## Signals and Systems

Homework 12 — Due : May 31 2024

**Problem 1** (20 pts). Given that

$$e^{-at}u(t) \longleftrightarrow \frac{\mathfrak{L}}{s+a}, \quad \mathbf{Re}\{s\} > \mathbf{Re}\{-a\},$$

determine the function of time, x(t), for the following Laplace transforms:

(a) 
$$\frac{s+2}{s^2+7s+12}$$
,  $\mathbf{Re}\{s\} < -4$ 

(b) 
$$\frac{s+1}{s^2+5s+6}$$
,  $-3 < \mathbf{Re}\{s\} < -2$ 

**Problem 2** (20 pts). We are given the following five facts about a real signal x(t) with Laplace transform X(s):

- 1. X(s) has exactly two poles.
- 2. X(s) has no zeros in the finite s-plane.
- 3. X(s) has a pole at s = 2 + j.
- 4. X(0) = 5.
- 5.  $e^{-3t}x(t)$  is not absolutely integrable.

Determine X(s) and specify its region of convergence.

**Problem 3** (20 pts). A causal LTI system with impulse response h(t) has the following properties:

- 1. When the input to the system is  $x(t) = e^{2t}$  for all t, the output is  $y(t) = (1/6)e^{2t}$  for all t.
- 2. The impulse response h(t) satisfies the differential equation

$$\frac{d}{dt}h(t) + 2h(t) = e^{-4t}u(t) + bu(t),$$

where b is an unknown constant.

Determine the system function H(s) of the system, consistent with the information above. (There should be no unknown constants in your answer.)

**Problem 4** (10 pts). Consider the system characterized by the differential equation

$$\frac{d^2}{dt^2}y(t) + 3\frac{d}{dt}y(t) + 2y(t) = x(t),$$

with initial conditions y(-1) = 1 and  $\frac{d}{dt}y(t)\big|_{t=-1} = -1$ . What is the output of the system with input x(t) = 3u(t+1)?

**Problem 5** (30 pts). Consider the following sub-problems:

- (a) Find the inverse Laplace transform of  $\frac{s}{(s+1)(s-1)}$ , ROC:  $\mathbf{Re}\{s\} > 1$ . Let the answer be  $x_1(t)$ .
- (b) Find the inverse Laplace transform of  $\frac{s-1}{(s+1)s}$ , ROC:  $-1 < \mathbf{Re}\{s\} < 1 1 < \mathbf{Re}\{s\} < 0$ . Let the answer be  $x_2(t)$ .
- (c) Find  $x_1(t) * x_2(t)$ .

**Problem 1** (20 pts). Given that

(a)  $\frac{s+2}{s^2+7s+12}$ ,  $\mathbf{Re}\{s\} < -4$ 

determine the function of time, x(t), for the following Laplace transforms:

 $e^{-at}u(t) \xleftarrow{\mathfrak{L}} \frac{1}{a+a}, \quad \mathbf{Re}\{s\} > \mathbf{Re}\{-a\},$ 

$$\frac{s+2}{s^2+7s+12} = \frac{s+2}{(s+3)(s+4)} = \frac{-1}{s+3} + \frac{2}{s+4}, Re[s] < -4$$

$$\chi(t) = e^{-t}u(-t) - 2 e^{-t}u(-t)$$

(b) 
$$\frac{s+1}{s^2+5s+6}$$
,  $-3 < \text{Re}\{s\} < -2$ 

$$\frac{s+1}{s^2+5s+6}, \quad -3 < \text{Re}\{s\} < -2$$

$$\mathbf{S+1} \qquad \qquad \mathbf{S+1} \qquad \qquad \mathbf{S+1} \qquad \qquad \mathbf{-}$$

$$\frac{|s+1|}{|s^2+5s+6|} = \frac{|s+1|}{|(s+2)(s+3)|} = \frac{-1}{|s+2|} + \frac{2}{|s+3|}, \quad -3 < \Re\{s\} < -2$$

$$\chi(t) = e^{-2t}u(-t) + 2e^{-3t}u(t)$$

1. X(s) has exactly two poles.

- 2. X(s) has no zeros in the finite s-plane.
- 4. X(0) = 5.

3. X(s) has a pole at s = 2 + j.

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$$\chi(s) = \frac{k}{(s-2-j)(s-2+j)}, \quad \chi(0) = \frac{k}{(-2-j)(-2+j)} = \frac{k}{s} = s, \quad k = 2s, \quad k = 5$$

$$\chi(s) = \frac{2s}{(s-2-j)(s-2+j)} = \frac{\frac{2s}{2j}}{s-2-j} - \frac{\frac{2s}{2j}}{s-2+j} = \frac{2s}{2j} \left(\frac{1}{s-(2+j)} - \frac{1}{s-(2-j)}\right)$$

5. 
$$e^{-3t}x(t)$$
 is not absolutely integrable

 $\chi(t) = \frac{25}{2i} \left( -e^{(2+i)t} + e^{(2-i)t} \right) u(-t) = \frac{25}{2i} e^{2t} \left( e^{-it} - e^{it} \right) u(-t) = -25 \sin(t) \cdot u(-t)$ 

**Problem 2** (20 pts). We are given the following five facts about a real signal 
$$x(t)$$
 with Laplace transform  $X(s)$ :

1.  $X(s)$  has exactly two poles.







**Problem 3** (20 pts). A causal LTI system with impulse response h(t) has the following properties:

- 1. When the input to the system is  $x(t) = e^{2t}$  for all t, the output is  $y(t) = (1/6)e^{2t}$  for all t.
- 2. The impulse response h(t) satisfies the differential equation

$$\frac{d}{dt}h(t) + 2h(t) = e^{-4t}u(t) + bu(t),$$

where b is an unknown constant.

Determine the system function H(s) of the system, consistent with the information above. (There should be no unknown constants in your answer.)

$$g H(s) + 2 H(s) = \frac{1}{3+4} + \frac{b}{s}$$

$$H(s) = \frac{1}{(s+2)(s+4)} + \frac{b}{s(s+2)} = \frac{\frac{1}{2}}{s+2} - \frac{\frac{1}{2}}{s+4} + \frac{\frac{b}{2}}{s} - \frac{\frac{b}{2}}{s+2}$$

$$H(2) = \frac{1}{24} + \frac{b}{8} = \frac{1}{6}$$
,  $b = 1$   
 $\Rightarrow H(s) = \frac{2s+4}{s(s+2)(s+4)} = \frac{2}{s(s+4)}$ 

$$\frac{d^2}{dt^2}y(t) + 3\frac{d}{dt}y(t) + 2y(t) = x(t),$$

Let  $Y_1(t) = Y_1(t-1)$ ,  $Y_1(t) = Y_1(t-1)$ ,  $\frac{d^2}{dt^2} Y_1(t) + 3 \frac{d}{dt} Y_1(t) + 2 Y_1(t) = Y_1(t)$ 

 $dt^{2}$ 

 $e^{st} \longrightarrow H(s) e^{st} \Rightarrow e^{zt} \longrightarrow H(2) e^{zt}$ 

with initial conditions 
$$y(-1) = 1$$
 and  $\frac{d}{dt}y(t)\big|_{t=-1} = -1$ . What is the output of the system with input  $x(t) = 3u(t+1)$ ?

$$\frac{d^{2}}{dt^{2}} \chi(t-1) + 3 \frac{d}{dt} \chi(t-1) + 2 \chi(t-1) = \chi(t-1) \cdot 2et \chi(t) = 3 u(t), \chi(t) = 3 u(t+1)$$

$$15 \frac{d}{dt} u(t)^{2} - 2 \chi(t) - u(t) = 3 u(t) \cdot \chi(t) = 3 u(t+1)$$

$$\mathcal{L}\left\{\frac{d}{dt}y_{i}(t)\right\} = SY_{i}(S) - y_{i}(0) + \mathcal{L}\left\{\frac{d^{2}}{dt^{2}}y_{i}(t)\right\} = S^{2}Y_{i}(S) - Sy_{i}(0) - y_{i}(0)$$

$$S^{2}Y_{i}(S) - S + | + 3SY_{i}(S) - 3 + 2Y_{i}(S) = \frac{3}{S}$$

$$Y_{1}(s) = \frac{3}{s(s+1)(s+2)} + \frac{s+2}{(s+1)(s+2)} = \frac{3}{2} \cdot \frac{1}{s} - 3 \cdot \frac{1}{s+1} + \frac{3}{2} \cdot \frac{1}{s+2} + \frac{1}{s+1}$$

$$Y_{1}(t) = Y(t-1) = \left(\frac{3}{2} - 2e^{-t} + \frac{3}{2}e^{2t}\right) u(t)$$

$$y_1(t) = y(t-1) = \left(\frac{3}{2} - 2e^{-t} + \frac{3}{2}e^{-2t}\right) u(t)$$

$$y(t) = \left(\frac{3}{2} - 2e^{-(t+1)} + \frac{3}{2}e^{-2(t+1)}\right) u(t+1)$$

