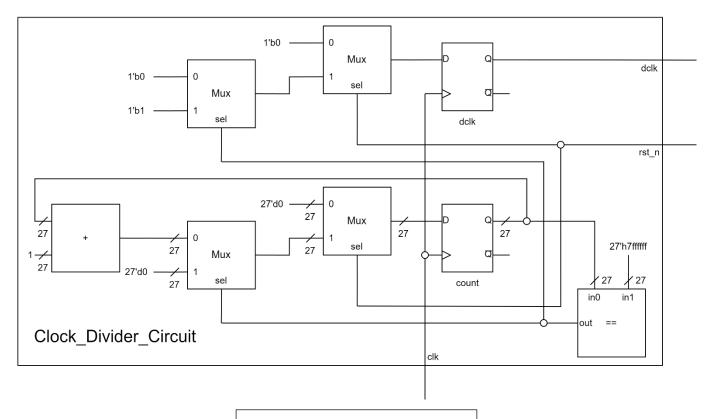
Picture 5.1 FPGA



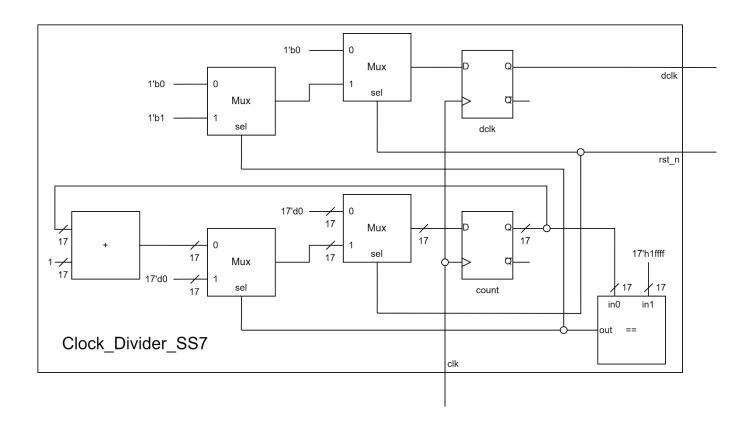


Picture 5.3 Debounce

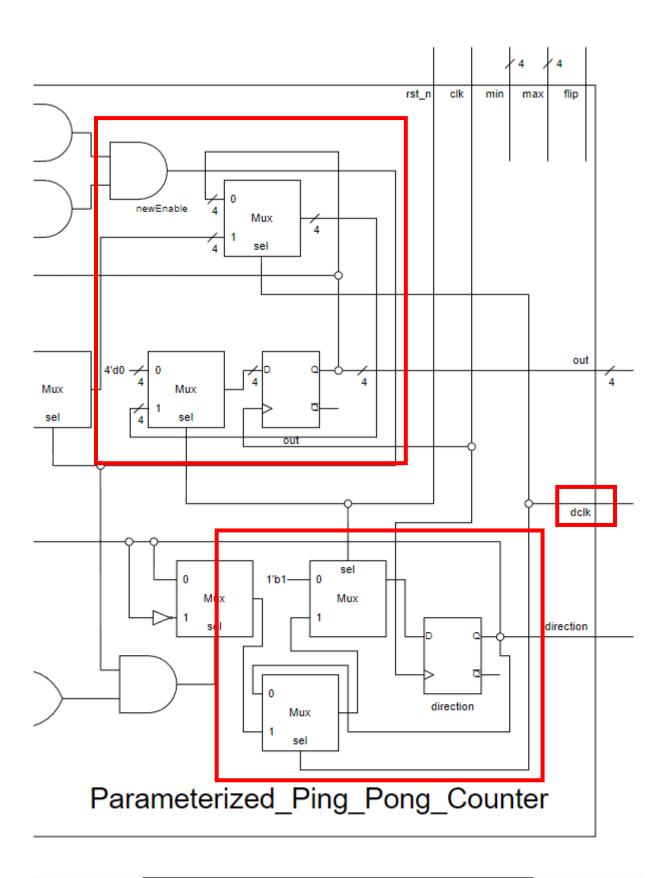




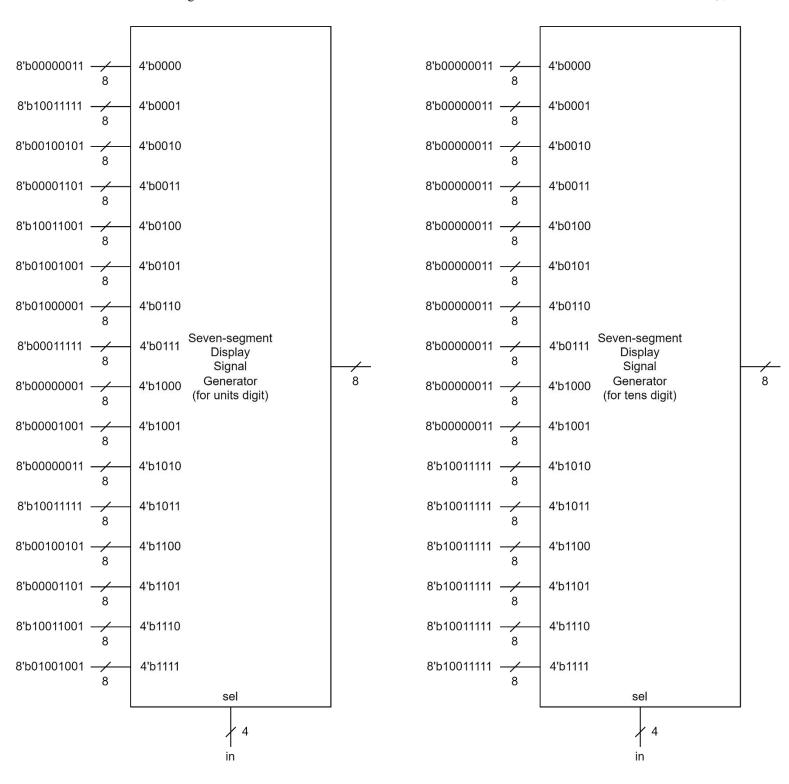
Picture 5.5 Clock_Divider_Circuit

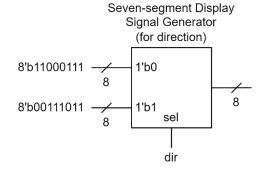


Picture 5.6 Clock_Divider_SS7



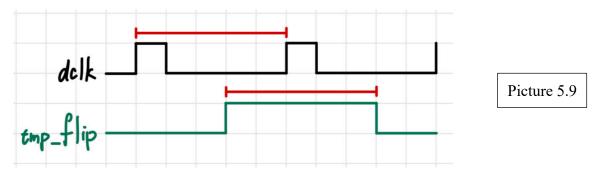
Picture 5.7 Parameterized_Ping_Pong_Counter for FPGA





Picture 5.8 Seven-segment Display Signal Generator

In this problem, there are three clocks with different frequency. Clock_Divider_Circuit generates dclk for 4-bit Parameterized Ping-Pong Counter. Clock_Divider_SS7 generates dclk for seven-segment display. For rst_n, it will reset the counter output to min and direction to 1'b1 depends on the original clock generated by the FPGA board. Therefore, it seems like reset action happens immediately after the reset button being pushed. However, for flip, it is synchronized according to the dclk. Once it detects a one-pulse signal of flip (ssg_flip), tmp_flip will be pulled up and keep for a dclk cycle of the 4-bit Parameterized Ping-Pong Counter. In this way, I can ensure that it must be caught by positive edge of dclk as Picture 5.9.



For **Parameterized_Ping_Pong_Counter** module, I change three different things of it. First is that I add an input port called **dclk** to access the **dclk** generated from **Clock_Divider_Circuit**. And in order to synchronize to the **dclk**, I change the circuit as Picture 5.7 shows to make it work properly.

6. What I Have Learned

In this lab, I learned how to write my code in a good code style, separating combinational circuit and sequential circuit. In **Round-Robin FIFO Arbiter**, I had a big obstacle about how to let **valid** work properly. Therefore, I drew out wave form and analyzed it to help me solve this problem. In FPGA question, I had some strange results while I was debugging. The result seemed not related to my code. Instead, it turned out unexpected. I spent two whole days to think which part went wrong. Finally, I found that according to my original code, if **rst_n** was pulled down, **dclk** would be reset and the **tmp_rst_n** would be set at the same time, which was ambiguous to Verilog. (Originally, I designed **tmp_rst_n** as **tmp_flip** as mentioned above) From this event, I will be more careful about this problem and try not make this error again.