OS Pthread

Implementation

main

```
int main(int argc, char** argv) {
    assert(argc == 4);
    int n = atoi(argv[1]);
    std::string input_file_name(argv[2]);
    std::string output_file_name(argv[3]);
    TSQueue<Item*> reader_queue(READER_QUEUE_SIZE);
    TSQueue<Item*> worker_queue(WORKER_QUEUE_SIZE);
    TSQueue<Item*> writer_queue(WRITER_QUEUE_SIZE);
    Transformer transformer;
    // TODO: implements main function
    Reader* reader = new Reader(n, input_file_name, &reader_queue);
    Producer* producer1 = new Producer(&reader_queue, &worker_queue,
&transformer);
    Producer* producer2 = new Producer(&reader_queue, &worker_queue,
&transformer);
    Producer* producer3 = new Producer(&reader_queue, &worker_queue,
&transformer);
    Producer* producer4 = new Producer(&reader_queue, &worker_queue,
&transformer);
    Writer* writer = new Writer(n, output_file_name, &writer_queue);
    ConsumerController* consumer_controller = new ConsumerController(
        &worker_queue,
        &writer_queue,
        &transformer,
        CONSUMER_CONTROLLER_LOW_THRESHOLD_PERCENTAGE,
        CONSUMER_CONTROLLER_HIGH_THRESHOLD_PERCENTAGE,
        CONSUMER_CONTROLLER_CHECK_PERIOD
    );
    reader->start();
    producer1->start();
    producer2->start();
    producer3->start();
    producer4->start();
    consumer_controller->start();
    writer->start();
    reader->join();
```

```
writer->join();

// Clean up resources
delete reader;
delete producer1;
delete producer2;
delete producer3;
delete producer4;
delete consumer_controller;
delete writer;

return 0;
}
```

首先根據設置好的queue_size宣告reader_queue, worker_queue 以及 output_queue。接著創建 Reader, Producers, Consumer_controller 以及 Writer,依序開始執行。最後等待 Reader 及 Writer 執行結束並釋放資源。

Ts_Queue

TSQueue<T>::TSQueue

TSQueue的建構子,初始化各個變數。

```
template <class T>
TSQueue<T>::TSQueue(int buffer_size) : buffer_size(buffer_size) {
    // TODO: implements TSQueue constructor
    this->buffer = new T[this->buffer_size];
    //this->buffer_size = 0;
    this->head = 0;
    this->size = 0;
    this->size = 0;
    pthread_mutex_init(&this->mutex, nullptr);
    pthread_cond_init(&this->cond_enqueue, nullptr);
    pthread_cond_init(&this->cond_dequeue, nullptr);
}
```

TSQueue<T>::~TSQueue

TSQueue的解構子,釋放各個變數的資源。

```
template <class T>
TSQueue<T>::~TSQueue() {
    // TODO: implements TSQueue destructor
    delete[] buffer;
    pthread_mutex_destroy(&this->mutex);
    pthread_cond_destroy(&this->cond_enqueue);
```

```
pthread_cond_destroy(&this->cond_dequeue);
}
```

TSQueue<T>::enqueue

首先,取得 lock 以避免其他 threads 同時對 queue 進行操作。若 queue 為滿的狀態,則呼叫 pthread_cond_wait(&this->cond_enqueue, &this->mutex),等待其他 threads 進行 dequeue 後 signal。若 queue 仍有空間,則將 item 放入最後端(head處),並更新 size 及 head 的值(這邊採用的是 circular queue)。

```
template <class T>
void TSQueue<T>::enqueue(T item) {
    // TODO: enqueues an element to the end of the queue
    pthread_mutex_lock(&this->mutex);
    while(this->head == this->tail && this->size == this->buffer_size) {
        pthread_cond_wait(&this->cond_enqueue, &this->mutex);
    }
    this->buffer[this->head] = item;
    this->head = (this->head + 1) % this->buffer_size;
    this->size++;
    pthread_cond_signal(&this->cond_dequeue);
    pthread_mutex_unlock(&this->mutex);
}
```

TSQueue<T>::dequeue

首先,取得 lock 以避免其他 threads 同時對 queue 進行操作。若 queue 為空,則呼叫 pthread_cond_wait(&this->cond_dequeue, &this->mutex),等待其他 threads 進行 enqueue 後 signal。若仍有 items 在 queue 之中,則將最前端的 item 取出(tail處),更新 size 及 tail 的值(這邊採用的是 circular queue),最後將取出的 item 回傳。

```
template <class T>
TSQueue<T>::dequeue() {
    // TODO: dequeues the first element of the queue
    pthread_mutex_lock(&this->mutex);
    while(this->tail == this->head && this->size == 0){
        pthread_cond_wait(&this->cond_dequeue, &this->mutex);
    }
    T item = this->buffer[this->tail];
    this->tail = (this->tail + 1) % this->buffer_size;
    this->size--;
    pthread_cond_signal(&this->cond_enqueue);
    pthread_mutex_unlock(&this->mutex);
    return item;
}
```

回傳 private 變數 size,用以取得目前 queue 中 item 的數量。

```
template <class T>
int TSQueue<T>::get_size() {
    // TODO: returns the size of the queue
    pthread_mutex_lock(&mutex);
    int current_size = this->size;
    pthread_mutex_unlock(&mutex);
    return current_size;
}
```

Reader

No implement

根據 expected_lines,依次從檔案流(ifs)中讀取指定行數的資料。為每一行資料動態分配一個 Item 物件,並將初始化完成的 Item 放入input_queue,供後續處理使用(enqueue)。

```
void* Reader::process(void* arg) {
   Reader* reader = (Reader*)arg;
   while (reader->expected_lines--) {
        Item *item = new Item;
        reader->ifs >> *item;
        reader->input_queue->enqueue(item);
   }
   return nullptr;
}
```

Producer

Producer::start

創建執行 Producer::process 的 Producer thread

```
void Producer::start() {
    // TODO: starts a Producer thread
    pthread_create(&t, 0, Producer::process, (void*)this);
}
```

Producer::process

從 input_queue 中 dequeue,取出最前端的item。接著將 item->opcode 及 item->val 傳入 producer_transform 並將 item->val 更新為回傳值。最後,將 item 放入 worker queue 中(enqueue)。

```
void* Producer::process(void* arg) {
    // TODO: implements the Producer's work
    Producer* producer = (Producer*)arg;

    while(true) {
        Item * item = producer->input_queue->dequeue();
        item->val = producer->transformer->producer_transform(item->opcode, item->val);
        producer->worker_queue->enqueue(item);
    }
    return nullptr;
}
```

Consumer_controller

ConsumerController::start

創建執行 ConsumerController::process 的 ConsumerController thread

```
void ConsumerController::start() {
    // TODO: starts a ConsumerController thread
    pthread_create(&t, 0, ConsumerController::process, (void*)this);
}
```

ConsumerController::process

每 CONSUMER_CONTROLLER_CHECK_PERIOD 微秒檢查一次 worker_queue 的狀態。如果 worker_queue 中 item 的數量超過 high_threshold(%),則創建一個新的 Consumer thread 來處理工作。反之,如果 worker_queue 中 item 的數量低於 low_threshold(%),則將最新創建的 Consumer thread 砍掉(透過呼叫 Consumer->cancel 方法),此時須確保至少仍有一個 Consumer 在運作。其中,我們使用 ConsumerController::consumers 來紀錄目前正在執行的 Consumer 清單,確保其狀態正確。

```
new_consumer->start(); // Start the consumer thread
            controller->consumers.push_back(new_consumer);
            std::cout << "Scaling up consumers from "<< controller-</pre>
>consumers.size() - 1 << " to " << controller->consumers.size() <<</pre>
std::endl;
        // Scale down consumers if the worker queue falls below the low
threshold
        else if (worker_queue_size < controller->worker_queue->buffer_size
* controller->low_threshold / 100 && controller->consumers.size() > 1) {
            // Remove the most recently added consumer
            Consumer* last_consumer = controller->consumers.back();
            last_consumer->cancel(); // Cancel the consumer thread
            last_consumer->join(); // Wait for the thread to finish
            //delete last_consumer; // Free memory
            controller->consumers.pop_back();
            std::cout << "Scaling down consumers from "<< controller-</pre>
>consumers.size() + 1 << " to " << controller->consumers.size() <<</pre>
std::endl;
        }
        // Ensure there is always at least one consumer
        // Sleep for the check period
        usleep(controller->check_period);
    }
    return nullptr;
}
```

Consumer

Consumer::start

創建執行 Consumer::process 的 consumer thread

```
void Consumer::start() {
    // TODO: starts a Consumer thread
    pthread_create(&t, 0, Consumer::process, (void*)this);
}
```

Consumer::cancel

將 consumer 中的 is_cancel 設為 true,代表該 consumer 即將被砍掉。

```
int Consumer::cancel() {
   is_cancel = true;
   return 0;
}
```

Consumer::process

將 thread 的取消型態設定為「延遲型」(PTHREAD_CANCEL_DEFERRED),表示 thread 僅在安全點(如 pthread_testcancel)檢查取消請求。

在 consumer 處理工作項目時(consumer->is_cancel == false)禁用取消狀態,確保工作不會在處裡過程中因 thread 被取消而被中斷。

若 consumer->is_cancel 為 false,則從 worker_queue 中 dequeue,取出最前端的item。接著將 item->opcode 及 item->val 傳入 consumer_transform 並將 item->val 更新為回傳值。最後,將 item 放入 output_queue 中 (enqueue)。

在完成工作邏輯後將 thread 恢復到可以取消的狀態,使其能夠接收取消請求。

```
void* Consumer::process(void* arg) {
   Consumer* consumer = (Consumer*)arg;
   pthread_setcanceltype(PTHREAD_CANCEL_DEFERRED, nullptr);
   while (!consumer->is_cancel) {
        // TODO: implements the Consumer's work
        pthread_setcancelstate(PTHREAD_CANCEL_DISABLE, nullptr);
        Item *item = consumer->worker_queue->dequeue();
        item->val = consumer->transformer->consumer_transform(item->opcode,
item->val);
        consumer->output_queue->enqueue(item);
        pthread_setcancelstate(PTHREAD_CANCEL_ENABLE, nullptr);
   }
   delete consumer;
   return nullptr;
}
```

Writer

Writer::start

創建執行 Writer::process 的 writer thread

```
void Writer::start() {
    // TODO: starts a Writer thread
    pthread_create(&t, 0, Writer::process, (void*)this);
}
```

Writer::process

從 output_queue 中 dequeue,取出最前端的item。接著將 item 傳入輸出流(ofs)中輸出。

```
void* Writer::process(void* arg) {
    // TODO: implements the Writer's work
    Writer* writer = (Writer*)arg;
    while(writer->expected_lines--){
        Item* item = writer->output_queue->dequeue();
        writer->ofs << *item;
        delete item;
    }
    return nullptr;
}</pre>
```

Experiment

Different values of CONSUMER_CONTROLLER_CHECK_PERIOD

Discussion

減少 check period time 可以更及時的分配資源,因此可以增快執行速度,但是太過頻繁的檢查並調度也會花費更多的時間,因此可以在 test 01 1/10 times check period 的測試中看到,其執行速度沒有比 1/2 times check period 的速度更快,因此 check period time 應該是有一個最佳表現區間,太大或太小都會導致執行速度低落。

Result

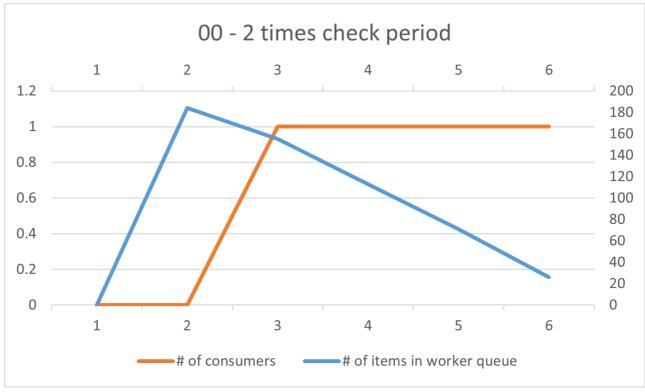
· test 00 Runtime

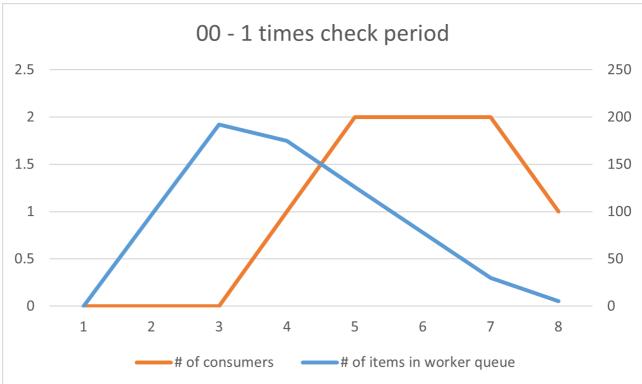
Check period	Runtime
2 times	11.1133
1 times	7.25883
1/2 times	5.39247
1/10 times	3.46049

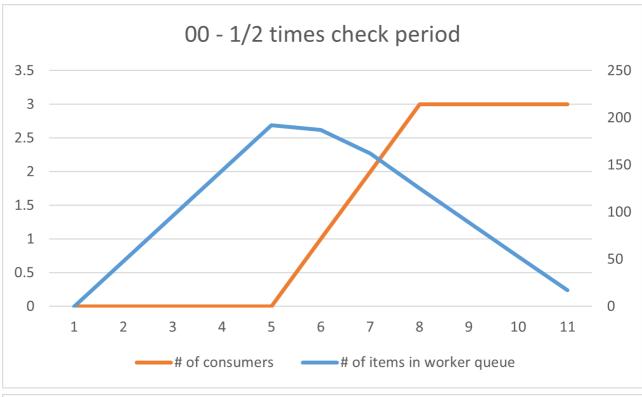
• test 01 Runtime

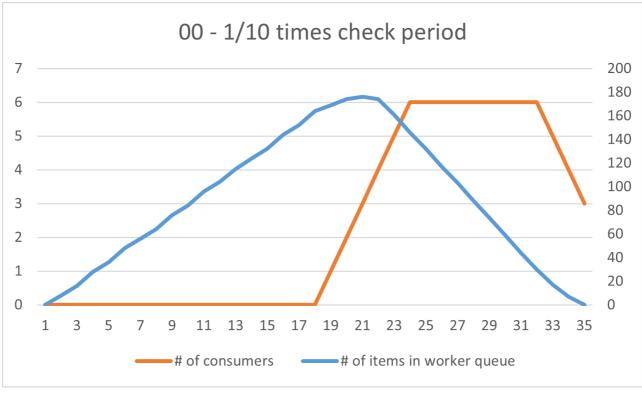
Check period	Runtime
2 times	68.8665
1 times	59.7507
1/2 times	52.8105
1/10 times	52.8789

• test 00 Figures

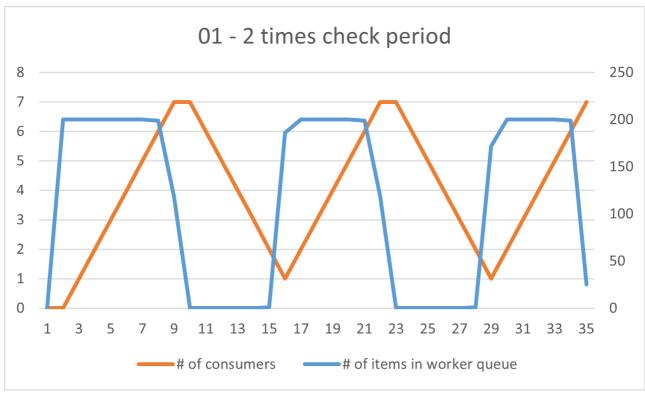


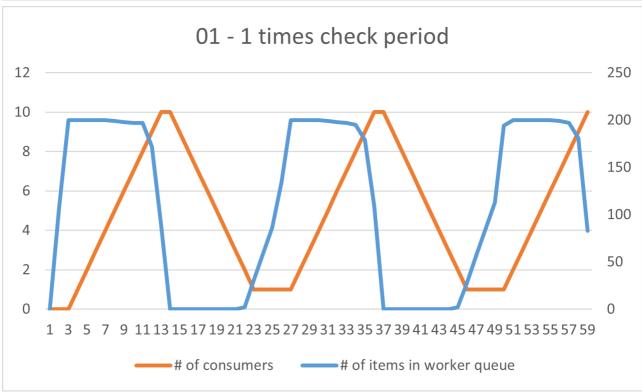


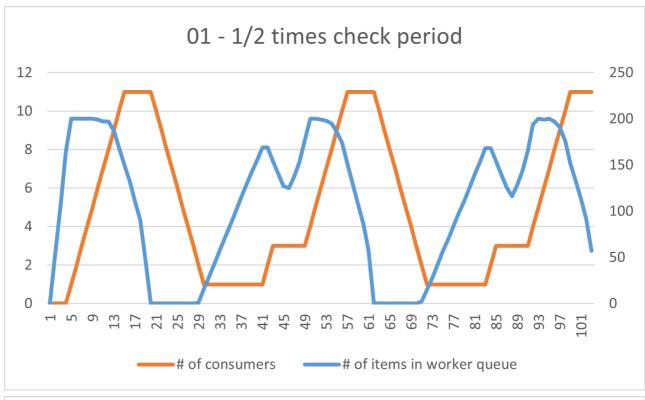


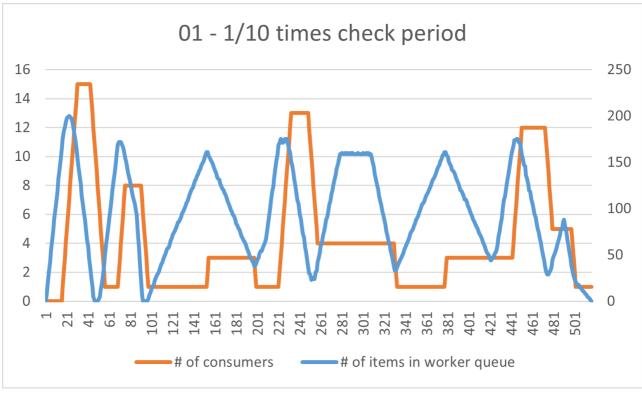


• test 01 Figures









Different values of CONSUMER_CONTROLLER_LOW_THRESHOLD_PERCENTAGE and CONSUMER_CONTROLLER_HIGH_THRESHOLD_PERCENTAGE

Discussion

從 test 00 看起來,較小的 min threshold 與較小的 max threshold 執行速度更快,但當數量放大之後,從 test 01 的結果可以看出,這兩個 threshold 的設置對於執行速度上的影響甚微。

Result

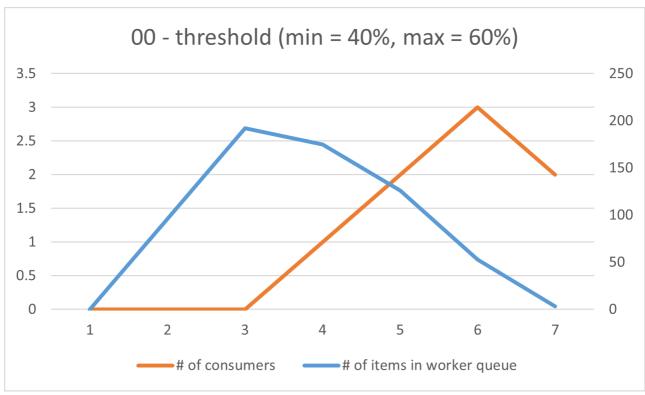
· test 00 Runtime

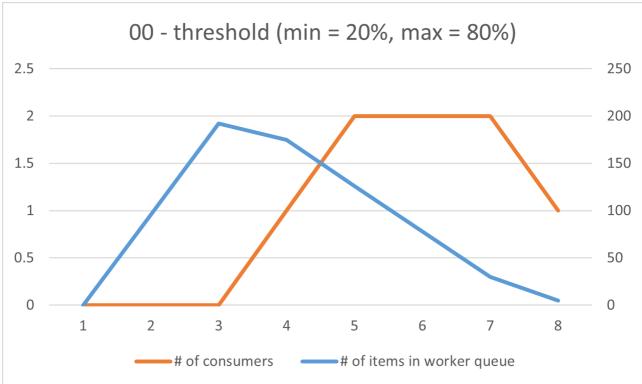
Threshold (min, max)	Runtime
(40%, 60%)	6.17829
(20%, 80%)	7.25883
(20%, 60%)	5.77848
(40%, 80%)	8.25213

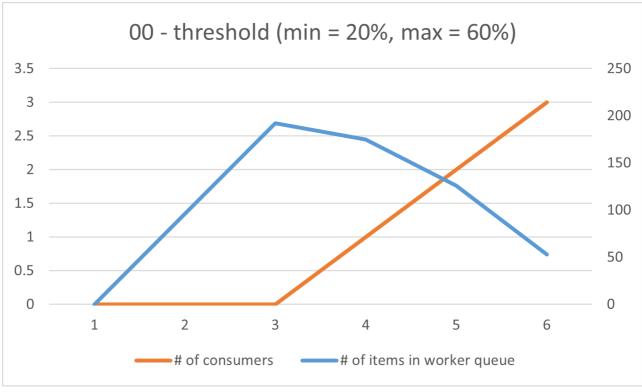
• test 01 Runtime

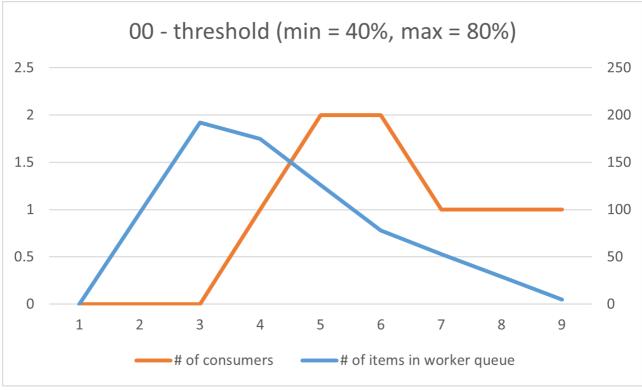
Threshold (min, max)	Runtime
(40%, 60%)	58.9171
(20%, 80%)	59.7507
(20%, 60%)	58.7007
(40%, 80%)	59.7340

• test 00 Figures

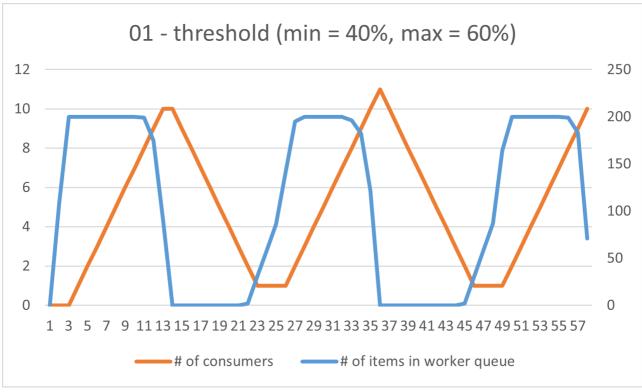


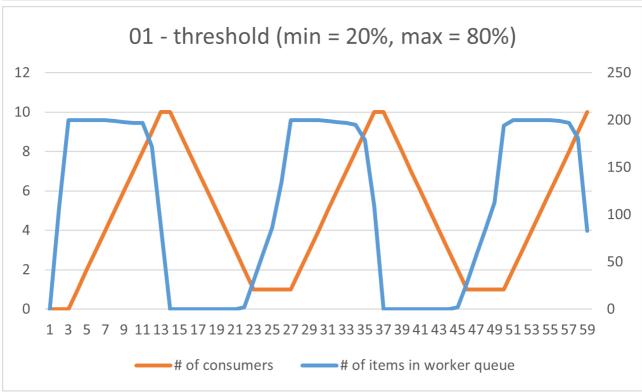


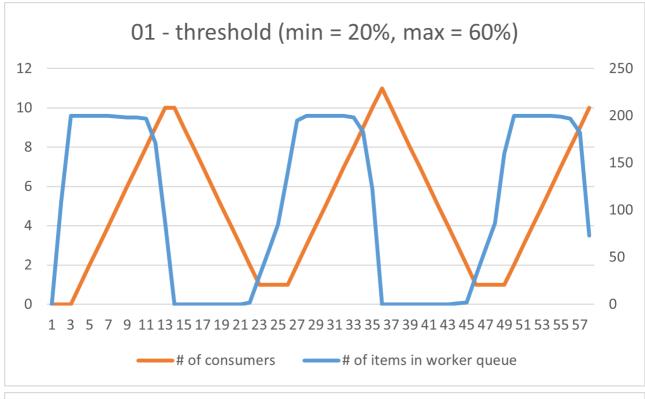


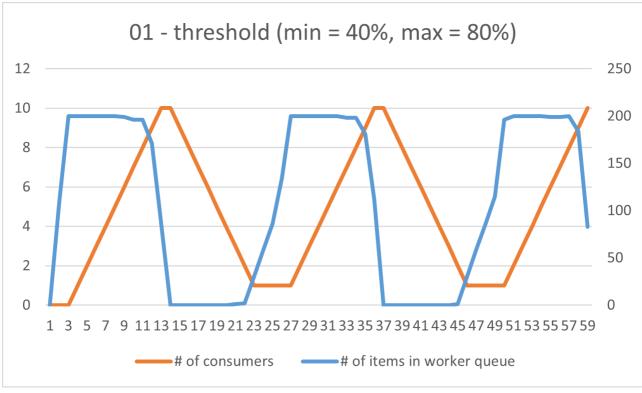


• test 01 Figures









Different values of WORKER_QUEUE_SIZE

Discussion

Worker queue size 設定的大一點,雖然能增加處理更多 items 的能力,但當 work queue size 太大的時候會導致 consumer controler 沒有創建 consumer 或是 consumer 數量增長延遲的情況。

Result

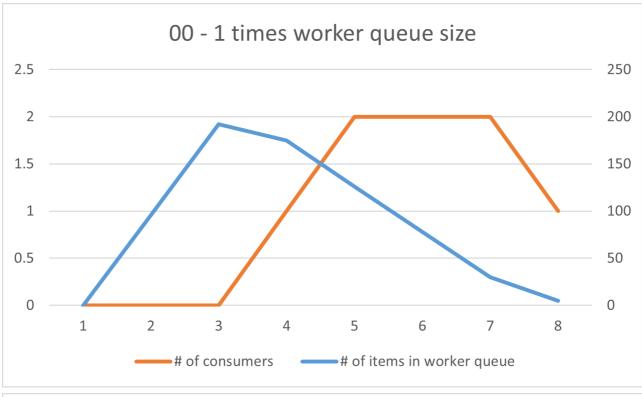
· test 00 Runtime

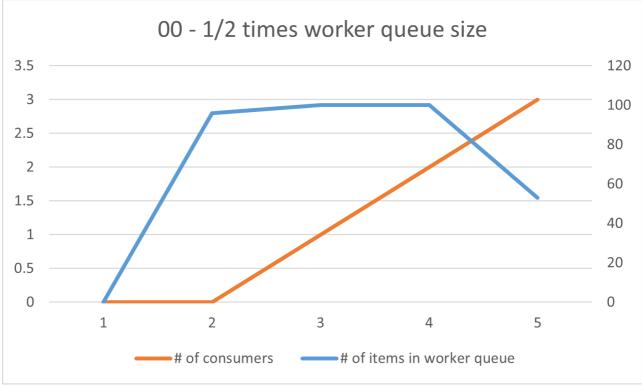
Work queue size	Runtime
2 times	Infinity (never end)
1 times	7.25883
1/2 times	4.77562

• test 01 Runtime

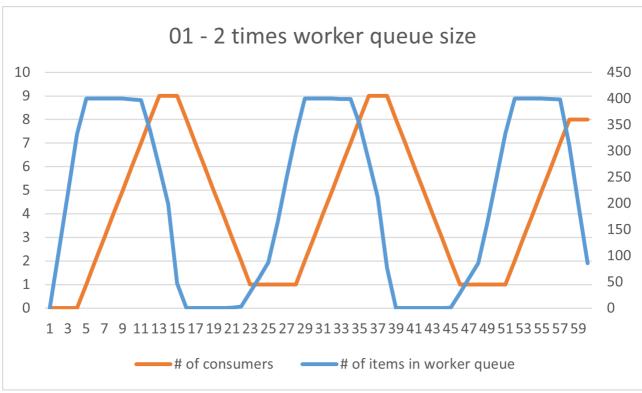
Work queue size	Runtime
2 times	60.4075
1 times	59.7507
1/2 times	56.7949

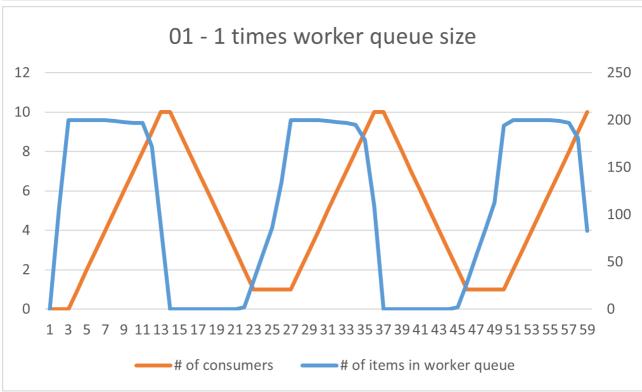
• test 00 Figures

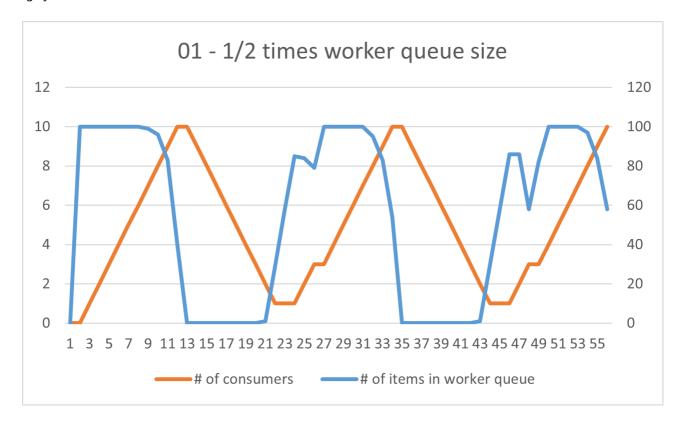




• test 01 Figures







What happens if WRITER_QUEUE_SIZE is very small?

1/4 times original writer queue size

Discussion

好像不會怎樣?

Result



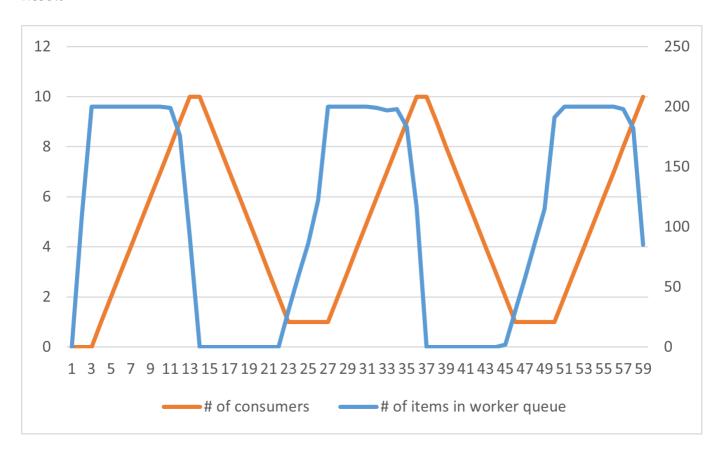
What happens if READER_QUEUE_SIZE is very small?

1/4 times original reader queue size

Discussion

好像不會怎樣?

Result



What difficulties did you encounter when implementing this assignment?

feedback