# EC708 Discussion 8 Non-Regular Estimators

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Non-Regular Estimators

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Hodges Super-Efficient Estimator

Suppose  $(X_1,\ldots,X_T)\stackrel{\text{i.i.d.}}{\sim} N(\theta_0,1)$ . Define

$$\hat{\theta}_T = \begin{cases} \bar{X}_T & \text{if } |\bar{X}_T| \ge T^{-1/4} \\ 0 & \text{if } |\bar{X}_T| < T^{-1/4} \end{cases}.$$

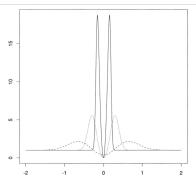
Why truncate? Note that  $\sqrt{T}(\bar{X}_T - \theta_0) \sim N(0, 1)$ .

$$\begin{split} \Pr(\hat{\theta}_T = 0) &= \Pr(|\bar{X}_T| < T^{-1/4}) \\ &= \Phi(\sqrt{T}(T^{-1/4} - \theta_0)) - \Phi(\sqrt{T}(-T^{-1/4} - \theta_0)). \end{split}$$

- If  $\theta_0 \neq 0$ ,  $\Pr(\hat{\theta}_T = 0) \rightarrow 0 \Rightarrow \hat{\theta}_T$  behaves the same as  $\bar{X}_T$ .
- If  $\theta_0=0$ ,  $\Pr(\hat{\theta}_T=0)\to 1\Rightarrow \hat{\theta}_T$  converges to  $\theta_0$  "arbitrarily fast".

Hodges Super-Efficient Estimator

- Quadratic risk function:  $\theta_0 \mapsto E_{\theta_0}(\hat{\theta}_T \theta_0)^2$
- $\hat{\theta}_T$  "buys" its better asymptotic behavior at  $\theta_0 = 0$  at the expense of erratic behavior close to zero



**Figure 8.1.** Quadratic risk functions of the Hodges estimator based on the means of samples of size 10 (dashed), 100 (dotted), and 1000 (solid) observations from the  $N(\theta, 1)$ -distribution.

Hodges Super-Efficient Estimator

Is  $\hat{\theta}_T$  regular? Consider  $\theta_T = h/\sqrt{T}$  and  $(X_1, \dots, X_T) \overset{\text{i.i.d.}}{\sim} N(\theta_T, 1)$ . Then,

$$\sqrt{T}(\bar{X}_T - \theta_T) = \sqrt{T}\bar{X}_t - h \sim N(0, 1).$$

Hence,

$$\Pr(\hat{\theta}_T = 0) = \Pr(|\bar{X}_T| < T^{-1/4})$$
  
=  $\Phi(T^{1/4} - h) - \Phi(-T^{1/4} - h) \to 1.$ 

This implies

$$\sqrt{T}(\hat{\theta}_T - \theta_T) \stackrel{d}{\to} -h \quad \Rightarrow \quad \hat{\theta}_T \text{ is not regular.}$$

Post Model Selection Estimator

#### Consider the linear model:

$$Y_t = D_t \alpha + X_t' \beta + U_t, \quad E[U_t | D_t, X_t] = 0.$$

- $D_t$ : treatment/policy variable of interest
- $X_t$ :  $p \times 1$  control variables, where p can be larger than T:  $p \gg T$ .
- Approximate sparsity assumption:  $D_t$  is exogenous after controlling for a small number s < T of variables in  $X_t$
- Natural idea: variable selection via Lasso

Post Model Selection Estimator

#### Lasso solves

$$(\hat{\alpha}, \hat{\beta}) = \underset{\alpha \in \mathbb{R}, \beta \in \mathbb{R}^p}{\min} \sum_{t=1}^{T} (Y_t - D_t \alpha - X_t' \beta)^2 + \lambda \sum_{j=1}^{p} |l_j \beta_j|,$$

where  $\lambda$  is penalty level and  $l_i$ 's are loadings.

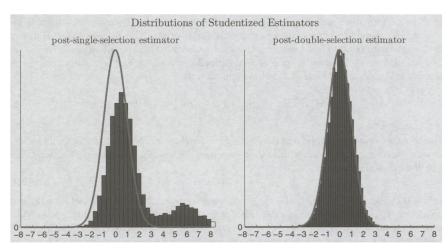
- Non-differentiability of the penalty function at zero induces  $\hat{\beta}$  to have components set exactly to zero
- Let  $\hat{I}$  denote the nonzero components of  $\hat{\beta} \Rightarrow$  selected controls
- Post-single-selection estimator  $\tilde{\alpha}$  of  $\alpha$ :

$$(\tilde{\alpha}, \tilde{\beta}) = \operatorname*{arg\,min}_{\alpha \in \mathbb{R}, \beta \in \mathbb{R}^p} \Big\{ \sum_{t=1}^T (Y_t - D_t \alpha - X_t' \beta)^2 : \beta_j = 0, \forall j \notin \hat{I} \Big\}.$$

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Post Model Selection Estimator

#### Conventional t-test based on $\tilde{\alpha}$ has size distortion (left panel)



Post Model Selection Estimator

What are the problems with the naive single selection approach?

- It ignores the relationship between  $D_t$  and  $X_t$
- It is based on a "structural model" where the target is to learn the treatment effects given controls, while Lasso targets prediction
- ⇒ Work with a reduced form, predictive equation system:

$$Y_t = D_t \alpha + X_t' \beta + U_t = X_t' (\underbrace{\alpha \pi + \beta}_{=\theta}) + \underbrace{\alpha V_t + U_t}_{=\varepsilon_t},$$

$$D_t = X_t' \pi + V_t,$$

where  $E[\varepsilon_t|X_t]=0$  and  $E[V_t|X_t]=0$ .

Post Model Selection Estimator

#### **Double selection procedure** (Belloni, Chernozhukov, and Hansen, 2014):

• Select controls that predict  $D_t \Rightarrow \hat{I}_1$ :

$$\min_{\pi \in \mathbb{R}^p} \sum_{t=1}^T (D_t - X_t' \pi)^2 + \lambda \sum_{j=1}^p |l_j^d \pi_j|.$$

② Select controls that predict  $Y_t \Rightarrow \hat{I}_2$ :

$$\min_{\theta \in \mathbb{R}^p} \sum_{t=1}^T (Y_t - X_t' \theta)^2 + \lambda \sum_{j=1}^p |l_j^y \theta_j|.$$

**3** Post-double-selection estimator  $\check{\alpha}$  of  $\alpha$ :

$$(\check{\alpha}, \check{\beta}) = \operatorname*{arg\,min}_{\alpha \in \mathbb{R}, \beta \in \mathbb{R}^p} \Big\{ \sum_{t=1}^T (Y_t - D_t \alpha - X_t' \beta)^2 : \beta_j = 0, \forall j \notin \hat{I}_1 \cup \hat{I}_2 \Big\}.$$

Post Model Selection Estimator

Why is double selection important? Consider the model with one control:

$$Y_t = D_t \alpha + X_t \beta + U_t,$$
  
$$D_t = X_t \pi + V_t,$$

where

$$\begin{bmatrix} U_t \\ V_t \end{bmatrix} \middle| X_t \sim N \bigg( 0, \begin{bmatrix} \sigma_u^2 & 0 \\ 0 & \sigma_v^2 \end{bmatrix} \bigg), \quad X_t \sim N(0, 1).$$

Then,  $X_t$  and  $D_t$  are jointly normal with  $\sigma_d^2 = \pi^2 + \sigma_v^2$  and correlation  $\rho = \pi/\sigma_d$ .

Post Model Selection Estimator

Single selection drops  $X_t$  wp $\rightarrow 1$  if

$$\beta \le \frac{\sqrt{\log T}}{\sqrt{T}} \frac{\sigma_u}{\sqrt{1 - \rho^2}}.$$

- In low-dimensional settings, implemented with a conservative t-test: drop  $X_t$  if  $|t| = \hat{\beta}/\sec(\hat{\beta}) \leq \Phi^{-1}(1-1/(2T)) = \sqrt{2\log T}(1+o(1))$
- In high-dimensional settings, implemented with Lasso

Post Model Selection Estimator

Consider a sequence 
$$\beta_T = \frac{\sqrt{\log T}}{\sqrt{T}} \frac{\sigma_u}{\sqrt{1-\rho^2}}$$
.

- t-test cannot distinguish  $\beta_T$  from 0 and drops  $X_t$  wp $\rightarrow 1$ .
- In this case, post-single-selection estimator  $\tilde{\alpha}$  performs poorly:

$$\begin{split} \sqrt{T}(\tilde{\alpha} - \alpha) &= \frac{\frac{1}{\sqrt{T}} \sum_{t=1}^{T} D_t(X_t \beta_T + U_t)}{\frac{1}{T} \sum_{t=1}^{T} D_t^2} \\ &= \sqrt{T} \beta_T \cdot \frac{\frac{1}{T} \sum_{t=1}^{T} D_t X_t}{\frac{1}{T} \sum_{t=1}^{T} D_t^2} + \underbrace{\frac{\frac{1}{\sqrt{T}} \sum_{t=1}^{T} D_t U_t}{\frac{1}{T} \sum_{t=1}^{T} D_t^2}}_{\geq \frac{1}{2} \sqrt{\log T} \frac{\sigma_u}{\sqrt{1 - \rho^2}} \frac{|\rho|}{\sigma_d} \operatorname{wp} \to 1} + \underbrace{\frac{\frac{1}{\sqrt{T}} \sum_{t=1}^{T} D_t U_t}{\frac{1}{T} \sum_{t=1}^{T} D_t^2}}_{\Rightarrow N(0, \sigma_u^2 / \sigma_d^2)} \propto \sqrt{\log T} \to \infty. \end{split}$$

Post Model Selection Estimator

Double selection drops  $X_t$  with positive probability only if

$$\text{both } |\beta| < \frac{\sqrt{\log T}}{\sqrt{T}} \frac{\sigma_u}{\sqrt{1-\rho^2}} \text{ and } |\pi| < \frac{\sqrt{\log T}}{\sqrt{T}} \sigma_v.$$

When  $X_t$  is dropped, wp $\rightarrow 1$ ,

$$\frac{1}{\sqrt{T}} \sum_{t=1}^{T} D_t X_t \beta \le 2\sqrt{T} |\pi\beta| \propto \frac{\log T}{\sqrt{T}} \to 0.$$

Hence, post-double-selection estimator  $\check{\alpha}$  is asymptotically normal:

$$\sqrt{T}(\check{\alpha} - \alpha) = \frac{\frac{1}{\sqrt{T}} \sum_{t=1}^{T} D_t(X_t \beta + U_t)}{\frac{1}{T} \sum_{t=1}^{T} D_t^2} \xrightarrow{d} N(0, \sigma_u^2 / \sigma_d^2).$$

Post Model Selection Estimator

- When p is small relative to T, post-double selection estimator is first-order equivalent to the full regression.
- When  $p \propto T$  or  $p \gg T$ , this equivalence disappears, but the post-double selection method continues to be regular.

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Non-Regular Estimators

Selected Questions from PS3

### PS3 Q2

2:

Consider a panel data model with  $1 \le i \le n$  individuals, each observed for  $1 \le t \le T$  periods. Let  $Y_i = (Y_{i1}, \dots, Y_{iT})'$ , with  $Y_{it} \in \mathbb{R}$ , and  $X_i = (X_{i1}, \dots, X_{iT})'$  with  $X_{it} \in \mathbb{R}^{d_X}$ . Further, suppose

$$Y_{it} = X'_{it}\beta + \alpha_i + U_{it} , \qquad (4)$$

where  $U_i = (U_{i1}, \dots, U_{iT})' \in \mathbb{R}^T$  is distributed according to  $U_i \sim N(0, \Sigma)$  for some unknown covariance matrix  $\Sigma$ . Throughout this problem, assume  $\{Y_i, X_i, U_i\}_{i=1}^N$  are i.i.d. and  $U_i$  is independent of  $X_i$ . We will treat  $\beta$ ,  $\Sigma$  and  $\alpha = (\alpha_1, \dots, \alpha_N)' \in \mathbb{R}^N$  as the unknown parameters to be estimated.

#### PS3 Q2

- (a) Write down the log-likelihood for this problem.
- (b) For simplicity, assume  $Var(U_{it}) = \sigma^2$  for all  $1 \le t \le T$ , and write down an explicit form for:

$$\sum_{i=1}^{n} \sum_{t=1}^{T} \log\{f(Y_{it}|X_i)\}, \qquad (5)$$

where  $f(Y_{it}|X_i)$  denotes the density of  $Y_{it}$  given  $X_i$ . This partial log-likelihood differs from your answer to (a) because it does not fully use  $U_i$ 's joint distribution, but this likelihood can be used to estimate some of the model parameters. Explain why the partial likelihood in (5) cannot: (i) fully identify  $\beta$  if elements of  $X_{it}$  are time-invariant for all t, (ii) fully identify  $\Sigma$ .

- (c) In what follows, assume  $X_{it}$  does not contain time invariant elements. Derive closed-form expressions for the maximum (partial) likelihood estimators of  $(\beta, \alpha, \sigma^2)$  obtained by using part (b). Going forward, we will denote these estimators by  $(\hat{\beta}, \hat{\alpha}, \hat{\sigma}^2)$ .
- (d) Establish the asymptotic normality of  $\sqrt{N}(\hat{\beta} \beta)$  using an asymptotic framework in which  $N \to \infty$  but T remains fixed. State what assumptions you need to impose.
- (e) Is  $\hat{\alpha}_i$  an unbiased estimator of  $\alpha_i$ ? Is it consistent as  $N \to \infty$  but T is fixed?

## PS3 Q2(a)

Let  $\mathbf{1}_T$  be a  $T \times 1$  vector with 1 in every component. Observing that

$$Y_i|X_i \sim N(X_i\beta + \alpha_i \mathbf{1}_T, \Sigma),$$

the likelihood of  $Y_i$  given  $X_i$  is

$$L_i(\beta, \alpha, \Sigma) = f_i(Y_i | X_i; \beta, \alpha, \Sigma)$$
  
=  $(2\pi)^{-T/2} \det(\Sigma)^{-1/2} \exp\left\{-\frac{1}{2}(Y_i - X_i\beta - \alpha_i \mathbf{1}_T)'\Sigma^{-1}(Y_i - X_i\beta - \alpha_i \mathbf{1}_T)\right\}.$ 

Since  $\{Y_i, X_i, U_i\}_{i=1}^N$  are i.i.d., the log-likelihood function is

$$\begin{split} \bar{\ell}_N(\beta,\alpha,\Sigma) &= \sum_{i=1}^N \ln L_i(\beta,\alpha,\Sigma) \\ &= -\frac{NT}{2} \ln(2\pi) - \frac{N}{2} \ln(\det(\Sigma)) - \frac{1}{2} \sum_{i=1}^N (Y_i - X_i\beta - \alpha_i \mathbf{1}_T)' \Sigma^{-1} (Y_i - X_i\beta - \alpha_i \mathbf{1}_T). \end{split}$$

# PS3 Q2(b)

The partial log-likelihood is

$$\tilde{\ell}_{N}(\beta, \alpha, \sigma^{2}) = \sum_{i=1}^{N} \sum_{t=1}^{T} \ln f(Y_{it}|X_{it})$$

$$= -\frac{NT}{2} \ln(2\pi) - \frac{NT}{2} \ln(\sigma^{2}) - \frac{1}{2\sigma^{2}} \sum_{i=1}^{N} \sum_{t=1}^{T} (Y_{it} - X'_{it}\beta - \alpha_{i})^{2}.$$

- For simplicity, let  $X_{it} \equiv X_i$ . Take any  $\beta^{(1)} \neq \beta^{(2)}$ . Let  $\alpha^{(1)}, \alpha^{(2)} \in \mathbb{R}^N$  satisfy  $\alpha_i^{(2)} \alpha_i^{(1)} = X_i'(\beta^{(1)} \beta^{(2)})$  for each i. Then,  $\tilde{\ell}_N(\beta^{(1)}, \alpha^{(1)}, \sigma^2) = \tilde{\ell}_N(\beta^{(2)}, \alpha^{(2)}, \sigma^2)$ . Hence,  $\beta$  is not identified.
- ② Since  $\tilde{\ell}_N(\beta, \alpha, \sigma^2)$  does not depend on the off-diagonal elements of  $\Sigma$ , these elements are not identified.

# PS3 Q2(c)

#### The FOCs are

$$\frac{\partial \tilde{\ell}_N(\hat{\beta}, \hat{\alpha}, \hat{\sigma^2})}{\partial \beta} = \frac{1}{\hat{\sigma}^2} \sum_{i=1}^N \sum_{t=1}^T X_{it} (Y_{it} - X'_{it} \hat{\beta} - \hat{\alpha}_i) = 0, \tag{1}$$

$$\frac{\partial \tilde{\ell}_N(\hat{\beta}, \hat{\alpha}, \hat{\sigma}^2)}{\partial \alpha_i} = \frac{1}{\hat{\sigma}^2} \sum_{t=1}^T (Y_{it} - X'_{it} \hat{\beta} - \hat{\alpha}_i) = 0, \quad i = 1, \dots, N, \quad (2)$$

$$\frac{\partial \tilde{\ell}_N(\hat{\beta}, \hat{\alpha}, \hat{\sigma}^2)}{\partial \sigma^2} = -\frac{NT}{2\hat{\sigma}^2} + \frac{1}{2\hat{\sigma}^4} \sum_{i=1}^N \sum_{t=1}^T (Y_{it} - X'_{it}\hat{\beta} - \hat{\alpha}_i)^2 = 0.$$
 (3)

## PS3 Q2(c)

Let 
$$\bar{Y}_i = \frac{1}{T} \sum_{t=1}^{T} Y_{it}$$
 and  $\bar{X}_i = \frac{1}{T} \sum_{t=1}^{T} X_{it}$ . By (2),

$$\hat{\alpha}_i = \bar{Y}_i - \bar{X}_i' \hat{\beta}, \quad i = 1, \dots, N.$$
(4)

Plugging (4) into (1),

$$\hat{\beta} = \left[ \sum_{i=1}^{N} \sum_{t=1}^{T} X_{it} (X_{it} - \bar{X}_i)' \right]^{-1} \sum_{i=1}^{N} \sum_{t=1}^{T} X_{it} (Y_{it} - \bar{Y}_i).$$

By (3),

$$\hat{\sigma}^2 = \frac{1}{NT} \sum_{i=1}^{N} \sum_{t=1}^{T} (Y_{it} - X'_{it}\hat{\beta} - \hat{\alpha}_i)^2.$$

# PS3 Q2(d)

We need to impose the following assumptions:

- $\operatorname{rank}(E[X_i'Q_TX_i]) = d_X;$
- $E[||X_{it}||^2] < \infty$ .

We can write

$$\sqrt{N}(\hat{\beta} - \beta) = \left(\underbrace{\frac{1}{N} \sum_{i=1}^{N} X_i' Q_T X_i}_{\stackrel{p}{\to} E[X_i' Q_T X_i]}\right)^{-1} \frac{1}{\sqrt{N}} \sum_{i=1}^{N} X_i' Q_T U_i.$$

We can calculate  $\operatorname{Var}(X_i'Q_TU_i) = E[X_i'Q_T\Sigma Q_TX_i]$ . By the CLT,

$$\frac{1}{\sqrt{N}} \sum_{i=1}^{N} X_i' Q_T U_i \stackrel{d}{\to} N(0, E[X_i' Q_T \Sigma Q_T X_i]).$$

Put together, by Slutsky's theorem,

$$\sqrt{N}(\hat{\beta} - \beta) \stackrel{d}{\to} N(0, E[X_i'Q_TX_i]^{-1}E[X_i'Q_T\Sigma Q_TX_i]E[X_i'Q_TX_i]^{-1}).$$

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# PS3 Q2(e)

Let  $\bar{U}_i = \frac{1}{T} \sum_{t=1}^{T} U_{it}$ . We have

$$\hat{\alpha}_i - \alpha_i = \bar{Y}_i - \bar{X}_i'\hat{\beta} - \alpha_i = -\bar{X}_i'(\hat{\beta} - \beta) + \bar{U}_i.$$

Note that

$$E[\hat{\beta} - \beta | \mathbf{X}] = \left(\sum_{i=1}^{N} X_i' Q_T X_i\right)^{-1} \sum_{i=1}^{N} X_i' Q_T E[U_i] = 0.$$

By the law of iterated expectations,

$$E[\hat{\alpha}_i - \alpha_i] = E[\bar{X}_i'(\hat{\beta} - \beta) + \bar{U}_i] = -E[\bar{X}_i'E[\hat{\beta} - \beta|\mathbf{X}]] + E[\bar{U}_i] = 0.$$

Hence,  $\hat{\alpha}_i$  is an unbiased estimator of  $\alpha_i$ . Since  $\hat{\beta} - \beta \xrightarrow{p} 0$  by part (d), as  $N \to \infty$  but T is fixed,  $\hat{\alpha}_i - \alpha_i \xrightarrow{p} \bar{U}_i \neq 0$ . Hence,  $\hat{\alpha}_i$  is not consistent for  $\alpha$ .

### PS3 Q4

4: A log-likelihood function  $\bar{\ell}_T(\theta_1, \theta_2)$  is a function of two sets of parameters  $\theta_1$  and  $\theta_2$ . Define  $\theta_2^*(\theta_1)$  by the identity

$$\frac{\partial \bar{\ell}_T(\theta_1,\theta_2)}{\partial \theta_2}\Big|_{\theta_2=\theta_2^*(\theta_1)}=0$$

and define  $\bar{\ell}_T^*(\theta_1) = \bar{\ell}_T(\theta_1, \theta_2^*(\theta_1)).$ 

- (a) Show that maximizing  $\bar{\ell}_T$  with respect to  $\theta_1$  and  $\theta_2$  is the same as maximizing  $\bar{\ell}_T^*$  with respect to  $\theta_1$ .
- (b) What is  $\frac{\partial \bar{\ell}_T^*(\theta_1)}{\partial \theta_1}$ ? Show how it is related to a partial derivative of  $\bar{\ell}_T$ . (Hint: Use the envelope theorem.)
- (c) Show that  $H^* = H_{11} H_{12}H_{22}^{-1}H_{21}$  where  $H^*$  and H are the Hessians of  $\bar{\ell}_T^*$  and  $\bar{\ell}_T$  and H is partitioned in an obvious way.
- (d) Discuss the advantages of applying the Newton-Raphson method before or after concentration.

# PS3 Q4(a)

Let

$$(\hat{\theta}_1,\hat{\theta}_2) = \argmax_{\theta_1,\theta_2} \bar{\ell}_T(\theta_1,\theta_2), \quad \tilde{\theta}_1 = \argmax_{\theta_1} \bar{\ell}_T^*(\theta_1), \quad \tilde{\theta}_2 = \theta_2^*(\tilde{\theta}_1).$$

The FOCs for  $(\hat{\theta}_1, \hat{\theta}_2)$  are

$$\frac{\partial \bar{\ell}_T(\theta_1, \theta_2)}{\partial \theta_1} \Big|_{(\theta_1, \theta_2) = (\hat{\theta}_1, \hat{\theta}_2)} = 0, \quad \frac{\partial \bar{\ell}_T(\theta_1, \theta_2)}{\partial \theta_2} \Big|_{(\theta_1, \theta_2) = (\hat{\theta}_1, \hat{\theta}_2)} = 0.$$

## PS3 Q4(a)

On the other hand, by the envelope theorem, for any  $\theta_1$ ,

$$\frac{\partial \bar{\ell}_{T}^{*}(\theta_{1})}{\partial \theta_{1}} = \frac{\partial \bar{\ell}_{T}(\theta_{1}, \theta_{2})}{\partial \theta_{1}} \Big|_{\theta_{2} = \theta_{2}^{*}(\theta_{1})} + \underbrace{\frac{\partial \bar{\ell}_{T}(\theta_{1}, \theta_{2})}{\partial \theta_{2}} \Big|_{\theta_{2} = \theta_{2}^{*}(\theta_{1})}}_{=0} \underbrace{\frac{\partial \theta_{2}^{*}(\theta_{1})}{\partial \theta_{1}}.$$
(5)

Hence, the FOC for  $\tilde{\theta}_1$  is

$$0 = \frac{\partial \bar{\ell}_T^*(\tilde{\theta}_1)}{\partial \theta_1} = \frac{\partial \bar{\ell}_T(\theta_1, \theta_2)}{\partial \theta_1} \Big|_{\theta_1 = \tilde{\theta}_1, \theta_2 = \theta_2^*(\tilde{\theta}_1)} = \frac{\partial \bar{\ell}_T(\theta_1, \theta_2)}{\partial \theta_1} \Big|_{(\theta_1, \theta_2) = (\tilde{\theta}_1, \tilde{\theta}_2)}.$$

Also, by the definition of  $\theta_2^*(\theta_1)$ , the FOC for  $\tilde{\theta}_2$  is

$$0 = \frac{\partial \bar{\ell}_T(\theta_1, \theta_2)}{\partial \theta_2} \Big|_{\theta_1 = \tilde{\theta}_1, \theta_2 = \theta_2^*(\tilde{\theta}_1)} = \frac{\partial \bar{\ell}_T(\theta_1, \theta_2)}{\partial \theta_2} \Big|_{(\theta_1, \theta_2) = (\tilde{\theta}_1, \tilde{\theta}_2)}.$$

Therefore, the FOCs for  $(\hat{\theta}_1, \hat{\theta}_2)$  and  $(\tilde{\theta}_1, \tilde{\theta}_2)$  coincide.

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# PS3 Q4(c)

We know that  $\theta_2^*(\theta_1)$  satisfies that for all  $\theta_1$ ,

$$\frac{\partial \bar{\ell}_T(\theta_1, \theta_2^*(\theta_1))}{\partial \theta_2} = 0.$$

Differentiating with respect to  $\theta_1$  yields

$$0 = \frac{\partial^{2} \ell_{T}(\theta_{1}, \theta_{2}^{*}(\theta_{1}))}{\partial \theta_{2} \partial \theta_{1}'}$$

$$= \underbrace{\frac{\partial^{2} \bar{\ell}_{T}(\theta_{1}, \theta_{2})}{\partial \theta_{2} \partial \theta_{1}'}\Big|_{\theta_{2} = \theta_{2}^{*}(\theta_{1})}}_{=H_{21}} + \underbrace{\frac{\partial^{2} \bar{\ell}_{T}(\theta_{1}, \theta_{2})}{\partial \theta_{2} \partial \theta_{2}'}\Big|_{\theta_{2} = \theta_{2}^{*}(\theta_{1})}}_{=H_{22}} \frac{\partial \theta_{2}^{*}(\theta_{1})}{\partial \theta_{1}'}.$$

Hence,

$$\frac{\partial \theta_2^*(\theta_1)}{\partial \theta_1'} = -H_{22}^{-1} H_{21}. \tag{6}$$

## PS3 Q4(c)

On the other hand, differentiating (5) with respect to  $\theta_1$  yields

$$H^* = \frac{\partial^2 \ell_T^*(\theta_1)}{\partial \theta_1 \partial \theta_1'}$$

$$= \underbrace{\frac{\partial^2 \bar{\ell}_T(\theta_1, \theta_2)}{\partial \theta_1 \partial \theta_1'}}_{=H_{11}} \Big|_{\theta_2 = \theta_2^*(\theta_1)} + \underbrace{\frac{\partial^2 \bar{\ell}_T(\theta_1, \theta_2)}{\partial \theta_1 \partial \theta_2'}}_{=H_{12}} \Big|_{\theta_2 = \theta_2^*(\theta_1)} \underbrace{\frac{\partial \theta_2^*(\theta_1)}{\partial \theta_1'}}_{=H_{12}}.$$
(7)

Plugging (6) into (7) yields

$$H^* = H_{11} - H_{12}H_{22}^{-1}H_{21}.$$

# PS3 Q4(d)

Newton-Raphson before concentration uses

$$\hat{\theta}_{k+1} = \hat{\theta}_k - H(\hat{\theta}_k)^{-1} s(\hat{\theta}_k).$$

 $\Rightarrow$  solve a  $(K_1+K_2)$ -dimensional linear system  $H(\hat{\theta}_k)\Delta=-s(\hat{\theta}_k)$ .

• Newton-Raphson after concentration uses

$$\tilde{\theta}_{1,k+1} = \tilde{\theta}_{1,k} - H^*(\tilde{\theta}_{1,k})^{-1} s^*(\tilde{\theta}_{1,k}).$$

 $\Rightarrow$  solve a  $K_1$ -dimensional linear system  $H^*(\tilde{\theta}_{1,k})\Delta = -s^*(\tilde{\theta}_{1,k})$ .