view\_frames Result Recorded at time: 1524009800.796 map Broadcaster: /slam\_gmapping Average rate: 10000.000 Hz Most recent transform: 1524009800.731 ( 0.065 sec old) Buffer length: 0.000 sec odom Broadcaster: /movo/movo\_driver Average rate: 10000.000 Hz Most recent transform: 1524009800.668 ( 0.127 sec old) Buffer length: 0.000 sec base\_link Broadcaster: /robot\_state\_publisher Average rate: 10407.702 Hz Most recent transform: 1524009800.660 ( 0.136 sec old) Buffer length: 0.000 sec base\_chassis\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10407.702 Hz Most recent transform: 1524009800.660 ( 0.136 sec old) \ Most recent transform: 1524009800.660 ( 0.136 sec old) Most recent transform: 1524009800.660 ( 0.136 sec old) Buffer length: 0.000 sec linear\_actuator\_fixed\_link mid\_body\_link lower\_body\_link rear\_laser\_link sic\_imu\_frame front\_laser\_link Broadcaster: /robot\_state\_publisher Average rate: 10407.702 Hz Most recent transform: 1524009800.660 ( 0.136 sec old) Buffer length: 0.000 sec linear\_actuator\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10407.702 Hz Average rate: 10407.702 Hz Average rate: 10407.702 Hz Average rate: 10407.702 Hz Most recent transform: 1524009800.660 ( 0.136 sec old) | Most recent transform: 1524009800.660 ( 0.136 sec old) | Most recent transform: 1524009800.660 ( 0.136 sec old) | Most recent transform: 1524009800.660 ( 0.136 sec old) | Most recent transform: 1524009800.660 ( 0.136 sec old) | Most recent transform: 1524009800.660 ( 0.136 sec old) | Most recent transform: 1524009800.660 ( 0.136 sec old) | Most recent transform: 1524009800.660 ( 0.136 sec old) | Most recent transform: 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