PROBKB Web-Scale Probabilistic Knowledge Base

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Outline

Introduction Introduction

The PROBKB System
PROBKB Architecture
Grounding
Inference



Knowledge bases-Introduction

- A knowledge base is a collection of entities, facts, and relationships that conforms with a certain data model.
- A knowledge base helps machines understand humans, languages, and the world.





Figure: Google knowledge graph



Challenges & Motivation Knowledge Acquisition

- Statistical Inference
 - Markov logic
- Information extraction
 - NELL (CMU), OpenIE (UW)
 - Entities, relations, rules
- Human collaboration
 - Wikipedia
 - Freebase



Challenges & Motivation Uncertainty Management

- Statistical Inference
 - Probabilistic graphical models
 - Markov chain Monte Carlo
- Data integration
 - Merging multiple data sources
 - Crowdsourcing/user feedback
- Data cleaning
 - Conflict, incomplete, outdated data



Challenges & Motivation Scalability

- Scalable data management systems
 - Relational DBMS
 - Hadoop
 - Spark, GraphLab, Datapath, etc
- Scalable algorithms
 - Incremental inference
 - Query-driven inference





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Introduction
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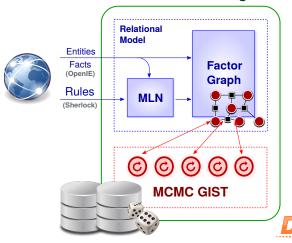
The PROBKB System PROBKB Architecture

Grounding Inference



Architecture

PROBabilistic Knowledge Base



Markov Logic-Probabilistic Inference Framework

A *Markov logic network* (MLN) is a set of formulae with weights. Together with a finite set of constants $C = \{c_1, \ldots, c_{|C|}\}$, it defines a Markov network.

| Weight | First-Order Logic |
|--------|---|
| 0.7 | $Fr(x,y) \land Fr(y,z) \rightarrow Fr(x,z)$ |
| 1.5 | $Sm(x) \rightarrow Ca(x)$ |
| 1.1 | $\operatorname{Fr}(x,y) \wedge \operatorname{Sm}(x) \rightarrow \operatorname{Sm}(y)$ |

A set of constants (entities, or objects)

Table: Example Markov logic network.

$$C = \{A, B\}.$$

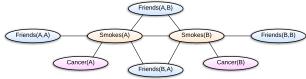


Figure: Grounded Markov network.



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Grounding

Grounding is the process of substituting constants into MLN clauses.

The result of grounding is a *factor graph* (or *Markov network*) from which we can infer marginal probabilities for individual facts.

Key Challenges

- Time-consuming, especially if the numbers of rules and entites are large.
- Grounded network has an intractably large size, making inference tasks slow.





Markov Logic: A Relational Point of View

- State-of-the-art (TUFFY, NELL): one table for each relation
- By considering only Horn clauses, we store the rules and relationships in a few tables:

Table: MLN (M)

| head | body1 | body2 | |
|-------|-------|-------|--|
| p_1 | q_1 | r_1 | |
| p_2 | q_2 | r_2 | |
| p_3 | q_3 | r_3 | |
| p_4 | q_4 | r_4 | |
| | | | |

Table: Relationships (R)

| pred | ent1 | ent2 |
|-------|-------|-------|
| p_1 | x_1 | y_1 |
| p_1 | x_2 | y_2 |
| p_2 | x_1 | y_1 |
| p_2 | x_2 | y_2 |
| | | |



Markov Logic: A Relational Pointer of View

The grounding of ALL rules of form

$$p(x,y) \leftarrow q(x,z), r(z,y)$$

is then expressed as a relational operation:

$$R \leftarrow \rho_{R(\text{pred,ent1,ent2})}(\pi_{M.\text{head},R_2.\text{ent1},R_3.\text{ent2}})$$
 (1)
 $((M \bowtie_{M.\text{body1}=R_2.\text{pred}} R_2)$
 $\bowtie_{M.\text{body2}=R_3.\text{pred AND } R_2.\text{ent2}=R_3.\text{ent1}} R_3))$
 $G \leftarrow R_1 \bowtie R$





Grounding Results

The relational Markov logic model saves us from managing thousands of tables as in previous approaches. As a result, We grounded the Sherlock-Holmes dataset in 85 seconds using Greenplum, while the state-of-the-art implementation MLN crashes during its grouding phase.

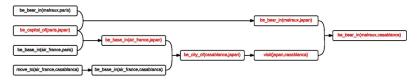
| #entities | 480K | |
|----------------|--------|--|
| #relations | 10,672 | |
| #relationships | 5K | |
| #rules | 31,000 | |
| Tuffy | Crash | |
| ProbKB | 85s | |

Table: Dataset statistics and performance.



Evaluation

- We learned 100K facts from the original 5K.
- Not all results are correct; errors propagate.



- Errors come from word ambiguity, incorrect extractions and rules.
- Need pruning and re-evaluating.



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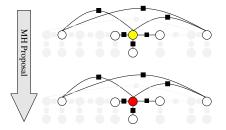
The PROBKB System

PROBKB Architecture Grounding

Inference



Inference: MCMC-MH



Markov locality property allows for parallel computing.



Datapath GIST

Generalized Iterable State Transforms (GIST)

• GIST Performs *transitions* upon a *state* until that state has converged to the desired result.

Transition MCMC Proposal function.

State Factor graph with its samples.

- A user-defined local scheduler allows general MCMC proposal implementation.
- The GIST state keeps track of the inference result.



Datapath GIST

Parallel Mcmc implementation modification on datapath

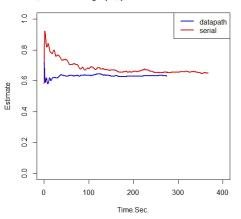
- Previous approach: cut the graph to smaller graphs, run mcmc on each partition.
 - Lost information when a factor is accross multiple subgraphs. Inaccurate, but the faster performance.
- Modified approach: Do not cut the graph. Add write lock on each variables.
 - More accurate, but lower performance.





Parallel mcmc with write lock in datapath

50,000 vertices graph, parallel mcmc with write lock

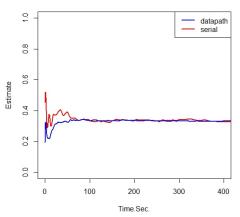






Parallel mcmc with write lock in datapath

50,000 vertices graph, parallel mcmc with write lock





Preliminary Results

| # Vertices | 5000 | 10,000 | 25,000 | 250,000 | 2,500,000 |
|---------------|-------|--------|---------|----------|-----------|
| Single Thread | 7 sec | 28 sec | 228 sec | Hours | N/A |
| Datapath | 7 sec | 13 sec | 30 sec | 2661 sec | N/A |

Table: Time to generate 5000 joint samples for different graphs.



Responsibilities

Yang Grounding Xing Inference



Questions?

Thank you!

